

# Constraint Satisfaction Problems

## Constraint Networks

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April 24, 2007

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## Constraint Networks

Reminder

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## Constraint Networks

Recall:

### Definition

A **constraint network** is a triple

$$\mathcal{C} = \langle V, \text{dom}, C \rangle$$

where:

- ▶  $V$  is a non-empty and finite set of **variables**.
- ▶  $\text{dom}$  is a function that assigns a non-empty (value) set (**domain**) to each variable  $v \in V$ .
- ▶  $C$  is a set of relations over variables of  $V$  (**constraints**), i. e., each constraint is a relation  $R_{v_1, \dots, v_n}$  over some variables  $v_1, \dots, v_n$  in  $V$ .

Without loss of generality, we can assume that, for each subset  $S$  of variables,  $C$  contains only one constraint with scope  $S$ . The set of scopes  $\{S_1, \dots, S_t\}$  is called **network scheme**.

## Example: 4-Queens Problem

Consider variables  $v_1, \dots, v_4$  (associated to the columns of a  $4 \times 4$ -chess board). Each of these variables  $v_i$  has as its domain  $\{1, \dots, 4\}$  (conceived of as the row positions of a queen in column  $i$ ).

	$v_1$	$v_2$	$v_3$	$v_4$
1				
2				
3				
4				

Define then binary constraints (thus encoding possible queen movements):

$$R_{v_1, v_2} := \{(1, 3), (1, 4), (2, 4), (3, 1), (4, 1), (4, 2)\}$$

$$R_{v_1, v_3} := \{(1, 2), (1, 4), (2, 1), (2, 3), (3, 2), (3, 4), (4, 1), (4, 3)\}$$

...

## Instantiation, Solution

Let  $\mathcal{C} = \langle V, \text{dom}, C \rangle$  be a constraint network.

### Definition

- (a) An **instantiation** of a subset  $V'$  of  $V$  is an assignment  $a : V' \rightarrow \bigcup_{v \in V'} \text{dom}(v_i)$  with  $a(v_i) \in \text{dom}(v_i)$ .
- (b) An instantiation  $a$  is a **partial solution** if  $a$  satisfies each constraint with scope  $S \subseteq V'$  (we also say:  $a$  is **consistent** relative to  $\mathcal{C}$ ).
- (c) For an instantiation  $a$  of a subset  $V' = \{v_1, \dots, v_k\}$  and a constraint  $R$  with scope  $S \subseteq V'$ , let

$$\bar{a}[S] := (a(v_1), \dots, a(v_k)).$$

- (d) A **solution** is an instantiation of all variables in  $V$  that is consistent relative to  $\mathcal{C}$ .

## Instantiation, Solution

Note:

- (a) An instantiation of variables in  $V' \subseteq V$ ,  $a$ , is consistent relative to  $\mathcal{C}$  iff

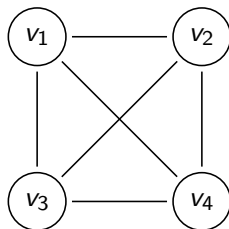
$$\bar{a}[S] \in R, \quad \text{for each constraint } R \text{ with } S \subseteq V'.$$

- (b) Not each partial solution is part of a (full) solution, i. e., there may be partial solutions of a constraint network that cannot be extended to a solution. For the 4-queens problem, for example,

	$v_1$	$v_2$	$v_3$	$v_4$
1	q			
2			q	
3				
4		q		

## Example: Primal Constraint Graph

The primal constraint graph for the 4-queens problem is a complete graph:



Its dual constraint graph? Its hypergraph?

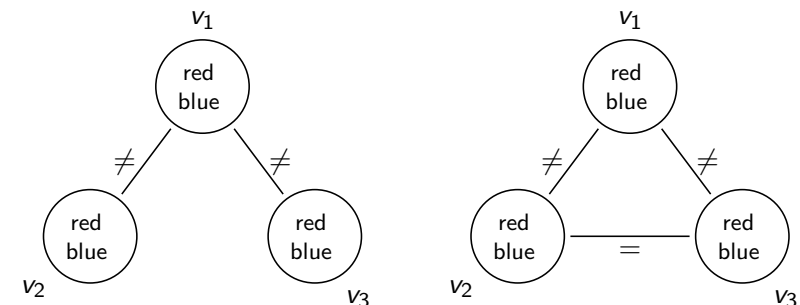
## Equivalence

Let  $\mathcal{C}$  and  $\mathcal{C}'$  be constraint networks on the same set of variables and on the same domains for each variable.

### Definition

$\mathcal{C}$  and  $\mathcal{C}'$  are **equivalent** if each solution of  $\mathcal{C}$  is a solution of  $\mathcal{C}'$ , and vice versa.

Example:



## Tighter Networks and Equivalence

Let  $\mathcal{C}$  and  $\mathcal{C}'$  be constraint networks on the same set of variables and on the same domains for each variable. We assume that for each set of variables  $S$ , both networks contain at most one constraint with scope  $S$ .

### Definition

$\mathcal{C}'$  is **at least as tight as**  $\mathcal{C}$  if for each constraint  $R'$  of  $\mathcal{C}'$  with scope  $S$ , it holds:

- (a)  $\mathcal{C}$  has no constraint with scope  $S$ , or
- (b)  $R' \subseteq R$ , where  $R$  is the constraint of  $\mathcal{C}$  with scope  $S$ .

Note:  $\mathcal{C}'$  may be **at least as tight as**  $\mathcal{C}$  although  $|\mathcal{C}'| > |\mathcal{C}|$ .

## Intersection of Networks

Let  $\mathcal{C}$  and  $\mathcal{C}'$  be constraint networks as above.

### Definition

The **intersection** of  $\mathcal{C}$  and  $\mathcal{C}'$ ,  $\mathcal{C} \cap \mathcal{C}'$ , is the network defined by intersecting for each scope  $S$  of constraints  $R_S \in \mathcal{C}$  and  $R'_S \in \mathcal{C}'$  the respective relations, i. e.,

$$R''_S := R_S \cap R'_S.$$

If for a scope  $S$  only one of the networks contains a constraint, then we set:

$$R''_S := R_S \quad (\text{or } := R'_S, \text{ resp.})$$

### Lemma

*If  $\mathcal{C}$  and  $\mathcal{C}'$  are equivalent networks, then  $\mathcal{C} \cap \mathcal{C}'$  is equivalent to both networks and at least as tight as both networks.*

## Minimal Network

### Definition

Let  $\mathcal{C}_0$  be a constraint network and let  $\mathcal{C}_1 \dots, \mathcal{C}_k$  be the set of *all* constraint network (defined on the same set of variables and the same domains) that are equivalent to  $\mathcal{C}_0$ .

$$\bigcap_{1 \leq i \leq k} \mathcal{C}_i$$

is the **minimal network** of  $\mathcal{C}_0$ .

The minimal network is equivalent to and as least as tight as all the constraint networks  $\mathcal{C}_i$ . There is no network equivalent to  $\mathcal{C}_0$  that is tighter than the minimal network.

## Projecting Relations

Let  $R_S$  be a relation with scope  $S = \{v_1, \dots, v_k\}$  (we can conceive of  $R_S$  as a constraint network ...).

### Definition

The **projection network** of  $R_S$ ,  $\text{Proj}(R_S)$ , is the constraint network defined by

$$\begin{aligned} V &:= S \\ \text{dom}(v_i) &:= \pi_{v_i}(R_S) \\ R_{v_i, v_j} &:= \pi_{v_i, v_j}(R_S) \end{aligned}$$

Note: The projection network is an upper approximation by binary networks in the following sense:

### Lemma

*Any solution of  $R_S$  (as a network) defines a solution of  $\text{Proj}(R_S)$ .*

## Binary Representation

### Definition

A relation  $R_S$  with scope  $S$  **has a binary representation** if the relation (conceived of as a network) is equivalent to  $\text{Proj}(R_S)$ .

From the fact that a relation has a binary representation, it does not follow that all its projections have binary representations as well (Exercise!).

### Definition

A relation  $R_S$  with scope  $S$  is **binary decomposable** if the relation itself and all its projections to subsets of  $S$  (with at least 3 elements) have a binary representation.

## Literature



Rina Dechter.

Constraint Processing,

Chapter 2, Morgan Kaufmann, 2003