

7 Hashing: chaining

Summer Term 2011

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Possible ways of treating collisions



- Collisions are treated differently in different methods.
- A data set with key s is called a **colliding element** if bucket $B_{h(s)}$ is already taken by another data set.
- What can we do with colliding elements?
 1. **Chaining**: Implement the buckets as linked lists. Colliding elements are stored in these lists.
 2. **Open Addressing**: Colliding elements are stored in other vacant buckets. During storage and lookup, these are found through so-called **probing**.

Chaining (1)



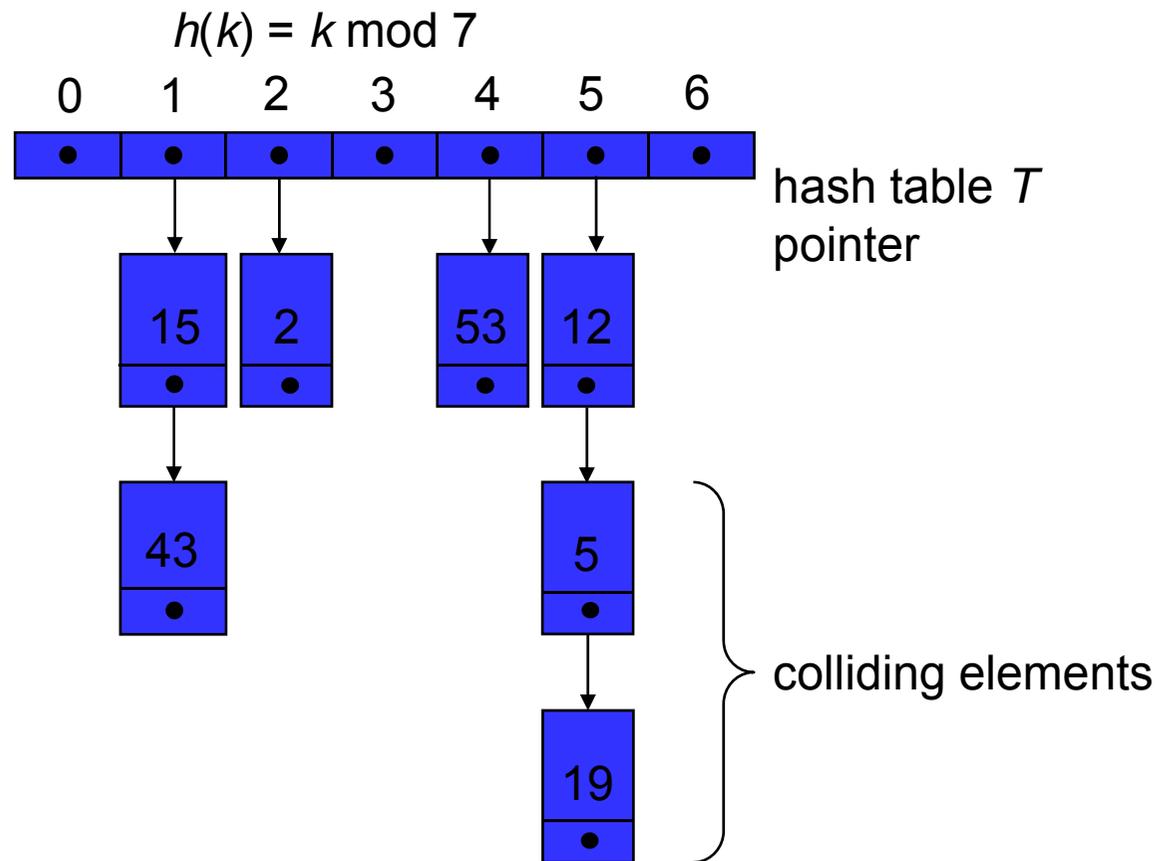
- The hash table is an array (length m) of lists. Each bucket is implemented by a list.

```
class hashTable {
    List[] ht;           // an array of lists
    hashTable (int m){  // Constructor
        ht = new List[m];
        for (int i = 0; i < m; i++)
            ht[i] = new List(); // Construct a list
    }
    ...
}
```

- Two different ways of using lists:
 1. **Direct chaining:**
Hash table only contains list headers; **all** data sets are stored in the lists.
 2. **Separate chaining:**
Hash table contains at most one data set in each bucket as well as a list header. **Colliding** elements are stored in the list.

Direct chaining

Keys are stored in **overflow lists**



Chaining



Lookup key k

- Compute $h(k)$ and overflow list $\mathcal{T}[h(k)]$
- Look for k in the overflow list

Insert a key k

- Lookup k (fails)
- Insert k in the overflow list

Remove a key k

- Lookup k (successfully)
- Remove k from the overflow list

→ only list operations

Implementation in Java



```
class TableEntry {
    private Object key,value;
}
abstract class HashTable {
    private TableEntry[] tableEntry;
    private int capacity;
    // Constructor
    HashTable (int capacity) {
        this.capacity = capacity;
        tableEntry = new TableEntry [capacity];
        for (int i = 0; i <= capacity-1; i++)
            tableEntry[i] = null;
    }
    // the hash function
    protected abstract int h (Object key);
    // insert element with given key and value (if not there already)
    public abstract void insert (Object key, Object value);
    // delete element with given key (if there)
    public abstract void delete (Object key);
    // lookup element with given key
    public abstract Object search (Object key);
} // class hashTable
```

Implementation in Java



```
class ChainedTableEntry extends TableEntry {
    // Constructor
    ChainedTableEntry(Object key, Object value) {
        super(key, value);
        this.next = null;
    }
    private ChainedTableEntry next;
}

class ChainedHashTable extends HashTable {
    // the hash function
    public int h(Object key) {
        return key.hashCode() % capacity ;
    }

    // lookup key in the hash table
    public Object search (Object key) {
        ChainedTableEntry p;
        p = (ChainedTableEntry) tableEntry[h(key)];
        // Go through the liste until end reached or key found
        while (p != null && !p.key.equals(key)) {
            p = p.next;
        }
        // Return result
        if (p != null)
            return p.value;
        else return null;
    }
}
```

Implementation in Java



```
/* Insert an element with given key and value (if not there) */
public void insert (Object key, Object value) {
    ChainedTableEntry entry = new ChainedTableEntry(key, value);
    // Get table entry for key
    int k = h (key);
    ChainedTableEntry p;
    p = (ChainedTableEntry) tableEntry [k];
    if (p == null){
        tableEntry[k] = entry;
        return ;
    }
    // Lookup key
    while (!p.key.equals(key) && p.next != null) {
        p = p.next;
    }
    // Insert the element (if not there)
    if (!p.key.equals(key))
        p.next = entry;
}
```

Implementation in Java



```
// Delete element with given key (if there)
public void delete (Object key) {
    int k = h (key);
    ChainedTableEntry p;
    p = (ChainedTableEntry) TableEntry [k];
    TableEntry[k] = recDelete(p, key);
}

// Delete element with key recursively (if there)
public ChainedTableEntry recDelete (ChainedTableEntry p, Object key) {
    /* recDelete returns a pointer to the start of the list that p points to,
    in which key was deleted */
    if (p == null)
        return null;
    if (p.key.equals(key))
        return p.getNext();
    // otherwise:
    p.next = recDelete(p.next, key);
    return p;
}

public void printTable () {...}
} // class ChainedHashTable
```

Test program



```
public class ChainedHashingTest {
    public static void main(String args[]){
        Integer[] t= new Integer[args.length];
        for (int i = 0; i < args.length; i++)
            t[i] = Integer.valueOf(args[i]);
        ChainedHashTable h = new ChainedHashTable(7);
        for (int i = 0; i <= t.length - 1; i++)
            h.insert(t[i], null);
        h.printTable ();
        h.delete(t[0]); h.delete(t[1]);
        h.delete(t[6]); h.printTable();
    }
}
```

Call:

```
java ChainedHashingTest 12 53 5 15 2 19 43
```

Output:

```
0: -|          0: -|
1: 15 -> 43 -| 1: 15 -|
2: 2 -|        2: 2 -|
3: -|          3: -|
4: 53 -|       4: -|
5: 12 -> 5 -> 19 -| 5: 5 -> 19 -|
6: -|          6: -|
```

Analysis of direct chaining



Uniform hashing assumption:

- All hash addresses are chosen with the same probability, i.e.:

$$\Pr(h(k_i) = j) = 1/m$$

- independent from operation to operation

Average chain length for n entries (load factor):

$$n/m = \alpha$$

Definition:

C'_n = Expected number of entries inspected during a failed search

C_n = Expected number of entries inspected during a successful search

Analysis:

$$\begin{aligned} C'_n &= \alpha \\ C_n &\approx 1 + \frac{\alpha}{2} \end{aligned}$$

Chaining



Advantages:

- + C_n and C'_n are small
- + $\alpha > 1$ possible
- + real distances
- + suitable for secondary memory

Efficiency of lookup

α	C_n (successful)	C'_n (unsuccessful)
0.50	1.250	0.50
0.90	1.450	0.90
0.95	1.457	0.95
1.00	1.500	1.00
2.00	2.000	2.00
3.00	2.500	3.00

Disadvantages:

- Additional space for pointers
- Colliding elements are outside the hash table

Summary



Analysis of hashing with chaining:

- **worst case:**

$h(s)$ always yields the same value, all data sets are in a list.
Behavior as in linear lists.

- **average case:**

- Successful lookup & delete:

complexity (in inspections) $\approx 1 + 0.5 \times \text{load factor}$

- Failed lookup & insert:

complexity $\approx \text{load factor}$

This holds for **direct** chaining, with **separate** chaining the complexity is a bit higher.

- **Best case:**

lookup is an immediate success: complexity $\in O(1)$.