

# Principles of AI Planning

## Planning by state-space search

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B. Nebel

Normal form

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search

# Normal form for effects

- 1 Similarly to normal forms in propositional logic (DNF, CNF, NNF, ...) we can define **a normal form** for effects.
- 2 Nesting of conditionals, as in  $a \triangleright (b \triangleright c)$ , can be eliminated.
- 3 Effects  $e$  within a conditional effect  $\phi \triangleright e$  can be restricted to atomic effects ( $a$  or  $\neg a$ ).
- 4 Only a small polynomial increase in size by transformation to normal form.  
Compare: transformation to CNF or DNF may increase formula size exponentially.

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# Equivalences on effects

$$c \triangleright (e_1 \wedge \cdots \wedge e_n) \equiv (c \triangleright e_1) \wedge \cdots \wedge (c \triangleright e_n) \quad (1)$$

$$c_1 \triangleright (c_2 \triangleright e) \equiv (c_1 \wedge c_2) \triangleright e \quad (2)$$

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# Normal form for operators and effects

## Definition

An operator  $\langle c, e \rangle$  is in **normal form** if for all occurrences of  $c' \triangleright e'$  in  $e$  the effect  $e'$  is either  $a$  or  $\neg a$  for some  $a \in A$ , and there is at most one occurrence of any atomic effect in  $e$ .

## Theorem

*For every operator there is an equivalent one in normal form.*

Proof is constructive: we can transform any operator into normal form by using the equivalences from the previous slide.

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# Normal form for effects

## Example

### Example

$$(a \triangleright (b \wedge (c \triangleright (\neg d \wedge e)))) \wedge (\neg b \triangleright e)$$

transformed to normal form is

$$(a \triangleright b) \wedge ((a \wedge c) \triangleright \neg d) \wedge ((\neg b \vee (a \wedge c)) \triangleright e)$$

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# STRIPS operators

## Definition

An operator  $\langle c, e \rangle$  is a **STRIPS operator** if

- 1  $c$  is a conjunction of literals, and
- 2  $e$  is a conjunction of atomic effects.

Hence every STRIPS operator is of the form

$$\langle l_1 \wedge \dots \wedge l_n, \quad l'_1 \wedge \dots \wedge l'_m \rangle$$

where  $l_i$  are literals and  $l'_j$  are atomic effects.

## STRIPS

STanford Research Institute Planning System, Fikes & Nilsson, 1971.

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# Planning by state-space search

There are many alternative ways of doing planning by state-space search.

- ① different ways of expressing planning as a search problem:
  - ① **search direction**: forward, backward
  - ② **representation** of search space: states, sets of states
- ② different **search algorithms**: depth-first, breadth-first, informed (heuristic) search (**systematic**: A\*, IDA\*, ...; **local**: hill-climbing, simulated annealing, ...), ...
- ③ different ways of controlling search:
  - ① **heuristics** for heuristic search algorithms
  - ② **pruning techniques**: invariants, symmetry elimination, ...

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Ideas

Progression

Regression

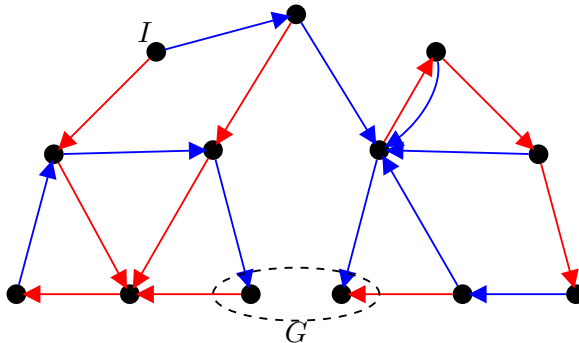
Complexity

Branching



# Planning by forward search

with depth-first search



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**Ideas**

Progression

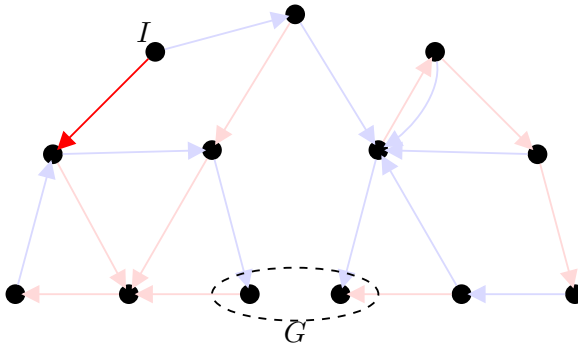
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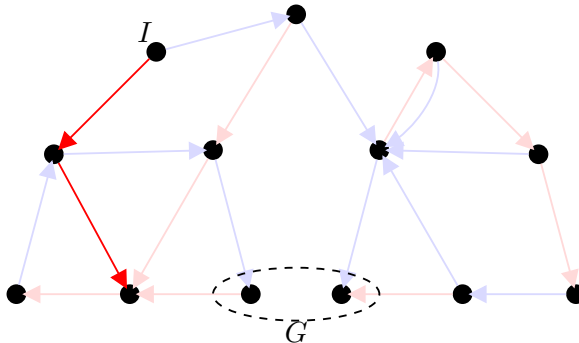
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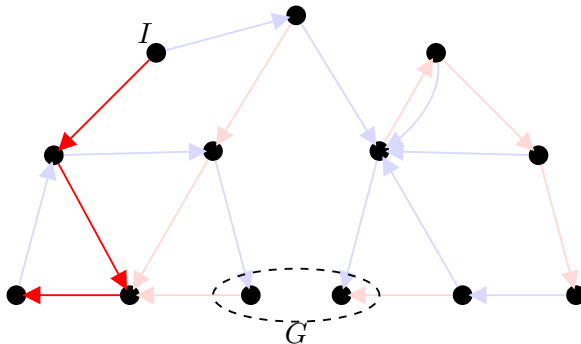
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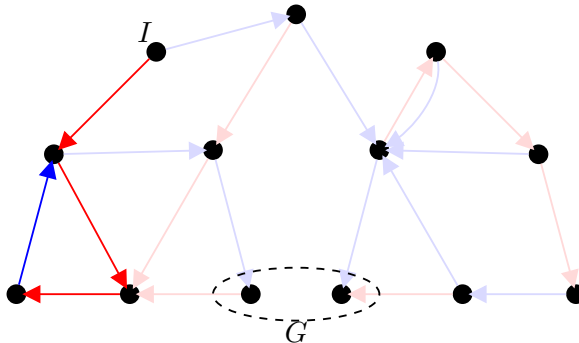
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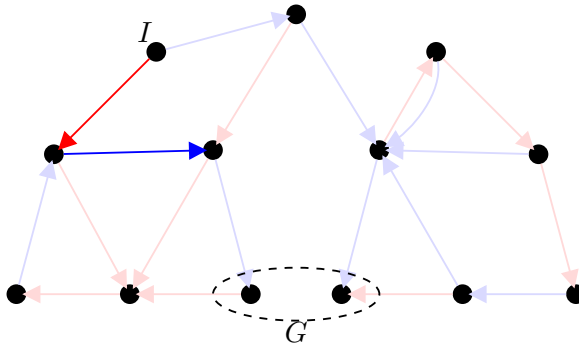
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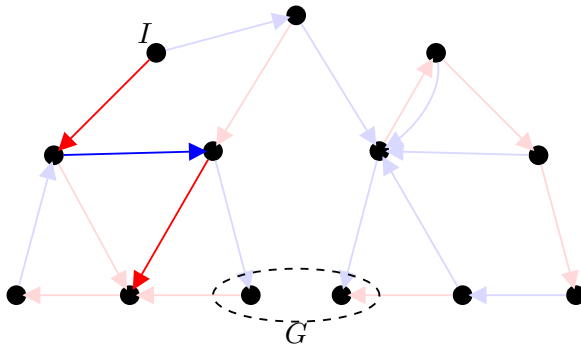
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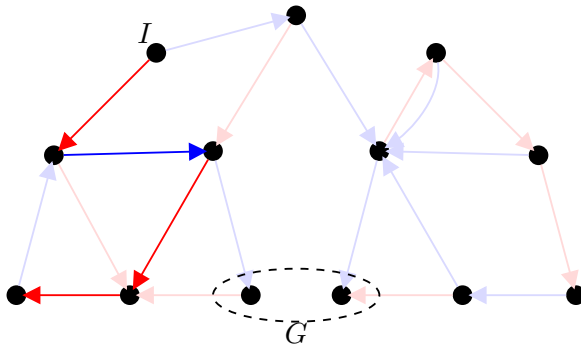
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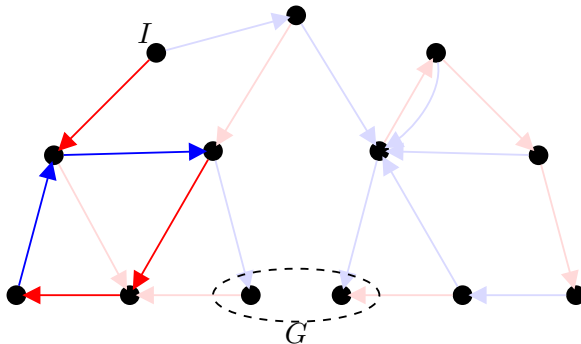
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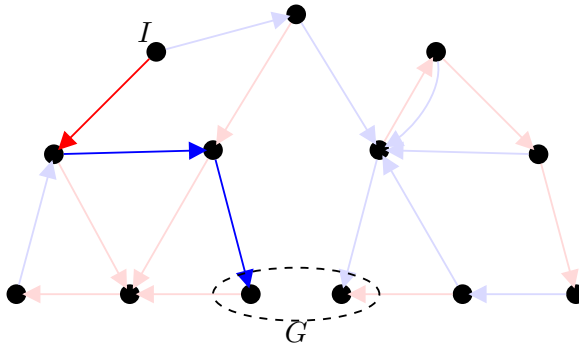
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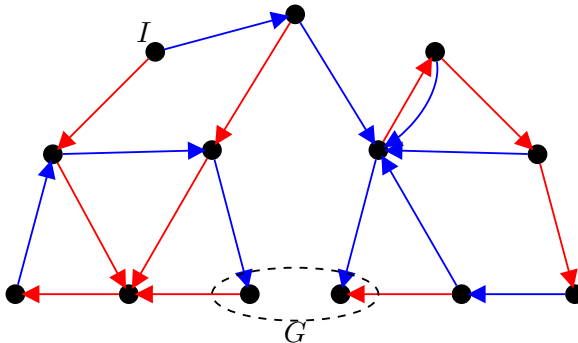
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# Planning by backward search

with depth-first search, one state at a time



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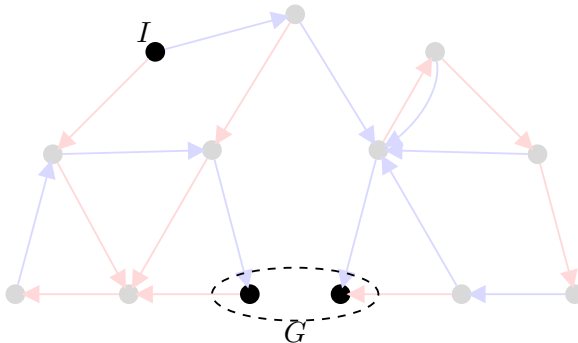
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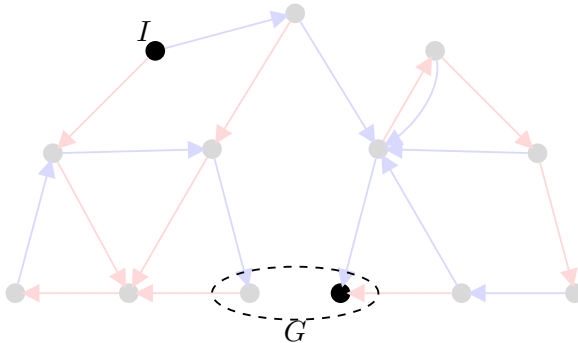
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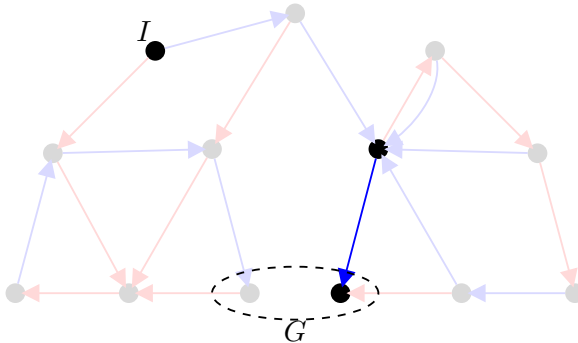
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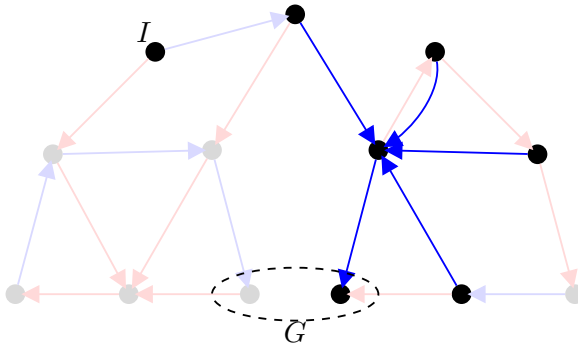
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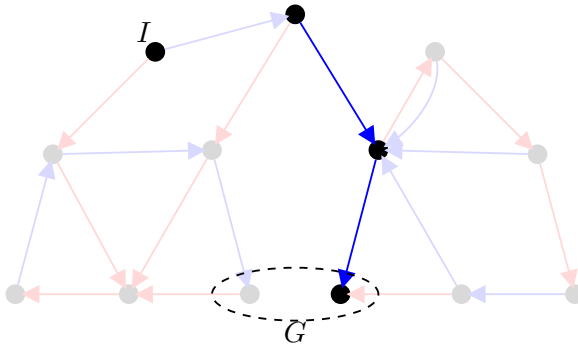
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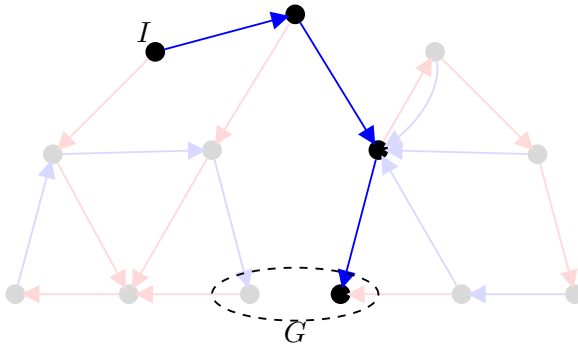
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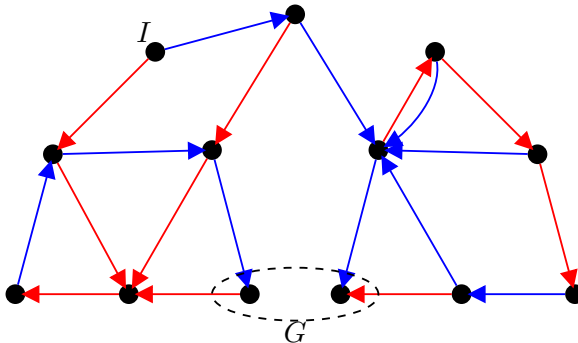
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# Planning by backward search

with depth-first search, for state sets (represented as formulae)



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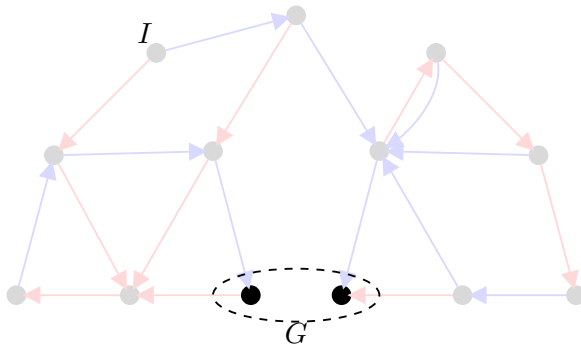
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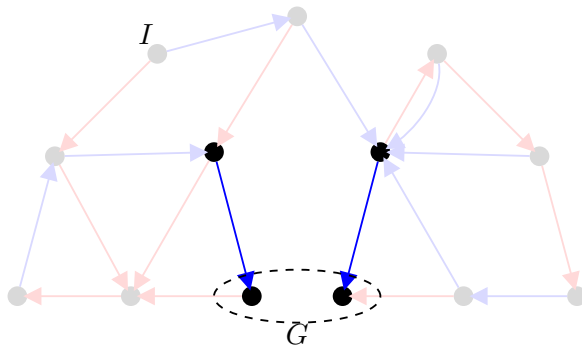
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# Planning by backward search

with depth-first search, for state sets (represented as formulae)

$$\phi_1 = \text{regr} \rightarrow (G)$$

$$\phi_1 \longrightarrow G$$



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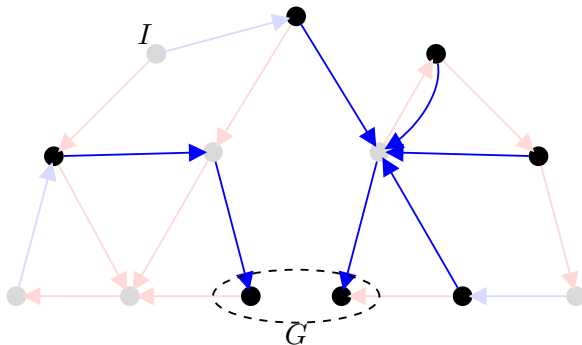
# Planning by backward search

with depth-first search, for state sets (represented as formulae)

$$\phi_1 = \text{regr} \rightarrow (G)$$

$$\phi_2 = \text{regr} \rightarrow (\phi_1)$$

$$\phi_2 \rightarrow \phi_1 \rightarrow G$$



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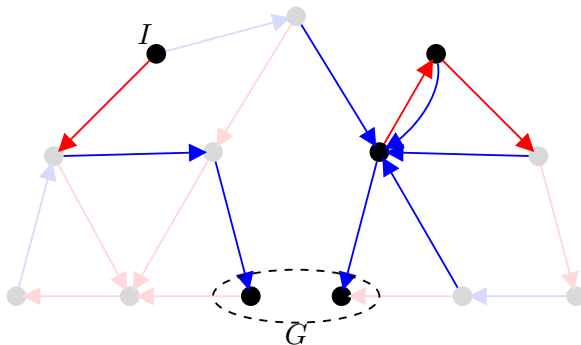
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# Planning by backward search

with depth-first search, for state sets (represented as formulae)

$$\begin{aligned}\phi_1 &= \text{regr}_{\rightarrow}(G) & \phi_3 &\xrightarrow{\text{red}} \phi_2 \xrightarrow{\text{blue}} \phi_1 \xrightarrow{\text{blue}} G \\ \phi_2 &= \text{regr}_{\rightarrow}(\phi_1) \\ \phi_3 &= \text{regr}_{\rightarrow}(\phi_2), I \models \phi_3\end{aligned}$$



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# Progression

- **Progression** means computing the successor state  $app_o(s)$  of  $s$  with respect to  $o$ .
- Used in **forward search**: from the initial state toward the goal states.
- Very easy and efficient to implement.

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# Regression

- **Regression** is computing the possible predecessor states of a set of states.
- The formula  $regr_o(\phi)$  represents the states from which a state represented by  $\phi$  is reached by operator  $o$ .
- Used in **backward search**: from the goal states toward the initial state.
- Regression is powerful because it allows handling sets of states (progression: only one state at a time.)
- Handling state sets (formulae) is more complicated than handling states: many questions about regression are **NP-hard**.

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# Regression for STRIPS operators

- Regression **for STRIPS operators** is very simple.
- Goals are conjunctions of literals  $l_1 \wedge \dots \wedge l_n$ .
- **First step**: Choose an operator that makes some of  $l_1, \dots, l_n$  true and makes none of them false.
- **Second step**: Form a new goal by removing the fulfilled goal literals and adding the preconditions of the operator.

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# Regression for STRIPS operators

## Definition

### Definition

The **STRIPS-regression**  $\text{regr}_o^{str}(\phi)$  of  $\phi = l_1'' \wedge \dots \wedge l_k''$  with respect to

$$o = \langle l_1 \wedge \dots \wedge l_n, \quad l_1' \wedge \dots \wedge l_m' \rangle$$

is the conjunction of literals

$$\bigwedge ((\{l_1'', \dots, l_k''\} \setminus \{l_1', \dots, l_m'\}) \cup \{l_1, \dots, l_n\})$$

provided that  $\{l_1', \dots, l_m'\} \cap \{\overline{l_1''}, \dots, \overline{l_k''}\} = \emptyset$ .

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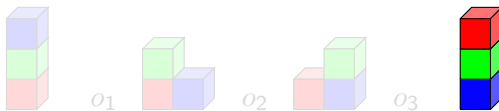
**Regression**

Complexity

Branching

# Regression for STRIPS operators

## Example



**NOTE:** Predecessor states are in general not unique.

This picture is just for illustration purposes.

$$o_1 = \langle \text{blue on green} \wedge \text{blue clr}, \neg \text{blue on green} \wedge \text{blue on T} \wedge \text{green clr} \rangle$$

$$o_2 = \langle \text{green on red} \wedge \text{green clr} \wedge \text{blue clr}, \neg \text{blue clr} \wedge \neg \text{green on red} \wedge \text{green on blue} \wedge \text{red clr} \rangle$$

$$o_3 = \langle \text{red on T} \wedge \text{red clr} \wedge \text{green clr}, \neg \text{green clr} \wedge \neg \text{red on T} \wedge \text{red on green} \rangle$$

$$G = \text{red on green} \wedge \text{green on blue}$$

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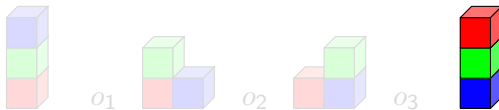
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# Regression for STRIPS operators

## Example



$$G = \text{red on green} \wedge \text{green on blue}$$

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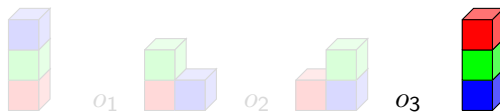
**Regression**

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# Regression for STRIPS operators

## Example



$$o_3 = \langle \text{red on T} \wedge \text{red clr} \wedge \text{green clr}, \neg \text{green clr} \wedge \neg \text{red on T} \wedge \text{red on green} \rangle$$

$$G = \text{red on green} \wedge \text{green on purple}$$

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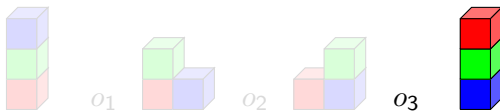
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# Regression for STRIPS operators

## Example



$$o_3 = \langle \text{red on T} \wedge \text{red clr} \wedge \text{green clr}, \neg \text{green clr} \wedge \neg \text{red on T} \wedge \text{red on green} \rangle$$

$$G = \text{red on green} \wedge \text{green on blue}$$

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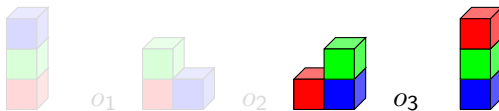
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# Regression for STRIPS operators

## Example



$$o_3 = \langle \text{red on T} \wedge \text{red clr} \wedge \text{green clr}, \neg \text{green clr} \wedge \neg \text{red on T} \wedge \text{red on green} \rangle$$

$$G = \text{red on green} \wedge \text{green on blue}$$

$$\phi_1 = \text{regr}_{o_3}^{str}(G) = \text{green on blue} \wedge \text{red on T} \wedge \text{red clr} \wedge \text{green clr}$$

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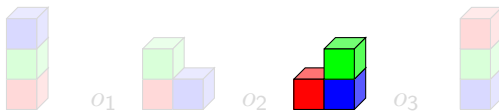
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# Regression for STRIPS operators

## Example



$$\phi_1 = \text{regr}_{o_3}^{str}(G) = \text{green on blue} \wedge \text{red on T} \wedge \text{red clr} \wedge \text{green clr}$$

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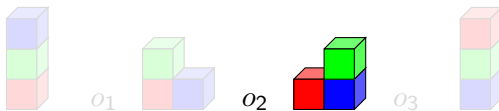
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# Regression for STRIPS operators

## Example



$$o_2 = \langle \text{green on red} \wedge \text{green clr} \wedge \text{purple clr}, \neg \text{purple clr} \wedge \neg \text{green on red} \wedge \text{green on blue} \wedge \text{red clr} \rangle$$

$$\phi_1 = \text{regr}_{o_3}^{str}(G) = \text{green on blue} \wedge \text{red on top} \wedge \text{red clr} \wedge \text{green clr}$$

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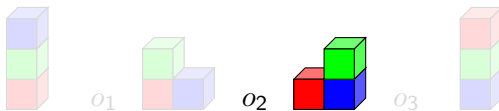
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# Regression for STRIPS operators

## Example



$$o_2 = \langle \text{green on red} \wedge \text{green clr} \wedge \text{blue clr}, \neg \text{purple clr} \wedge \neg \text{green on red} \wedge \text{green on purple} \wedge \text{red clr} \rangle$$

$$\phi_1 = \text{regr}_{o_3}^{str}(G) = \text{green on purple} \wedge \text{red on T} \wedge \text{red clr} \wedge \text{green clr}$$

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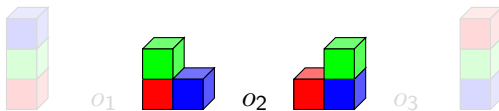
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# Regression for STRIPS operators

## Example



$$o_2 = \langle \text{green on red} \wedge \text{green clr} \wedge \text{blue clr}, \neg \text{purple clr} \wedge \neg \text{green on red} \wedge \text{green on purple} \wedge \text{red clr} \rangle$$

$$\phi_1 = \text{regr}_{o_3}^{str}(G) = \text{green on purple} \wedge \text{red on T} \wedge \text{red clr} \wedge \text{green clr}$$

$$\phi_2 = \text{regr}_{o_2}^{str}(\phi_1) = \text{red on T} \wedge \text{green clr} \wedge \text{green on red} \wedge \text{blue clr}$$

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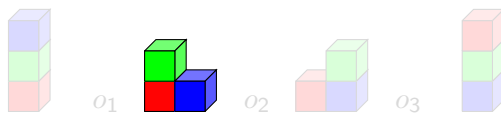
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# Regression for STRIPS operators

## Example



$$\phi_2 = \text{regr}_{o_2}^{str}(\phi_1) = \text{red on T} \wedge \text{green clr} \wedge \text{green on red} \wedge \text{blue clr}$$

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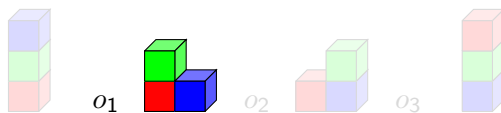
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# Regression for STRIPS operators

## Example



$$o_1 = \langle \text{purple on green} \wedge \text{purple clear}, \neg \text{purple on green} \wedge \text{purple on top} \wedge \text{green clear} \rangle$$

$$\phi_2 = \text{regr}_{o_2}^{str}(\phi_1) = \text{red on top} \wedge \text{green clear} \wedge \text{green on red} \wedge \text{purple clear}$$

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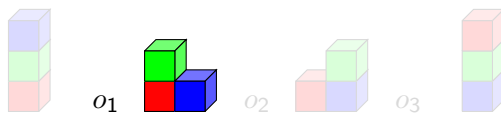
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# Regression for STRIPS operators

## Example



$$o_1 = \langle \text{blue on green} \wedge \text{blue clr}, \neg \text{purple on green} \wedge \text{purple on T} \wedge \text{green clr} \rangle$$

$$\phi_2 = \text{regr}_{o_2}^{str}(\phi_1) = \text{red on T} \wedge \text{green clr} \wedge \text{green on red} \wedge \text{blue clr}$$

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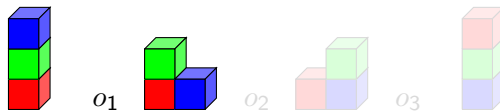
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# Regression for STRIPS operators

## Example



$$o_1 = \langle \text{blue on green} \wedge \text{blue clr}, \neg \text{purple on green} \wedge \text{purple on top} \wedge \text{green clr} \rangle$$

$$\phi_2 = \text{regr}_{o_2}^{str}(\phi_1) = \text{red on top} \wedge \text{green clr} \wedge \text{green on red} \wedge \text{blue clr}$$

$$\phi_3 = \text{regr}_{o_1}^{str}(\phi_2) = \text{red on top} \wedge \text{green on red} \wedge \text{blue clr} \wedge \text{blue on green}$$

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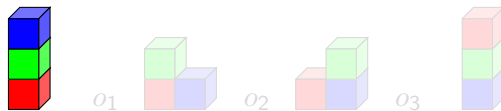
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# Regression for STRIPS operators

## Example



$$\phi_3 = \text{regr}_{o_1}^{str}(\phi_2) = \text{red on T} \wedge \text{green on red} \wedge \text{blue clr} \wedge \text{blue on green}$$

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# Regression for general operators

- With disjunction and conditional effects, things become more tricky. How to regress  $A \vee (B \wedge C)$  with respect to  $\langle Q, D \triangleright B \rangle$ ?
- The story about goals and subgoals and fulfilling subgoals, as in the STRIPS case, is no longer useful.
- We present a general method for doing regression for any formula and any operator.
- Now we extensively use the idea of *representing sets of states as formulae*.

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# Regression for general operators

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# Precondition for effect $l$ to take place: $EPC_l(e)$

## Definition

### Definition

The condition  $EPC_l(e)$  for **literal  $l$  to become true under effect  $e$**  is defined as follows.

$$EPC_l(l) = \top$$

$$EPC_l(l') = \perp \text{ when } l \neq l' \text{ (for literals } l')$$

$$EPC_l(\top) = \perp$$

$$EPC_l(e_1 \wedge \dots \wedge e_n) = EPC_l(e_1) \vee \dots \vee EPC_l(e_n)$$

$$EPC_l(c \triangleright e) = EPC_l(e) \wedge c$$

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# Precondition for effect $l$ to take place: $EPC_l(e)$

## Example

### Example

$$EPC_a(b \wedge c) = \perp \vee \perp \equiv \perp$$

$$EPC_a(a \wedge (b \triangleright a)) = \top \vee (\top \wedge b) \equiv \top$$

$$EPC_a((c \triangleright a) \wedge (b \triangleright a)) = (\top \wedge c) \vee (\top \wedge b) \equiv c \vee b$$

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# Precondition for effect $l$ to take place: $EPC_l(e)$

## Example

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# Precondition for effect $l$ to take place: $EPC_l(e)$

Example

## Example

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# Precondition for effect $l$ to take place: $EPC_l(e)$

Connection to  $[e]_s$

## Lemma (A)

*Let  $s$  be a state,  $l$  a literal and  $e$  an effect. Then  $l \in [e]_s$  if and only if  $s \models EPC_l(e)$ .*

## Proof.

Induction on the structure of the effect  $e$ .

Base case 1,  $e = \top$ : By definition of  $[\top]_s$  we have  $l \notin [\top]_s = \emptyset$  and by definition of  $EPC_l(\top)$  we have  $s \not\models EPC_l(\top) = \perp$ :

Both sides of the equivalence are false.

Base case 2,  $e = l$ :  $l \in [l]_s = \{l\}$  by definition, and  $s \models EPC_l(l) = \top$  by definition. Both sides are true.

Base case 3,  $e = l'$  for some literal  $l' \neq l$ :  $l \notin [l']_s = \{l'\}$  by definition, and  $s \not\models EPC_l(l') = \perp$  by definition. Both sides are false.

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# Precondition for effect $l$ to take place: $EPC_l(e)$

Connection to  $[e]_s$

proof continues...

Inductive case 1,  $e = e_1 \wedge \dots \wedge e_n$ :

$l \in [e]_s$  iff  $l \in [e_1]_s \cup \dots \cup [e_n]_s$  (Def  $[e_1 \wedge \dots \wedge e_n]_s$ )

iff  $l \in [e']_s$  for some  $e' \in \{e_1, \dots, e_n\}$

iff  $s \models EPC_l(e')$  for some  $e' \in \{e_1, \dots, e_n\}$  (IH)

iff  $s \models EPC_l(e_1) \vee \dots \vee EPC_l(e_n)$

iff  $s \models EPC_l(e_1 \wedge \dots \wedge e_n)$ . (Def  $EPC$ )

Inductive case 2,  $e = c \triangleright e'$ :

$l \in [c \triangleright e']_s$  iff  $l \in [e']_s$  and  $s \models c$  (Def  $[c \triangleright e']_s$ )

iff  $s \models EPC_l(e')$  and  $s \models c$  (IH)

iff  $s \models EPC_l(e') \wedge c$

iff  $s \models EPC_l(c \triangleright e')$ . (Def  $EPC$ )



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# Precondition for effect $l$ to take place: $EPC_l(e)$

Connection to  $[e]_s$

proof continues. . .

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iff  $s \models EPC_l(e') \wedge c$

iff  $s \models EPC_l(c \triangleright e')$ . (Def  $EPC$ )



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# Precondition for effect $l$ to take place: $EPC_l(e)$

Connection to  $[e]_s$

proof continues...

Inductive case 1,  $e = e_1 \wedge \dots \wedge e_n$ :

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iff  $s \models EPC_l(e_1) \vee \dots \vee EPC_l(e_n)$

iff  $s \models EPC_l(e_1 \wedge \dots \wedge e_n)$ . (Def  $EPC$ )

Inductive case 2,  $e = c \triangleright e'$ :

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# Precondition for effect $l$ to take place: $EPC_l(e)$

Connection to  $[e]_s$

proof continues...

Inductive case 1,  $e = e_1 \wedge \dots \wedge e_n$ :

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# Precondition for effect $l$ to take place: $EPC_l(e)$

Connection to  $[e]_s$

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# Precondition for effect $l$ to take place: $EPC_l(e)$

Connection to the normal form

## Remark

Notice that in terms of  $EPC_a(e)$  any operator  $\langle c, e \rangle$  can be expressed in normal form as

$$\left\langle c, \bigwedge_{a \in A} (EPC_a(e) \triangleright a) \wedge (EPC_{\neg a}(e) \triangleright \neg a) \right\rangle.$$

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# Regression: definition for state variables

## Regressing a state variable

The formula  $EPC_a(e) \vee (a \wedge \neg EPC_{\neg a}(e))$  expresses the **value of  $a \in A$  after applying  $o$**  in terms of **values of state variables before applying  $o$** : Either

- $a$  became true, or
- $a$  was true before and it did not become false.

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## Example

Let  $e = (b \triangleright a) \wedge (c \triangleright \neg a) \wedge b \wedge \neg d$ .

<i>variable</i>	$EPC_{\dots}(e) \vee (\dots \wedge \neg EPC_{\neg \dots}(e))$
$a$	$b \vee (a \wedge \neg c)$
$b$	$\top \vee (b \wedge \neg \perp) \equiv \top$
$c$	$\perp \vee (c \wedge \neg \perp) \equiv c$
$d$	$\perp \vee (d \wedge \neg \top) \equiv \perp$

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## Lemma (B)

*Let  $a$  be a state variable,  $o = \langle c, e \rangle \in O$  an operator,  $s$  a state and  $s' = \text{app}_o(s)$ . Then  $s \models \text{EPC}_a(e) \vee (a \wedge \neg \text{EPC}_{\neg a}(e))$  if and only if  $s' \models a$ .*

## Proof.

First prove the implication from left to right.

Assume  $s \models \text{EPC}_a(e) \vee (a \wedge \neg \text{EPC}_{\neg a}(e))$ . Do a case analysis on the two disjuncts.

- ① Assume that  $s \models \text{EPC}_a(e)$ . By Lemma A  $a \in [e]_s$  and hence  $s' \models a$ .
- ② Assume that  $s \models a \wedge \neg \text{EPC}_{\neg a}(e)$ . By Lemma A  $\neg a \notin [e]_s$ . Hence  $a$  remains true in  $s'$ .

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We showed that if the formula is **true** in  $s$ , then  $a$  is **true** in  $s'$ .  
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  - ① Assume that  $s \models a$ . Now  $s \models EPC_{\neg a}(e)$  because  $s \models \neg a \vee EPC_{\neg a}(e)$ . Hence by Lemma A  $\neg a \in [e]_s$  and we get  $s' \not\models a$ .
  - ② Assume that  $s \not\models a$ . Because  $s \models \neg EPC_a(e)$ , by Lemma A  $a \notin [e]_s$  and hence  $s' \not\models a$ .

Therefore in both cases  $s' \not\models a$ .



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# Regression: general definition

We base the definition of regression on formulae  $EPC_l(e)$ .

## Definition

Let  $\phi$  be a propositional formula and  $o = \langle c, e \rangle$  an operator. The **regression of  $\phi$  with respect to  $o$**  is

$$\text{regr}_o(\phi) = c \wedge \phi_r \wedge f$$

where

- ①  $\phi_r$  is obtained from  $\phi$  by replacing each  $a \in A$  by  $EPC_a(e) \vee (a \wedge \neg EPC_{\neg a}(e))$ , and
- ②  $f = \bigwedge_{a \in A} \neg(EPC_a(e) \wedge EPC_{\neg a}(e))$ .

The formula  $f$  says that no state variable may become simultaneously true and false.

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# Regression: examples

$$\textcircled{1} \text{ } \textit{regr}_{\langle a, b \rangle}(b) \equiv a \wedge (\top \vee (b \wedge \neg \perp)) \wedge \top \equiv a$$

$$\textcircled{2} \text{ } \textit{regr}_{\langle a, b \rangle}(b \wedge c \wedge d) \equiv a \wedge (\top \vee (b \wedge \neg \perp)) \wedge (\perp \vee (c \wedge \neg \perp)) \wedge (\perp \vee (d \wedge \neg \perp)) \wedge \top \equiv a \wedge c \wedge d$$

$$\textcircled{3} \text{ } \textit{regr}_{\langle a, c \triangleright b \rangle}(b) \equiv a \wedge (c \vee (b \wedge \neg \perp)) \wedge \top \equiv a \wedge (c \vee b)$$

$$\textcircled{4} \text{ } \textit{regr}_{\langle a, (c \triangleright b) \wedge (b \triangleright \neg b) \rangle}(b) \equiv a \wedge (c \vee (b \wedge \neg b)) \wedge \neg(c \wedge b) \equiv a \wedge c \wedge \neg b$$

$$\textcircled{5} \text{ } \textit{regr}_{\langle a, (c \triangleright b) \wedge (d \triangleright \neg b) \rangle}(b) \equiv a \wedge (c \vee (b \wedge \neg d)) \wedge \neg(c \wedge d) \equiv a \wedge (c \vee b) \wedge (c \vee \neg d) \wedge (\neg c \vee \neg d)$$

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# Regression: examples

## Blocks World with conditional effects

Operators to move blocks A and B onto the table from the other block if they are clear:

$$o_1 = \langle \top, (AonB \wedge Aclear) \triangleright (AonT \wedge Bclear \wedge \neg AonB) \rangle$$

$$o_2 = \langle \top, (BonA \wedge Bclear) \triangleright (BonT \wedge Aclear \wedge \neg BonA) \rangle$$

Plan for putting both blocks onto the table **from any blocks world state** with two blocks is  $o_2, o_1$ . Proof by regression:

$$G = AonT \wedge BonT$$

$$\phi_1 = regr_{o_1}(G) \equiv ((AonB \wedge Aclear) \vee AonT) \wedge BonT$$

$$\phi_2 = regr_{o_2}(\phi_1)$$

$$\begin{aligned} &\equiv ((AonB \wedge ((BonA \wedge Bclear) \vee Aclear)) \vee AonT) \\ &\quad \wedge ((BonA \wedge Bclear) \vee BonT) \end{aligned}$$

All three 2-block states satisfy  $\phi_2$ . Similar plans exist for any number of blocks.

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# Regression: examples

## Incrementing a binary number

$$\begin{aligned} & (\neg b_0 \triangleright b_0) \wedge \\ & ((\neg b_1 \wedge b_0) \triangleright (b_1 \wedge \neg b_0)) \wedge \\ & ((\neg b_2 \wedge b_1 \wedge b_0) \triangleright (b_2 \wedge \neg b_1 \wedge \neg b_0)) \end{aligned}$$

$$EPC_{b_2}(e) = \neg b_2 \wedge b_1 \wedge b_0$$

$$EPC_{b_1}(e) = \neg b_1 \wedge b_0$$

$$EPC_{b_0}(e) = \neg b_0$$

$$EPC_{\neg b_2}(e) = \perp$$

$$EPC_{\neg b_1}(e) = \neg b_2 \wedge b_1 \wedge b_0$$

$$EPC_{\neg b_0}(e) = (\neg b_1 \wedge b_0) \vee (\neg b_2 \wedge b_1 \wedge b_0) \equiv (\neg b_1 \vee \neg b_2) \wedge b_0$$

Regression replaces state variables as follows:

$$b_2 \quad \text{by} \quad (\neg b_2 \wedge b_1 \wedge b_0) \vee (b_2 \wedge \neg \perp) \equiv (b_1 \wedge b_0) \vee b_2$$

$$\begin{aligned} b_1 \quad \text{by} \quad & (\neg b_1 \wedge b_0) \vee (b_1 \wedge \neg(\neg b_2 \wedge b_1 \wedge b_0)) \\ & \equiv (\neg b_1 \wedge b_0) \vee (b_1 \wedge (b_2 \vee \neg b_0)) \end{aligned}$$

$$b_0 \quad \text{by} \quad \neg b_0 \vee (b_0 \wedge \neg((\neg b_1 \vee \neg b_2) \wedge b_0)) \equiv \neg b_0 \vee (b_1 \wedge b_2)$$

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# Regression: properties

## Lemma (C)

*Let  $\phi$  be a formula,  $o$  an operator,  $s$  any state and  $s' = \text{app}_o(s)$ . Then  $s \models \text{regr}_o(\phi)$  if and only if  $s' \models \phi$ .*

## Proof.

Let  $e$  be the effect of  $o$ . We show by structural induction over subformulae  $\phi'$  of  $\phi$  that  $s \models \phi'_r$  iff  $s' \models \phi'$ , where  $\phi'_r$  is  $\phi'$  with every  $a \in A$  replaced by  $\text{EPC}_a(e) \vee (a \wedge \neg \text{EPC}_{\neg a}(e))$ . Rest of  $\text{regr}_o(\phi)$  just states that  $o$  is applicable in  $s$ .

Induction hypothesis  $s \models \phi'_r$  if and only if  $s' \models \phi'$ .

Base cases 1 & 2  $\phi' = \top$  or  $\phi' = \perp$ : Trivial as  $\phi'_r = \phi'$ .

Base case 3  $\phi' = a$  for some  $a \in A$ : Now  
 $\phi'_r = \text{EPC}_a(e) \vee (a \wedge \neg \text{EPC}_{\neg a}(e))$ .  
By Lemma B  $s \models \phi'_r$  iff  $s' \models \phi'$ .

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# Regression: properties

proof continues. . .

**Inductive case 1**  $\phi' = \neg\psi$ : By the induction hypothesis  $s \models \psi_r$  iff  $s' \models \psi$ . Hence  $s \models \phi'_r$  iff  $s' \models \phi'$  by the truth-definition of  $\neg$ .

**Inductive case 2**  $\phi' = \psi \vee \psi'$ : By the induction hypothesis  $s \models \psi_r$  iff  $s' \models \psi$ , and  $s \models \psi'_r$  iff  $s' \models \psi'$ . Hence  $s \models \phi'_r$  iff  $s' \models \phi'$  by the truth-definition of  $\vee$ .

**Inductive case 3**  $\phi' = \psi \wedge \psi'$ : By the induction hypothesis  $s \models \psi_r$  iff  $s' \models \psi$ , and  $s \models \psi'_r$  iff  $s' \models \psi'$ . Hence  $s \models \phi'_r$  iff  $s' \models \phi'$  by the truth-definition of  $\wedge$ .



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# Regression: complexity issues

The following two tests are useful when generating a search tree with regression.

- 1 Testing that a formula  $regr_o(\phi)$  does not represent the empty set (= search is in a blind alley).  
For example,  $regr_{\langle a, \neg p \rangle}(p) \equiv a \wedge \perp \equiv \perp$ .
- 2 Testing that a regression step does not make the set of states smaller (= more difficult to reach).  
For example,  $regr_{\langle b, c \rangle}(a) \equiv a \wedge b$ .

Both of these problems are **NP-hard**.

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# Regression: complexity issues

The formula  $\text{regr}_{o_1}(\text{regr}_{o_2}(\dots \text{regr}_{o_{n-1}}(\text{regr}_{o_n}(\phi))))$  may have size  $\mathcal{O}(|\phi||o_1||o_2|\dots|o_{n-1}||o_n|)$ , i.e. the product of the sizes of  $\phi$  and the operators.

The size in the worst case  $\mathcal{O}(m^n)$  is hence exponential in  $n$ .

## Logical simplifications

①  $\perp \wedge \phi \equiv \perp, \top \wedge \phi \equiv \phi, \perp \vee \phi \equiv \phi, \top \vee \phi \equiv \top$

②  $a \vee \phi \equiv a \vee \phi[\perp/a], \neg a \vee \phi \equiv \neg a \vee \phi[\top/a],$   
 $a \wedge \phi \equiv a \wedge \phi[\top/a], \neg a \wedge \phi \equiv \neg a \wedge \phi[\perp/a]$

To obtain the maximum benefit from the last equivalences, e.g. for  $(a \wedge b) \wedge \phi(a)$ , the equivalences for associativity and commutativity are useful:  $(\phi_1 \vee \phi_2) \vee \phi_3 \equiv \phi_1 \vee (\phi_2 \vee \phi_3)$ ,  $\phi_1 \vee \phi_2 \equiv \phi_2 \vee \phi_1$ ,  $(\phi_1 \wedge \phi_2) \wedge \phi_3 \equiv \phi_1 \wedge (\phi_2 \wedge \phi_3)$ ,  $\phi_1 \wedge \phi_2 \equiv \phi_2 \wedge \phi_1$ .

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# Regression: generation of search trees

**Problem** Formulae obtained with regression may become very big.

**Cause** **Disjunctivity** in the formulae. Formulae **without disjunctions** easily convertible to small formulae  $l_1 \wedge \dots \wedge l_n$  where  $l_i$  are literals and  $n$  is at most the number of state variables.

**Solution** Handle disjunctivity when generating search trees.  
Alternatives:

- ① Do nothing. (May lead to very big formulae!!!)
- ② Always eliminate all disjunctivity.
- ③ Reduce disjunctivity if formula becomes too big.

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Regression

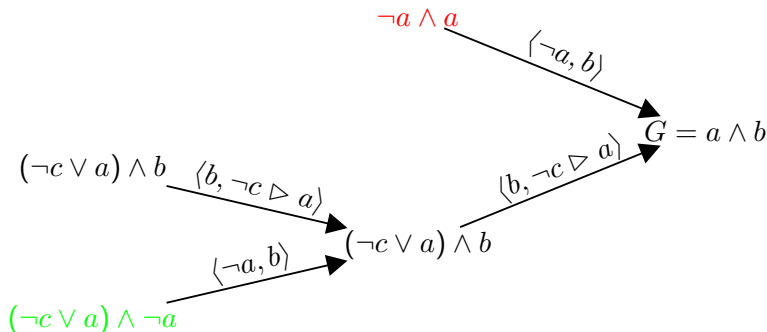
Complexity

Branching

# Regression: generation of search trees

Unrestricted regression (= do nothing about formula size)

Reach goal  $a \wedge b$  from state  $I$  such that  $I \models \neg a \wedge \neg b \wedge \neg c$ .



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# Regression: generation of search trees

Full splitting (= eliminate all disjunctivity)

- Planners for STRIPS operators only need to use formulae  $l_1 \wedge \dots \wedge l_n$  where  $l_i$  are literals.
- Some PDDL planners also restrict to this class of formulae. This is done as follows.
  - 1  $regr_o(\phi)$  is transformed to **disjunctive normal form (DNF)**:  $(l_1^1 \wedge \dots \wedge l_{n_1}^1) \vee \dots \vee (l_1^m \wedge \dots \wedge l_{n_m}^m)$ .
  - 2 Each disjunct  $l_1^i \wedge \dots \wedge l_{n_i}^i$  is handled in its own subtree of the search tree.
  - 3 The DNF formulae need not exist in its entirety explicitly: generate one disjunct at a time.
- Hence **branching** is both on the **choice of operator** and on the **choice of the disjunct** of the DNF formula.
- This leads to an **increased branching factor** and bigger search trees, but **avoids big formulae**.

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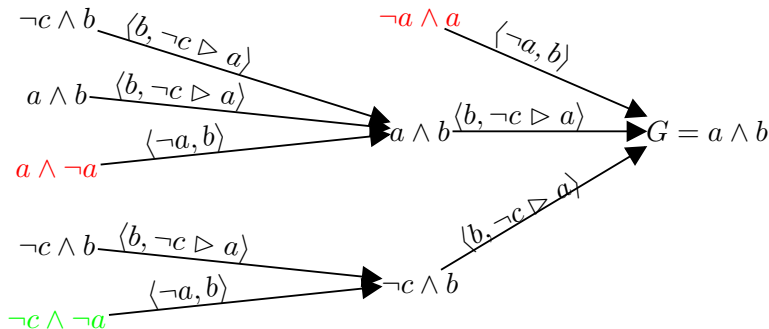
# Regression: generation of search trees

## Full splitting

Reach goal  $a \wedge b$  from state  $I$  such that  $I \models \neg a \wedge \neg b \wedge \neg c$ .

$(\neg c \vee a) \wedge b$  in DNF is  $(\neg c \wedge b) \vee (a \wedge b)$ .

It is split to  $\neg c \wedge b$  and  $a \wedge b$ .



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# Regression: generation of search trees

## Restricted splitting

- With full splitting search tree can be exponentially bigger than without splitting. (But it is not necessary to construct the DNF formulae explicitly!)
- Without splitting the formulae may have size that is exponential in the number of state variables.
- A compromise is to split formulae only when necessary: combine benefits of the two extremes.
- There are several ways to split a formula  $\phi$  to  $\phi_1, \dots, \phi_n$  such that  $\phi \equiv \phi_1 \vee \dots \vee \phi_n$ . For example:
  - 1 Transform  $\phi$  to  $\phi_1 \vee \dots \vee \phi_n$  by equivalences like distributivity  $(\phi_1 \vee \phi_2) \wedge \phi_3 \equiv (\phi_1 \wedge \phi_3) \vee (\phi_2 \wedge \phi_3)$ .
  - 2 Choose state variable  $a$ , set  $\phi_1 = a \wedge \phi$  and  $\phi_2 = \neg a \wedge \phi$ , and simplify with equivalences like  $a \wedge \psi \equiv a \wedge \psi[\top/a]$ .

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