

Principles of AI Planning

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Exercise Sheet 6

Due: Friday, December 4th, 2015

Exercise 6.1 (Stability of h_{add} , 2 points)

Show that it is important to test for stability when computing h_{add} by giving an example where you get an unnecessarily high overestimation when not performing this test.

Hint: The solution to this exercise is a planning task and its relaxed planning graph where h_{add} is higher in the goal node in layer k than in the goal node of layer $j > k$.

Exercise 6.2 (Relaxed planning graph and heuristics, 4 points)

Consider the relaxed planning task Π^+ with variables $A = \{a, b, c, d, e\}$, operators $O = \{o_1, o_2, o_3\}$, $o_1 = \langle d, c \wedge (c \triangleright e) \rangle$, $o_2 = \langle c, a \rangle$, $o_3 = \langle a, b \rangle$, goal $\gamma = b \wedge e$ and initial state $s = \{a \mapsto 0, b \mapsto 0, c \mapsto 0, d \mapsto 1, e \mapsto 0\}$. Solve the following exercises by drawing the relaxed planning graph for the lowest depth k that is necessary to extract a solution.

- Calculate $h_{\text{max}}(s)$ for Π^+ .
- Calculate $h_{\text{add}}(s)$ for Π^+ .
- Calculate $h_{\text{sa}}(s)$ for Π^+ .
- Calculate $h_{\text{FF}}(s)$ for Π^+ .

Exercise 6.3 (Finite-domain representation, 1+1+2 points)

Consider the propositional Blocksworld planning task $\Pi = \langle A, I, O, \gamma \rangle$, with

- the set of variables

$$A = \{A\text{-clear}, B\text{-clear}, C\text{-clear}, A\text{-on-}B, A\text{-on-}C, A\text{-on-}T, \\ B\text{-on-}A, B\text{-on-}C, B\text{-on-}T, C\text{-on-}A, C\text{-on-}B, C\text{-on-}T\}$$

- $I(a) = 1$ for $a \in \{B\text{-on-}T, A\text{-on-}B, A\text{-clear}, C\text{-on-}T, C\text{-clear}\}$,
 $I(a) = 0$, else.

- O contains the actions

$$\begin{aligned} \text{move-}X\text{-}Y\text{-}Z &= \langle X\text{-on-}Y \wedge X\text{-clear} \wedge Z\text{-clear}, \\ &\quad \neg X\text{-on-}Y \wedge Y\text{-clear} \wedge X\text{-on-}Z \wedge \neg Z\text{-clear} \rangle \\ \text{move-}X\text{-Table-}Z &= \langle X\text{-on-}T \wedge X\text{-clear} \wedge Z\text{-clear}, \\ &\quad \neg X\text{-on-}T \wedge X\text{-on-}Z \wedge \neg Z\text{-clear} \rangle \\ \text{move-}X\text{-}Y\text{-Table} &= \langle X\text{-on-}Y \wedge X\text{-clear}, \\ &\quad \neg X\text{-on-}Y \wedge Y\text{-clear} \wedge X\text{-on-}T \rangle \end{aligned}$$

for pair-wise distinct $X, Y, Z \in \{A, B, C\}$

- $\gamma = B\text{-on-}C \wedge C\text{-on-}A$.

(a) The following mutex groups can be found for Π :

$$L_1 = \{B\text{-on-}A, C\text{-on-}A, A\text{-clear}\}$$

$$L_2 = \{A\text{-on-}B, C\text{-on-}B, B\text{-clear}\}$$

$$L_3 = \{A\text{-on-}C, B\text{-on-}C, C\text{-clear}\}$$

$$L_4 = \{A\text{-on-}B, A\text{-on-}C, A\text{-on-}T\}$$

$$L_5 = \{B\text{-on-}A, B\text{-on-}C, B\text{-on-}T\}$$

$$L_6 = \{C\text{-on-}A, C\text{-on-}B, C\text{-on-}T\}$$

Specify a planning task Π' that is equivalent to Π and in finite-domain representation by using these mutex groups. Please name the variables in a reasonable way (e.g., analogously to the examples given in the lecture).

(b) Specify the propositional planning task Π'' that is induced by Π' .

(c) A planning task $\Pi' = \langle V, I', O', \gamma' \rangle$ in finite-domain representation is equivalent to a propositional planning task Π if there is an isomorphism between $\Pi'' = \langle A'', I'', O'', \gamma'' \rangle$ and Π , where Π'' is the propositional planning task induced by Π' .

There is an isomorphism between Π'' and Π if there are injective mappings $f : S \mapsto S''$ and $g : O \mapsto O''$ (where S is the set of reachable states in Π and S'' the set of states in Π'') with:

- $I'' = f(I)$
- For reachable states s_1 and s_2 , if $s_2 = \text{app}_o(s_1)$ then $f(s_2) = \text{app}_{g(o)}(f(s_1))$.
- For all reachable states $s \in S$ it is true that $s \models \gamma$ iff $f(s) \models \gamma''$.

Show that the planning task Π' from exercise (a) is equivalent to Π by specifying $f : S \mapsto S''$ and $g : O \mapsto O''$ and showing that they have the required properties.

You may and should solve the exercise sheets in groups of two. Please state both names on your solution.