

Nondeterministic effects: definition

Effects are recursively defined as follows.

1. a and $\neg a$ for state variables $a \in P$ are effects.
2. $e_1 \wedge \dots \wedge e_n$ is an effect if e_1, \dots, e_n are effects (the special case with $n = 0$ is the empty conjunction \top .)
3. $c \triangleright e$ is an effect if c is a formula over P and e is an effect.
4. $p_1 e_1 | \dots | p_n e_n$ is an effect if e_1, \dots, e_n for $n \geq 0$ are effects, $p_i > 0$ for all $i \in \{1, \dots, n\}$ and $\sum_{i=1}^n p_i = 1$.

Nondeterministic effects: semantics

Let $\langle c, e \rangle$ be an operator over P and s a state. The operator is applicable in s if $s \models c$. Define $[e]_s$ recursively as follows.

1. $[a]_s = \{\{a\}\}$ and $[\neg a]_s = \{\{\neg a\}\}$ for $a \in P$.
2. $[e_1 \wedge \dots \wedge e_n]_s = \{\bigcup_{i=1}^n f_i \mid f_1 \in [e_1]_s, \dots, f_n \in [e_n]_s\}$.
3. $[c' \triangleright e']_s = [e']_s$ if $s \models c'$ and $[c' \triangleright e']_s = \{\emptyset\}$ otherwise.
4. $[p_1 e_1 | \dots | p_n e_n]_s = [e_1]_s \cup \dots \cup [e_n]_s$

The successor states are determined by members of $[e]_s$.

Nondeterministic effects: probabilistic semantics

1. $[a]_s = \{\langle 1, \{a\} \rangle\}$ and $[\neg a]_s = \{\langle 1, \{\neg a\} \rangle\}$ for $a \in P$.
2. $[e_1 \wedge \dots \wedge e_n]_s = \{\langle \prod_{i=1}^n p_i, \bigcup_{i=1}^n f_i \rangle \mid \langle p_1, f_1 \rangle \in [e_1]_s, \dots, \langle p_n, f_n \rangle \in [e_n]_s\}$.
3. $[c' \triangleright e']_s = [e']_s$ if $s \models c'$ and $[c' \triangleright e']_s = \{\langle 1, \emptyset \rangle\}$ otherwise.
4. $[p_1 e_1 | \dots | p_n e_n]_s = \{\langle p_1 \cdot p, e \rangle \mid \langle p, e \rangle \in [e_1]_s\} \cup \dots \cup \{\langle p_n \cdot p, e \rangle \mid \langle p, e \rangle \in [e_n]_s\}$

Nondeterministic effects: probabilistic semantics

Consider a state s with $s \models A \wedge B \wedge C$. Successor states under e and their probabilities are determined by members of $[e]_s$.

Let $[e]_s = \{\langle 0.3, \{A, \neg B\} \rangle, \langle 0.5, \{\neg B\} \rangle, \langle 0.2, \{\neg B, \neg C\} \rangle\}$.

With e state s has two successor states s_1 and s_2 such that

$$\begin{aligned} s_1 &\models A \wedge \neg B \wedge C \\ s_2 &\models A \wedge \neg B \wedge \neg C \end{aligned}$$

Probability of reaching s_1 is 0.8 and that of s_2 is 0.2.

Nondeterministic effects: examples

$$a \triangleright (0.5(\neg a \wedge b \wedge c) | 0.5(a \wedge \neg b \wedge \neg c))$$

$$0.5(a \triangleright (a \wedge b \wedge c)) | 0.5(a \triangleright (b \wedge \neg c))$$

$$0.5(a \triangleright (a \wedge b \wedge c)) | 0.5\top$$

$$(0.2a | 0.8b) \wedge (0.3c | 0.7d) \wedge (0.4e | 0.6f)$$

$$(0.2a | 0.8b) \wedge (0.3\neg a | 0.7d) \quad \text{not well-defined}$$

Nondeterministic effects: more equivalences

$$c \triangleright (p_1 e_1 | \dots | p_n e_n) \equiv p_1(c \triangleright e_1) | \dots | p_n(c \triangleright e_n)$$

$$e \wedge (p_1 e_1 | \dots | p_n e_n) \equiv p_1(e \wedge e_1) | \dots | p_n(e \wedge e_n)$$

$$p_1(p'_1 e'_1 | \dots | p'_n e'_n) | p_2 e_2 | \dots | p_n e_n \equiv (p_1 p'_1) e'_1 | \dots | (p_1 p'_n) e'_n | p_2 e_2 | \dots | p_n e_n$$

Nondeterministic effects: normal form I

DEFINITION: Let e_1, \dots, e_n be any deterministic effects in normal form as defined earlier. Then e obtained from e_1, \dots, e_n with \wedge and $|$ is in normal form I.

EXAMPLES:

$$(0.5((a \triangleright b) \wedge (b \triangleright \neg c) \wedge (d \triangleright c)) | 0.5(a \triangleright b)) \wedge (d \triangleright \neg c)$$

$$(0.5(a \triangleright b) | 0.4(b \triangleright q) | 0.1(j \triangleright e)) \wedge (0.3(\neg a \triangleright \neg b) | 0.7(c \triangleright \neg c))$$

THEOREM: Any effect can be transformed into normal form I in polynomial time.

Nondeterministic effects: normal form II

DEFINITION: Let e_1, \dots, e_n for $n \geq 0$ be any deterministic effects in normal form as defined earlier. Then $e = p_1 e_1 | \dots | p_n e_n$ is in normal form II.

EXAMPLES:

$$(a \triangleright b) \wedge (c \triangleright \neg d)$$

$$0.3((a \triangleright b) \wedge (c \triangleright \neg d)) | 0.2(g \triangleright \neg h) | 0.5((b \triangleright a) \wedge ((f \vee q) \triangleright h))$$

THEOREM: Any effect can be transformed into normal form II.

Nondeterministic effects: size of normal form II

Size increase in transforming into normal form II may be exponential.

Let $Q = \{q_1, \dots, q_n\}$ be a set of state variables. Effect that can produce every valuation of Q in one step is

$$(0.5q_1|0.5\neg q_1) \wedge (0.5q_2|0.5\neg q_2) \wedge \dots \wedge (0.5q_n|0.5\neg q_n).$$

The effect in normal form II is

$$2^{-n}(q_1 \wedge q_2 \wedge \dots \wedge q_n) | 2^{-n}(\neg q_1 \wedge q_2 \wedge \dots \wedge q_n) | \dots | 2^{-n}(\neg q_1 \wedge \neg q_2 \wedge \dots \wedge \neg q_n).$$