Principles of Knowledge Representation and Reasoning Qualitative Representation and Reasoning: Introduction

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Quantitative vs. Qualitative



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Spatio-temporal configurations can be described quantitatively by specifying the coordinates of the relevant objects:

Example: At time point 10.0 object A is at position (11.0,1.0,23.7), at time point 11.0 at position (15.2,3.5,23.7). From time point 0.0 to 11.0, object B is at position (15.2,3.5,23.7). Object C is at time point 11.0 at position (300.9,25.6,200.0) and at time point 35.0 at (11.0,1.0,23.7).

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Quantitative vs. Qualitative



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Often, however, a qualitative description (using a finite vocabulary) is more adequate:

Example: Object A hit object B. Afterwards, object C arrived.

Sometimes we want to reason with such descriptions, e.g.:

Object C was not close to object A when it hit object B.

Representation of Qualitative Knowledge



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Intention: Description of configurations using a finite vocabulary and reasoning about these descriptions

- Specification of a vocabulary: usually a finite set of relations (often binary) that are pairwise disjoint and exhaustive
- Specification of a language: often sets of atomic formulae (constraint networks), perhaps restricted disjunction
- Specification of a formal semantics
- Analysis of computational properties and design of reasoning methods (often constraint propagation)
- Perhaps, specification of operational semantics for verifying whether a relation holds in a given quantitative configuration

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Applications in ...



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- Natural language processing
- Specification of abstract spatio-temporal configurations
- Query languages for spatio-temporal information systems
- Layout descriptions of documents (and learning of such layouts)
- Action planning
- ...

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Qualitative Temporal Relations: *Point Calculus*



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We want to talk about time instants (points) and binary relations over them.

Vocabulary:

- \blacksquare X equals Y: X = Y
- X before Y: X < Y</p>
- \blacksquare X after Y: X > Y

■ Language:

- Allow for disjunctions of basic relations to express indefinite information. Use set of relations to express that. For instance, {<,=} expresses ≤.</p>
- 2³ different relations (including the impossible and the universal relation)
- Use sets of atomic formulae with these relations to describe configurations. For example:

$$\{x\{=\}y,y\{<,>\}z\}$$

Semantics: Interpret the time point symbols and relation

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Some Reasoning Problems



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$$\{x\{<,=\}y,y\{<,=\}z,v\{<,=\}y,w\{>\}y,z\{<,=\}x\}$$

- Satisfiability: Are there values for all time points such that all formulae are satisfied?
- Satisfiability with v{=}w?
- Finding a satisfying instantiation of all time points
- Deduction: Does x = y logically follow? Does v < = w follow?
- Finding a minimal description: What are the most constrained relations that describe the same set of instantiations?

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In general, qualitatively described configurations are simple logical theories:

- Only sets of atomic formulae to describe the configuration
- Only existentially quantified variables (or constants)
- A fixed background theory that describes the semantics of the relations (e.g., dense linear orders)
- We are interested in satisfiability, model finding, and deduction
- Constraint Satisfaction Problems

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Definition

A constraint satisfaction problem (CSP) is given by

- \blacksquare a set V of n variables $\{v_1, \ldots, v_n\}$,
- for each v_i , a value domain D_i
- constraints (relations over subsets of the variables)

Tasks:

Find one (or all) solution(s), i. e., tuples

$$(d_1,\ldots,d_n)\in D_1\times\cdots\times D_n$$

such that the assignment $v_i \mapsto d_i$ (1 $\leq i \leq n$) satisfies all constraints.

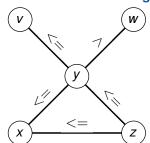
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- Our point relation CSP is a binary CSP with infinite domains.
- It can be represented as a constraint graph:



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CSP – Example



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k-colorability: Can we color the nodes of a graph with *k* colors in a way such that all nodes connected by an edge have different colors?

- The node set is the set of variables.
- The domain of each variable is $\{1, ..., k\}$
- The constraints are that nodes connected by an edge must have a different value

Note: This CSP has a particular restricted form:

- Only binary constraints
- The domains are finite

Other examples: Many problems (e.g. cross-word puzzle, *n*-queens problem, configuration, ...) can be cast as a CSP (and solved this way)

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Computational Complexity



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Theorem

It is NP-hard to decide solvability of CSPs, even binary CSPs.

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Since k-colorability is NP-complete (even for fixed $k \ge 3$), solvability of CSPs in general must be NP-hard.

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Question: Is CSP solvability in NP?

Solving CSP



- Enumeration of all assignments and testing
- - Backtracking search
- → 1001 different strategies, often "dead" search paths are explored extensively
 - Constraint propagation: elimination of obviously impossible values followed by backtracking search
 - Many other search methods, e.g., local search, stochastic search, etc.
- → How do we solve CSP with infinite domains?

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- Only at most binary constraints (i.e., we can use constraint graph)
- Uniform domain D for all variables
- Unary constraints D_i and binary constraints R_{ij} are sets of values or sets of pairs of values, resp.
- We assume that for all nodes i,j:

$$(x,y) \in R_{ij} \Rightarrow (y,x) \in R_{ji}$$

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- A CSP is **locally consistent** if for particular subsets of the variables, solutions of the restricted CSP can be extended to solutions of a larger set of variables.
- Methods to transform a CSP into a tighter, but "equivalent" problem.

Definition

A binary CSP $\langle V, D, C \rangle$ is arc consistent (or 2-consistent) if for all nodes 1 < i, j < n,

$$x \in D_i \Rightarrow \exists y \in D_j \text{ s.t. } (x,y) \in R_{ij}$$

→ When a CSP is arc consistent, each one variable assignment $\{v_i\} \to D$ that satisfies all (unary) constraints in v_i , i. e., D_i , can be extended to a two variable assignment $\{v_i, v_i\} \to D$ that satisfies all unary/binary constraints in these variables, i. e., D_i , D_i , and R_{ii} .

Arc Consistency



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EnforceArcConsistency (C):

Input: a (binary) CSP $C = \langle V, D, C \rangle$

Output: an equivalent, but arc consistent CSP \mathcal{C}'

repeat

for each arc (v_i, v_j) with $R_{ij} \in C$ $D_i := D_i \cap \{x \in D : \text{ex. } y \in D_j \text{ s.t. } (x, y) \in R_{ij}\}$

endfor

until no domain is changed

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- Terminates in time $O(n^3 \cdot k^3)$ if we have finite domains (where k is the number of values)
- There exist different (more efficient) algorithms for enforcing arc consistency.

Arc Consistency



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Lemma

- Enforcing arc consistency yields an arc consistent CSP.
- Enforcing arc consistency is solution invariant, i. e. it does not change the set of solutions.
- Arc consistent CSPs need not be consistent, and vice versa.

Arc Consistency – Example

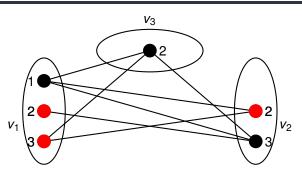




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$$D_1 = \{1,2,3\}$$
 $D_2 = \{2,3\}$
 $D_3 = \{2\}$
 $R_{ij} = "\neq" \text{ for } i \neq j$

Since all unary constraints are singletons, this is a solution of the CSP.



Definition

A binary CSP $\langle V, D, C \rangle$ is said to be path consistent (or 3-consistent) if for all nodes $1 \le i, j, k \le n$,

$$x \in D_i, y \in D_j, (x,y) \in R_{ij} \Rightarrow$$

 $\exists z \in D_k \text{ s.t. } (x,z) \in R_{ik} \text{ and } (y,z) \in R_{ik}$

When a CSP is path consistent, each two variable assignment $\{v_i, v_j\} \to D$ satisfying all constraints in v_i and v_j can be extended to any three variable assignment $\{v_i, v_j, v_k\} \to D$ such that all constraints in these variables are satisfied.

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Path Consistency



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EnforcePathConsistency (C):

Input: a (binary) CSP $C = \langle V, D, C \rangle$ of size n *Output*: an equivalent, but path consistent CSP C'

repeat

```
for all 1 \le i, j, k \le n

R_{ij} := R_{ij} \cap \{(x,y) : \text{ex. } z \in D_k \text{ s.t. } (x,z) \in R_{ik} \text{ and } (y,z) \in R_{jk}\}
```

endfor

until no binary constraint is changed

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- Terminates in time $O(n^5 \cdot k^5)$ if we have finite domains (where k is the number of values)
- → Enforcing path consistency is solution invariant.



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Definition

- A binary CSP $\langle V, D, C \rangle$ is k-consistent if, given variables x_1, \ldots, x_k and an assignment $a : \{x_1, \ldots, x_{k-1}\} \to D$ that satisfies all constraint in these variables, a can be extended to an assignment $a' : \{x_1, \ldots, x_k\} \to D$ that satisfies all constraints in these k variables.
- A binary CSP $\langle V, D, C \rangle$ is strongly *k*-consistent if it is k'-consistent for each k' < k.
- A binary CSP $\langle V, D, C \rangle$ is globally consistent if it is strongly n-consistent where n is the size of V.

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Local Consistency (3)



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- k-consistency: The computation costs grow exponentially with k.
- If a CSP is globally consistent, then
 - a solution can be constructed in polynomial time,
 - its constraints are minimal,
 - and it has a solution iff there is no empty constraint.
- k-consistent $\neq k-1$ -consistent

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Qualitative Reasoning with CSP



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If we want to use CSPs for qualitative reasoning, we have

- infinite domains
- mostly only finitely many relations (basic relations and their unions)
- arc consistent CSPs (usually)

Questions:

- How do we achieve k-consistency (for some fixed k)?
- Is k-consistency (for some fixed k) enough to guarantee global consistency?

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Operations on Binary Relations



Composition:

$$R_1 \circ R_2 = \{(x,y) \in D^2 : \exists z \in D \text{ s. t. } (x,z) \in R_1 \text{ and } (z,y) \in R_2\}$$

Converse:

$$R^{-1} = \{(x,y) \in D^2 : (y,x) \in R\}$$

Intersection:

$$R_1 \cap R_2 = \{(x,y) \in D^2 : (x,y) \in R_1 \text{ and } (x,y) \in R_2\}$$

Union:

$$R_1 \cup R_2 = \{(x,y) \in D^2 : (x,y) \in R_1 \text{ or } (x,y) \in R_2\}$$

Complement:

$$\overline{R} = \{(x,y) \in D^2 : (x,y) \notin R\}$$

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Conditions on Vocabulary for Qualitative Reasoning



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- Let **B** be a finite set of (binary) base relations.
- The relations in **B** should be JEPD, i. e., jointly exhaustive and pairwise disjoint.
 - **B** should be **closed under converse**.
 - Let **A** be the set of relations that can be built by taking the unions of relations from **B** (\rightsquigarrow 2^{|**B**|} different relations).
- → A is closed under converse, complement, intersection, union.
- A should be closed under composition of base relations, i. e., for all $B, B' \in \mathbf{B}$, $B \circ B' \in A$.
- → A is closed under composition of arbitrary relations.
- This condition does not hold necessarily.

 Example: **B** = {<,=,>} interpreted over the integers is not closed under composition (and has no finite closure):

$$\langle \circ \langle = \langle \setminus \{(i,j) : i = j-1\} \subsetneq \langle$$

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Computing Operations on Relations



Let **A** be a relation system over the set of base relations **B** that satisfies the conditions spelled out above.

→ We may write relations as sets of base relations:

$$B_1 \cup \cdots \cup B_n \sim \{B_1, \ldots, B_n\}$$

Then the operations on the relations can be computed as follows: Composition:

$$\{B_1,\ldots B_n\}\circ \{B'_1,\ldots,B'_m\}=\bigcup_{i=1}^n\bigcup_{j=1}^n(B_i\circ B'_j)$$

Converse:

$${B_1,\ldots,B_n}^{-1}={B_1^{-1},\ldots,B_n^{-1}}$$

Complement:

$$\overline{\{B_1,\ldots,B_n\}}=\{B\in \mathbf{B}: B\neq B_i, \text{ for each } 1\leq i\leq n\}$$

Intersection and union are defined set-theoretically.

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Reasoning Problems



Given a qualitative CSP:

CSP-Satisfiability (CSAT):

Is the CSP satisfiable/solvable?

CSP-Entailment (CENT):

Given in addition xRy: Is xRy satisfied in each solution of the CSP?

Computation of an equivalent minimal CSPs (CMIN):

Compute for each pair x, y the strongest constrained (minimal) relation entailed by the CSP.

→ These problems are equivalent under Turing reductions

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Reductions between CSP Problems



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Theorem

CSAT, CENT and CMIN are equivalent under polynomial Turing reductions.

Beweis.

CSAT $\leq_{\mathcal{T}}$ CENT and CENT $\leq_{\mathcal{T}}$ CMIN are obvious.

CENT \leq_T CSAT: We solve CENT ($CSP \models xRy$?) by testing satisfiability of the CSP extended by $x\{B\}y$ where B ranges over all base relations. Let B_1, \ldots, B_k be the relations for which we get a positive answer. Then $x\{B_1, \ldots, B_k\}y$ is entailed by the CSP.

CMIN \leq_T CENT: We use entailment for computing the minimal constraint for each pair. Starting with the universal relation, we remove one base relation until we have a minimal relation that is still entailed.

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Path Consistency for Qualitative CSPs



Given a qualitative CSP with $R_{ij} = R_{ji}^{-1}$. Then path consistency can be enforced by doing the following:

$$R_{ii} := R_{ii} \cap (R_{ik} \circ R_{ki}).$$

Path consistency guarantees ...

- sometimes minimality
- sometimes satisfiability
- however sometimes the CSP is not satisfiable, even if the CSP contains only base relations
- All this depends on the vocabulary.

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Example: Point Relations



Composition table:

	<	=	>
<	<	<	<,=,>
=	<	=	>
>	<,=,>	>	>

Abbildung: Composition table for the point algebra. For example:

$$\{<\} \circ \{=\} = \{<\}$$

$$\{<,=\} \circ \{<\} = \{<\}$$

$$\blacksquare \{<,>\} \circ \{<\} = \{<,=,>\}$$

$$\{<,=\}^{-1} = \{>,=\}$$

$$\{<,=\} \cap \{>,=\} = \{=\}$$

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Some Properties of the Point Relations



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Theorem

A path consistent CSP over the point relations is consistent.

Corollary

CSAT, CENT and CMIN are polynomial problems for the point relations.

Theorem

A path consistent CSP over all point relations without $\{<,>\}$ is minimal.

Proofs later ...

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Let e,d,i be (self-converse) base relations between points on a circle:

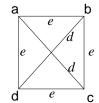
- e: Rotation by 72 degrees (left or right)
- d: Rotation by 144 degrees (left or right)
- *i*: Identity

Composition table:

$$e \circ e = \{i, d\}$$

 $d \circ d = \{i, e\}$
 $e \circ d = \{e, d\}$
 $d \circ e = \{e, d\}$

The following CSP is path consistent and contains only base relations, but it is not satisfiable:



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- Qualitative representation and reasoning usually starts with a finite vocabulary (a finite set of relations).
- Qualitative descriptions are usually simply logical theories consisting of sets of atomic formulae (and some background theory).
- Reasoning problems are (as usual) satisfiability, model finding, and deduction.
- Can be addressed with CSP methods (but note: infinite domains).
- Path consistency is the basic reasoning step ... sometimes this is enough.
- Usually, path-consistent atomic CSPs are satisfiable.
 However, there exist some pathological relation systems.
- Can be taken further ~> relation algebra

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Literature

January 8, 2014 Nebel, Wölfl, Hué – KRR

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Literature II



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(Contains a pathological set of relations.)

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