

# Constraint Satisfaction Problems

## Global Constraints

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# Constraint Satisfaction Problems

December 21, 2009 — Global Constraints

## Motivation

- Global Constraints
- All-different
- Sum and Cardinality
- Circuit

## Filtering

- Arc consistency
- All-different Constraint

# Global Constraints

What are global Constraints?

- ▶ Type of similar constraint relations . . .
- ▶ . . . differing in the number of variables
- ▶ **Semantically redundant**: same constraint can be expressed by a conjunction of simpler constraints
- ▶ **Similar structure**: can be exploited by constraint solvers

Examples:

- ▶ sum constraint, knapsack constraint, element constraint, all-different constraint, cardinality constraints

# All-different constraint

## Definition

Let  $v_1, \dots, v_n$  be variables each with a domain  $D_i$  ( $1 \leq i \leq n$ ).

$$\text{alldifferent}(v_1, \dots, v_n) := \\ \{(d_1, \dots, d_n) \in D_1 \times \dots \times D_n : d_i \neq d_j \text{ for } i \neq j\}$$

The all-different constraint is a simple, but widely used global constraint in constraint programming.

It allows for compact modeling of CSP problems.

## Example: $n$ -Queens Problem

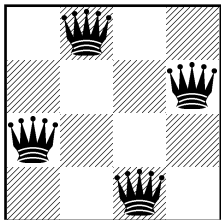


Figure: 4-queens problem

*Problem representation:*

Variables  $v_i$  for each  
column  $1, \dots, n$ ;

$v_i$  can take a “row value”  
 $1, \dots, n$ .

No-attack constraints:

$$v_i \neq v_j \text{ for } 1 \leq i < j \leq n$$

$$v_i - v_j \neq i - j \text{ for } 1 \leq i < j \leq n$$

$$v_j - v_i \neq j - i \text{ for } 1 \leq i < j \leq n$$

$$\text{alldifferent}(v_1, \dots, v_n)$$

$$\text{alldifferent}(v_1 - 1, \dots, v_n - n)$$

$$\text{alldifferent}(v_1 + 1, \dots, v_n + n)$$

# Sum Constraint

Let  $v_1, \dots, v_n, z$  be variables with subsets of  $\mathbb{Q}$  as domain.  
 For each  $v_i$ , let  $c_i \in \mathbb{Q}$  be some fixed scalar,  $c = (c_1, \dots, c_n)$ .

## Definition

The **sum constraint** is defined as:

$$\text{sum}(v_1, \dots, v_n, z, c) := \left\{ (d_1, \dots, d_n, d) \in \left( \prod_{1 \leq i \leq n} D_i \right) \times D_z : d = \sum_{1 \leq i \leq n} c_i d_i \right\}.$$

## Global Cardinality Constraint

$v_1, \dots, v_n$ : “assignment variables” with  $D_i \subseteq \{d_1^*, \dots, d_m^*\}$ .

$c_1, \dots, c_m$ : “count variables” with sets of integers as domains.

### Definition

The **global cardinality constraint** is defined as:

$$\text{gcc}(v_1, \dots, v_n, c_1, \dots, c_m) :=$$

$$\left\{ (d_1, \dots, d_n, o_1, \dots, o_m) \in \prod_{1 \leq i \leq n} D_{v_i} \times \prod_{1 \leq j \leq m} D_{c_j} : \right.$$

for each  $j$ ,  $d_j^*$  occurs in  $(d_1, \dots, d_n)$  exactly  $o_j$  times  $\left. \right\}$

The global cardinality constraint can be considered a generalization of the all-different constraint.

## Circuit Constraint

Let  $s = (s_1, \dots, s_n)$  be a permutation of  $\{1, \dots, n\}$ .

Define  $C_s$  as the smallest set that contains 1 and with each element  $i$  also  $s_i$ .

$(s_1, \dots, s_n)$  is called **cyclic** if  $C_s = \{1, \dots, n\}$ .

### Definition

Let  $v_1, \dots, v_n$  be variables with domains  $D_i = \{1, \dots, n\}$  ( $1 \leq i \leq n$ ).

$$\text{circuit}(v_1, \dots, v_n) := \\ \{(d_1, \dots, d_n) \in D_1 \times \dots \times D_n : (d_1, \dots, d_n) \text{ is cyclic}\}$$

Given an assignment  $a = (d_1, \dots, d_n)$ , define

$$A := \{(v_i, v_{d_i}) : d_i \in D_i, 1 \leq i \leq n\}.$$

Then,  $a$  satisfies  $\text{circuit}(v_1, \dots, v_n)$  if and only if  $(V, A)$  is a directed cycle (without proper sub-cycles).



# Example: Traveling Salesperson Problem

## Traveling Salesperson Problem (TSP):

Given a set of  $n$  cities and distances  $c_{ij}$  between city  $i$  and city  $j$ , find the shortest route that visits all cities and finishes in the starting city.

TSP is not a constraint satisfaction problem, but a constraint optimization problem ...



# Constraint Optimization Problem

## Definition

A **constraint optimization problem** (COP) is a constraint satisfaction problem together with an **objective function**  $f$  that assign to each variable assignment  $a$  a value  $f(a) \in \mathbb{Q}$ .

- ▶ **Minimization COP**: Find a solution  $a$  that minimizes  $f(a)$ .
- ▶ **Maximization COP**: Find a solution  $a$  that maximizes  $f(a)$ .
- ▶ **Optimal solution**: Solution to a minimization (maximization) COP.

## Decision problem associated to a COP:

Given an instance of a COP,  $(P, f)$ , and some threshold  $t \in \mathbb{Q}$ , is there a solution  $a$  of  $P$  such that  $f(a) \geq t$  ( $f(a) \leq t$ , resp.)?

# The Decision Problem of TSP

$v_i$  : variable for city  $i$  with domain  $D_i := \{1, \dots, n\} \setminus \{i\}$   
(read as: value of  $v_i$  is the city to be visited next)

$c_{ij}$  : distance between cities  $i$  and  $j$  (may not be symmetric)

$t$  : bound for the total tour length

Then:

$\text{circuit}(v_1, \dots, v_n)$

$$\sum_{1 \leq i \leq n} c_{iv_i} \leq t$$

# Filtering

- ▶ Constraint propagation techniques aim at **filtering** variable domains: remove useless values (that cannot participate in any solution) as early as possible.
- ▶ Filtering allows **false-positives** (values are kept though they are useless),
- ▶ ..... but not false-negatives (useful value is removed).
- ▶ A constraint is “good” if it allows significant filtering (pruning of domain values) with low computational efforts.
- ▶ Constraint solver may benefit from exploiting the structure of such good constraints.

# Filtering

Let  $(s, R)$  be a constraint.

**Filtering algorithm:** a filtering algorithm for a constraint  $(s, R)$  is an algorithm that filters the domains with respect to  $(s, R)$

**Complete filtering:** every useless value from the domain of every variable that  $C$  is defined on is removed

**Partial filtering:** incomplete filtering

## Enforcing Arc Consistency as Filtering Method

- ▶ In general, enforcing generalized arc consistency on a constraint network requires exponential time w.r.t. the largest arity of some constraint relation in the network.

Recall: Enforcing generalized arc consistency runs in time

$$O(erd^r),$$

where  $e$  is the number of constraints and  $r$  is the largest arity of some constraint in the network,

- ▶ Though general constraints have often high arity, there exist efficient methods to enforce generalized arc consistency.
- ▶ In the following we consider the all-different constraints.

# Value Graphs

## Definition

An undirected graph  $G = \langle V, E \rangle$  is **bipartite** if there exists a partition  $S \dot{\cup} T$  of  $V$  such that  $E \subseteq S \times T$ .

A directed graph  $G = \langle V, A \rangle$  is **bipartite** if there exists a partition  $S \dot{\cup} T$  of  $V$  such that  $A \subseteq (S \times T) \cup (T \times S)$ .

$G$  is then written in the form  $G = \langle S, T, E \rangle / G = \langle S, T, A \rangle$ .

## Definition

Let  $V$  be a set of variables and  $D$  be the union of all domains  $D_v$  for  $v \in V$ .

The **value graph** of  $V$  is defined as the following bipartite graph:

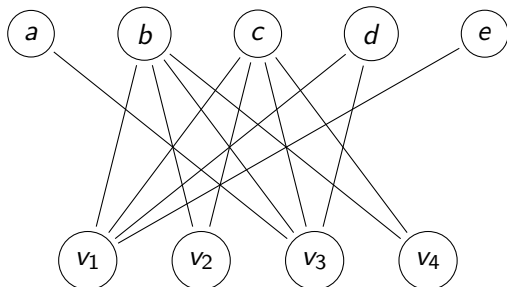
$$G = \langle V, D, E \rangle$$

where  $E = \{\{v, d\} : v \in V, d \in D_v\}$ .

## Example: Value graph

Consider variables  $v_1, \dots, v_4$  with  $D_1 = \{b, c, d, e\}$ ,  $D_2 = \{b, c\}$ ,  $D_3 = \{a, b, c, d\}$ ,  $D_4 = \{b, c\}$ .

Value graph:





## Matchings

Let  $G = \langle V, E \rangle$  be an undirected graph.

### Definition

A **matching** in  $G$  is a set  $M \subseteq E$  of pairwise disjoint edges.

A matching  $M$  **covers** a set  $S \subseteq V$  if  $S \subseteq \bigcup M$ , i.e., each  $v \in S$  is contained in some edge in  $M$ .

$v \in V$  is  **$M$ -free** if  $M$  does not cover  $\{v\}$ .

Cardinality of a matching  $M$ : number of edges in  $M$ .

### Definition

A path  $v_0, \dots, v_k$  in  $G$  is  **$M$ -alternating** if all the edges  $\{v_i, v_{i+1}\}$  are alternatingly out of and in  $M$ .

A path  $v_0, \dots, v_k$  is  **$M$ -augmenting** if  $k$  is odd,  $M$  does not cover  $v_0$  and  $v_k$ , and its edges  $\{v_i, v_{i+1}\}$  are alternatingly out of and in  $M$ .

Let  $G = \langle V, E \rangle$  be a graph and  $M$  be a matching in  $G$ .

### Theorem (Peterson)

*$M$  is a max-cardinality matching (i.e., it is a matching of maximum cardinality) if and only if there is no  $M$ -augmenting path in  $G$ .*

Hence a max-cardinality matching can be obtained if one repeatedly searches for an  $M$ -augmenting path in  $G$  and uses it to extend  $M$ .

Note: If  $M$  is a matching and  $v_0, \dots, v_k$  is an  $M$ -augmenting path, then

$$M' := M \oplus \{\{v_i, v_{i+1}\} : 0 \leq i \leq k - 1\}$$

is a matching with  $|M'| = |M| + 1$ .

## Max-Cardinality Matching on Bipartite Graphs

Let  $G = \langle U, W, E \rangle$  be a bipartite graph and  $M$  be some matching. We may assume  $|U| \leq |W|$ .

Define a directed bipartite graph  $G_M = \langle U, W, A \rangle$  by

$$A := \left\{ (w, u) : \{u, w\} \in M, u \in U, w \in W \right\} \cup \left\{ (u, w) : \{u, w\} \in E \setminus M, u \in U, w \in W \right\}$$

Every directed path in  $G_M$  starting in an  $M$ -free vertex in  $U$  and ending in an  $M$ -free vertex in  $W$  corresponds to an  $M$ -augmenting path in  $G$ .

We need to find at most  $|U|$  such paths.

Each path can be identified by breadth-first search in time  $O(|A|)$ .

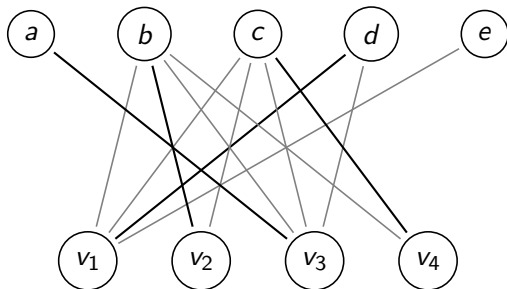
This method by van der Waerden and König can be improved by an algorithm by Hopcroft and Karp ( $O(\sqrt{|U|} \cdot |A|)$ ).

## All-different Constraint and Matching

Let  $V = \{v_1, \dots, v_n\}$  be a set of variables and  $G$  be the value graph of  $V$ .  
 Let  $(d_1, \dots, d_n)$  be a variable assignment.

### Lemma

$(d_1, \dots, d_n) \in \text{alldifferent}(v_1, \dots, v_n)$  if and only if  
 $M = \{\{v_1, d_1\}, \dots, \{v_n, d_n\}\}$  is a matching in  $G$ .



# Arc-consistent All-different Constraint

## Lemma

*The constraint  $alldifferent(v_1, \dots, v_n)$  is generalized arc-consistent, if and only if every edge in  $G$  belongs to a matching in  $G$  that covers  $V$ .*

Proof.

Simple. □

# Edges in Max-Cardinality Matchings

## Theorem

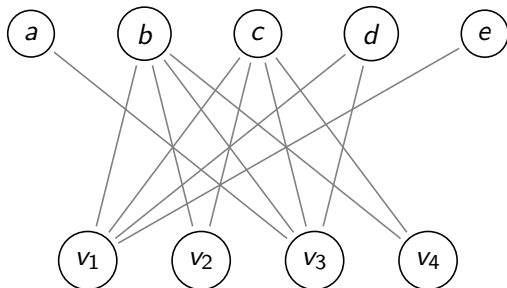
*Let  $G$  be a graph and let  $M$  be a max-cardinality matching in  $G$ . An edge  $e$  belongs to some max-cardinality matching in  $G$  if and only if one of the following conditions holds:*

- ▶  $e \in M$ .
- ▶  $e$  is on an even-length  $M$ -alternating path starting at an  $M$ -free vertex;
- ▶  $e$  is on an even-length  $M$ -alternating circuit.

# Enforcing Arc Consistency on All-different Constraints

1. Compute a max-cardinality matching  $M$  in the value graph of  $V$   
(can be done in time  $O(m\sqrt{n})$  where  $m = \sum_{1 \leq i \leq n} |D_i|$ )
2. Identify the even  $M$ -alternating paths starting in an  $M$ -free vertex and the  $M$ -alternating cycles:
  - 2.1 Define dir. bipartite graph  $G_M = \langle V, D_V, A \rangle$  with  $A = \{(v, d) : v \in V, \{v, d\} \in M\} \cup \{(d, v) : v \in V, \{v, d\} \in E \setminus M\}$
  - 2.2 Compute the strongly connected components in  $G_M$  (in time  $O(n + m)$ )
  - 2.3 Mark acrs between vertices in the same component as “used”: they belong to an even  $M$ -alternating cycle
  - 2.4 Mark acrs as “used” that belong to a directed path in  $G_M$ , start in an  $M$ -free vertex (breadth-first search in time  $O(m)$ ).
3. Update  $D_v \leftarrow D_v \setminus \{d\}$  for all edges  $\{v, d\}$  where the corresponding arc is not marked as used.

# Example: Enforcing Arc-Consistency

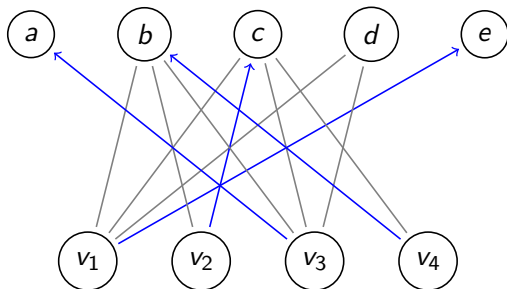


1. Compute max-cardinality matching

$$M = \{\{v_4, b\}, \{v_2, c\}, \{v_1, e\}, \{v_3, a\}\}$$



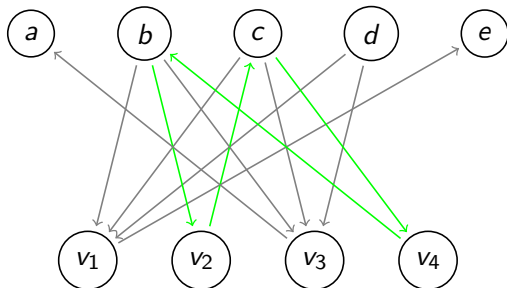
## Example: Enforcing Arc-Consistency



2. Identify supported values:

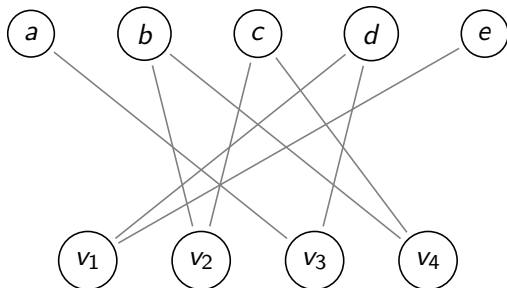
- (a) Identify  $G_M$  (b) Compute strongly connected components (e.g. by Kosaraju's algorithm)
- (c) Mark "used" arcs ( $d$  is the only  $M$ -free vertex)

# Example: Enforcing Arc-Consistency



3. Filter unsupported values:  
Remove unused arcs

# Example: Enforcing Arc-Consistency



# Literature



Willem-Jan van Hoeve and Irit Katriel.  
Global Constraints,  
Handbook of Constraint Programming, Elsevier, 2006