# Principles of Knowledge Representation and Reasoning

Semantic Networks and Description Logics V: Description Logics – Decidability and Complexity

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## 1 Decidability & Undecidability



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## Decidability



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 $L_2$  is the fragment of first-order predicate logic using only two different variable names (note: variable names can be reused!).  $L_2^=: L_2$  plus equality.

#### Theorem

 $L_2^{=}$  is decidable.

## Corollary

Subsumption and satisfiability of concept descriptions is decidable in description logics using only the following concept and role forming operators:  $C \sqcap D$ ,  $C \sqcup D$ ,  $\neg C$ ,  $\forall r.C$ ,  $\exists r.C$ ,  $r \sqsubseteq s$ ,  $r \sqcap s$ ,  $r \sqcup s$ ,  $\neg r$ ,  $r^{-1}$ .

Potential problems: Role composition and cardinality restrictions for role fillers. Cardinality restrictions, however, are not a real problem.

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## Undecidability



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- $\blacksquare$   $r \circ s$ ,  $r \sqcap s$ ,  $\neg r$ , 1 [Schild 88]
  - ... already shown by Tarski (for relation algebras)
- $r \circ s$ , r = s,  $C \sqcap D$ ,  $\forall r.C$  [Schmidt-Schauß 89]
  - ... This is, in fact, a fragment of the early description logic KL-ONE, where people had hoped to come up with a complete subsumption algorithm

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# Decidable, polynomial-time cases



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- FL<sup>-</sup> has obviously a polynomial subsumption problem (in the empty TBox) – the SUB algorithm needs only quadratic time.
- Donini et al. [IJCAI 91] have shown that in the following languages subsumption can be decided using only polynomial time:

$$C := A |\neg A| \top |\bot| C \sqcap C' |\forall r.C| (\geq nr) | (\leq nr),$$
  
$$r := t | r^{-1}$$

and

$$C := A |C \sqcap C'| \forall r.C |\exists r$$
$$r := t |r^{-1}| r \sqcap r' |r \circ r'$$

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## 3 Complexity of $\mathcal{ALC}$ Subsumption



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## How hard is ALC subsumption?



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## Proposition

 $\mathcal{ALC}$  subsumption and unsatisfiability are co-NP-hard.

#### Proof.

Unsatisfiability and subsumption are reducible to each other. We give a reduction from UNSAT. A propositional formula  $\varphi$  over the atoms  $a_i$  is mapped to  $\pi(\varphi)$ :

$$egin{aligned} a_i &\mapsto a_i \ \psi \wedge \psi' &\mapsto \pi(\psi) \sqcap \pi(\psi') \ \psi' ee \psi &\mapsto \pi(\psi) \sqcup \pi(\psi') \ 
eg \psi &\mapsto 
eg \pi(\psi) \end{aligned}$$

Obviously,  $\varphi$  is satisfiable iff  $\pi(\varphi)$  is satisfiable (use structural induction). If  $\varphi$  has a model, construct a model for  $\pi(\varphi)$  with just one element t standing for the truth of the atoms and the formula.

Conversely, if  $\pi(\varphi)$  satisfiable, pick one element  $d \in \pi(\varphi)^{\mathcal{I}}$  and set the truth value of atom  $a_i$  according to the fact that  $d \in \pi(a_i)^{\mathcal{I}}$ .

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- Is ALC unsatisfiability and subsumption also complete for co-NP?
- Unlikely since models of a single concept description can already become exponentially large!
- We will show PSPACE-completeness, whereby hardness is proved using a complexity result for (un)satisifiability in the modal logic K.
- Satisifiability and unsatisfiability in *K* is PSPACE-complete.

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#### Lemma (Lower bound for ALC)

ALC subsumption, unsatisfiability and satisfiability are all PSPACE-hard.

#### Proof.

Extend the reduction given in the last proof by the following two rules – assuming that *b* is a fixed role name:

$$\Box \psi \mapsto \forall b.\pi(\psi)$$

$$\Diamond \psi \mapsto \exists b. \pi(\psi)$$

Again, obviously,  $\varphi$  is satisfiable iff  $\pi(\varphi)$  is satisfiable (again using structural induction). If  $\varphi$  has a Kripke model, interpret each world w as an object in the universe of discourse, that is, w is an instance of the primitive concept  $\pi(a_i)$  iff  $a_i$  is true in w. For the converse direction use the interpretation the other way around.

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# Computational complexity of $\mathcal{ALC}$ subsumption



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### Lemma (Upper Bound for ALC)

ALC subsumption, unsatisfiability and satisfiability are all in PSPACE.

#### Proof.

This follows from the tableau algorithm for  $\mathcal{ALC}$ . Although there may be exponentially many closed constraint systems, we can visit them step by step generating only one at a time. When closing a system, we have to consider only one role at a time – resulting in an only polynomial space requirement, i.e., satisfiability can be decided in PSPACE.

## Theorem (Complexity of $\mathcal{ALC}$ )

 $\mathcal{ALC}$  subsumption, unsatisfiability and satisfiability are all PSPACE-complete.

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- In the reduction we used only one role symbol. Are there modal logics that would require more than one such role symbol?
  - The multi-modal logic  $K_n$  has n different Box operators  $\square_i$  (for n different agents).
  - $\rightarrow$   $\mathcal{ALC}$  (wrt. TBox reasoning) is a notational variant of  $K_n$ . [Schild, IJCAI-91]
- Are there other modal logics that correspond to other descriptions logics?
  - propositional dynamic logic (PDL), e.g., transitive closure, composition, role inverse, ...
- DL can be thought as fragments of first-order predicate logic. However, they are much more similar to modal logics.
- Algorithms and complexity results can be borrowed. Works also the other way around.

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## 4 Expressive Power vs. Complexity



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## Expressive power vs. complexity





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- Of course, one wants to have a description logic with high expressive power. However, high expressive power implies usually that the computational complexity of the reasoning problems might also be high, e.g.,  $\mathcal{FL}^-$  vs.  $\mathcal{ALC}$ .
- Does it make sense to use languages such as  $\mathcal{ALC}$  or even extensions (corresponding to PDL) with higher complexity?
- There are three approaches to this problem:
  - Use only small description logics with complete inference algorithms.
  - 2 Use expressive description logics, but employ incomplete inference algorithms.
  - 3 Use expressive description logics with complete inference algorithms.
- For a long time, only options 1 and 2 were studied.

  Meanwhile, most researcher concentrate on option 3!

## 5 The Complexity of Subsumption in TBoxes



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# Is subsumption in the empty TBox enough?



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- We have shown that we can reduce concept subsumption in a given TBox to concept subsumption in the empty TBox.
- However, it is not obvious that this can be done in polynomial time ...
- In the following example unfolding leads to an exponential blowup:

$$C_1 \stackrel{.}{=} \forall r.C_0 \sqcap \forall s.C_0$$
 $C_2 \stackrel{.}{=} \forall r.C_1 \sqcap \forall s.C_1$ 
 $\vdots$ 
 $C_n \stackrel{.}{=} \forall r.C_{n-1} \sqcap \forall s.C_{n-1}$ 

- Unfolding  $C_n$  leads to a concept description with a size  $\Omega(2^n)$ .
- Is it possible to avoid this blowup? Can we avoid exponential preprocessing?

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- Question: Can we decide in polynomial time TBox subsumption for a description logic such as  $\mathcal{FL}^-$ , for which concept subsumption in the empty TBox can be decided in polynomial time?
- Let us consider  $\mathcal{FL}_0$ :  $C \sqcap D$ ,  $\forall r.C$  with terminological axioms
- Subsumption without a TBox can be done easily, using a structural subsumption algorithm.
- Unfolding + strucural subsumption gives us an exponential algorithm.

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## Complexity of TBox subsumption



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## Theorem (Complexity of TBox subsumption)

TBox subsumption for  $\mathcal{FL}_0$  is NP-hard.

*r*-transition from q to  $q' \mapsto q = \dots \sqcap \forall r : q' \sqcap \dots$ 

#### Proof sketch.

We use the NDFA-equivalence problem, which is NP-complete for cycle-free automatons and PSPACE-complete for general NDFAs. We transform a cycle-free NDFA to a  $\mathcal{FL}_0$ -terminology with the mapping  $\pi$  as follows:

automaton  $A\mapsto$  terminology  $\mathcal{T}_A$  state  $q\mapsto$  concept name q terminal state  $q_f\mapsto$  concept name  $q_f$  input symbol  $r\mapsto$  role name r

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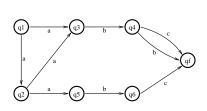
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## "Proof" by example







```
q_1 \stackrel{.}{=} \forall a.q_3 \sqcap \forall a.q_2
q_2 \stackrel{.}{=} \forall a.q_3 \sqcap \forall a.q_5
```

$$q_3 \stackrel{\cdot}{=} \forall b.q_4$$

$$q_{4} \stackrel{\cdot}{=} \forall b. q_{f} \sqcap \forall c. q_{f}$$

$$q_5 \stackrel{\cdot}{=} \forall b.q_6$$

$$q_6 \stackrel{\cdot}{=} \forall b.q_f$$

$$q_1 \equiv \forall abc. q_f \sqcap \forall abb. q_f \sqcap$$
  
 $\forall aabc. q_f \sqcap \forall aabb. q_f$ 

$$q_2 \equiv \forall abb.q_f \sqcap \forall abc.q_f$$

$$q_1 \sqsubseteq_{\mathcal{T}} q_2$$
 and  $\mathcal{L}(q_2) \subseteq \mathcal{L}(q_1)$ 

In general, we have:  $\mathcal{L}(q) \subseteq \mathcal{L}(q')$  iff  $q' \sqsubseteq_{\mathcal{T}} q$ , from which the correctness of the reduction and the complexity result follows.

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# What does this complexity result mean?





- Note that for expressive languages such as  $\mathcal{ALC}$ , we do not notice any difference!
- The TBox subsumption complexity result for less expressive languages does not play a large role in practice
- Pathological situations do not happen very often.
- In fact, if the definition depth is logarithmic in the size of the TBox, the whole problem vanishes.
- However, in order to protect oneself against such problems, one often uses lazy unfolding ...
- Similarly, also for  $\mathcal{ALC}$  concept descriptions, one notices that they are usually very well behaved.

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- Description logics have a long history (Tarski's relation algebras and Brachman's KL-ONE).
- Early on, either small languages with provably easy reasoning problems (e.g., the system CLASSIC) or large languages with incomplete inference algorithms (e.g., the system Loom) were used.
- Meanwhile, one uses complete algorithms on very large descriptions logics (e.g., SHIQ), e.g., in the systems FaCT++ and BACER.
- Nowadays tools can handle KBs with up to 160,000 concepts (example from unified medical language system) in reasonable time.
- Description logics are used as the semantic backbone for OWL (a Web-language extending RDF).

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