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Introduction to Game Theory

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Definition • Let G be a Bayesian game

A pure strategy of player i is any mapping
 $s_i: \Theta_i \rightarrow X_i$.

A mixed strategy of player i is any mapping
 $s_i: \Theta_i \rightarrow \Delta A_i$.

In the latter case define

$$s_i(a_i | p_i) = s_i(p_i)(a_i)$$

i.e., as the probability of player i that he
plays action a_i under the condition that his type is p_i .

In the context of Bayesian games we have different notions
of expected utility:

- * ex-ante: the player knows nothing about which player has
which type (including himself)
- * ex-interim: the player knows his own type only
- * ex-post: the player knows the type of all players (incl. himself)

Assume in what follows a common prior p .

Ex-post:

$$U_i(s, \sigma_i) := \sum_{a \in A} \left(\prod_{j \in U} s_j(a_j | \sigma_j) \right) \cdot u_i(a, \sigma_i)$$

Ex-ante:

$$U_i(s, \sigma_i) := \sum_{\sigma_{-i} \in \Theta_{-i}} p(\sigma_{-i} | \sigma_i) \cdot U_i(s, \underbrace{\sigma_{-i}, \sigma_i}_{\sigma})$$

Ex-ante:

$$\begin{aligned} U_i(s) &:= \sum_{\sigma_i \in \Theta_i} p(\sigma_i) \cdot U_i(s, \sigma_i) \\ &\stackrel{!}{=} \sum_{\sigma_i \in \Theta} p(\sigma_i) \cdot U_i(s, \sigma_i) \end{aligned}$$

Define $B_i(s_{-i}) := \arg \max_{s_i \in S_i} U_i(s_{-i}, s_i)$

Definition: A Bayes-NE is a mixed strategy profile $s \in S$ such that for each $i \in N$, $s_i \in B_i(s_{-i})$

A Bayesian game G can be represented as a strategic game in normal form G' . Define G' as follows:

$$N' := N$$

$$A'_i := \{ \text{pure strategies of } i \text{ in } G \}$$

$$u'_i(\underline{s}) = U_i^c(\underline{s})$$

One can prove the Bayes-NE of G are exactly the NE of the induced game G' .

Thus every finite Bayesian game has a Bayes-NE!

Example:

		L	R
T	•	2, 0	0, 2
B		0, 2	2, 0
		$p = 0.3$	

		L	R
T		2, 2	0, 3
B	•	3, 0	1, 1
		$p = 0.1$	

		L	R
T		2, 2	0, 0
B		0, 0	1, 1
		$p = 0.2$	

		L	R
T		2, 1	0, 0
B		0, 0	1, 2
		$p = 0.4$	

Σ_1

p_{11}	p_{12}
T	T
T	B
B	T
B	B

Σ_2

p_{21}	p_{22}
L	L
L	R
R	L
R	R

Now calculate for all strategy profiles $u_i^G(s), \dots$

For example:

$$\begin{aligned} u_1^G(TT, LR) &= u_1^G(TT, LR) = \sum_{j \in \Theta} p(j) \cdot u_1(TT, LR, j) \\ &= p(j_{11}, j_{21}) \cdot u_1(TT, LR, j_{11}, j_{21}) + p(j_{11}, j_{22}) \cdot u_1(TT, LR, j_{11}, j_{22}) \\ &\quad + p(j_{12}, j_{21}) \cdot u_1(TT, LR, j_{12}, j_{21}) + p(j_{12}, j_{22}) \cdot u_1(TT, LR, j_{12}, j_{22}) \\ &= 0.3 \cdot 2 + 0.1 \cdot 0 + 0.2 \cdot 2 + 0.4 \cdot 0 \\ &= 1 \end{aligned}$$

↓

	LL	LR	RL	RR
→ TT	2, 1	1, 0.7	1, 1.2	0, 0.9
TB	..	..	..	..
BT	..	..	---	...
BB	...	...	..	...

Now you can start to use the methods learned before!

2.10 Solving Strategic Games

In this section we will learn how to find mixed NE by using methods known from linear optimization. We will consider 2 player games only.

Zero-sum games • By the Nash theorem we know that each finite strategic game has a NE (in mixed strategies). By the Proposition about NE and MM (in section 2.6), each NE is a pair of maximinimizers. Thus, it is sufficient to search for pairs of maximinimizers.

Idea • Consider the mixed strategies of player 1. For each such strategy α find a response β_α of player 2 that minimizes the utility of player 1. By the Support Lemma it suffices to consider the pure strategies of player 2.

Given this setting, we try to maximize $U_1(\alpha, \beta_\alpha)$

→ Optimization problem

Excursion : Linear Optimization Problems / Linear Programming

A linear optimization problem (LOP) over real-valued variables $x_1, \dots, x_n$ is defined by a finite set of linear in-/equality constraints of the form:

$$\sum_{1 \leq i \leq n} a_{ji} x_i \quad \textcircled{*} \quad c_j$$

with $a_{ji}, c_j \in \mathbb{R}$ and $\textcircled{*} \in \{ \leq, \geq, =, \neq, \neq \}$

and an objective function

$$F(x_1, \dots, x_n) = \sum_{1 \leq i \leq n} b_i x_i$$

($b_i \in \mathbb{R}$) that is to be minimized.

Each LP can be transformed into normal form:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = c_1$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = c_m$$

$$x_1 \geq 0$$

$$\vdots$$

$$x_n \geq 0$$

} Non-negativity
constraints

Maximization problems: To maximize an objective
function $F(x_1, \dots, x_n)$, simply consider

$$\bar{F}(x_1, \dots, x_n) := -F(x_1, \dots, x_n)$$

$\geq$ -Inequalities : Linear constraints of the form

$\sum_j a_{ji} x_j \geq c_j$ can simply be replaced by

$$\sum_j -a_{ji} x_j \leq -c_j$$

$\leq$ -Inequalities : Linear constraints of the form

$\sum_j a_{ji} x_j \leq c_j$ can be transformed into expressions

in normal form :

$$\left(\sum_j a_{ji} x_j \right) + \underline{s_j} = c_j$$

$$\underline{s_j} \geq 0$$

slack variable

Non-negativity constraints :

To ensure the non-negativity of the variables we can introduce for a variable x_i the variables x_i' and x_i'' , add the constraints $x_i' \geq 0$, $x_i'' \geq 0$, and substitute x_i by $x_i' - x_i''$ in all constraints and the objective function.

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