

Multi-Agent Systems

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Course outline



- 1 Introduction
- 2 Agent-Based Simulation
- 3 Agent Architectures
- 4 Beliefs, Desires, Intentions
- 5 Norms and Duties
- 6 Communication and Argumentation
- 7 Coordination and Decision Making
 - Distributed Constraint Satisfaction
 - Auctions and Markets
 - Cooperative Game Theory

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Motivation



The famous prisoner's dilemma with the following **payoff matrix**:

	<i>Silent</i>	<i>Betray</i>
<i>Silent</i>	-1, -1	-3, 0
<i>Betray</i>	0, -3	-2, -2

In games like this one cooperation is prevented, because:

- Binding agreements are not possible
- Pay-off is given directly to individuals as the result of individual action

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Cooperative Game Theory



- In many situations...
 - **Contracts** can form binding agreements
 - Pay-off is given to **groups** of agents rather than to individuals
- Hence, cooperation is both possible and rational.
- **Cooperative game theory** asks which contracts are meaningful solutions among self-interested agents.

Characterization (Shoham, Keyton-Brown, 2009, Ch. 12)

[Cooperative game theory is about] how self-interested agents can combine to form effective teams.

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Real-world examples



- Political parties form coalitions to ensure majorities. Division of power (ministry posts).
- Companies cooperate to save resources.
- People buy expensive things together they could not buy themselves.
- Buildings are built by several people with different capabilities (craftsmen, electricians, architects, ...). Who should earn how much?

Key Questions



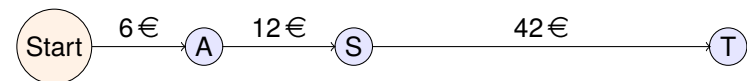
- Which coalition should/will form?
- How should the value be divided among the members?

Voting game



- Let A, B, C, D be four political parties in a parliament. They have 45, 25, 15, and 15 representatives, respectively.
- They are to vote on whether to pass a 100 million € spending bill and how much of it should be controlled by each of the parties.
- 51 votes are required to pass the bill, if the bill is not passed, every party gets zero to spend.
- Which coalition should form? How much does each of the parties in the coalition get to spend?

Cost sharing game



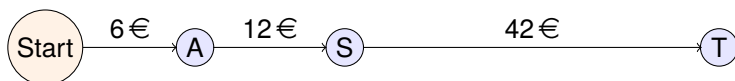
- Alvin drives home by taxi alone: 6 €
- Simon drives home by taxi alone: 12 €
- Theodore drives home by taxi alone: 42 €
- They could form coalitions to share a taxi.
 - How many coalitions will form?
 - If they all decide on sharing a taxi, the total price would be 42 €. Would you be fine if the total price of 42 € is divided by 3? Alternatives?

Cooperative Game (with transferable utility)

A cooperative game with transferable utility is a pair (N, v) :

- N : Set of agents
- Any subset $S \subseteq N$ is called a **coalition**
- N is the **grand coalition**
- $v : 2^N \rightarrow \mathbb{R}$: characteristic function that assigns a value $v(S)$ to each $S \subseteq N$, $v(\emptyset) = 0$.
- Transferable value assumption:
 - Value of a coalition can be (arbitrarily) redistributed among the coalition's members
 - I.e., value is dispensed in some universal currency
 - Each coalition can be assigned a single value

- Agents: $N = \{A, B, C, D\}$
- Coalitions: $\{A\}, \dots, \{A, B, C, D\}$
- Characteristic function $v : 2^N \rightarrow \mathbb{R}$
 - $v(\{A\}) = v(\{B\}) = v(\{C\}) = v(\{D\}) = v(\{B, C\}) = v(\{B, D\}) = v(\{C, D\}) = 0$
 - $v(\{A, B\}) = v(\{A, C\}) = v(\{A, D\}) = v(\{B, C, D\}) = 1$



- Agents: $N = \{A, S, T\}$
- Coalitions: $\{A\}, \{S\}, \{T\}, \{A, S\}, \{A, T\}, \{S, T\}, \{A, S, T\}$
- Characteristic function $v : 2^N \rightarrow \mathbb{R}$
 - $v(\{A\}) = 6$
 - $v(\{S\}) = 12$
 - $v(\{T\}) = 42$
 - $v(\{A, S\}) = 12$
 - $v(\{A, T\}) = 42$
 - $v(\{S, T\}) = 42$
 - $v(\{A, S, T\}) = 42$

- Again, which problems to solve?
 - 1 Which coalition will form?
 - 2 How should that coalition divide its value among its members?

The answer to 1) most of the times is the **grand coalition** N . But this also may depend on how 2) is answered, i.e., the grand coalition will only form if its in the interest of all its members.

Superadditive game

A game (N, v) is **superadditive** iff for all $S, T \subset N$, if $S \cap T = \emptyset$, then $v(S \cup T) \geq v(S) + v(T)$.

- Assumes that coalitions can work together without interfering with one another (adding someone to a team does not decrease its value).
- Consequently, the grand coalition is among the coalitions with highest value. \Rightarrow Unless stated otherwise, it is often assumed that the grand coalition will form.
- For cost-sharing games **subadditivity** defined in an analog way.

- Notation:** $\Psi(S, v) = (\Psi_1(S, v), \dots, \Psi_k(S, v))$ is a **distribution of value** to members $1, \dots, k$ of S .

Feasible distribution

A distribution $\Psi(S, v)$ is **feasible** for a coalition S iff

$$\sum_{i \in S} \Psi_i(S, v) \leq v(S)$$

Efficient distribution

A distribution $\Psi(S, v)$ is **efficient** for a coalition S iff

$$\sum_{i \in S} \Psi_i(S, v) \geq v(S)$$

- Goal:** Coalition is to divide its value 'fair'.
- Shapley's idea:** Members should receive value proportional to their contributions.
- But:
 - Consider $v(N) = 1$ and $v(S) = 0$ for all $S \neq N$.
 - Thus, $v(N) - v(N \setminus \{i\}) = 1$ for every agent i : everybody's contribution is 1 (everybody is indeed likewise essential).
 - Clearly, one cannot pay 1 to everybody
 - Needed: Some way of weighing. How to design it?
 - Next: **Axiomatic characterization** of properties of a fair value division (due to Shapley).

Definition Interchangeability

Agents i and j are **interchangeable** relative to v iff they always contribute the same amount to every coalition of the other agents, i.e., for all S that contain neither i nor j , $v(S \cup \{i\}) = v(S \cup \{j\})$.

Axiom Symmetry

For any $S \subseteq N, v$, if i and j are interchangeable then $\Psi_i(S, v) = \Psi_j(S, v)$.

- Agents who contribute the same to every possible coalition should get the same.

Definition Dummy Player

Agent i is a **dummy player** iff the amount that i contributes to any coalition is $v(\{i\})$, i.e., for all $S \setminus \{i\}$, $v(S \cup \{i\}) = v(S) + v(\{i\})$.
If $v(\{i\}) = 0$, i is called a **null player**.

Axiom Dummy Player

For any $S \subseteq N$, v if i is a dummy player then $\Psi_i(S, v) = v(\{i\})$.

Axiom Additivity

For any two v_1, v_2 , it holds that
 $\Psi_i(N, v_1 + v_2) = \Psi_i(N, v_1) + \Psi_i(N, v_2)$ for each i , where the game $(N, v_1 + v_2)$ is defined by $(v_1 + v_2)(S) = v_1(S) + v_2(S)$.

Theorem

Given a coalitional game (N, v) , there is a unique payoff division $\Psi(N, v)$ that divides the full payoff of the grand coalition and that satisfies Symmetry, Dummy Player, and Additivity: The **Shapley Value**.

Marginal value of agent i

The **marginal value of an agent i** to any coalition $S \subseteq N$ is defined by $\mu_i : 2^N \rightarrow \mathbb{R}$:

$$\mu_i(S) := \begin{cases} v(S \cup \{i\}) - v(S), & i \notin S \\ v(S) - v(S \setminus \{i\}), & i \in S \end{cases}.$$

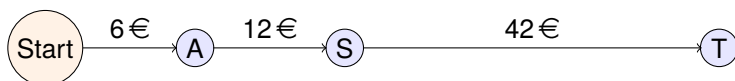
Definition Shapley Value

Given a cooperative game (N, v) , the **Shapley Value** divides value according to:

$$\Psi_i(N, v) = \frac{1}{N!} \sum_{o \in \Pi(N)} \mu_i(C_i(o))$$

- $\Pi_n = \{(x_1, \dots, x_n) | x_i \in N, \forall i, j [i \neq j \Rightarrow x_i \neq x_j]\}$
- $C_i(o)$: set containing only those agents that appear before agent i in o , e.g., $o = (3, 1, 2)$, then $C_3(o) = \emptyset$, $C_2(o) = \{1, 3\}$

- Agents: $N = \{A, B, C, D\}$
- Coalitions: $\{A\}, \dots, \{A, B, C, D\} \in 2^N$
- Characteristic function $v : 2^N \rightarrow \mathbb{R}$
 - $v(\{A\}) = v(\{B\}) = v(\{C\}) = v(\{D\}) = v(\{B, C\}) = v(\{B, D\}) = v(\{C, D\}) = 0$
 - $v(\{A, B\}) = v(\{A, C\}) = v(\{A, D\}) = v(\{B, C, D\}) = v(\{A, B, C\}) = v(\{A, B, C, D\}) = 1$
 - $(A, B, C) \rightarrow (0, 1, 0)$ because: $v(\{A\} \cup A) - v(\{A\}) = 0$, $v(\{A\} \cup \{B\}) - v(\{A\}) = 1$, $v(\{A, B\} \cup \{C\}) - v(\{A, B\}) = 0$
 - $(A, C, B) \rightarrow (0, 0, 1)$ because: $v(\{A\} \cup A) - v(\{A\}) = 0$, $v(\{A, C\} \cup \{B\}) - v(\{A, C\}) = 0$, $v(\{A\} \cup \{C\}) - v(\{A\}) = 1$
 - $(B, A, C) \rightarrow (1, 0, 0)$, $(B, C, A) \rightarrow (1, 0, 0)$
 - $(C, A, B) \rightarrow (1, 0, 0)$, $(C, B, A) \rightarrow (1, 0, 0)$
 - $\Psi(\{A, B, C\}, v) = (0.66, 0.16, 0.16)$
 - $\Psi(\{A, B, C, D\}, v) = (0.5, 0.16, 0.16, 0.16)$
 - What if $\{A, B\}$ form a coalition?



- characteristic function v
 - $v(\{A\}) = 6$
 - $v(\{S\}) = 12$
 - $v(\{T\}) = 42$
 - $v(\{A, S\}) = 12$
 - $v(\{A, T\}) = 42$
 - $v(\{S, T\}) = 42$
 - $v(\{A, S, T\}) = 42$
- Shapley value computation
 - $(A, S, T) \rightarrow (6, 6, 30)$
 - $(A, T, S) \rightarrow (6, 0, 36)$
 - $(S, A, T) \rightarrow (0, 12, 30)$
 - $(S, T, A) \rightarrow (0, 12, 30)$
 - $(T, A, S) \rightarrow (0, 0, 42)$
 - $(T, S, A) \rightarrow (0, 0, 42)$
 - $\Psi(N, v) = (2, 5, 35)$

- Shapley value is concerned with a **fair** distribution among members of an **already formed coalition**.
- But it does not consider that some agents may prefer to form a smaller coalition (e.g., the parties A and B can form a smaller coalition and hope for more money each).

Core

The **core** of a cooperative game (N, v) is the set of feasible and efficient distributions of value Ψ , such that for all $S \subseteq N$ it's true that

$$\sum_{i \in S} \Psi_i \geq v(S)$$

- The sum of distributed value to the agents in any subcoalition S is at least as much as they could earn on their own. (Thus, \leq for cost-sharing games).
- E.g., not fulfilled by the Shapley values for the voting game, because $\{A, B\}$ can gain more if they are not in the grand coalition.

- Is the core always nonempty? No.

- Voting game example: $\{A, B\}$, $\{A, C\}$, $\{A, D\}$, $\{B, C, D\}$, $\{A, B, C\}$, $\{A, B, D\}$, and $\{A, B, C, D\}$ have more than 50 votes.
- If the sum of distributed value given to B, C, D is less than 100 mio. €, then they have interest to form own coalition.
- Otherwise, A has interest to form a coalition with, e.g., B .
- Thus, the core is empty.

- Is the core always unique? No.

- Voting game example but 80 votes needed.
- $\{A, B, C\}$ and $\{A, B, D\}$ can reach 80 votes.
- Any distribution of the 100 mio. € among A and B belongs to the core, because all winning coalitions need the support of these two parties.

- How come that in the 80-vote game, the core concept does not grant value to C, D in the grand coalition $N = \{A, B, C, D\}$, $v(N) = 1$, although one of C, D is needed? Three cases:

- 1 Both of C, D get something: $\Psi = (a, b, c, d)$, $c, d > 0$, $a + b + c + d = 1$:
 - Then A, B, C together only get $1 - d < v(\{A, B, C\}) = 1$. Likewise, A, B, D together only get $1 - c < v(\{A, B, D\}) = 1$. Hence, both these subcoalitions have an incentive to leave the grand coalition. \Rightarrow **Not in core!**
- 2 Only C gets something: $\Psi = (a, b, c, 0)$, $c > 0$, $a + b + c = 1$
 - Then A, B, D get $1 - c < v(\{A, B, D\}) = 1$. Thus, this coalition has an incentive to leave the grand coalition. \Rightarrow **Not in core!** (Similar argument if D gets s.th. instead of C .)
- 3 None of C, D get something: $\Psi = (a, b, 0, 0)$, $a + b = 1$.
 - Ψ is **in the core**: $a \geq v(\{A\}) = 0$, $b \geq v(\{B\}) = 0$, $0 \geq v(\{C\}) = 0$, \dots , $1 \geq v(\{A, B\}) = 0$, $1 \geq v(\{A, B, C\}) = 1$, $\dots \Rightarrow$ No subcoalition of N can do better (stability), is not concerned with the individual fate of players.

Simple game

A game (N, v) is a **simple game** iff for all $S \subseteq N$, $v(S) \in \{0, 1\}$

Veto agent

An agent i is a **veto agent** iff $v(N \setminus \{i\}) = 0$.

Theorem

In a simple game the core is empty iff there is no veto agent. If there are veto agents, the core consists of all value distributions in which the nonveto agents get 0.

- As we saw in the 80%-voting example: A and B are veto players \Rightarrow The core consists of all distributions s.th. A and B get everything and the other get nothing.

Convex game

A game (N, v) is **convex**, iff the value of a coalition increases no slower when these coalitions grow in size, i.e.,
 $v(S \cup \{i\}) - v(S) \leq v(T \cup \{i\}) - v(T)$ for all $S \subseteq T \subseteq N, i \in N \setminus T$.

Theorem

In every convex game, the Shapley value is in the core.
 Note the relation between convexity and Shapley value via marginal contribution.

Theorem

Every convex game has a nonempty core.

\Rightarrow Fair and stable distributions exist!

- Claimants: $N = \{A, B\}$
- Claims: $c_A = 80, c_B = 40$
- Estate: $E = 100$
- $v(C) = \max\{0, \sum_{i \in N \setminus C} c_i\}$
 - $v(\emptyset) = 0, v(\{A\}) = 60, v(\{B\}) = 20, v(\{A, B\}) = 100$

Properties

- This game is convex \Rightarrow the Shapley value is in the core.
- Shapley value: $\Psi = (\Psi_A, \Psi_B) = \frac{(60, 40) + (80, 20)}{2} = (70, 30)$
- In core indeed, because:
 - $\Psi_A = 70 \geq v(\{A\}) = 60$ 😊
 - $\Psi_B = 30 \geq v(\{B\}) = 20$ 😊
 - $\Psi_A + \Psi_B = 70 + 30 \geq v(\{A, B\}) = 100$ 😊

- Cooperative game theory is concerned with what agents can achieve if they form **coalitions**, viz., binding agreements.
 - Values are given to coalitions first
 - Coalitions redistribute value to their members
- Solution concepts for cooperative games
 - Shapley value: fairness; always exists; unique
 - Core: stability; sometimes exists; not unique
 - For convex games, the Shapley value is in the Core
- **Next**
 - More compact representations for some types of games
 - Coalition structure formation

Remember: Given a cooperative game (N, v) , the **Shapley Value** divides value according to:

$$\Psi_i(N, v) = \frac{1}{N!} \sum_{o \in \Pi(N)} \mu_i(C_i(o))$$

- Imagine you wanted to compute the Shapley value of an agent i of a cooperative game (N, v)

def shapleyValue(N, v, i):

...

- How many entries are in v ?
- How many steps are necessary to compute Shapley value?

- Some cooperative games can be treated more efficiently
 - Weighted graph games
 - Weighted voting games
- Centralized algorithm for coalition structure generation

Weighted graph game: Definition

Assumption

The value of a coalition is the sum of the pairwise synergies among agents.

Definition

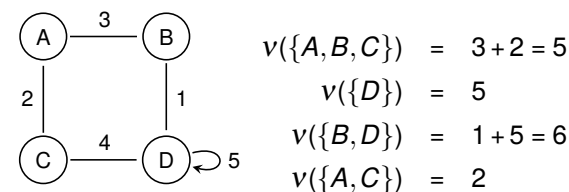
Let (V, W) denote an undirected weighted graph, where V is the set of vertices and $W \in \mathbb{R}^{V \times V}$ is the set of edge weights; denote the weight of the edge between vertices i and j as $w_{\{i,j\}}$. This graph defines a weighted graph game, where the cooperative game is constructed as follows:

- $N = V$
- $v(S) = \sum_{\{i,j\} \subseteq S} w_{\{i,j\}}$

Weighted graph game: Example

Revenue Sharing game

Consider the problem of dividing the revenues from toll highways between the cities that the highways connect. The pair of cities connected by a highway get to share in the revenues only when they form an agreement on revenue splitting; otherwise, the tolls go to the state.



Weighted graph game: Shapley Value



- 1 Only N^2 many values to store (adjacency matrix).
- 2 Shapley-Value sh_i of agent i : $sh_i = w_{\{i,i\}} + \frac{1}{2} \sum_{i \neq j} w_{\{i,j\}}$

Each pair of agents plays a game, in which they are interchangeable. Thus, they get the same value (**Symmetry**).

Axiom Symmetry

For any $S \subseteq N, v$, if i and j are interchangeable then $\Psi_i(S, v) = \Psi_j(S, v)$.

Value adds up in “bigger” games due to **Additivity**.

Axiom Additivity

For any two v_1, v_2 , it holds that

$\Psi_i(N, v_1 + v_2) = \Psi_i(N, v_1) + \Psi_i(N, v_2)$ for each i , where the game $(N, v_1 + v_2)$ is defined by $(v_1 + v_2)(S) = v_1(S) + v_2(S)$.

Weighted graph game: Properties



Theorem

If all the weights are nonnegative then the game is convex.

Remember:

Theorem

Every convex game has a nonempty core.

Theorem

In every convex game, the Shapley value is in the core.

⇒ A fair and stable value distribution exists and can be computed in polynomial time w.r.t. to number of agents.

Weighted graph game: Incompleteness



- For a sample game that cannot be represented as a weighted graph game remember the voting game from last lecture:
- Parties A, B, C, D have 45, 25, 15, and 15 representatives, respectively. 51 votes are required to pass the bill.
 - Agents: $N = \{A, B, C, D\}$
 - Coalitions: $\{A\}, \dots, \{A, B, C, D\} \in 2^N$
 - Characteristic function $v : 2^N \rightarrow \mathbb{R}$
 - $v(\{A\}) = v(\{B\}) = v(\{C\}) = v(\{D\}) = v(\{B, C\}) = v(\{B, D\}) = v(\{C, D\}) = 0$
 - $v(\{A, B\}) = v(\{A, C\}) = v(\{A, D\}) = v(\{B, C, D\}) = 1$
 - E.g., $v(\{B, C\}) + v(\{B, D\}) + v(\{C, D\}) \neq v(\{B, C, D\})$ ☹

Weighted voting game: Definition



Definition

A weighted voting game $(q; w_1, \dots, w_n)$ consists of a set of agents $Ag = \{1, \dots, n\}$ and a quota q . The cooperative game (N, v) is then given by:

- $N = Ag$
- $v(C) = \begin{cases} 1, & \sum_{i \in C} w_i \geq q \\ 0, & \text{else} \end{cases}$

Weighted voting game: Example



- Parties A, B, C, D have 45, 25, 15, and 15 representatives, respectively. 51 votes are required to pass the bill.
 - Weighted voting game: (51; 45, 25, 15, 15)

Weighted voting game: Properties



- Computing the Shapley value is NP-hard
- But checking if core is non-empty is easy

Remember:

Theorem

In a simple game the core is empty iff there is no veto agent. If there are veto agents, the core consists of all value distributions in which the nonveto agents get 0.

- Check if agent i is veto agent:
 - 1 Draw up $C = N \setminus \{i\}$
 - 2 Check that both hold:
 - $\sum_{j \in C} w_j < q$, i.e., no winner without i
 - $\sum_{j \in C \cup \{i\}} w_j \geq q$, i.e., winner with i

Next



- Some cooperative games can be treated more efficiently
 - Weighted graph games
 - Weighted voting games
- Centralized algorithm for coalition structure generation

Coalition Structure Formation



- Agents can use their capacity to compute Shapley values to try to optimize their local payoff.
- If, however, there is a central component that knows of all the agents, this component can attempt to **maximize social welfare** of the whole system.

Coalition Structure

A **coalition structure** is a **partition** of the overall set of agents N into **mutually disjoint coalitions**.

Example, with $N = \{1, 2, 3\}$:

- Seven possible coalitions:

$\{1\}, \{2\}, \{3\}, \{1, 2\}, \{2, 3\}, \{3, 1\}, \{1, 2, 3\}$

- Five possible coalition structures:

$\{\{1\}, \{2\}, \{3\}\}, \{\{1\}, \{2, 3\}\}, \{\{2\}, \{1, 3\}\},$

$\{\{3\}, \{1, 2\}\}, \{\{1, 2, 3\}\}$

Coalition Structure Formation

Given game $G = (N, v)$, the **socially optimal coalition structure** CS^* is defined as:

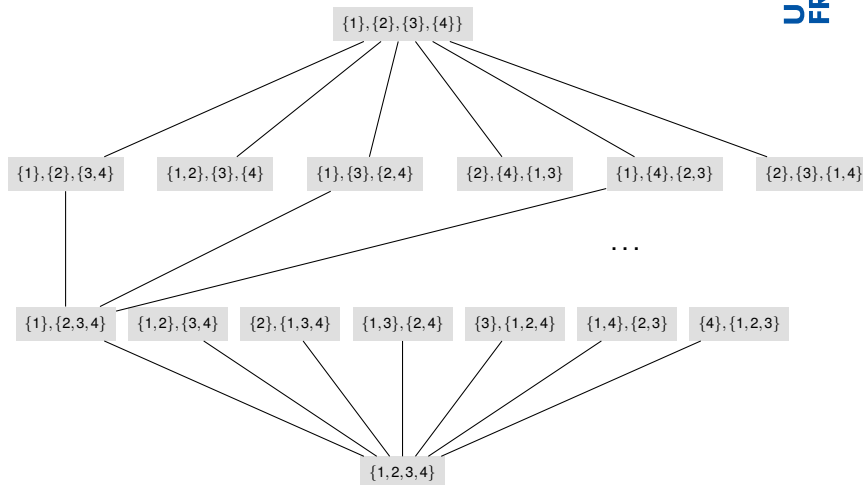
$$CS^* = \operatorname{argmax}_{CS \in \text{partitions of } N} V(CS)$$

where

$$V(CS) = \sum_{C \in CS} v(C)$$

Unfortunately, there are **exponentially more** coalition structures over the sets of agents N than there will be coalitions over N
 \Rightarrow **Exhaustive search is infeasible!**

Coalition Structure Graph



Coalition Structure Graph: Search

- Observation: At the first two levels every coalition is present.
- Let CS' be the best structure we find in these levels.
- Let CS^* be the best structure overall (as defined earlier).
- Let $C^* = \operatorname{argmax}_{C \subseteq N} v(C)$ the coalition with highest possible value.

Then:




- $V(CS^*) \leq |N|v(C^*) \leq |N|V(CS')$
- \Rightarrow in worst case, $V(CS') = \frac{V(CS^*)}{|N|}$

Algorithm:

- 1 Search first two bottom levels, keep track of best one.
- 2 Continue with breadth-first search beginning with top level.

- Weighted graph games
 - Compact representation of games with additive values
 - Efficient computation of Shapley values
- Weighted voting games
 - Compact representation of certain simple games
 - Efficient computation of a core value distribution
- Coalition Structure Formation
 - Centralized search-based algorithm to find a partition of agents into coalitions maximizing overall value.
 - Provable bounds of solution quality.

- 1 Introduction
- 2 Agent-Based Simulation
- 3 Agent Architectures
- 4 Beliefs, Desires, Intentions
 - The GOAL Agent Programming Language
 - Introduction to Modal Logics
 - Part I: Graphical Models, Kripke Models
 - Part II: Syntax & Semantics
 - Part III: Tableaux via Graph Rewriting
 - Epistemic Logic
 - Knowledge, Belief, Group knowledge
 - Dynamic Knowledge and Puzzles
 - BDI Logic
- 5 Norms and Duties
- 6 Communication and Argumentation
- 7 Coordination and Decision Making
 - Distributed Constraint Satisfaction
 - Auctions and Markets
 - Cooperative Game Theory

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