

Principles of AI Planning

Expressive power

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AI Planning

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Motivation

Propositional
STRIPS and
Variants

Expressive
Power

Summary

Motivation: Why Analyzing the Expressive Power?

- **Expressive power** is the motivation for designing new planning languages
- Often there is the question: *Syntactic sugar* or *essential feature*?
- ⇒ *Compiling away* or change planning algorithm?
- If a feature can be compiled away, then it is apparently only *syntactic sugar*.
- Sometimes, however, a compilation can lead to **much larger planning domain descriptions** or to **much longer plans**.
- ⇒ This means the planning algorithm will probably choke, i.e., it cannot be considered as a **compilation**

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Example: DNF Preconditions

- Assume we have **DNF preconditions** in STRIPS operators
 - This can be **compiled away** as follows
 - **Split** each operator with a DNF precondition $c_1 \vee \dots \vee c_n$ into n operators with the same effects and c_i as preconditions
- ↪ If there exists a plan for the original planning task there is one for the new planning task and *vice versa*
- The **planning task** has almost the **same size**
- The **shortest plans** have the **same size**

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Example: Conditional effects

- Can we compile away **conditional effects** to STRIPS?

- Example operator: $\langle a, b \triangleright d \wedge \neg c \triangleright e \rangle$

- Can be translated into four operators:

$\langle a \wedge b \wedge c, d \rangle, \langle a \wedge b \wedge \neg c, d \wedge e \rangle, \dots$

- Plan **existence** and plan **size** are identical

- **Exponential blowup** of domain description!

→ Can this be avoided?

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Propositional STRIPS and Variants

- In the following we will only consider **propositional STRIPS** and some variants of it.

- **Planning task:**

$$\mathcal{T} = \langle A, I, O, G \rangle.$$

- Often we refer to **domain structures** $\mathcal{D} = \langle A, O \rangle$.

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Disjunctive Preconditions: Trivial or Essential?

- Kambhampati et al [ECP 97] and Gazeen & Knoblock [ECP 97]: Disjunctive preconditions are trivial – since they can be translated to basic STRIPS (**DNF**-preconditions)
- Bäckström [AIJ 95]: Disjunctive preconditions are probably essential – since they can not easily be translated to basic STRIPS (**CNF**-preconditions)
- Anderson et al [AIPS 98]: “[D]isjunctive preconditions ... are ... essential prerequisites for handling conditional effects” \rightsquigarrow conditional effects imply disjunctive preconditions (?) (**General Boolean** preconditions)

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Summary

More “Expressive Power”

- STRIPS_N : plain strips with negative literals
- STRIPS_{Bd} : precondition in disjunctive normal form
- STRIPS_{Bc} : precondition in conjunctive normal form
- STRIPS_B : Boolean expressions as preconditions
- STRIPS_C : conditional effects
- STRIPS_{C,N} : conditional effects & negative literals
- ...

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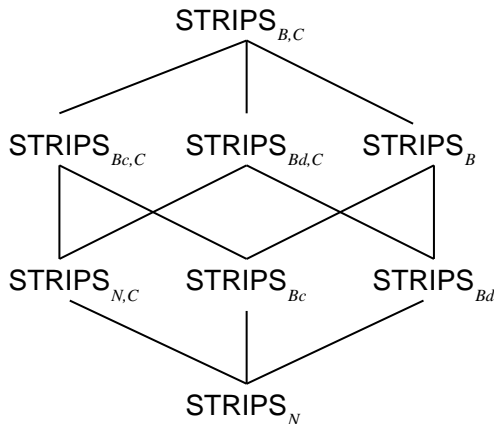
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Ordering Planning Formalisms Partially



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Computational Complexity ...

Theorem

PLANEX is PSPACE-complete for STRIPS_N, STRIPS_{C,B}, and for all formalisms “between” the two.

Proof.

Follows from theorems proved in the previous lecture. ☐

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Measuring Expressive Power

Consider **mappings** between planning problems in different formalisms

- that **preserve**
 - solution existence
 - plan size linearly or polynomially etc.
 - the exact plan size
 - the plan “structure”
 - the solutions/plans themselves
- that **are limited**
 - in the *size* of the result (poly. size)
 - in the *computational resources* (poly. time)
- that **transform**
 - entire planning instances
 - domain structure and states in isolation

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Method 1: Polynomial Transformation

- **preserving**

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⇒ all formalisms have the **same expressiveness** (?)

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Method 2: Bäckström's ESP-reductions

- **preserving**

- solution existence
- plan size linearly or polynomially etc.
- the exact plan size
- the plan “structure”
- the solutions/plans themselves

- **limiting**

- in the *size* of the result (poly. size)
- in the *computational resources* (poly. time)

- **transforming**

- entire planning instances
- domain structure and states in isolation

⇒ However, **expressiveness** is independent of the **computational resources** needed to compute the mapping

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Method 3: Polysize Mappings

- **preserving**

- solution existence
- plan size linearly or polynomially etc.
- the exact plan size
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↪ All formalisms are **trivially equivalent** (because planning is PSPACE-complete for all propositional STRIPS formalisms)

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Method 4: Modular & Polysize Mappings

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↪ When measuring the expressiveness of **planning formalisms**, domain structures should be considered independently from states

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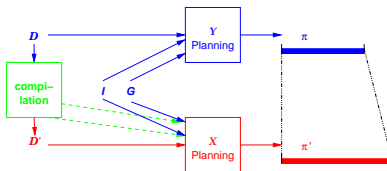
The Right Method: Compilation Schemes (Simplified)

- Transform **domain structure** $\mathcal{D} = \langle A, O \rangle$ (with polynomial blowup) to \mathcal{D}' preserving solution existence

- Only trivial changes to **states** (independent of operator set)

- Resulting **plans** π' should not grow too much (additive constant, linear growth, polynomial growth)

→ Similar to **knowledge compilation**, with operators as the *fixed part* and initial states & goals as the *varying part*



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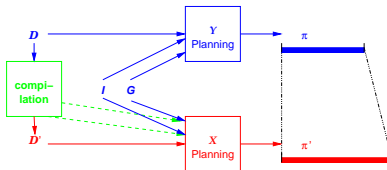
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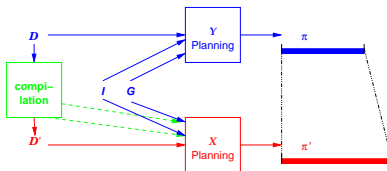
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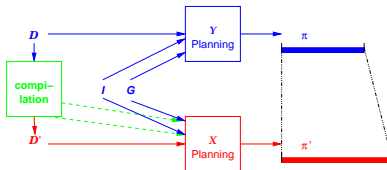
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Summary

Compilability

$\mathcal{Y} \preceq \mathcal{X}$ (\mathcal{Y} is compilable to \mathcal{X})

iff

there exists a compilation scheme from \mathcal{Y} to \mathcal{X} .

$\mathcal{Y} \preceq^1 \mathcal{X}$: preserving plan size **exactly** (modulo additive constants)

$\mathcal{Y} \preceq^c \mathcal{X}$: preserving plan size **linearly** (in $|\pi|$)

$\mathcal{Y} \preceq^p \mathcal{X}$: preserving plan size **polynomially** (in $|\pi|$ and $|\mathcal{D}|$)

$\mathcal{Y} \preceq_p^x \mathcal{X}$: **polynomial-time** compilability

Theorem

For all x, y , the relations \preceq_y^x are transitive and reflexive.

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Summary

Back-Translatability

- Shouldn't we also require that plans in the compiled instance can be *translated back* to the original formalism?
- Yes, if we want to use this technique, one should require that!
- In all *positive cases*, there was never any problem to translate the plan back
- For the *negative case*, it is easier to prove **non-existence**
- So, in order to prove negative results, we do not need it, for positive it never had been a problem
- ~> So, similarly to the concentration on *decision problems* when determining complexity, we simplify things here

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Summary

A (Trivial) Positive Result: $\text{STRIPS}_{Bd} \preceq_p^1 \text{STRIPS}_N$

DNF preconditions can be **“compiled away.”**

Assume operator $o = \langle c, e \rangle$ and

$$c = L_1 \vee \dots \vee L_k$$

with L_i being a conjunction of literals. Create k operators

$$o_i = \langle L_i, e \rangle$$

- compilation is solution-preserving,
- \mathcal{D}' is only polynomially larger than \mathcal{D} ,
- compilation can be computed in polynomial time,
- resulting plans do not grow at all.

$$\Rightarrow \text{STRIPS}_{Bd} \preceq_p^1 \text{STRIPS}_N$$

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A (Trivial) Positive Result: $\text{STRIPS}_{Bd} \preceq_p^1 \text{STRIPS}_N$

DNF preconditions can be “**compiled away.**”

Assume operator $o = \langle c, e \rangle$ and

$$c = L_1 \vee \dots \vee L_k$$

with L_i being a conjunction of literals. Create k operators

$o_i = \langle L_i, e \rangle$

- 1 compilation is solution-preserving,
- 2 \mathcal{D}' is only polynomially larger than \mathcal{D} ,
- 3 compilation can be computed in polynomial time,
- 4 resulting plans do not grow at all.

$\rightsquigarrow \text{STRIPS}_{Bd} \preceq_p^1 \text{STRIPS}_N$

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Another Positive Result: $\text{STRIPS}_{C,Bc} \preceq_p^c \text{STRIPS}_{C,N}$

CNF preconditions can be “**compiled away**” – provided we have already conditional effects.

- Evaluate the truth value of all disjunctions appearing in operators by using a **special evaluation operator** with conditional effects that make new “clause atoms” true
- Alternate between executing original operators (clauses replaced by new atoms) and evaluation operators
- ↪ Operator sets grow only **polynomially**
- ↪ Plans are **double as long** as the original plans
- ↪ **Anderson et al's conjecture** holds in a weak version

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A First Negative Result: Conditional Effects Cannot be Compiled into Boolean Preconditions

Consider domain \mathcal{D} with only one ($\text{STRIPS}_{C,B}$) operator o :

$$\langle \top, (p_1 \triangleright \neg p_1) \wedge (\neg p_1 \triangleright p_1) \wedge \dots \wedge (p_k \triangleright \neg p_k) \wedge (\neg p_k \triangleright p_k) \rangle,$$

which “inverts” a given state. For all (I, G) with

$$G = \bigwedge \{ \neg v \mid v \in A, I \models v \} \wedge \bigwedge \{ v \mid v \in A, I \not\models v \},$$

there exists a $\text{STRIPS}_{C,B}$ **one-step** plan.

Assume there exists a compilation preserving plan size linearly leading to a STRIPS_B domain structure \mathcal{D}' . There are exponentially many possible initial states, but only polynomially many different c -step plans for \mathcal{D}' . Some STRIPS_B plan π is used for different initial states I_1, I_2 (for large enough k). Let v be a variable with $I_1(v) \neq I_2(v)$.

\rightsquigarrow In one case, v must be set by π , in the other case, it must be cleared.

\rightsquigarrow This is not possible in an **unconditional** plan.

\rightsquigarrow The transformation is **not solution preserving**!

\rightsquigarrow **Conditional effects** cannot be compiled away (if plan size can grow only linearly)

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Another Negative Result: $\text{STRIPS}_{Bc} \not\leq^c \text{STRIPS}_N$

k -**FISEX**: Planning problem with fixed plan length k and varying initial state. Does there exist an initial state leading to a successful k -step plan?

1-FISEX is NP-complete for STRIPS_{Bc} (= SAT).

k -FISEX is polynomial for STRIPS_N (regression analysis)

$$\rightsquigarrow \text{STRIPS}_{Bc} \not\leq_p^c \text{STRIPS}_N \text{ (if } P \neq \text{NP)}$$

Using a technique first used by Kautz & Selman, one can show that even arbitrary compilations can be ruled out – provided the polynomial hierarchy does not collapse. The proof method uses **non-uniform complexity classes** such as $P/poly$.

\rightsquigarrow **Bäckström's conjecture holds** in the compilation framework.

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A Final Negative Result: Boolean Preconditions Cannot be Compiled Away Even in the Presence of Conditional Effects

- Boolean preconditions have the power of **families of Boolean circuits with logarithmic depth** (because Boolean formula have this power) ($= NC^1$)
 - Conditional effects can simulate only **families of circuits with fixed depth** ($= AC^0$).
 - The parity function can be expressed in the first framework (NC^1) while it cannot be expressed in the second (AC^0).
- ⇒ The negative result follows **unconditionally**!

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A Final Negative Result: Boolean Preconditions Cannot be Compiled Away Even in the Presence of Conditional Effects

- Boolean preconditions have the power of **families of Boolean circuits with logarithmic depth** (because Boolean formula have this power) ($= NC^1$)
 - Conditional effects can simulate only **families of circuits with fixed depth** ($= AC^0$).
 - The parity function can be expressed in the first framework (NC^1) while it cannot be expressed in the second (AC^0).
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Boolean Circuits

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- When we want to *recognize formal languages* with circuits, we need a *sequence of circuits* with an increasing number of input gates \rightsquigarrow **family of circuits**
- Families with polynomial size and poly-log ($\log^k n$) depth
- complexity classes **NC^k** (Nick's class)
- $NC = \bigcup_k NC^k \subseteq P$, the class of problems that can be solved efficiently in parallel
- The class of languages that can be characterized by polynomially sized Boolean formulae is identical to NC^1

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Summary

The classes AC^k

- The classes NC^k are defined with a fixed fan-in
- If we have *unbounded fan-in*, we get the classes AC^k
 - gate types: NOT, n -ary AND, n -ary OR for all $n \geq 2$
- Obviously: $NC^k \subseteq AC^k$
- Possible to show: $AC^{k-1} \subseteq NC^k$
- The *parity language* is in NC^1 , but not in AC^0 !

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Summary

Accepting languages with families of domain structures with fixed goals

- We will view *families of domain structures* with fixed goals and fixed size plans as “machines” that accept languages
 - Consider families of poly-sized domain structures in STRIPS_B and use one-step plans for acceptance.
 - Obviously, this is the same as using Boolean formulae
- ⇒ All languages in NC^1 can be accepted in this way

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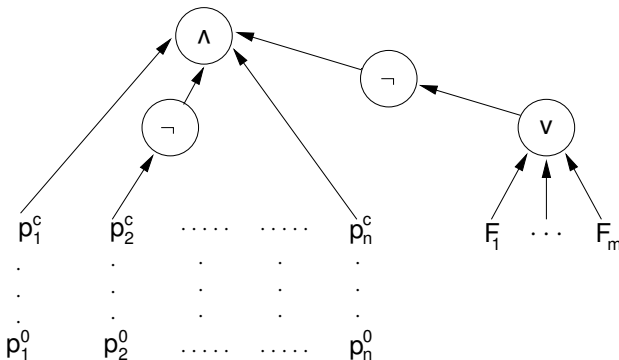
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Summary

Simulating STRIPS_{C,N} c -Step Plans with AC⁰ circuits (1)

- Represent each operator and then chain the actions together ($O(|O|^c)$ different plans):



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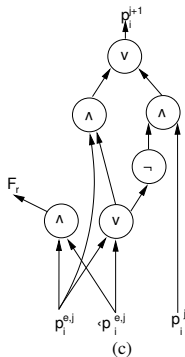
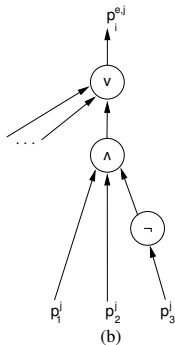
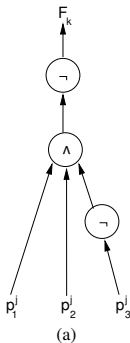
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Summary

Simulating STRIPS_{C,N} c -Step Plans with AC⁰ circuits (2)

- For each single action (precondition testing (a), conditional effects (b), and the computation of effects (c))



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Summary

$\text{STRIPS}_B \not\preceq^c \text{STRIPS}_{C,N}$

Theorem

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Proof.

Assuming $\text{STRIPS}_B \preceq^c \text{STRIPS}_{C,N}$ has the consequence that the underlying compilation scheme could be used to compile a NC^1 circuit family into an AC^0 circuit family, which is impossible in the general case. □

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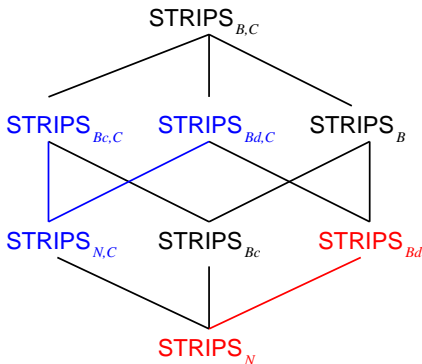
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General Results for Compilability

Preserving Plan Size Linearly



All other potential positive results have been ruled out by our 3 negative results and transitivity.

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Summary

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- Compilation schemes seem to be the right method to measure the *relative expressive power* of planning formalisms
- Either we get a positive result preserving plan size *linearly* with a *polynomial-time compilation*
- or we get an *impossibility result*
- *Results are relevant for building planning systems*
- ~→ *CNF preconditions* do not add much when we have already conditional effects
- Note: In all cases we can get a positive result if we allow for a polynomial blow-up of the plans.

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