

Foundations of Artificial Intelligence

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Summer Term 2009

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Exercise Sheet 3

Due: Tuesday, May 19, 2009

Exercise 3.1 (Path planning)

Consider the problem of finding the shortest path between two points on a plane that has convex polygonal obstacles (see Fig. 1). This is an idealization of the problem a robot has to solve to navigate its way around in a crowded environment.

- Suppose the state space consists of all positions (x,y) in the plane. How many states are there? How many paths are there to the goal?
- Explain briefly why the shortest path from one polygon vertex to any other in the scene must consist of (a) straight-line segments joining (b) vertices of the polygons. Define a good state space now. How large is this state space?
- In order to implement the search problem define (in text or pseudo code) a successor function that takes a vertex as input and returns the set of vertices that can be reached in a straight line from the given vertex.

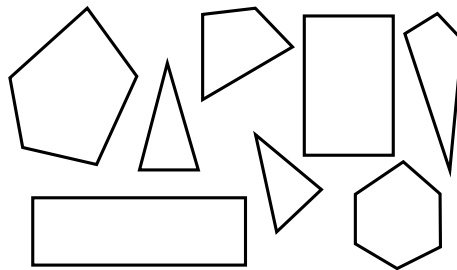


Figure 1: Robot navigation among polygons

Exercise 3.2 (Local search)

We will now examine *hill-climbing* in the same setting (planar robot navigation among polygonal obstacles).

- Explain how hill-climbing would work as a method of reaching a particular end point.
- Show how nonconvex obstacles can result in a local maximum for the hill-climber, using an example.
- Is it possible for it to get stuck with convex obstacles?

- (d) Would simulated annealing always escape local maxima on this family of problems? Explain!

Exercise 3.3 (CSPs)

The $SEND + MORE = MONEY$ problem consists in finding distinct digits for the letters D, E, M, N, O, R, S, Y such that S and M are different from zero, i.e. no leading zeros, and the equation

$$SEND + MORE = MONEY$$

is satisfied.

- (a) Explain in a nutshell, why it would be good to formulate the problem as a *constraint satisfaction problem*?
- (b) Formulate the problem as a *constraint satisfaction problem*, i.e. what are the variables, what constraints do we have, etc.
- (c) Find a solution using *forward checking* and *arc consistency*. Give the search tree.
(Hint: consider the letters in the following order: O, M, Y, E, N, D, R, S .)

Exercise 3.4 (Arc consistency)

AC-3 puts back on the queue *every* arc (X_k, X_i) whenever *any* value is deleted from the domain of X_i , even if each value of X_k is consistent with several remaining values of X_i . Suppose that, for every arc (X_k, X_i) and each value of X_k , we keep track of the number of remaining values of X_i that are consistent with this value of X_k . Explain how to update these numbers efficiently and hence show that arc consistency can be enforced in total time $O(n^2 d^2)$.

The exercise sheets may and should be handed in and be worked on in groups of three (3) students. Please fill the cover sheet¹ and attach it to your solution.

¹<http://www.informatik.uni-freiburg.de/~ki/teaching/ss09/gki/coverSheet-english.pdf>