

Constraint Satisfaction Problems

Global Constraints

Bernhard Nebel and **Stefan Wöfl**

based on a slideset by
Malte Helmert and Stefan Wöfl
(summer term 2007)

Albert-Ludwigs-Universität Freiburg

December 21, 2009

Constraint Satisfaction Problems

December 21, 2009 — Global Constraints

Motivation

Global Constraints
All-different
Sum and Cardinality
Circuit

Filtering

Arc consistency
All-different Constraint

Global Constraints

What are global Constraints?

- ▶ Type of similar constraint relations ...
- ▶ ... differing in the number of variables
- ▶ **Semantically redundant**: same constraint can be expressed by a conjunction of simpler constraints
- ▶ **Similar structure**: can be exploited by constraint solvers

Examples:

- ▶ sum constraint, knapsack constraint, element constraint, all-different constraint, cardinality constraints

All-different constraint

Definition

Let v_1, \dots, v_n be variables each with a domain D_i ($1 \leq i \leq n$).

$$\text{alldifferent}(v_1, \dots, v_n) := \\ \{(d_1, \dots, d_n) \in D_1 \times \dots \times D_n : d_i \neq d_j \text{ for } i \neq j\}$$

The all-different constraint is a simple, but widely used global constraint in constraint programming.

It allows for compact modeling of CSP problems.

Example: n -Queens Problem

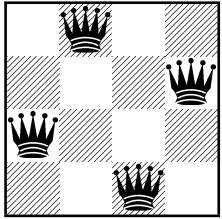


Figure: 4-queens problem

Problem representation:
 Variables v_i for each
 column $1, \dots, n$;
 v_i can take a “row value”
 $1, \dots, n$.

No-attack constraints:

$$\begin{aligned} v_i &\neq v_j \text{ for } 1 \leq i < j \leq n \\ v_i - v_j &\neq i - j \text{ for } 1 \leq i < j \leq n \\ v_j - v_i &\neq j - i \text{ for } 1 \leq i < j \leq n \end{aligned}$$

$$\begin{aligned} &\text{alldifferent}(v_1, \dots, v_n) \\ &\text{alldifferent}(v_1 - 1, \dots, v_n - n) \\ &\text{alldifferent}(v_1 + 1, \dots, v_n + n) \end{aligned}$$

Sum Constraint

Let v_1, \dots, v_n, z be variables with subsets of \mathbb{Q} as domain.
 For each v_i , let $c_i \in \mathbb{Q}$ be some fixed scalar, $c = (c_1, \dots, c_n)$.

Definition

The **sum constraint** is defined as:

$$\begin{aligned} \text{sum}(v_1, \dots, v_n, z, c) := \\ \{(d_1, \dots, d_n, d) \in (\prod_{1 \leq i \leq n} D_i) \times D_z : d = \sum_{1 \leq i \leq n} c_i d_i\}. \end{aligned}$$

Global Cardinality Constraint

v_1, \dots, v_n : “assignment variables” with $D_i \subseteq \{d_1^*, \dots, d_m^*\}$.
 c_1, \dots, c_m : “count variables” with sets of integers as domains.

Definition

The **global cardinality constraint** is defined as:

$$\begin{aligned} \text{gcc}(v_1, \dots, v_n, c_1, \dots, c_m) := \\ \{(d_1, \dots, d_n, o_1, \dots, o_m) \in \prod_{1 \leq i \leq n} D_{v_i} \times \prod_{1 \leq j \leq m} D_{c_j} : \\ \text{for each } j, d_j^* \text{ occurs in } (d_1, \dots, d_n) \text{ exactly } o_j \text{ times}\} \end{aligned}$$

The global cardinality constraint can be considered a generalization of the all-different constraint.

Circuit Constraint

Let $s = (s_1, \dots, s_n)$ be a permutation of $\{1, \dots, n\}$.
 Define C_s as the smallest set that contains 1 and with each element i also s_i .
 (s_1, \dots, s_n) is called **cyclic** if $C_s = \{1, \dots, n\}$.

Definition

Let v_1, \dots, v_n be variables with domains $D_i = \{1, \dots, n\}$ ($1 \leq i \leq n$).

$$\begin{aligned} \text{circuit}(v_1, \dots, v_n) := \\ \{(d_1, \dots, d_n) \in D_1 \times \dots \times D_n : (d_1, \dots, d_n) \text{ is cyclic}\} \end{aligned}$$

Given an assignment $a = (d_1, \dots, d_n)$, define

$$A := \{(v_i, v_{d_i}) : d_i \in D_i, 1 \leq i \leq n\}.$$

Then, a satisfies $\text{circuit}(v_1, \dots, v_n)$ if and only if (V, A) is a directed cycle (without proper sub-cycles).

Example: Traveling Salesperson Problem

Traveling Salesperson Problem (TSP):

Given a set of n cities and distances c_{ij} between city i and city j , find the shortest route that visits all cities and finishes in the starting city.

TSP is not a constraint satisfaction problem, but a constraint optimization problem ...



Constraint Optimization Problem

Definition

A **constraint optimization problem** (COP) is a constraint satisfaction problem together with an **objective function** f that assign to each variable assignment a a value $f(a) \in \mathbb{Q}$.

- ▶ **Minimization COP:** Find a solution a that minimizes $f(a)$.
- ▶ **Maximization COP:** Find a solution a that maximizes $f(a)$.
- ▶ **Optimal solution:** Solution to a minimization (maximization) COP.

Decision problem associated to a COP:

Given an instance of a COP, (P, f) , and some threshold $t \in \mathbb{Q}$, is there a solution a of P such that $f(a) \geq t$ ($f(a) \leq t$, resp.)?

The Decision Problem of TSP

v_i : variable for city i with domain $D_i := \{1, \dots, n\} \setminus \{i\}$
(read as: value of v_i is the city to be visited next)

c_{ij} : distance between cities i and j (may not be symmetric)

t : bound for the total tour length

Then:

$$\text{circuit}(v_1, \dots, v_n) \\ \sum_{1 \leq i \leq n} c_{i v_i} \leq t$$

Filtering

- ▶ Constraint propagation techniques aim at **filtering** variable domains: remove useless values (that cannot participate in any solution) as early as possible.
- ▶ Filtering allows **false-positives** (values are kept though they are useless),
- ▶ ... but not false-negatives (useful value is removed).
- ▶ A constraint is "good" if it allows significant filtering (pruning of domain values) with low computational efforts.
- ▶ Constraint solver may benefit from exploiting the structure of such good constraints.

Filtering

Let (s, R) be a constraint.

Filtering algorithm: a filtering algorithm for a constraint (s, R) is an algorithm that filters the domains with respect to (s, R)

Complete filtering: every useless value from the domain of every variable that C is defined on is removed

Partial filtering: incomplete filtering

Enforcing Arc Consistency as Filtering Method

- ▶ In general, enforcing generalized arc consistency on a constraint network requires exponential time w.r.t. the largest arity of some constraint relation in the network.

Recall: Enforcing generalized arc consistency runs in time

$$O(erd^r),$$

where e is the number of constraints and r is the largest arity of some constraint in the network,

- ▶ Though general constraints have often high arity, there exist efficient methods to enforce generalized arc consistency.
- ▶ In the following we consider the all-different constraints.

Value Graphs

Definition

An undirected graph $G = \langle V, E \rangle$ is **bipartite** if there exists a partition $S \dot{\cup} T$ of V such that $E \subseteq S \times T$.

A directed graph $G = \langle V, A \rangle$ is **bipartite** if there exists a partition $S \dot{\cup} T$ of V such that $A \subseteq (S \times T) \cup (T \times S)$.

G is then written in the form $G = \langle S, T, E \rangle / G = \langle S, T, A \rangle$.

Definition

Let V be a set of variables and D be the union of all domains D_v for $v \in V$.

The **value graph** of V is defined as the following bipartite graph:

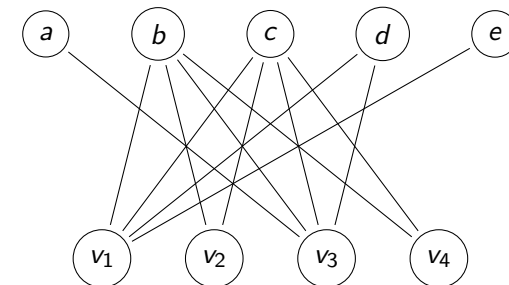
$$G = \langle V, D, E \rangle$$

where $E = \{\{v, d\} : v \in V, d \in D_v\}$.

Example: Value graph

Consider variables v_1, \dots, v_4 with $D_1 = \{b, c, d, e\}$, $D_2 = \{b, c\}$, $D_3 = \{a, b, c, d\}$, $D_4 = \{b, c\}$.

Value graph:



Matchings

Let $G = \langle V, E \rangle$ be an undirected graph.

Definition

A **matching** in G is a set $M \subseteq E$ of pairwise disjoint edges.

A matching M **covers** a set $S \subseteq V$ if $S \subseteq \bigcup M$, i.e., each $v \in S$ is contained in some edge in M .

$v \in V$ is **M -free** if M does not cover $\{v\}$.

Cardinality of a matching M : number of edges in M .

Definition

A path v_0, \dots, v_k in G is **M -alternating** if all the edges $\{v_i, v_{i+1}\}$ are alternatingly out of and in M .

A path v_0, \dots, v_k is **M -augmenting** if k is odd, M does not cover v_0 and v_k , and its edges $\{v_i, v_{i+1}\}$ are alternatingly out of and in M .

Let $G = \langle V, E \rangle$ be a graph and M be a matching in G .

Theorem (Peterson)

M is a **max-cardinality matching** (i.e., it is a matching of maximum cardinality) if and only if there is no M -augmenting path in G .

Hence a max-cardinality matching can be obtained if one repeatedly searches for an M -augmenting path in G and uses it to extend M .

Note: If M is a matching and v_0, \dots, v_k is an M -augmenting path, then

$$M' := M \oplus \{\{v_i, v_{i+1}\} : 0 \leq i \leq k-1\}$$

is a matching with $|M'| = |M| + 1$.

Max-Cardinality Matching on Bipartite Graphs

Let $G = \langle U, W, E \rangle$ be a bipartite graph and M be some matching. We may assume $|U| \leq |W|$.

Define a directed bipartite graph $G_M = \langle U, W, A \rangle$ by

$$A := \{(w, u) : \{u, w\} \in M, u \in U, w \in W\} \cup \{(u, w) : \{u, w\} \in E \setminus M, u \in U, w \in W\}$$

Every directed path in G_M starting in an M -free vertex in U and ending in an M -free vertex in W corresponds to an M -augmenting path in G .

We need to find at most $|U|$ such paths.

Each path can be identified by breadth-first search in time $O(|A|)$.

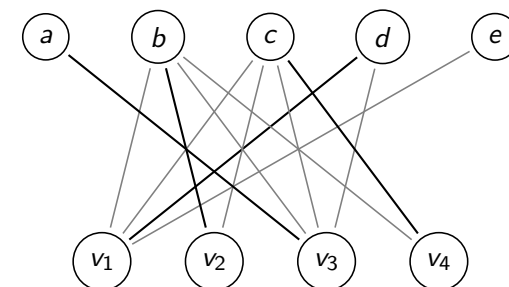
This method by van der Waerden and König can be improved by an algorithm by Hopcroft and Karp ($O(\sqrt{|U|} \cdot |A|)$).

All-different Constraint and Matching

Let $V = \{v_1, \dots, v_n\}$ be a set of variables and G be the value graph of V . Let (d_1, \dots, d_n) be a variable assignment.

Lemma

$(d_1, \dots, d_n) \in \text{alldifferent}(v_1, \dots, v_n)$ if and only if $M = \{\{v_1, d_1\}, \dots, \{v_n, d_n\}\}$ is a matching in G .



Arc-consistent All-different Constraint

Lemma

The constraint $alldifferent(v_1, \dots, v_n)$ is generalized arc-consistent, if and only if every edge in G belongs to a matching in G that covers V .

Proof.

Simple. □

Edges in Max-Cardinality Matchings

Theorem

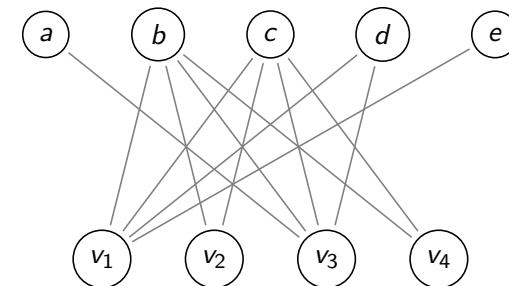
Let G be a graph and let M be a max-cardinality matching in G . An edge e belongs to some max-cardinality matching in G if and only if one of the following conditions holds:

- ▶ $e \in M$.
- ▶ e is on an even-length M -alternating path starting at an M -free vertex;
- ▶ e is on an even-length M -alternating circuit.

Enforcing Arc Consistency on All-different Constraints

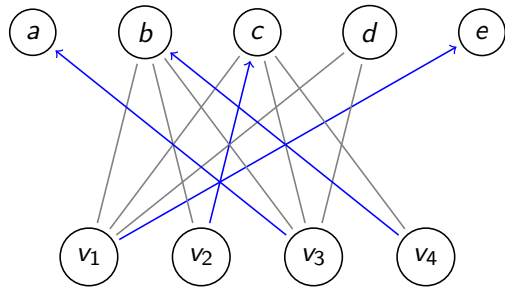
1. Compute a max-cardinality matching M in the value graph of V (can be done in time $O(m\sqrt{n})$ where $m = \sum_{1 \leq i \leq n} |D_i|$)
2. Identify the even M -alternating paths starting in an M -free vertex and the M -alternating cycles:
 - 2.1 Define dir. bipartite graph $G_M = \langle V, D_V, A \rangle$ with $A = \{(v, d) : v \in V, \{v, d\} \in M\} \cup \{(d, v) : v \in V, \{v, d\} \in E \setminus M\}$
 - 2.2 Compute the strongly connected components in G_M (in time $O(n + m)$)
 - 2.3 Mark acrs between vertices in the same component as "used": they belong to an even M -alternating cycle
 - 2.4 Mark acrs as "used" that belong to a directed path in G_M , start in an M -free vertex (breadth-first search in time $O(m)$).
3. Update $D_v \leftarrow D_v \setminus \{d\}$ for all edges $\{v, d\}$ where the corresponding arc is not marked as used.

Example: Enforcing Arc-Consistency



1. Compute max-cardinality matching
 $M = \{\{v_4, b\}, \{v_2, c\}, \{v_1, e\}, \{v_3, a\}\}$

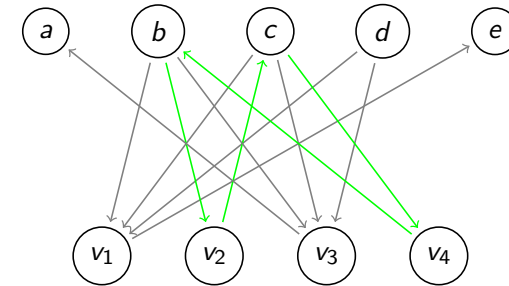
Example: Enforcing Arc-Consistency



2. Identify supported values:

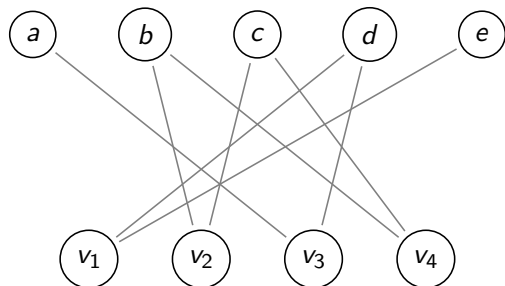
- (a) Identify G_M
- (b) Compute strongly connected components (e.g. by Kosaraju's algorithm)
- (c) Mark "used" arcs (d is the only M -free vertex)

Example: Enforcing Arc-Consistency



3. Filter unsupported values:
Remove unused arcs

Example: Enforcing Arc-Consistency



Literature



Willem-Jan van Hoeve and Irit Katriel.

Global Constraints,

Handbook of Constraint Programming, Elsevier, 2006