Constraint Satisfaction Problems

The \textit{ECL\textsuperscript{i}PS\textsuperscript{e}} Constraint Logic Programming System

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1 Motivation
“ECL\textsuperscript{i}PS\textsuperscript{e} is designed for solving combinatorial optimization problems, for the development of new constraint solver technology and their hybrids, and for the teaching of modelling, solving and search techniques.”

(http://sourceforge.net/projects/eclipse-clp/)
What is \( ECL^iPS^e \)?

\( ECL^iPS^e \): 
1. is a declarative language 
2. is a Constraint Programming toolkit 
3. is available open source (Mozilla Public License) 
4. has been applied to areas of planning, scheduling, resource allocation, timetabling, transport... 
5. provides bindings for Python, C/C++, Tcl/Tk, Java (Eclipse IDE plugin), SQL, ... 
6. can be interfaced to remotely (RPC)
Why $ECL^iPS^e$ ?

The TPK (Trabb Pardo-Knuth) algorithm of Donald Knuth and Luis Trabb Pardo (1976) (the “Hello World!” of algorithms):

“The algorithm prompts for 11 real numbers ($a_0 \ldots a_{10}$) and for each $a_i$ computes $b_i = f(a_i)$, where $f(t) = \sqrt{|t|} + 5t^3$. After that for $i = 10 \ldots 0$ (in that order) the algorithm outputs a pair $(i, b_i)$ if $b_i \leq 400$, or $(i, TOO\ LARGES)$ otherwise.” (Dymchenko & Mykhailova, 2014)
The TPK algorithm in \( ECL^iPS^e \) / Prolog:

1 \( f(T, Y) :- \)
2 \[ Y \text{ is } \sqrt{\text{abs}(T)} + 5 \times T^3. \]
3 \text{main} :-
4 \text{read}(As),
5 \text{length}(As, N), \text{reverse}(As, Rs),
6 ( \text{foreach}(Ai, Rs), \text{for}(I, N - 1, 0, -1) \text{ do}
7 \quad \text{Bi is } f(Ai),
8 \quad ( \text{Bi > 400 } \rightarrow
9 \quad \quad \text{printf("%w TOO LARGE
10 \quad \};
11 \quad \text{printf("%w %w\n", [I, Bi])}
12 \quad )}\).
Declarative programming with functions

The TPK algorithm in python 3:

```python
1 >>> def f(x): return abs(x) ** 0.5 + 5 * x**3
2
3 >>> print(', '.join('%s:%s' %
4     (x, v if v<=400 else "TOO LARGE!")
5     for x,v in ((y, f(float(y)))
6     for y in input('\nnumbers: ')
7     .strip.split()[1][::-1]))
```

(http://rosettacode.org/wiki/Trabb_Pardo%E2%80%93Knuth_algorithm#Python)

Is the logical Prolog version “easier/better” than the functional Python version?
Python binding for $ECL^{PSe}$

The “Search Solution” example of pyclp:

```python
from pyclp import *
init()  # Init ECLiPSe engine
Compound("lib", Atom("ic")).post_goal()  # Load ic library
A_var=Var()  # Create variable A
B_var=Var()  # Create variable B
# [A,B]::1..10
Compound("#::", PList([A_var, B_var]),
    Compound("..", 1, 10)).post_goal()
Compound("#<", A_var, B_var).post_goal()  # A<B
Compound("#=" ,A_var, 5).post_goal()  # A=5
# labeling([A,B])
Compound("labeling",
    PList([A_var, B_var])).post_goal()
# Loop on all solution and print them.
while (resume()[0]==SUCCEED):
    print(B_var)
    # backtracking over solutions
    Atom("fail").post_goal()
cleanup()  # Shutdown ECLiPSe engine
```
So again, why $ECL^iPS^e$?

⇒ Because it can be considered more elegant and even easier to (only) declare a problem logically and then use all the power of standard reasoning and search algorithms to find a solution. $ECL^iPS^e$ contains all major CLP algorithms as libraries and provides the full power of the Prolog language for problem modeling.
Suitable problems for $ECL^iPS^e$

Characteristics of problems suitable for $ECL^iPS^e$:

1. There are no general methods or algorithms
   - NP-completeness
   - Different strategies and heuristics have to be tested

2. Requirements are quickly changing
   - Programs should be flexible enough to adapt

3. Decision support required
   - Co-operate with user
   - Friendly interfaces
2 Problem modeling

- Issues
- CLP and $ECL_e^{PS}$
Logic programming

Constraint Programming can be characterized by two pseudo-equations:

\[ \text{Solution} = \text{Logic} + \text{Control} \] (1)

\[ \text{Control} = \text{Reasoning} + \text{Search} \] (2)

Equation (1): a solution can be found by:

1. a logical, declarative description of the problem, and
2. control information for the computer to deduce it.

Equation (2): control is a combination of:

1. reasoning to (efficiently) limit the search space, and
2. subsequent (inefficient) search through that space

Problem modeling deals with the Logic part of Equation (1).
Issues in Problem Modeling

A good formalism should fulfill the following criteria:

1. Expressive power:
   formal model of real world problem possible?

2. Clarity for humans:
   ease of use of formalism (read, write, understand, modify)

3. Solvability for computers:
   Good methods available to solve problem?

Higher-level models

+ closer to the user and the problem
+ easier to understand and trust, to debug and modify, but
  - difficult to see how they can be solved
Issues in Problem Modeling

Classical source of error in application development:
⇒ Transition from formal description to final program
⇒ Can the final program be trusted?

CLP solution:
- Keep initial formal model as part of the final program
- Enhance rather than rewrite:
  - Add control annotations (e.g., algorithmic or heuristic information)
  - Transform higher-level (problem) constraints into low-level (solver) constraints
Built-in language constructs used in modeling:

- **Build-in constraints**: \( X \#> Y \)

- **Abstraction**:
  \[
  \text{bef}(\text{task}(S_i,D_i),\text{task}(S_j,D_j)) \leftarrow S_i + D_j \#<= S_j.
  \]

- **Conjunction**: \( \text{betw}(X,Y,Z) \leftarrow X \#< Y, Y \#< Z \)

- **Disjunction**: \( \text{neighb}(X,Y) \leftarrow (X \#= Y+1 ; Y \#= X+1) \)

- **Iteration**:
  \[
  \text{not_among}(X,L) \leftarrow
  (\text{foreach}(Y,L), \text{param}(X) \text{ do } X \#\not= Y).
  \]

- **Recursion**:
  \[
  \text{not_among}(X,[]) \leftarrow
  \text{not_among}(X,[Y|Ys]) \leftarrow X \#\not= Y, \text{not_among}(X,Ys).
  \]
An example constraint network (Cheadle et al., 2014):

![Constraint Network Diagram](image)

**Variables**  
with attributes  
e.g. domain

**Constraints**  
predicates involving  
one or more variables

**Model**  
= setup program:  
[X1,X2,X3,X4]:1..9,  
X1 => X2,  
alloddifferent([X2,X3,X4]),  
X1 #\= X4.

But, of course, one problem can be modeled in multiple ways..
Same Problem – Different Model

```prolog
sendmore(Digits) :-
    Digits = [S,E,N,D,M,O,R,Y],
    Digits :: [0..9],
    alldifferent(Digits),
    S #\= 0, M #\= 0,
    1000*S + 100*E + 10*N + D
    + 1000*M + 100*O + 10*R + E
    #= 10000*M + 1000*O + 100*N + 10*E + Y.
```

```prolog
sendmore(Digits) :-
    Digits = [S,E,N,D,M,O,R,Y],
    Digits :: [0..9],
    Carries = [C1,C2,C3,C4],
    Carries :: [0..1],
    alldifferent(Digits),
    S #\= 0, M #\= 0,
    C1 #= M,
    C2 + S + M #= 0 + 10*C1,
    C3 + E + O #= N + 10*C2,
    C4 + N + R #= E + 10*C3,
    D + E #= Y + 10*C4.
```
Modeling rules

Both models work fine, but involve different variables and constraints.

⇒ “Finding good models [...] requires substantial expertise and experience.” (Cheadle et al., 2014)

Declarative model is constraint setup code ⇒ should be deterministic and terminating, so general rules:

- **Careful with disjunctions**: Don’t leave choice points (i.e., alternatives for backtracking); should be deferred until search phase

- **Use only simple conditionals**: Conditions (\ldots \rightarrow \ldots ; \ldots) must be true or false at modeling time!

- **Use only structural recursion and loops**: Termination conditions must be known at modeling time!
Preliminary summary

\[ ECL^iPS^e : \]
- is a declarative constraint programming framework
- interfaces with many programming languages
- is based on the paradigm: \( \text{Solution} = \text{Logic} + \text{Control} \)
- uses Prolog for problem modeling

⇒ Next, introduction to Prolog..
3 Prolog & $ECL^iPS^e$

- Terms and their data types
- Predicates, Goals, and Queries
- Conjunctions & Disjunctions
- Unification and Logical Variables
Introduction: Terms and their data types

Prolog data (terms) and programs are built from the following data types:

- Numbers
- Strings
- Atoms
- Lists
- Structures

They are introduced next..
Numbers in $ECL^iPS^e$ come in several flavors:

1. Integers can be as large as fits into memory, e.g.:
   
   \[
   123 \quad 0 \quad -27 \quad 393423874981724
   \]

2. Floating point number (repr. as IEEE double floats), e.g.:
   
   \[
   0.0 \quad 3.141592653589793 \quad 6.02e23 \quad -35e-12 \quad -1.0Inf
   \]

3. Also available: rationals and bounded reals

**Beware**: Performing arithmetic requires \texttt{is/2} predicate:

1. ?- X \texttt{is} 3 + 4.
2. \texttt{X = 7}
3. \texttt{Yes}

Predicate \texttt{=/2} constructs term corresp. to arithmetic expression:

1. ?- X = 3 + 4.
2. \texttt{X = 3 + 4}
3. \texttt{Yes}
Strings

Strings represent arbitrary sequences of bytes:

1 "I am a string!"
2 "string with a newline \n and a null \000 character"

Strings versus Atoms:

1 many predicates accept both strings and atoms
2 internally, the data types are quite different:
   - string stored as character sequence
   - atom mapped into internal constant via dictionary table

→ Copying and comparing:
   - atoms in unit time
   - strings in time proportional to string length

→ However, recollection of freed dictionary memory needs garbage collection
Strings versus Atoms

Consider the following example:

1 [eclipse 1]: [user].
2 afather(john, george).
3 afather(sue, harry).
4 afather(george, edward).
5 sfather("john", "george").
6 sfather("sue", "harry").
7 sfather("george", "edward").
8 yes.
9
10 [eclipse 2]: afather(sue,X).
11 X = harry
12 yes.
13
14 [eclipse 3]: sfather("sue",X).
15 X = "harry" More? (;)
16 no (more) solution.

⇒ Atoms should always be preferred when they are involved in unification and matching.
Atoms

Atoms are simple symbolic constants:

1. similar to enumeration type constants in other languages
2. no special meaning attached to them by the language
3. syntactically:
   - all words starting with a lower case letter are atoms
   - sequences of symbols are atoms
   - anything in single quotes is an atom
4. E.g.: atom quark i5 -*- ?? ? 'Atom' 'an atom'
Lists

Lists are:

1. ordered sequences of (any number of) elements, each of which is itself a term
2. delimited by square brackets ([ ]) and its elements comma separated

Examples: [1,2,3], [berlin, tokyo, freiburg], ["csp1415", 42, [1,2,3], freiburg]

More notation:

1. empty list: []
2. head and tail: [Head|Tail], with
   - Head a single element
   - Tail a (possibly empty) list

→ Equivalent lists: [1,2,3], [1|[2,3]], [1|[2|[3]]], [1|[2|[3|[[]]]]]
Structures

Structures correspond to structs or records in other languages:

1. always has a name, which looks like an atom
2. aggregates a fixed number of components, i.e. arguments that themselves are terms
3. general structure: \( <name>(<arg>_1, \ldots, <arg>_n) \)
4. arity is the number of arguments
5. name and arity together is called functor, often written as name/arity, e.g., flight/4

Examples:

date(december, 25, "Christmas")
element(hydrogen, composition(1,0))
flight(london, new_york, 12.05, 17.55)
Operator syntax (structures)

Prefix, infix, and postfix notation:

1. Unary structures also possible in prefix or postfix notation, e.g., `old berta.` the same as `old(berta).

2. Binary structures also possible in prefix or infix notation, e.g., `1 plus 5.` the same as `plus(1, 5).

3. These notations need to be declared with:
   
   ```prolog
   :- op(+Precedence, +Associativity, ++Name)
   ```

4. If in doubt, use `display/1` to check parsing of term:
   
   ```prolog
   [eclipse]: display(a+b*c).
   +(a, *(b, c))
   yes.
   ```
Summary of data types

1. **Numbers**: $ECL^iPS^e$ has intergers, floats, rationals, and bounded reals

2. **Strings**: character sequences in double quotes

3. **Atoms**: symbolic constants, usually lower case or in single quotes

4. **Lists**: constructed from cells that have an arbitrary head and a tail, which is again a (possibly empty) list

5. **Structures**: have a name and a certain number (arity) of arbitrary arguments, this characteristic is called the functor, and written name/arity
Predicates

Other programming languages have procedures and functions

⇒ Prolog and ECL\textsuperscript{i}PS\textsuperscript{e} have predicates:

1. a predicate is something that has a truth value
2. a predicate \textit{definition} defines what is \textit{true}
3. a predicate \textit{invocation} or \textit{call} checks its truth value
Goals and queries

Predicate examples for integer/1:

integer(123) is true
integer(atom) is false
integer([1,2]) is false

These predicate calls are goals.
If supplied by a user as a starting goal, the goal becomes a query, e.g.:

?- integer(123).
Yes.
?- integer(atom).
No.

Queries always return either Yes. or No.
Conjunctions

Goals are often combined to form *conjunctions* (AND) or *disjunctions* (OR).

Conjunctions:

1. are built using commas
2. are only true if all conjuncts are true

Examples:

?- integer(5), integer(7), integer(9).
Yes.

?- integer(5), integer(hello).
No.
Disjunctions:

1. are built using semicolons
2. are true if at least one disjunct is true

Examples:

?- ( integer(5); integer(hello); integer(world) ).
Yes.
?- ( integer(hello); integer(world) ).
No.

Use parentheses with disjunctions to clarify the structure.
Disjunctions

Special case: multiple answers in case of disjunctions! ⇒ $ECL^iPS^e$ gives separate **Yes** answers for every way in which a disjunctive query can be satisfied.

1 ?- ( integer(5) ; integer(7) ).
2 Yes (0.00s cpu, solution 1, maybe more)
3 Yes (0.02s cpu, solution 2)

1 ?- ( integer(5) ; integer(hello) ).
2 Yes (0.00s cpu, solution 1, maybe more)
3 No (0.02s cpu)
Symbolic Equality

Equality in Prolog:

→ structural equality by pattern matching
  • two terms only equal, if they have exactly same structure
  • No evaluation of any kind involved

Examples:

1  ?- 3 = 3.
2   Yes.
3  ?- 3 = 4.
4    No.
5  ?- foo(a,2) = foo(a,2).
6     Yes.
7  ?- foo(a,2) = foo(b,2).
8     No.
9  ?- +(3,4) = 7.
10    No.
11  ?- 3 + 4 = 7.
12    No.
Logical variables:

1. are variables in the mathematical sense (not in the usual programming language sense)
2. are placeholders for values which are not yet known, not labels for storage locations
3. are aliases for logical values and refer to terms
4. keep their value once assigned to them
5. are written beginning with an upper-case letter or an underscore, e.g.:
   X Var Quark _123 R2D2 Wumpus
6. same identifier multiple times in input term denotes the same variable
Unification

With logical variables equality test become much more interesting: **Unification**

**Unification:**

1. is an extension of pattern matching of two terms
2. also causes binding (instantiation, aliasing) of variables in the two terms
3. Idea: instantiate variables such that terms become equal

**Examples:**

- \( X = 7 \) is true with \( X \) instantiated to 7
- \( X = Y \) is true with \( X \) aliased to \( Y \) (or vice versa)
- \( \text{foo}(X) = \text{foo}(7) \) is true with \( X \) instantiated to 7
- \( \text{foo}(X,Y) = \text{foo}(3,4) \) is true with \( X \) instantiated to 3 and \( Y \) to 4
- \( \text{foo}(X,4) = \text{foo}(3,Y) \) is true with \( X \) instantiated to 3 and \( Y \) to 4
- \( \text{foo}(X) = \text{foo}(Y) \) is true with \( X \) aliased to \( Y \) (or vice versa)
- \( \text{foo}(X,X) = \text{foo}(3,4) \) is false because no possible value for \( X \)
- \( \text{foo}(X,4) = \text{foo}(3,X) \) is false because no possible value for \( X \)
Summary: Basic Terminology

- **Predicate**: Something that is true or false, depending on its definition and its arguments. Defines a relationship between its arguments.

- **Goal**: A logical formula whose truth value we want to know. A goal can be a conjunction or disjunction of other (sub-)goals.

- **Query**: The initial Goal given to a computation.

- **Unification**: An extension of pattern matching which can bind logical variables (placeholders) in the matched terms to make them equal.

- **Clause**: One alternative definition for when a predicate is true. A clause is logically an implication rule.
4 Programming in Prolog

- Defining your own predicates
- Execution scheme
- Control structures
- Using Cut
Comments can be:

1. **Block comments** enclosed between /* and */
2. **Line comments** anything following % in a line (unless ‘%’ character is part of a quoted atom or string)

(Nothing more to say..)
Clauses and facts

In Prolog a program is a collection of predicates, and a predicate is a collection of clauses. So, what is a clause:

1. defines that something is true
2. simplest form is a fact, which syntactically is a structure or an atom terminated by a full stop, e.g.:
   
   capital(london, england).
   brother(fred, jane).
3. General form of a clause:
   Head :- Body
   Where Head is a structure (or atom) and Body is a Goal, e.g.:
   uncle(X,Z) :- brother(X,Y), parent(Y,Z).
Clauses and logical implication

The example clause:

uncle(X,Z) :- brother(X,Y), parent(Y,Z).

is equivalent to the following **reverse implication**:

\[ \text{uncle}(X, Z) \leftarrow \text{brother}(X, Y) \land \text{parent}(Y, Z) \]

or more precisely:

\[ \forall X \forall Z : \text{uncle}(X, Z) \leftarrow \exists Y : \text{brother}(X, Y) \land \text{parent}(Y, Z) \]

A **fact** is equivalent to a clause with its **Body** being **true**:

brother(fred, jane) :- true.
Clauses and predicates

One or multiple clauses with the same head functor define(s) a predicate, e.g. (with facts):

1. parent(abe, homer).
2. parent(abe, herbert).
3. parent(homer, bart).
4. parent(marge, bart).

Logically, multiple clauses:
- are read as disjunctions
- define multiple alternative ways a predicate can be true

Another example, the ancestor/2 predicate:

1. ancestor(X,Y) :- parent(X,Y).
2. ancestor(X,Y) :- parent(Z,Y), ancestor(X,Z).
Resolution:

- **Given**: set of facts and rules as a program
- **Starting point**: a query as an initial goal to be resolved
- **Resolvent**: set of goals that still have to be resolved
Execution scheme ⇒ resolution

Execution mechanism:

1. Pick one goal from the resolvent. If resolvent is empty, stop.
2. Find all clauses whose head successfully unifies with goal. If no such clause, go to step 6.
3. Select first of these clauses. If more exist, remember remaining ones. (choice point)
4. Unify goal with head of the selected clause. (may instantiate variables both in the goal and in the clause’s body).
5. Prefix this clause body to the resolvent and go to 1.
6. Backtrack: Reset whole computation state to how it was when the most recent choice point was created. Take the clauses remembered in this choice point and go to 3.
Execution scheme example

With query \texttt{?- ancestor(X, bart).} we get:

1. both \texttt{ancestor/2} predicates can unify the goal
2. but the textually first clause (1) is selected first:

   Goal (Query): \texttt{ancestor(X,bart)}
   Selected: \texttt{clause 1}
   Unifying: \texttt{ancestor(X,bart) = ancestor(X1,Y1)}
   results in: \texttt{X=X1, Y1=bart}
   New resolvent: \texttt{parent(X, bart)}
   More choices: \texttt{clause 2}
Execution scheme example

1. `ancestor(X,Y) :- parent(X,Y).` % clause 1
2. `ancestor(X,Y) :- parent(Z,Y), ancestor(X,Z).` % clause 2
3. `parent(abe, homer).` % clause 3
4. `parent(abe, herbert).` % clause 4
5. `parent(homer, bart).` % clause 5
6. `parent(marge, bart).` % clause 6

2. body of clause 1 `parent(X, bart)` is added to resolvent, i.e. a choice point is generated

2. `parent(X, bart)` is next selected for unification
   ⇒ possible matches are clause 5 and 6, try 5 first

2. no body goals to add, the resolvent is now empty

Goal: `parent(X, bart)`
Selected: clause 5
Unifying: `parent(X,bart) = parent(homer,bart)`
results in: `X = homer`
New resolvent:
More choices: clause 6, then clause 2
Execution scheme example

1. \texttt{ancestor(X,Y) :- parent(X,Y).} % clause 1
2. \texttt{ancestor(X,Y) :- parent(Z,Y), ancestor(X,Z).} % clause 2
3. \texttt{parent(abe, homer).} % clause 3
4. \texttt{parent(abe, herbert).} % clause 4
5. \texttt{parent(homer, bart).} % clause 5
6. \texttt{parent(marge, bart).} % clause 6

3. **empty resolvent** \(\Rightarrow\) execution completes successfully, found first solution \(X = \text{homer}\)

3. *ECL\textsuperscript{i}PS\textsuperscript{e}* returns solution and asks if more solutions wanted

3. If yes, **backtrack** to most recent *choice point*

3. any **variable bindings** done after *choice point* are **undone**, here binding of \(X\) to \(\text{homer}\) is undone

Goal: \(\text{parent}(X, \text{bart})\)
Selected: \(\text{clause 6}\)
Unifying: \(\text{parent}(X, \text{bart}) = \text{parent}(\text{marge}, \text{bart})\)
results in: \(X = \text{marge}\)

New resolvent:
More choices: \(\text{clause 2}\)
Execution scheme example

1. \texttt{ancestor(X,Y) :- parent(X,Y).} \hspace{1cm} \textcircled{1} \% clause 1
2. \texttt{ancestor(X,Y) :- parent(Z,Y), ancestor(X,Z).} \hspace{1cm} \textcircled{2} \% clause 2
3. \texttt{parent(abe, homer).} \hspace{1cm} \textcircled{3} \% clause 3
4. \texttt{parent(abe, herbert).} \hspace{1cm} \textcircled{4} \% clause 4
5. \texttt{parent(homer, bart).} \hspace{1cm} \textcircled{5} \% clause 5
6. \texttt{parent(marge, bart).} \hspace{1cm} \textcircled{6} \% clause 6

4. **empty resolvent** $\Rightarrow$ execution completes successfully, found second solution $X = marge$

4. If still more solutions wanted, \textbf{backtrack} to most recent \textit{choice point}

4. no further alternatives for \texttt{parent/2} $\Rightarrow$ check \texttt{ancestor/2}

Goal: \texttt{ancestor(X,bart)}

Selected: \texttt{clause 2}

Unifying: \texttt{ancestor(X,bart) = ancestor(X1,Y1)}

results in: \texttt{Y1 = bart, X1 = X}

New resolvent: \texttt{parent(Z1, bart), ancestor(X1, Z1)}

More choices:
Execution scheme example

1. ancestor(X, Y) :- parent(X, Y). % clause 1
2. ancestor(X, Y) :- parent(Z, Y), ancestor(X, Z). % clause 2
3. parent(abe, homer). % clause 3
4. parent(abe, herbert). % clause 4
5. parent(homer, bart). % clause 5
6. parent(marge, bart). % clause 6

5. new resolvent contains two goals: parent(Z1, bart), ancestor(X1, Z1)

5. Check leftmost first, parent(Z1, bart) ⇒ new choice point

5. Select clause 5 first
   Goal: parent(Z1, bart)
   Selected: clause 5
   Unifying: parent(Z1, bart) = parent(homer, bart)
   results in: Z1 = homer
   New resolvent: ancestor(X1, homer)
   More choices: clause 6
Execution scheme example

1. \texttt{ancestor(X,Y) :- parent(X,Y).} \hspace{2cm} \% clause 1
2. \texttt{ancestor(X,Y) :- parent(Z,Y), ancestor(X,Z).} \hspace{2cm} \% clause 2
3. \texttt{parent(abe, homer).} \hspace{2cm} \% clause 3
4. \texttt{parent(abe, herbert).} \hspace{2cm} \% clause 4
5. \texttt{parent(homer, bart).} \hspace{2cm} \% clause 5
6. \texttt{parent(marge, bart).} \hspace{2cm} \% clause 6

6. Via finding the ancestor of \texttt{homer} a few steps later:
   \begin{verbatim}
   ?- ancestor(X,bart).
   X = abe \hspace{0.5cm} \text{More? (;)}
   \end{verbatim}

6. Finally, \texttt{Z1} would be bound to \texttt{marge} for whom no ancestors are found \(\Rightarrow\) \texttt{False}.

Here, the execution terminates.
More control structures

- **Disjunction:**
  
  1. `at_part(X) :- (X=proton ; X=neutron ; X=electron).`

  is logically equivalent to:
  
  1. `at_part(proton).`
  2. `at_part(neutron).`
  3. `at_part(electron).`

- **Conditional:**
  
  - specified by the `->/2` operator
  - combined with `;/2`, a conditional similar to ‘if-then-else’ can be constructed: `X->Y;Z`
  - only **first solution** of `X` is explored ⇒ no new solutions are tried on backtracking!

  1. `max(X,Y, Max) :-`
  2. `number(X), number(Y),`
  3. `(X > Y -> Max = X ; Max = Y).`
More control structures

- Call:
  - in Prolog: data == programs
  - both are represented as terms
  - use predicate `call` to treat terms as goals
  - `call(X)`: at runtime `X` has to be instantiated, but not at compile time!
  - possible definition of disjunction `;`:
    1. `X ; Y :- call(X).`
    2. `X ; Y :- call(Y).`

- All solutions:
  - Alternative to one-by-one solution computation:
    1. `?- findall(X, weekday(X), List).`
    2. `X = X`
    3. `List = [mo, tu, we, th, fr, sa, su]`
    4. `Yes`
  - See also `setof/3` and `bagof/3` predicates
Using cut: Overview

Use cut (!) to prune away part of the Prolog search-space.

- Powerful mechanism to improve program performance
- Suppresses unwanted solutions
- BUT: easily mis- or overused!
- Cut does two things:
  1. **commit**: disregard later clauses for a predicate
  2. **prune**: Throw away alternative solutions to the goal to the left of the cut
Commit to current clause

Consider the following encoding of the “minimum” predicate:

1 \texttt{min}(X,Y, \texttt{Min}) :- X < Y, \texttt{Min} = X.
2 \texttt{min}(X,Y, \texttt{Min}) :- Y <= X, \texttt{Min} = Y.

Problems:

- logically correct, but non-optimal performance
- with \texttt{:- min}(2,3,\texttt{M}). Prolog leaves an open \textit{choice point} ⇒ during backtracking another minimum would be searched for unnecessarily!
- unnecessary \textit{choice point}:
  1 consumes memory
  2 costs execution time

Solution, use cut:

1 \texttt{min}(X,Y, \texttt{Min}) :- X < Y, !, \texttt{Min} = X.
2 \texttt{min}(X,Y, \texttt{Y}).
A cut may occur anywhere where a goal may occur:

```
1 first_prime(X, P) :-
2     prime(X,P), !.
```

**first_prime/2:**

- returns the first prime number smaller than `X`
- calls predicate `prime/2`, which generates prime numbers smaller than `X` in descending order
- `!` (cut) prunes away all remaining solutions
- → on backtracking no alternatives are tried
5  **ECLiPS**e Programming

- Control & data structures
- Input and Output
- More functions
- Modules
Structure Notation

Names for structures (so-called declared structures) make them more readable and maintainable, e.g. with:

```prolog
:- local struct(book(author, title, year, publisher)).
```

Structures with the functor `book/4` can be written as:

1. `book{}`
2. `book{title:'tom sawyer'}`
3. `book{title:'tom sawyer', year:1876, author:twain}`

which correspond to:

1. `book(_, _, _, _)`
2. `book(_, 'tom sawyer', _, _)`
3. `book(twain, 'tom sawyer', 1876, _)`
Structure Notation

Properties of declared structure notation:

- the arguments can be written in any order
- “dummy” arguments with anonymous variables do not need to be written
- the arity of the structure is not implied
- the of-syntax can be used to return index of argument, e.g.:
  \[
  \text{arg(year of book, B, Y) is equiv. to arg(3, B, Y)}
  \]
Loops

To reduce the need for auxiliary predicates ⇒ iteration construct:

\[(\text{IterationSpecs do Goals})\]

For example, iteration over a list:

\begin{verbatim}
?- ( foreach(X,[1,2,3]) do writeln(X) )
\end{verbatim}

\begin{verbatim}
1 1
2 2
3 3
4 Yes (0.00s cpu)
\end{verbatim}

If a parameter remains \texttt{constant} across all loop iterations ⇒ must be specified explicitly (via \texttt{param}):

\begin{verbatim}
?- Array = [], for(I,1,5), fromto(0,In,Out,Sum), param(Array) do Out = In + Array[I]
\end{verbatim}
Loops

Possible IterationSpecs:

- `fromto(First, In, Out, Last)`: iterate Goals starting with `In=First` until `Out=Last`.
- `foreach(X, List)`: iterate Goals with `X` ranging over all elements of `List`.
- `foreacharg(X, StructOrArray)`: iterate Goals with `X` ranging over all arguments of `StructOrArray`.
- `foreacharg(X, StructOrArray, Idx)`: same as before, but `Idx` is set to the argument position of `X` in `StructOrArray`.

- ...

- `for(I, MinExpr, MaxExpr, [Increment])`: iterate Goals with `I` ranging over integers from `MinExpr` to `MaxExpr` with optional increment.

- ...(see http://eclipseclp.org/doc/tutorial/tutorial025.html)
Arrays

Arrays can be of any dimension, indices start at 1, and they are declared with the `dim/2` predicate:

```
?- dim(M,[3,4]).
M = [[]([][131, 132, 133, 134]),
    []([126, 127, 128, 129]),
    []([121, 122, 123, 124])].
yes.
```

To query dimensions:

```
?- dim(M,[3,4]), dim(M,D).
... 
D = [3, 4]
yes.
```

To access specific elements, specify its index:

```
?- M = [[]([][2, 3, 5]),
    [](1, 4, 7)], X is M[1, 2] + M[2, 3].
X = 10
M = [[]([][2, 3, 5]), [](1, 4, 7)].
yes.
```
Printing \( ECL^iPS^e \) terms:

- `write(+Stream, ?Term)`: write one term in a default format
- `write_term(+Stream, ?Term, +Options)`: write one term, format options can be selected
- `printf(+Stream, +Format, +ArgList)`: write a string with embedded terms, according to a format string
- `writeq(+Stream, ?Term)`, `write_canonical(+Stream, ?Term)`: write one term so that it can be read back
- `put(+Stream, +Char)`: write one character
Reading $ECL^iPS^e$ terms:

- `read(+Stream, -Term, [Options]):` read one fullstop-terminated $ECL^iPS^e$ term.
- `get(+Stream, -Char):` read one character
- `read_string(+Stream, +Terminator, -Length, -String):` read a string up to a certain terminator character
- `read_token(+Stream, -Token, -Class):` read one syntactic token (e.g. a number, an atom, a bracket, etc)

Example:

```query
1 [eclipse 1]: read(X).
2 [3, X, foo(bar), Y].
3 X = [3, X, foo(bar), Y]
4 yes.
```
Matching (one-way unification)

Clauses can use matching (or one-way unification) instead of head unification:

- written with \texttt{?-} functor instead of \texttt{:-}
- No variables in the caller will be bound

```prolog
1 [eclipse 1]: [user].
2 p(f(a,X)) ?- writeln(X).
3 ?- p(F).
4 Query failed: ?- p(F)
5 ?- p(f(A,B)).
6 Query failed: ?- p(f(A, B))
7 ?- p(f(a,b)).
8 b

1 [eclipse 2]: [user].
2 p(f(a,X)) :- writeln(X).
3 ?- p(f(A,B)).
4 B
```
List processing

\textit{ECLiPS} provides \texttt{append/3}, \texttt{length/2}, \texttt{member/2}, and \texttt{sort/2}:

- \texttt{append/3}: append or split lists, e.g.
  
  1  \?- \texttt{append([1, 2], [3, 4], L)}.
  2  L = [1, 2, 3, 4]
  3  \?- \texttt{append(A, [3, 4], [1, 2, 3, 4])}.
  4  A = [1, 2]
  5  \?- \texttt{append([1, 2], B, [1, 2, 3, 4])}.
  6  B = [3, 4]

- \texttt{length/2}: compute the length of a list or construct list of given length, e.g.
  
  1  \?- \texttt{length([1, 2, 3, 4], N)}.
  2  N = 4
  3  \?- \texttt{length(List, 4)}.
  4  List = [\_1693, \_1695, \_1697, \_1699]
**List processing**

*ECLiPS* provides `append/3`, `length/2`, `member/2`, and `sort/2`:

- **member/2**: check membership in a list (but `memberchk/2` should be preferred), or backtrack over all list members, e.g.

  1. `?- memberchk(2, [1, 2, 3]).`
  2. **Yes (0.00 s cpu)**
  3. `?- member(X, [1, 2, 3]).`
  4. `X = 1`
  5. **More (0.00 s cpu)**
  6. `X = 2`
  7. **More (0.01 s cpu)**
  8. `X = 3`
  9. **Yes (0.01 s cpu)**

- **sort/2**: sort any list and remove duplicates, e.g.

  1. `?- sort([5, 3, 4, 3, 2], Sorted).`
  2. **Sorted = [2, 3, 4, 5]**
Term processing

Generic built-in predicates:

- `=..`: converts structures into lists and vice versa
- `arg/3`: extracts an argument from a structure
- `functor/3`: extracts functor name and arity from structured term
- `term_variables/2`: extracts all variables from arbitrarily complex terms
- `copy_term/2`: creates a copy of a term with fresh variables
Making a module

With module directive a new module is declared, e.g.:

1  :- module(greeting).
2  :- export hello/0.
3    hello :-
4        who(X),
5        printf("Hello \%w!\%n", [X]).
6    who(world).
7    who(friend).

and with export a predicate is exported.
One can now import the module and call its exported predicate, e.g.:

1  :- module(main).
2  :- import greeting. % or ‘import hello/0 from greeting.’
3     main :-
4        hello. % or (without ‘import’) ‘greeting:hello.’
Most commonly exported items (apart from predicates) are structure and operator declarations:

1. :- module(data).
2. :- export struct(\texttt{employee(name,age,salary)}).
3. :- export op(500, xfx, reports_to).
4. ...

Import declarations by importing module (\texttt{import data}).
6 Interval Constraints Library

- Constraints
- Global Constraints
Interval Constraints Library

The IC (Interval Constraints) library provides a general interval propagation solver which can be used to solve problems over both integer and real variables.

Load the IC library using either of the following:

\begin{verbatim}
1  :- lib(ic).
2  :- use_module(library(ic)).
\end{verbatim}

The typical top-level structure of a constraint program:

\begin{verbatim}
1  solve(Variables) :-
2      read_data(Data),
3      setup_constraints(Data, Variables),
4      labeling(Variables).
\end{verbatim}

The \texttt{labeling/2} predicate is the search part of the program and part of the IC library.
Modeling

Your code must:

- create variables with initial domains
- setup constraints between variables

Example, SEND+MORE = MONEY:

```prolog
:- lib(ic).
sendmore(Digits) :-
    Digits = [S,E,N,D,M,O,R,Y],
    Digits :: [0..9],
    alldifferent(Digits),
    S #\= 0,
    M #\= 0,
    1000*S + 100*E + 10*N + D
    + 1000*M + 100*O + 10*R + E
    #= 10000*M + 1000*O + 100*N + 10*E + Y,
    labeling(Digits).
```
Built-in constraints

The *ic* library provides the following predicates:

- **Vars :: Domain**
  - constrains *Vars* to take only integer or real values from the domain specified by *Domain*
  - *Domain* can be simple range Lo .. Hi, or a list of subranges and/or individual elements (integer variables)
  - type of bounds determines type of the variable
  - also allowed: symbolic bound values inf, +inf and -inf

- **Vars $:: Domain**
  - like ::/2, but for declaring real variables (never imposes integrality, regardless of the types of bounds)

- **Vars #:: Domain**
  - like ::/2, but for declaring integer variables

- **reals(Vars) and integer(Vars)**
  - declares that variables are IC variables / constraints variables to integer values only
Built-in constraints: examples

1  ?- X :: -10 .. 10. % integer values from -10 to 10
2  X = X{-10 .. 10}
3  Yes
4  ?- X :: -10.0 .. 10.0. % real values from -10 to 10
5  X = X{-10.0 .. 10.0}
6  Yes
7  ?- X #:: -10 .. 10. % explicitly declared integer values
8  X = X{-10 .. 10}
9  Yes
10 ?- X $:: -10 .. 10. % explicitly declared real values
11  X = X{-10.0 .. 10.0}
12  Yes
13  ?- X :: 0 .. 1.0Inf. % integers from zero to infinity
14  X = X{0 .. 1.0Inf}
15  Yes
16  ?- X :: 0.0 .. 1.0Inf. % reals from zero to infinity
17  X = X{0.0 .. 1.0Inf}
18  Yes
19  ?- X :: [1, 4 .. 6, 9, 10]. % subranges (integers only)
20  X = X{[1, 4 .. 6, 9, 10]}
21  Yes

January 26, 2015 Becker-Asano, Nebel and Wölfli – Constraint Satisfaction Problems
Arithmetic constraints in *integral* (#) and *non-integral* ($) version:

- # &= & $ = : equality of integer (#) or general ($) expressions
- # >= & $ >= : greater than or equal
- # <= & $ <= : less than or equal
- # > & $ > : greater than
- # < & $ < : less than
- # \= & $ \= : not equal
- ac_eq(X, Y, C): arc-consistent implementation of X ≠ Y + C. X and Y are constrained to be integer variables and to have “reasonable” bounds. C must be an integer.
Arithmetic constraints

Further notes:

- $X/2 + Y/2 
ot= 1$ and $X + Y 
ot= 2$ are **different constraints** $\Rightarrow$ the first constraints $X$ and $Y$ to be even

- Except for disequality and ac_eq/3, all basic constraints **propagate bound information** (performing interval reasoning), e.g.:

  1. $\text{?– } [X, \ Y] :: 0 .. 10, \ X 
  \quad \#>= \ Y + 2.$
  2. $X = X\{2 .. 10\}$
  3. $Y = Y\{0 .. 8\}$
  4. There is 1 delayed goal.
  5. Yes

- delayed goal indicates that still some combinations of values for $X$ and $Y$ violate the constraint
- constraint remains until no such violation is possible anymore
Constraint Expression Connectives

The following connectives can be used to combine constraint expressions:

1. **and**: Constraint conjunction, e.g. ‘X $> 3 \text{ and } X $< 8’
2. **or**: Constraint disjunction, e.g. ‘X $< 3 \text{ or } X $> 8’
3. **=>**: Constraint implication, e.g. ‘X $> 3 \Rightarrow X $< 8’
4. **and**: Constraint negation, e.g. ‘neg X $> 3’

Example:

1. `?- [X, Y] :: 0..10, X #>= Y + 6 \text{ or } X #=< Y - 6.`
2. `X = X{0 .. 10}`
3. `Y = Y{0 .. 10}`
4. There are 3 delayed goals.
5. Yes

No constraint can be enforced, but ...
Once it is known that $X \#=< Y - 6$ cannot be true, the constraint $X \#>= Y + 6$ is enforced.

Example:

```prolog
?- [X, Y] :: 0..10, X #>= Y + 6 or X #=< Y - 6, X #>= 5.
Y = Y{0 .. 4}
X = X{6 .. 10}
There is 1 delayed goal.
Yes
```
Global constraints

The IC (Interval Constraints) has optional components, which provide *global constraints* ⇒ high-level constraints that provide more global reasoning than the ones in main IC library.

- contained in `ic_global`, `ic_cumulative`, `ic_edge_finder`, and `ic_edge_finder3`

- To use, e.g., `ic_global`:

  1. `- lib(ic_global).
  2. `- use_module(library(ic_global)).`

- Note: some predicates appear in more than one library, e.g., `ic:alldifferent/1` and `ic_global:alldifferent/1`
Different strength of propagation

Compare the ic:alldifferent/1 version:

1 ?- [X1, X2] :: 1 .. 2, [X3, X4] :: 1 .. 4,
2   ic:alldifferent([X1, X2, X3, X4]).
3 X1 = X1{[1, 2]}
4 X2 = X2{[1, 2]}
5 X3 = X3{1 .. 4}
6 X4 = X4{1 .. 4}
7 There are 4 delayed goals.
8 Yes

with the ic_global:alldifferent/1 version:

1 ?- [X1, X2] :: 1 .. 2, [X3, X4] :: 1 .. 4,
2   ic_global:alldifferent([X1, X2, X3, X4]).
3 X1 = X1{[1, 2]}
4 X2 = X2{[1, 2]}
5 X3 = X3{[3, 4]}
6 X4 = X4{[3, 4]}
7 There are 2 delayed goals.
8 Yes

Trade-off: longer propagation time for ic_global version
7 Example

Motivation
Problem modeling
Prolog & $ECL^PS^e$
Programming in Prolog

$ECL^PS^e$ Programming
Interval Constraints Library
Example
Summary
Literature
N-Queens problem

N-Queens

Place \(N\) queens on an \(N \times N\) chessboard so that no queen attacks another. A queen attacks all cells in horizontal, vertical and diagonal direction.

- certain solutions for all sizes can be constructed
- not a hard problem
- long history in AI and CP papers
N-Queens problem: Column based Model

- A $1..N$ variable for each column, stating position of queen in the column
- ...because exactly one queen needed for each column
- $N$ variables $\Rightarrow N^2/2$ binary constraints

assign $[X_1, X_2, \ldots, X_N]$ so that:

$$\forall 1 \leq i \leq N : \quad X_i \in 1..N$$

$$\forall 1 \leq i < j \leq N : \quad X_i \neq X_j$$

$$\forall 1 \leq i < j \leq N : \quad X_i \neq X_j + i - j$$

$$\forall 1 \leq i < j \leq N : \quad X_i \neq X_j + j - i$$
Possible program

One possible $ECLiPS^e$-program is:

```prolog
1  :- module(nqueen).
2  :- export(top/0).
3  :- lib(ic).
4  top:-
5    nqueen(8,L), writeln(L).
6  nqueen(N,L):-
7    length(L,N),
8    L :: 1..N,
9    alldifferent(L),
10   noattack(L),
11   labeling(L).
```

(see: http://4c.ucc.ie/~hsimonis/ELearning/nqueen/slides.pdf)

- noattack/2 defines binary constraints
Definition of noattack/2:

1 noattack([]).
2 noattack([H|T]):- noattack1(H,T,1), noattack(T).
3 noattack1(_,[],_).
4 noattack1(X,[Y|R],N):-
5 X #\= Y+N,
6 Y #\= X+N,
7 N1 is N+1,
8 noattack1(X,R,N1).

see: http://4c.ucc.ie/~hsimonis/ELearning/nqueen/slides.pdf)
The search predicate:

```prolog
[...] top:-
nqueen(8,L), writeln(L).
nqueen(N,L):-
  length(L,N),
  L :: 1..N,
  alldifferent(L),
  noattack(L),
  labeling(L). % <-- change this line
```

- last line can be changed to:
  ```prolog
  search(L,0,first_fail,indomain,complete,[])
  ```

- packaged search library in ic constraint solver
- provides many alternative search methods
- just select the right keywords as arguments
search predicate parameters

\[
\text{search}(+L, ++\text{Arg}, ++\text{Select}, +\text{Choice}, ++\text{Method}, +\text{Option}): \\
\]

1. \(L\): List / collection of terms / domain variables
2. \(\text{Arg}\): 0 if list \(L\) is list of domain variables, greater than 0 if \(L\) consists of terms with arity at least \(\text{Arg}\)
3. \(\text{Select}\): name of variable selection method (\text{input_order}, \text{first_fail}, \text{smallest}, \text{largest}, ...)
4. \(\text{Choice}\): name of value choice method (\text{indomain}, \text{indomain_min}, \text{indomain_max}, \text{indomain_middle}, ...)
5. \(\text{Method}\): tree search method (\text{complete}, \text{bbs}(\text{Steps:integer}), \text{lds}(\text{Disc:integer}), ...)
6. \(\text{Option}\): list of option terms
search improvements

With first_fail strategy:

```prolog
1 search(L,0,first_fail,indomain,complete,[])
```

- solution is different from naive input_order approach
- more solutions can be found

Further improvements:

- start from the middle of the board
- use most_constraint instead of first_fail (tie break based on number of constraints in which variable occurs)
- try multiple strategies in parallel (multi-core CPUs)
- limit number of backtracks for search attempt and use randomization (of value and/or variable choice)

...
8 Summary
Summary

**ECLiPSe**:  
- interfaces with many programming languages  
- provides a stand-alone and a command line user interface  
- consists of a collection of libraries  
- is intended for problem solving in a declarative fashion enabling rapid prototyping based on the CLP paradigm

Last but not least:

- It is actively developed,  
- but already mature enough,  
- and very well documented.

We only scratched its surface here.

Check out [http://eclipseclp.org/](http://eclipseclp.org/), next...


Helmut Simonis. ECLiPSE ELEarning Website http://4c.ucc.ie/~hsimonis/ELEarning/index.htm