Introduction to Multi-Agent Programming

5. Agent Communication

Speech Acts, KIF, KQML, FIPA, JADE, IPC

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 KQML, KIF, FIPA, and Jade
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Introduction

- Communication in concurrent systems:
 - Synchronization of multiple processes
 - E.g., solving the "lost update scenario":
 - Two processes p_1 and p_2 access the shared variable v
 - During modifying of v by p_1 , p_2 reads v and writes back the old value
 - Update from p_1 is lost
- Communication in OOP
 - Method invocation between different modules
 - E.g., object o2 invokes method m1 on object o1 by executing the code o1. m1(arg), where "arg" is the argument to communicate
 - Which objects makes the decision about the execution of m1?
- Communication in MAS?
 - Autonomous agents have control over both state and behavior
 - Methods are executed according to the agent's self-interest
 - However, agents can perform communicative actions, i.e. attempt to influence other agents
 - Agent communication implies interaction, i.e. agents perform communication acts

Speech Acts I

- Most treatment of communication in MAS is inspired from speech act theory
- The theory of speech acts is generally recognized to have begun with the work of the philosopher John Austin: "How to Do Things with Words" (Austin, 1962)
- Speech act theory studies the pragmatic use of language
 - an attempt to account for how language is used by people every day to achieve their goals and intentions
- Speech act theory treats communication as action
 - speech actions are performed by agents just like other actions, in the furtherance of their intentions

Speech Acts II

- Austin noticed that some utterances are rather like 'physical actions' that appear to change the state of the world
- For example:
 - declaring war
 - 'I now pronounce you man and wife'
- Austin identified a number of performative verbs, which correspond to various different types of speech acts
 - Examples of performative verbs are *request*, *inform*, and *promise*

Speech Acts III

- Searle (1969) extended Austin's work and identified the following five key classes of possible types of speech acts:
 - Representatives: commits the speaker to the truth of an expression, e.g., 'It is raining' (*informing*)
 - Directives: attempts to get the hearer to do something e.g., 'please make the tea' (requesting)
 - Commissives: which commits the speaker to do something, e.g., 'I promise to...' (promising)
 - Expressives: whereby a speaker expresses a mental state, e.g., 'thank you!' (thanking)
 - Declarations: effect change of state, such as "declaring war" (declaring)
- Cohen and Perrault (1979) started to modeling speech acts in a planning system (STRIPS formalism)

Agent Communication Languages I KQML and KIF

- Agent communication languages (ACLs) are standard formats for the exchange of messages
- KSE (Knowledge Sharing Effort) in early 1990s designed two ACLs with different purpose
 - The Knowledge Query and Manipulation Language (KQML), which is an 'outer' language for agent communication
 - The Knowledge Interchange Format (KIF), a language for expressing content, closely based on First Order Logic

Knowledge Interchange Format (KIF)

- KIF allows agents to express
 - properties of things in a domain, e.g., "Michael is a vegetarian"
 - relationships between things in a domain, e.g., "Michael and Janine are married"
 - general properties of a domain, e.g., "All students are registered for at least one course" (quantification ∀)
- Examples:
 - "The temperature of m1 is 83 Celsius":
 (= (temperature m1) (scalar 83 Celsius))
 - "An object is a bachelor if the object is a man and is not married":

```
(defrelation bachelor (?x) :=
  (and (man ?x) (not (married ?x))))
```

- "Any individual with the property of being a person also has the property of being a mammal": (defrelation person (?x) :=> (mammal ?x))

Knowledge Query and Manipulation Language (KQML) I

- KQML defines communicative verbs, or performatives, for example:
 - ask-if (`is it true that...')
 - perform ('please perform the following action. . . ')
 - tell ('it is true that. . . ')
 - reply (`the answer is . . . ')
- Each message has a performative (the "class" of a message) and a number of parameters



KQML II Parameters of messages

Parameter	Meaning
:content	content of the message
:language	formal language the message is in
:ontology	terminology the message is based on
:force	will sender ever deny content of message?
:reply-with	reply expected? identifier of reply?
:in-reply-to	id of reply
:sender	sender ID
:receiver	receiver ID

KQML III Example dialogs





- The basic KQML performative set was overly large and not standardized
 - different implementations of KQML where developed that could not, in fact, interoperate
- The language was missing the performative commissives
 - Commissives are crucial for agents coordinating their actions.
- These criticisms amongst others led to the development of a new language by the FIPA consortium

Agent Communication Languages II Foundation for Intelligent Physical Agents (FIPA)

- FIPA is the organization for developing standards in multiagent systems. It was officially accepted by the IEEE at its eleventh standards committee in 2005
- FIPA's goal in creating agent standards is to promote interoperable agent applications and agent systems
- FIPA ACL's syntax and basic concepts are very similar to KQML, for example:

```
(inform
    :sender agent1
    :receiver agent2
    :content (price good2 150)
    :language sl
    :ontology hpl-auction
)
```

FIPA ACL Set of Performatives in FIPA ACL

performative	passing	requesting	negotiation	performing	error
	info	info		actions	handling
accept-proposal			х		
agree				х	
cancel		х		х	
cfp			х		
confirm	х				
disconfirm	х				
failure					х
inform	х				
inform-if	х				
inform-ref	х				
not-understood					х
propose			х		
query-if		х			
query-ref		х			
refuse				х	
reject-proposal			х		
request				х	
request-when				х	
request-whenever				х	
subscribe		х			

FIPA ACL Performatives Requesting Information

subscribe	sender asks to be notified when statement
	changes

- **query-if** direct query for the truth of a statement
- **query-ref** direct query for the value of an expression

FIPA ACL Performatives Passing Information

inform together with **request** most important performative; basic mechanism for communicating information; sender wants recipient to believe info; sender believes info itself

inform-ref

informs other agent about value of expression (in its content parameter); typically content of **request** message (thus asking the receiver to give me value of expression)

confirmconfirm truth of content (recipient was unsure)disconfirmconfirm falsity of content (recipient was unsure)

FIPA ACL Performatives Negotiation

cfp	call for proposals; initiates negotiation between agents; content-parameter contains action (desired to be done by some other agent) (e.g.: "sell me car") and condition (e.g.: "price < 1000\$")
propose	make proposal
accept-proposal	sender accepts proposal made by other agent
reject-proposal	sender does not accept proposal

FIPA ACL Performatives Performing Actions

refuse

requestissue request for an actionrequest-whenissue request to do action if and when a
statement is true

request-whenever issue request to do action if and whenever a statement is true

agree sender agrees to carry out requested action

cancelfollows request; indicates intention behind
request is not valid any more

reject request

FIPA Interaction Protocols (IPs)

Interaction Protocols (IPs) are standardized exchanges of performatives according to well known situations

FIPA defined IPs are:

- FIPARequest
- FIPAQuery
- FIPARequestWhen
- FIPAContractNet
- FIPAIteratedContractNet

- FIPAAuctionEnglish
- FIPAAuctionDutch
- FIPABrokering
- FIPARecruiting
- FIPASubscribe
- FIPAPropose

FIPA Interaction Protocols (IPs) FIPA IP Example: Request



FIPA Interaction Protocols (IPs) FIPA IP Example: Contract Net



Request

Ontologies

- Ontologies ground the terminology used by the agents
 - For example, an agent wants to buy a screw. But what means then "size"? Is it in inch or centimeter?
- Very important in the Internet, sometimes encoded by XML
 - In contrast to HTML, whose meta-language mainly describes the page layout, XML allows to tag data with semantics → semantic web

(a) Plain HTML

```
<m>Music</em>,
<b>Madonna<b>,
```

USD12
 Get Ready, New Order,

```
USD14<br>
```

```
</u]>
```

```
(b) XML
```

```
<catalogue>
<product type="CD">
<title>Music</title>
<artist>Madonna</artist>
<price currency="USD">12</price>
</product>
<product type="CD">
<title>Get Ready</title>
<artist>New Order</artist>
<price currency="USD">14</price>
</product>
</catalogue>
```

Plain HTML vs. XML

Java Agent Development Framework (JADE)

- Open Source project originated by Telecom (TILAB), currently governed by an international board, e.g. Motorola, France Telecom, Whitestein, ...
- JADE allows the rapid creation of distributed, multiagent systems in Java
- High interoperability through FIPA compliance
- JADE includes:
 - A library for developing agents (which implements message transport and parsing)
 - A runtime environment allowing multiple, parallel and concurrent agent activities
 - Graphical tools that support monitoring, logging, and debugging
 - Yellow Pages, a directory where agents can register their capabilities and search for other agents and services





Image taken from the Jade Tutorial

JADE III Code Example

```
public class AgentThatSearchesAndUseAService
   extends jade.core.Agent
{
   public void setup()
    {
       DFAgentDescription dfd = new DFAgentDescription();
       dfd.setType("SearchedService");
       DFAgentDescription[] agents = DFService.search(this,dfd);
       ACLMessage msg = new ACLMessage(ACLMessage.REQUEST);
       msg.addReceiver(agents[0].getAID();
       msg.setContent("execute service");
       send(msg);
       System.out.println(blockingReceive());
    }
}
```

Note DF means "Directory Faciliator", an agent for accessing the yellow pages



- JADE Behaviors
 - A behavior is basically an event handler, a method which describes how an agent reacts to an event: the reception of a message or a timer interrupt
 - The Event Handler code is placed in a method called action. Every behavior is scheduled following a round robin algorithm.
- Methods of the agents involving behaviors:
 - addBehaviour & removeBehaviour
- Examples of Behaviors already included in JADE:
 - SimpleBehavior

 - ReceiverBehavior
 - ParallelBehavior FSMBehavior
- CyclicBehavior
 - TickerBehavior WakerBehavior
 - SequentialBehavior

JADE V Debugging: "Dummy Agent"

- Functionalities:
 - compose and send a custom messages
 - load/save the queue of messages from/to a file

■ da0@IBM10312:1	099/JADE - DummyAgent		
General Current mes	sage Queued message		
🗅 🔽 🚄	2 8 8	ôo 🇙	Uave
ACLMessage Em	elape	24/09/04 10:59: 24/09/04 10:58:	PROPOSE QUERY-IF
Sender:	Set	24/09/04 10:58: 24/09/04 10:58;	FAILURE ACCEPT-PROPOSAL
Receivers:	da1@IBN10312:1099/JADE	24/09/04 10:58:	CANCEL ACCEPT-PROPOSAL
Reply-to:		24/09/04 10:52:	CONFIRM
Communicative act:	propose 💌		
Language:			
Encoding:			
Ontology:			
Protocol:	Null 👻		
Conversation-id:			
in-reply-to:			
Reply-with:	BM10312:1099JJADE1096016308500		
Reply by:	Set		
User Properties:			

Image taken from the Jade Tutorial

JADE VI Debugging: "Sniffer Agent"

- Functionalities:
 - display the flow of interactions between selected agents
 - display the content of each exchanged message
 - save/load the data flow



Image taken from the Jade Tutorial

JADE VII Debugging: "Log Manager Agent"

- Functionalities:
 - browse all Logger objects on its container (both JADE-specific and application-specific)
 - modify the logging level
 - add new logging handlers (e.g. files)

🛃da0@hpi11170:1099/JADE	- LogManag	erAgent		1×
			13.	Je
Logger Name	Set Level	Handlers	Set log file	
jade.contentlang.sl.SL0Ont	INFO	java utillogging ConsoleHandler	10 D	
jade.content.lang.sl.SL1Ont	INFO	java.util.logging.ConsoleHandler		
jade.content.lang.sl.SL2Ont	INFO	java.util.logging.ConsoleHandler	2	Bass
jade.content.lang.sl.SLOntol	INFO	java utillogging ConsoleHandler		2003
jade.content.onto.BasicOntol	SEVERE	java.util.logging.ConsoleHandler, java.util.logging.FileHandler	myLog.bt	2002
jade.content.onto.Ontology	INFO	java.util.logging.ConsoleHandler		2005
jade.content onto Serializabl	INFO	java utillogging ConsoleHandler		2012
Jade.content.schema.AgentA	INFO	java.util.logging.ConsoleHandler		1000
jade.content.schema.Aggreg	INFO	java.util.logging.ConsoleHandler	2	1000
jade.content.schema.Conce	INFO	java.util.logging.ConsoleHandler		1000
Jade.content.schema.Conte	INFO	java.util.logging.ConsoleHandler	1	1000
jade.content.schema.Conte	FINER	java.util.logging.ConsoleHandler		1000
jade.content.schema.IRESc	INFO	java.util.logging.ConsoleHandler		100
Jade.content.schema.Object	INFO 🔻	ava.uti.logging.ConsoleHandler		-
jade.content.schema.Predic	SEVERE 4	java.util.logging.ConsoleHandler		
jade.content.schema.Primiti	WARNING	java.util.logging.ConsoleHandler, java.util.logging.FileHandler	log.bd	
jade.content.schema.TermS	INFO	java.uti.logging.ConsoleHandler		
jade.content.schema.Variabl	CONFIG	java.util.logging.ConsoleHandler		
jade.core.AgentContainerImpl	CONFIG	java.util.logging.ConsoleHandler		
jade.domain.DFGUIManage	FINE	java.util.logging.ConsoleHandler		
jade.domain.DFMemKB	FINER	java.util.logging.ConsoleHandler		1
jade.domain.FIPAAgentMan	FINEST	java.util.logging.ConsoleHandler		
jade.domain.FIPAAgentMan	ALL 1	iava.uti.logging.ConsoleHandler		
jade.domain.JADEAgentMan	INFO	java.util.logging.ConsoleHandler		
jade.domain.ams	INFO	java.util.logging.ConscleHandler		
jade.domain.df	INFO	java util.logging ConsoleHandler		

Image taken from the Jade Tutorial

Inter Process Communication (IPC)

- NOT an ACL but an efficient tool within fully cooperative & distributed environments
- Very similar to ROS, the framework from WillowGarage (PR2)
- Platform-independent library for distributed network-based message passing, runs with C,C++, Lisp, and JAVA
- Provides facilities for client/server and publish / subscribe communication
 - Communication takes place either point-to-point or via a "central" thread, whereas the latter allows data logging and visualization
- Marshalling and passing of complex data structures
- Has been used by our group during RoboCup, the Sick Race, and the TechX challenge

IPC Communication Models I Publish/Subscribe



Publish/Subscribe Module Architecture

```
module MODULE C
static: quit, dataA, dataB
quit ← false
dataA ← NULL
dataB ← NULL
CONNECT-TO-CENTRAL()
SUBSCRIBE-HANDLER(msgHandlerA, dataA)
SUBSCRIBE-HANDLER(msgHandlerB, dataB)
DEFINE MESSAGE(msqC)
while (not quit) do
    listen for messages()
    dataC ← PROCESS-DATA(dataA, dataB)
    PUBLISH-DATA(dataC)
End
Function msgHandlerA(dataA)
    UPDATE-DATA(dataA)
End
Function msgHandlerB(dataB)
    UPDATE-DATA(dataB)
End
```

Distributed execution



IPC Data Formats Examples in C

. . .

```
#define RESCUE_BATTERY_STATUS_NAME "rescue_battery_status"
#define RESCUE_BATTERY_STATUS_FMT "{double, double, string}"
typedef struct {
    double level; ///< [V]
    double capacityLeft; ///< [0, 1] How full is the battery (estimated)
    double timestamp;
    char* host;
} rescue_battery_status_message;</pre>
```

#define RESCUE_JOYPAD_BUTTON_NAME "rescue_joypad_button"
#define RESCUE_JOYPAD_BUTTON_FMT "{int, double, string}"
//AUTOLOGGER LOGGER_PRINTF "Jb "
typedef struct {
 int button;
 double timestamp;
 char* host;
} rescue joypad button message;



IPC Example I Lurker Communication Graph



IPC Example I Video Lurker Exploration (IROS`07)



IPC Example II Autonomous team of Zerg Robots







IPC Example III Fast integration with Micro Aerial Vehicle (MAV)



We integrated our robot system within only one day with a MAV developed by another team from Sweden

IPC Communication Models II Parameter Daemon

- In a complex system composed of various modules, global parameters have to be handled somehow
- A parameter daemon is a separate module that reads parameters from a single configuration file
 - Stores specific parameters (typically fixed during runtime), but also module status information and commands (changing during runtime)
- Communication through "parameter changes"
 - Can be considered as blackboard system
 - Modules can install handler for parameter changes
- Implemented by publish/subscribe

Parameter Daemon Examples

<u>F</u> ile <u>V</u> iew				<u>File</u> <u>V</u> ie	ew		
<u> </u>							
global	planplayer cmd	0			global	use_gui	🖲 on 🛛 O off
pcs	planplayer state	0	j		pcs	no_of_scans_to_join	1
laser	telemax controller cmd	0			laser	goal_point_distance_to_stairs	1.5
rotating	telemax controller state	0			rotating	goal_point_distance_to_stairs_final	1.0
telemax	trajectory planner cmd	0			telemax	stairs width	2.0
telemaxController	trajectory_planner_crita	0		telen	naxController	stairs step height	0.15
sensors	visual convoing and	0			sensors	stairs step depth	0.3
smploop	visual_servoing_crit	0			smploop	stairs no of steps	5
techxmapper	visual_servoing_state	0		teo	chxmapper	sample resolution	0.01
techxIndoorMapUpdates	object_detection_cmd	0		techxind	doorMapUpdates	sample bottom floor	● on ○ off
mission	object_detection_state	0			mission	sample_top_floor	● on ○ off
missionData	reactive_control_cmd	0		m	issionData	sample_depth_images_angular_resolution	20.0
sensor	reactive_control_state	0			sensor	sample_depth_images_max_angle	70.0
floorDetection	nav_cmd	1		floo	orDetection	sample depth images distance	2.0
visualServoing	nav_state	0		visi	ualServoing	stairs depth image angular resolution	0.75
objectRecognition	con_cmd	0		obied	ctRecognition	scene depth image angular resolution	0.75
objectBecognitionTechX	con_state	0		objectB	ecognitionTechX	scene depth image max angle width	120.0
missionInformation	elevator_detect_cmd	0		missie	onInformation	scene depth image max angle height	120.0
-the Detector	elevator_detect_state	0			in-D-tt	mini depth image pixel size	8
stairsDetector	su1_cmd	0		sta	inspetector	mini depth image size	0.5
navigator	su1_state	0] [r	navigator	mini denth image max denth	0.5
navControl	su2_cmd	0]	n	avControl	mini denth image max descr dist	0.20
gpsTask	su2_state	0] –		gpsTask	max distance between line points	0.20
disasterCity	su3_cmd	0		di	isasterCity	max_distance_between_me_points	0.2
surveillance	su3_state	0]	รเ	urveillance	max_distance_between_points_and_line	25.0
trajectoryPlanner	gps_task_cmd	0	Ĩ	traje	ectoryPlanner	max_angle_between_staircase_lines	25.0
planPlayer	gps_task_state	0		p	lanPlayer	max_distance_to_stairs_plane	0.1
inverseKinematics	scan matcher cmd	0		inver	seKinematics		
indoorsm	scan matcher state	0		i	indoorsm		
•					•		

Interface for mission control: each module's action state can be set and the status read

Specific parameters of "stairsDetector"

Summary

- ACLs provide standards for communication among selfish agents, e.g. within an open systems
- Motivated from the theory of speech acts, communication is implemented in terms of actions
- The FIPA ACL can be considered as the de facto standard for agent communication
 - The JADE framework implements it in JAVA
- IPC/ROS offers all necessary functionality within fully cooperative and distributed environments
 - It is very efficient and simple to use

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