Computer Supported Modeling and Reasoning

Jan-Georg Smaus

WS05/06
CSMR in Time and Space
Organizational Matters

Instructor: Dr. Jan-Georg Smaus

Assistant: Zeno Gantner


Labs: Fri 9:15 – 11:00, SR 00-005, bldg. 52 (Hiwi room).

Language: English (questions: German, French . . . ).

Credit: 6 credit points. Written exam at the end. Participation in lecture and exercises required.
History of this Course

In previous years, this course was given by Prof. Dr. David Basin and Dr. Burkhart Wolff.

In WS01/02 and WS02/03, Jan-Georg Smaus was in charge of the labs and maintaining the lecture slides.

As of 2003, David Basin moved to ETH Zürich. Some members of the Software Engineering group have followed him.

Jan is now in the group of Prof. Dr. Bernhard Nebel and gave this course in WS03/04 and WS04/05.
Some Former Students of this Course

Karla Alcazar, Konrad Anton, Rafael Baumgartner, Diana Dragojević, Michael Drescher, Zeno Gantner, Harald Hiss, Steffen Kemmerer, Paul Hankes Drielsma (now in Zürich), Angelika Kimmig, Matthias Luber, Julia Peltason, Florian Pigorsch, Silvia Richter, Stefan Spinner, Maria Vassileva. Ask them!
The Slides

The slides for this course will be made available at http://www.informatik.uni-freiburg.de/~ki/teaching/ws0506/csmr/. You might take notes of things written on the blackboard. The slides are actually an online course. They are also available as lecture notes that can be printed out. If you note mistakes or have suggestions, please tell me!

The slides are around 1300, contained in a single file. The lecture notes are around 700, designed for being printed at a rate of four pages per sheet side. So please be mindful of resources when you print!
General Introduction
What this Course is about

- Mechanizing and using logic
  - program **verification**:
    - input: theories, programs, properties
    - output: correctness guarantees
  - Hilbert’s program:
    - input: arithmetic
    - output: theorems

- Technically: **mechanization and application**

- Generally: making logic **come to life and useful as a general tool**.
Overview: Four Conceptual Parts

1. Logics (propositional, first-order, higher-order): appr. 6 units
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2. **Metalogics** (Isabelle): appr. 2 units
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3. Modeling mathematics and computer science (programming languages) in higher-order logic: appr. 6 units
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1. **Logics** (propositional, first-order, higher-order): appr. 6 units

2. **Metalogics** (Isabelle): appr. 2 units

3. Modeling mathematics and computer science (programming languages) in higher-order logic: appr. 6 units

4. Some case study in formalizing a theory (functional or imperative programming, or the specification language Z): appr. 2 units

Presentation roughly follows conceptual structure.
Why this Course Matters

**Academic motivation:** deepen knowledge of logic and formal reasoning
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**Practical motivation:** verification and formal methods

- The last decade has seen spectacular hardware and software failures and the birth of a new discipline: the verification engineer
- Exciting positions at companies like Intel, Gemplus, . . .
Why this Course Matters (2)

In general:

- Understanding formal reasoning improves understanding of how to build correct systems
- Mechanization provides formal guarantees

Want to see some Isabelle/HOL applications?
Relationship to Other Courses

**Logic:** deduction, foundations, and applications

**Software engineering:** specification, refinement, verification

**Hardware:** formalizing and reasoning about circuit models

**Artificial Intelligence:** knowledge representation, reasoning, deduction

In general, you will develop a deeper understanding of mathematical and logical reasoning, which is central to computer science.
Requirements

Some knowledge of logic is useful for this course.
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- further develop course material
- present material on pragmatics of mechanized reasoning
- hands-on experience.
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Experience shows that it makes no sense to follow just a little bit. It is hard in the beginning but the rewards are large.
What’s Happening in Freiburg?

I might offer projects at some point. Harald Hiss and Stefan Wölfli work with Isabelle here at Freiburg:

- There is a trend to use XML (a generalisation of HTML) for database applications. However, this gives rise to possible inconsistencies. Harald uses Isabelle to prove formally that such inconsistencies cannot occur.

- There are various formal theories that allow to reason about the relationship of objects in space and time. Stefan uses Isabelle for proving consequences of such theories, dependencies between theories etc.

Also, David Basin occasionally seeks PhD students.
More Detailed Explanations
What is Verification?

Verification is the process of formally proving that a program has the desired properties. To this end, it is necessary to define a specification language in which the desired properties can be formulated, i.e. specified. One must define a semantics for this language as well as for the program. These semantics must be linked in such a way that it is meaningful to say: “Program X makes formula $\Phi$ true”.

Back to main referring slide
What is Hilbert’s Program?

In the 1920’s, David Hilbert attempted a single rigorous formalization of all of mathematics, named Hilbert’s program. He was concerned with the following three questions:

1. Is mathematics complete in the sense that every statement could be proved or disproved?

2. Is mathematics consistent in the sense that no statement could be proved both true and false?

3. Is mathematics decidable in the sense that there existed a definite method to determine the truth or falsity of any mathematical statement?

Hilbert believed that the answer to all three questions was ’yes’.

Thanks to the the incompleteness theorem of Gödel (1931) and the
undecidability of first-order logic shown by Church and Turing (1936–37) we know now that his dream will never be realized completely. This makes it a never-ending task to find partial answers to Hilbert’s questions.

For more details:

• Panel talk by Moshe Vardi
• Lecture by Michael J. O’Donnell
• Article by Stephen G. Simpson
• Original works Über das Unendliche and Die Grundlagen der Mathematik [vH67]
• Some quotations shedding light on Gödel’s incompleteness theorem
• Eric Weisstein’s world of mathematics explaining Gödel’s incompleteness theorem
Mechanizing Logic

We will learn to make logic run on a computer by using the Isabelle system.
What is (a) Logic?

The word logic is used in a wider and a narrower sense.
In a wider sense, logic is the science of reasoning. In fact, it is the science that reasons about reasoning itself.
In a narrower sense, a logic is just a precisely defined language allowing to write down statements, together with a predefined meaning for some of the syntactic entities of this language. Propositional logic, first-order logic, and higher-order logic are three different logics.
What is a Metalogic?

A metalogic is a logic that allows us to express properties of another logic.
What is a Theory?

Intuitively, whenever you do computer-supported modeling and reasoning, you have to formalize a tiny portion of the “world”, the portion that your problem lives in. For example, rational numbers may or may not exist in this portion. A theory is such a formalization of a tiny portion of the “world”. A theory extends a logic by axioms that describe that portion of the “world”.

Theories will be considered in more detail later.
What we Neglect

We will introduce different logics and formal systems (so-called calculi) used to deduce formulas in a logic. We will neglect other aspects that are usually treated in classes or textbooks on logic, e.g.:

• semantics (interpretations) of logics; and
• correctness and completeness of calculi.

As an introduction we recommend [vD80].
Propositional Logic
Propositional Logic: Overview

• System for formalizing certain valid patterns of reasoning

• Expressions built by combining “atomic propositions” using not, if...then..., and, or, etc.

• Validity means: no counterexample. Validity independent of content. Depends on form of the expressions ⇒ can make patterns explicit by replacing words by symbols

  From if A then B and A it follows that B.
Propositional Logic: Overview

• System for formalizing certain valid patterns of reasoning

• Expressions built by combining “atomic propositions” using not, if...then..., and, or, etc.

• Validity means: no counterexample. Validity independent of content. Depends on form of the expressions ⇒ can make patterns explicit by replacing words by symbols

\[
\begin{align*}
A \rightarrow B & \quad A \\
B & \quad \frac{B}{B}
\end{align*}
\]
Propositional Logic: Overview

- System for formalizing certain valid patterns of reasoning
- Expressions built by combining “atomic propositions” using not, if...then..., and, or, etc.
- Validity means: no counterexample. Validity independent of content. Depends on form of the expressions ⇒ can make patterns explicit by replacing words by symbols
  \[ A \rightarrow B \quad A \]
  \[ \quad B \]
- What about
  From if A then B and B it follows that A?
More Examples

1. If it is Sunday, then I don’t need to work.
   It is Sunday.
   Therefore I don’t need to work.

2. It will rain or snow.
   It will not snow.
   Therefore it will rain.

3. The Butler is guilty or the Maid is guilty.
   The Maid is guilty or the Cook is guilty.
   Therefore either the Butler is guilty or the Cook is guilty.
More Examples (Which are Valid?)

1. If it is Sunday, then I don’t need to work.
   It is Sunday.
   Therefore I don’t need to work.

2. It will rain or snow.
   It will not snow.
   Therefore it will rain.

3. The Butler is guilty or the Maid is guilty.
   The Maid is guilty or the Cook is guilty.
   Therefore either the Butler is guilty or the Cook is guilty.
History

• Propositional logic was developed to make this all precise.
• Laws for valid reasoning were known to the Stoic philosophers (about 300 BC).
• The formal system is often attributed to George Boole (1815-1864).

Further reading: [vD80], [Tho91, chapter 1].
More Formal Examples

Formalization allows us to “turn the crank”.

Smaus: CSMR; WS05/06
More Formal Examples

Formalization allows us to “turn the crank”. Phrases like “from . . . it follows” or “therefore” are formalized as derivation rules, e.g.

\[
\begin{array}{c}
A \rightarrow B \\
A \\
\hline
B \\
\rightarrow -E
\end{array}
\]
More Formal Examples

Formalization allows us to “turn the crank”. Phrases like “from . . . it follows” or “therefore” are formalized as derivation rules, e.g.

\[ \frac{A \rightarrow B}{B} \]

Rules are grafted together to build trees called derivations. This defines a proof system in the style of natural deduction.
Formalizing Propositional Logic

• We must formalize
  (a) Language
  (b) Deductive system
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• We must formalize
  (a) Language
  (b) Deductive system

• Here we will focus on formalizing the deductive machinery and implicitly assume semantics and metatheorems (soundness and completeness).
Formalizing Propositional Logic

- We must formalize
  (a) Language
  (b) Deductive system

- Here we will focus on formalizing the deductive machinery and implicitly assume semantics and metatheorems (soundness and completeness).

- For labs we will carry out proofs using the Isabelle System. Isabelle supports a Natural Deduction deductive system.
Propositional Logic: Language

Propositions are built from a collection of (propositional) variables and closed under disjunction, conjunction, implication, . . .
Propositional Logic: Language (2)

More formally: Let a set $V$ of variables be given. $L_P$, the language of propositional logic, is the smallest set where:

- $X$ in $L_P$ if $X$ in $V$.
- $\bot$ in $L_P$.
- $(A \land B)$ in $L_P$ if $A$ in $L_P$ and $B$ in $L_P$.
- $(A \lor B)$ in $L_P$ if $A$ in $L_P$ and $B$ in $L_P$.
- $(A \to B)$ in $L_P$ if $A$ in $L_P$ and $B$ in $L_P$.
- $(\neg A)$ in $L_P$ if $A$ in $L_P$.

The elements of $L_P$ are called (propositional) formulas. We omit unnecessary brackets.
Deductive System: Natural Deduction

Developed by Gentzen [Gen35] and Prawitz [Pra65]. Designed to support ‘natural’ logical arguments:

• we make (temporary) assumptions;
• we derive new formulas by applying rules;
• there is also a mechanism for “getting rid of” assumptions.
Natural Deduction (2)

Derivations are trees

\[
A \rightarrow (B \rightarrow C) \quad A
\]

\[
\frac{B \rightarrow C}{\rightarrow \neg E \quad B \rightarrow C}
\]

\[
\frac{C}{\rightarrow \neg E}
\]

where the leaves are called assumptions.
Natural Deduction (2)

Derivations are trees

\[
\frac{A \rightarrow (B \rightarrow C) \quad A}{B \rightarrow C \quad \rightarrow\!-E \quad B \quad \rightarrow\!-E}
\]

where the leaves are called assumptions.

Write \( A_1, \ldots, A_n \vdash A \) if there exists a derivation of \( A \) with assumptions \( A_1, \ldots, A_n \), e.g. \( A \rightarrow (B \rightarrow C), A, B \vdash C \).
Natural Deduction (2)

Derivations are trees

\[
\frac{A \to (B \to C) \quad A}{\frac{B \to C}{\frac{C}{\frac{\to-E}{B}}}} \to-E
\]

where the leaves are called assumptions.

Write \( A_1, \ldots, A_n \vdash A \) if there exists a derivation of \( A \) with assumptions \( A_1, \ldots, A_n \), e.g. \( A \to (B \to C), A, B \vdash C \).

A proof is a derivation where we “got rid” of all assumptions.
Natural Deduction: an Abstract Example

- Language $\mathcal{L} = \{\heartsuit, \spadesuit, \clubsuit, \diamondsuit\}$. 
Natural Deduction: an Abstract Example

• Language $\mathcal{L} = \{\heartsuit, \spadesuit, \clubsuit, \diamondsuit\}$.

• Deductive system given by rules of proof:

\[
\begin{align*}
\frac{\diamondsuit}{\alpha} \\
\frac{\spadesuit}{\beta} \\
\frac{\clubsuit \spadesuit}{\heartsuit} \gamma
\end{align*}
\]

How do you read these rules?
Natural Deduction: an Abstract Example

- Language $\mathcal{L} = \{\heartsuit, \spadesuit, \clubsuit, \diamondsuit\}$.
- Deductive system given by rules of proof:

  $\frac{\diamondsuit}{\alpha}$  $\frac{\diamondsuit}{\beta}$  $\frac{\spadesuit}{\heartsuit} \gamma \frac{\heartsuit}{\diamondsuit} \delta$

How about this one?
Natural Deduction: an Abstract Example

- Language $\mathcal{L} = \{\heartsuit, \clubsuit, \spadesuit, \diamondsuit\}$.
- Deductive system given by rules of proof:

\[
\begin{array}{c}
\diamondsuit \alpha \\
\spadesuit \beta \\
\heartsuit \gamma \\
\diamondsuit \delta
\end{array}
\]

How about this one?

$\alpha, \beta, \gamma, \delta$ are just names for the rules.
Proof of ♠

The rules:

The proof:

\[
\frac{\diamond}{\alpha} \quad \frac{\diamond}{\beta} \quad \frac{\clubsuit \spadesuit}{\gamma} \quad \frac{\diamond}{\delta}
\]
Proof of ♥

The rules:

The proof:

We make an assumption. The assumption is now open.
Deductive System: Natural Deduction

The rules:

\[ \begin{array}{c}
\text{The proof:} \\
\begin{array}{c}
\diamond \alpha \\
\spadesuit \beta \\
\heartsuit \gamma \\
\heartsuit \delta
\end{array}
\end{array} \]

We apply \( \alpha \).
Proof of $\heartsuit$

The rules:

\[
\begin{align*}
\Diamond & \quad \alpha \\
\blackdiamond & \quad \beta \\
\spadesuit & \quad \heartsuit \\
\spadesuit & \quad \gamma \\
\heartsuit & \quad \delta
\end{align*}
\]

The proof:

\[
\begin{align*}
\Diamond & \quad \alpha \\
\spadesuit & \quad \beta
\end{align*}
\]

Similarly with $\beta$. 
The rules:

\[ \frac{\blackdiamond \alpha}{\clubsuit} \]
\[ \frac{\blackdiamond \beta}{\spadesuit} \]
\[ \frac{\blackspadesuit \spadesuit \gamma}{\heartsuit} \]
\[ \frac{\heartsuit \delta}{\heartsuit} \]

The proof:

\[ \frac{\blackdiamond}{\alpha} \]
\[ \frac{\blackdiamond}{\beta} \]
\[ \frac{\spadesuit \spadesuit \gamma}{\heartsuit} \]
Proof of ♥

The rules:

\[
\frac{\heartsuit}{\alpha} \quad \frac{\heartsuit}{\beta} \quad \frac{\spadesuit}{\spadesuit}{\gamma} \quad \frac{\heartsuit}{\heartsuit}{\delta}
\]

The proof:

\[
\begin{align*}
\frac{\heartsuit}{\alpha} & \quad \frac{\heartsuit}{\beta} \\
\frac{\spadesuit}{\gamma} & \quad \frac{\heartsuit}{\heartsuit}{\delta} \\
\end{align*}
\]

We apply \(\delta\), discharging two occurrences of \(\heartsuit\). We mark the brackets and the rule with a label so that it is clear which assumption is discharged in which step. The derivation is now a proof: it has no open assumptions (all discharged).
Deductive System: Rules of Propositional Logic

We have rules for conjunction, implication, disjunction, falsity and negation.

Some rules introduce, others eliminate connectives.
Rules of Propositional Logic: Conjunction

- Rules of two kinds: introduce connectives

\[
\begin{array}{c}
A \\
B \\
\hline
A \land B
\end{array}
\]

\(\land-I\)
**Rules of Propositional Logic: Conjunction**

- Rules of two kinds: *introduce* and *eliminate* connectives

\[
\frac{A \quad B}{A \land B} \quad \land\text{-}I \quad \frac{A \land B}{A} \quad \land\text{-}EL \quad \frac{A \land B}{B} \quad \land\text{-}ER
\]
Rules of Propositional Logic: Conjunction

- Rules of two kinds: introduce and eliminate connectives

\[
\frac{A \quad B}{A \land B} \land -I \quad \frac{A \land B}{A} \land -EL \quad \frac{A \land B}{B} \land -ER
\]

- Rules are schematic.

- Why valid? If all assumptions are true, then so is conclusion

\[\mathcal{A} \models A \land B \text{ iff } \mathcal{A} \models A \text{ and } \mathcal{A} \models B\]
Example Derivation with Conjunction

The rules:

\[
\begin{align*}
A & \quad B \\
\hline
A \land B & \quad \land -I \\
A \land B & \quad \land -EL \\
A & \quad \land -ER \\
A \land B & \quad \land -ER
\end{align*}
\]
Example Derivation with Conjunction

The rules:

\[ \frac{A}{A \land B} \quad \land \text{-}I \]

\[ \frac{A \land B}{A} \quad \land \text{-}EL \]

\[ \frac{A \land B}{B} \quad \land \text{-}ER \]

\[ \frac{A \land (B \land C)}{A} \quad \land \text{-}EL \]
Example Derivation with Conjunction

The rules:

\[
\frac{A \quad B}{A \land B} \quad \land\text{-}I \\
\frac{A \land B}{A} \quad \land\text{-}EL \\
\frac{A \land B}{B} \quad \land\text{-}ER
\]

\[
\frac{A \land (B \land C)}{A \land (B \land C)} \quad \land\text{-}EL \\
\frac{B \land C}{B \land C} \quad \land\text{-}ER
\]
Example Derivation with Conjunction

The rules:

\[
\begin{align*}
\frac{A \quad B}{A \land B} \quad \land-I \\
\frac{A \land B}{A} \quad \land-EL \\
\frac{A \land B}{B} \quad \land-ER
\end{align*}
\]

\[
\frac{A \land (B \land C)}{A \land B} \quad \land-EL
\]

\[
\frac{A \land (B \land C)}{B \land C} \quad \land-ER
\]

\[
\frac{B \land C}{C} \quad \land-ER
\]
Example Derivation with Conjunction

The rules:

\[
\begin{align*}
\frac{A}{A} & \quad \land-I \\
\frac{B}{B} & \quad \land-I \\
\frac{A \land B}{A} & \quad \land-EL \\
\frac{A \land B}{B} & \quad \land-ER
\end{align*}
\]

\[
\begin{align*}
A \land (B \land C) & \quad \land-EL \\
\frac{B \land C}{C} & \quad \land-ER \\
\frac{A \land (B \land C) \land ER}{A} & \quad \land-EL \\
\frac{C}{C} & \quad \land-ER \\
\frac{A \land C}{A \land C} & \quad \land-I
\end{align*}
\]
Example Derivation with Conjunction

The rules:

\[
\begin{align*}
A & \quad B \\
\hline
A \land B & \quad \land -I \\
A \land B & \quad \land -EL \\
A \land B & \quad \land -ER
\end{align*}
\]

\[
\begin{align*}
A \land (B \land C) & \\
\hline
A \land B & \quad \land -EL \\
\quad \land -EL \\
B \land C & \quad \land -ER \\
\quad \land -ER \\
A \land C & \quad \land -I
\end{align*}
\]

Can we prove anything with just these three rules?
Rules of Propositional Logic: Implication

- Rules

\[
\begin{align*}
\frac{[A]}{A \to B} & \quad \rightarrow I \\
\frac{B}{A \to B} & \quad \rightarrow -I \\
\frac{A \to B}{B} & \quad \rightarrow -E \\
\frac{A}{A} & \quad \rightarrow -E
\end{align*}
\]
Rules of Propositional Logic: Implication

- Rules

\[
\begin{align*}
[A] \\
\vdots
\end{align*}
\]

\[
B \quad \rightarrow\text{-I}
\]

\[
A \rightarrow B \quad \rightarrow\text{-I}
\]

\[
A \rightarrow B \quad B \
A \rightarrow \quad \rightarrow\text{-E}
\]

- \(\rightarrow\text{-E}\) is also called modus ponens.
**Rules of Propositional Logic: Implication**

- **Rules**
  
  \[
  \vdash \begin{array}{c}
  \[A] \\
  \vdots \\
  B \\
  \end{array} \quad \frac{A \rightarrow B}{A \rightarrow B} \rightarrow \text{-I} \\
  \frac{A \rightarrow B}{B} \rightarrow \text{-E}
  \]

- **→-E** is also called *modus ponens*.

- **→-I** formalizes strategy:
  
  To derive \( A \rightarrow B \), derive \( B \) under the additional assumption \( A \).
A very Simple Proof

The simplest proof we can think of is the proof of $P \rightarrow P$. 

$P$
A very Simple Proof

The simplest proof we can think of is the proof of $P \rightarrow P$.

\[
\frac{[P]^1}{P \rightarrow P \rightarrow \bot^1}
\]

Do you find this strange?
Examples with Conjunction and Implication

1. $A \rightarrow B \rightarrow A$
2. $A \land (B \land C) \rightarrow A \land C$
3. $(A \rightarrow B \rightarrow C) \rightarrow (A \rightarrow B) \rightarrow A \rightarrow C$

Are these object or metavariables here?
Disjunction

- **Rules**

\[
\frac{A}{A \lor B} \quad \lor-IL \\
\frac{B}{A \lor B} \quad \lor-IR
\]

\[
\frac{A \lor B}{C} \quad \lor-E
\]

\[
\text{[A]} \quad \text{[B]}
\]
Disjunction

- Rules

\[
\frac{A}{A \lor B} \quad \lor-IL
\]
\[
\frac{B}{A \lor B} \quad \lor-IR
\]
\[
\frac{A \lor B \quad C \quad C}{C} \quad \lor-E
\]

- Formalizes case-split strategy for using \( A \lor B \).
Disjunction: Example

- Rules

\[
\frac{A}{A \lor B} \quad \lor IL
\]
\[
\frac{B}{A \lor B} \quad \lor IR
\]
\[
\frac{A \lor B}{C} \quad \lor E
\]

- Example: formalize and prove

When it rains then I wear my jacket.
When it snows then I wear my jacket.
It is raining or snowing.
Therefore I wear my jacket.
Falsity and Negation

- Falsity

\[
\begin{align*}
\bot & \rightarrow -E \\
\bot & \rightarrow A \\
A & \rightarrow -E
\end{align*}
\]

No introduction rule!
Falsity and Negation

• Falsity

\[ \frac{\bot}{A} \quad \bot,-E \]

No introduction rule!

• Negation: define \( \neg A \) as \( A \rightarrow \bot \). Rules for \( \neg \) just special cases of rules for \( \rightarrow \). Convenient to have

\[ \frac{\neg A}{A} \quad \frac{A}{\bot} \quad \rightarrow,-E \]

\[ \frac{\bot}{B} \quad \neg,-E \]

\[ \frac{B}{\bot} \quad \bot,-E \]

\( A \rightarrow \bot \) derived by \( \neg A \rightarrow B \rightarrow,-E \)
Intuitionistic versus Classical Logic

• Peirce’s Law: \(((A \to B) \to A) \to A\).

Is this valid? Provable?
Intuitionistic versus Classical Logic

- Peirce’s Law: \(((A \rightarrow B) \rightarrow A) \rightarrow A\).
  Is this valid? Provable?

- It is provable in classical logic, obtained by adding
  \[
  \frac{\neg A \quad \neg A}{\bot} \quad \frac{\bot}{\top} \quad \frac{\bot}{\bot} \quad \frac{\top}{\bot} \quad \frac{\bot}{\bot} \quad \frac{\bot}{\bot}
  \]
  \[A \lor \neg A\] or \[\text{RAA}\] or \[\text{classical}\].
Example of Classical Reasoning

There exist irrational numbers $a$ and $b$ such that $a^b$ is rational.
Example of Classical Reasoning

There exist irrational numbers \(a\) and \(b\) such that \(a^b\) is rational.

**Proof:** Let \(b\) be \(\sqrt{2}\) and consider whether or not \(b^b\) is rational.

Case 1: If rational, let \(a = b = \sqrt{2}\)

Case 2: If irrational, let \(a = \sqrt{2^{\sqrt{2}}}\), and then

\[
a^b = \sqrt{2^{\sqrt{2}} \sqrt{2}} = \sqrt{2^{(\sqrt{2} \cdot \sqrt{2})}} = \sqrt{2^2} = 2
\]
Example of Classical Reasoning

There exist irrational numbers $a$ and $b$ such that $a^b$ is rational.

Proof: Let $b$ be $\sqrt{2}$ and consider whether or not $b^b$ is rational.

Case 1: If rational, let $a = b = \sqrt{2}$

Case 2: If irrational, let $a = \sqrt{2}^{\sqrt{2}}$, and then

\[ a^b = \sqrt{2}^{\sqrt{2}^{\sqrt{2}}} = \sqrt{2}^{(\sqrt{2} \times \sqrt{2})} = \sqrt{2}^2 = 2 \]

We still don’t know how to choose $a$ and $b$ so that $a^b$ is rational. Hence the proof is non-constructive.
Overview of Rules

\[
\frac{A \quad B}{A \land B} \quad \land-I \\
\frac{A \land B}{A} \quad \land-EL \\
\frac{A \land B}{B} \quad \land-ER
\]

\[
\frac{A}{A \lor B} \quad \lor-IL \\
\frac{B}{A \lor B} \quad \lor-IR \\
\frac{A \lor B \quad C \quad C}{C} \quad \lor-E
\]

\[
\frac{[A] \quad [B]}{} \\
\frac{\vdots}{B} \quad \to-I \\
\frac{A \to B}{A \to B} \quad \to-E
\]

\[
\frac{A \to B}{B} \quad \to-E \\
\frac{A}{A} \quad \perp-E
\]
Deductive System: Derived Rules

Using the basic rules, we can derive new rules.
Example: Resolution rule.
Deductive System: Derived Rules

Using the basic rules, we can derive new rules.
Example: Resolution rule.

\[
\frac{R \lor S}{R} \quad \frac{\neg S}{\neg S}
\]

It looks like this.
**Deductive System: Derived Rules**

Using the basic rules, we can derive new rules.

Example: Resolution rule.

\[
\frac{R \lor S \quad \neg S}{R} \quad \frac{R \lor S}{R}
\]

We build a fragment of a derivation by writing the conclusion \( R \) and the assumptions \( R \lor S \) and \( \neg S \).
Deductive System: Derived Rules

Using the basic rules, we can derive new rules.
Example: Resolution rule.

\[
\begin{align*}
\neg S \\
R \lor S & \quad \neg S \\
\hline
R & \\
\end{align*}
\]

\[
\begin{align*}
R \lor S & \\
R & \\
\hline
\lor-E
\end{align*}
\]

Since we have assumption \( R \lor S \), using \( \lor-E \) seems a good idea. So we should make assumptions \( R \) and \( S \). First \( R \). But that is a derivation of \( R \) from \( R \)!
Deductive System: Derived Rules

Using the basic rules, we can derive new rules.

Example: Resolution rule.

\[
\begin{align*}
\neg S & \quad S \\
R \lor S & \quad \neg S \\
R & \quad R \\
R & \quad \neg E
\end{align*}
\]

So now \( S \).
Deductive System: Derived Rules

Using the basic rules, we can derive new rules.
Example: Resolution rule.

\[
\begin{array}{c}
\neg S \\ \downarrow \\ \rightarrow E
\end{array}
\]

\[
\begin{array}{c}
R \lor S \\ \neg S \\ \hline \\ R
\end{array}
\]

\[
\begin{array}{c}
R \lor S \\ R \\ \hline \\ \lor E
\end{array}
\]

\(\neg S\) and \(S\) allow us to apply \(\rightarrow E\).
Deductive System: Derived Rules

Using the basic rules, we can derive new rules.
Example: Resolution rule.

\[
\begin{align*}
\neg S & \quad S \\
\frac{\neg S}{R} & \quad \frac{R \lor S}{R} \\
\frac{S}{R} & \quad \frac{R \lor S}{R} \\
& \quad \frac{\bot}{R} \\
\end{align*}
\]

To apply \( \lor \)-E in the end, we need to derive \( R \). But that’s easy using \( \bot \)-E!
Deductive System: Derived Rules

Using the basic rules, we can derive new rules.
Example: Resolution rule.

\[ R \lor S \quad \neg S \quad \frac{\neg S \quad [S]^1}{\frac{\bot}{-E}} \]

Finally, we can apply \( \lor\text{-}E \). The derivation with open assumptions is a new rule that can be used like any other rule.
A Variation of Natural Deduction: Boxes

We have seen just one deductive system.

One variation of natural deduction is the following: A derivation is not a tree, but a sequence of numbered lines. Instead of subtrees relying on open assumptions, a subderivation relying on an assumption is enclosed in a box. You find this explained in [HR04].
Alternative Deductive System Using Sequent Notation

One can base the deductive system around the derivability judgement, i.e., reason about $\Gamma \vdash A$ where $\Gamma \equiv A_1, \ldots, A_n$ instead of individual formulae.
Sequent Rules (for $\rightarrow / \land$ Fragment)

Rules for assumptions and weakening:

- $\Gamma \vdash A$ (where $A \in \Gamma$)
- $\frac{\Gamma \vdash B}{A, \Gamma \vdash B}$ \textit{weaken}
**Sequent Rules (for $\rightarrow / \wedge$ Fragment)**

Rules for assumptions and weakening:

$$\Gamma \vdash A \quad (\text{where } A \in \Gamma) \quad \Gamma \vdash B \quad \text{weaken}$$

$$\frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \wedge B} \quad \wedge-I$$

$$\frac{\Gamma \vdash A \wedge B}{\Gamma \vdash A} \quad \wedge-EL$$

$$\frac{\Gamma \vdash A \wedge B}{\Gamma \vdash B} \quad \wedge-ER$$

$$\frac{A, \Gamma \vdash B}{\Gamma \vdash A \rightarrow B} \quad \rightarrow-I$$

$$\frac{\Gamma \vdash A \rightarrow B}{\Gamma \vdash B} \quad \rightarrow-E$$

More rules can be derived.
Example: Refinement Style with Metavariables

\[ \vdash A \land (B \land C) \rightarrow A \land C \rightarrow^I \]

We want to show that \( A \land (B \land C) \rightarrow A \land C \) is a tautology, i.e., that it is derivable without any assumptions.
Example: Refinement Style with Metavariabes

\[
\frac{A \land (B \land C) \vdash A \land C}{A \land (B \land C) \vdash A \land C \rightarrow A \land C \rightarrow -I \quad \land -I}
\]

The topmost connective of the formula is \(\rightarrow\), so the best rule to choose is \(\rightarrow -I\).
Example: Refinement Style with Metavariables

\[\begin{align*}
A \land (B \land C) & \vdash A \quad \land\text{-EL} \\
A \land (B \land C) & \vdash C \quad \land\text{-ER} \\
A \land (B \land C) & \vdash A \land C \quad \land\text{-I} \\
\vdash A \land (B \land C) & \rightarrow A \land C \quad \rightarrow\text{-I} 
\end{align*}\]

The topmost connective of the formula is \(\land\), so the best rule to choose is \(\land\text{-I}\).
Example: Refinement Style with Metavarniables

\[
\frac{A \land (B \land C) \vdash A \land ?X}{A \land (B \land C) \vdash A} \quad ^\land-EL
\]

\[
\frac{A \land (B \land C) \vdash C}{A \land (B \land C) \vdash A \land C} \quad ^\land-ER
\quad ^\land-I
\]

\[
\frac{A \land (B \land C) \vdash A \land C}{\vdash A \land (B \land C) \rightarrow A \land C} \quad ^\rightarrow-I
\]

Things are becoming less obvious. To know that \(^\land-EL\) is the best rule for the r.h.s., you need to inspect the assumption \(A \land (B \land C)\).
Example: Refinement Style with Metavarsiables

\[
A \land (B \land C) \vdash A \land ?X
\]

\[
\begin{align*}
\uparrow-EL & \quad A \land (B \land C) \vdash A \\
& \quad \frac{A \land (B \land C) \vdash A \land (B \land C) \vdash C}{A \land (B \land C) \vdash C} \uparrow-ER
\end{align*}
\]

\[
\begin{align*}
& \quad \frac{A \land (B \land C) \vdash A \land (B \land C) \vdash A \land C}{A \land (B \land C) \vdash A \land C} \uparrow-I
\end{align*}
\]

Now it’s becoming even more difficult. To know that \(\land-ER\) is the best rule for the l.h.s., you need to look deep into the assumption \(A \land (B \land C)\).
Example: Refinement Style with Metavariabes

\[
\begin{align*}
A \land (B \land C) & \vdash A \land ?X & ^\land\text{-}EL \\
& \vdash A \land (B \land C) & ^\land\text{-}I \\
& \vdash A \land (B \land C) & \rightarrow A \land C & ^\rightarrow\text{-}I \\
& \vdash A \land (B \land C) & \rightarrow A \land C & ^\rightarrow\text{-}I \\
& \vdash ?Z \land (?Y \land C) & \vdash ?Z \land (Y \land C) & ^\land\text{-}ER \\
& \vdash A \land (B \land C) & \vdash A \land C & ^\land\text{-}ER \\
& \vdash A \land (B \land C) & \vdash A \land (B \land C) & ^\land\text{-}ER
\end{align*}
\]

Again you need to look at both sides of the $\vdash$ to decide what to do.
Example: Refinement Style with Metavarsiables

\[
\begin{align*}
A \land (B \land C) & \vdash A \land ?X \\
\frac{A \land (B \land C) \vdash A}{A \land (B \land C) \vdash A \land (B \land C)} & \qquad \text{-EL}
\end{align*}
\]

\[
\begin{align*}
A \land (B \land C) & \vdash ?Z \land (?Y \land C) \\
\frac{A \land (B \land C) \vdash ?Z \land (?Y \land C)}{A \land (B \land C) \vdash ?Y \land C} & \qquad \text{-ER}
\end{align*}
\]

\[
\begin{align*}
A \land (B \land C) & \vdash C \\
\frac{A \land (B \land C) \vdash C}{A \land (B \land C) \vdash A \land C} & \qquad \text{-I}
\end{align*}
\]

\[
\begin{align*}
A \land (B \land C) & \vdash A \land (B \land C) \\
\frac{A \land (B \land C) \vdash A \land (B \land C)}{A \land (B \land C) \vdash A \land (B \land C) \rightarrow A \land C} & \qquad \text{-I}
\end{align*}
\]

Solution for \(?Z = A\), \(?Y = B\) and \(?X = (B \land C)\)
Comments about Refinement

This crazy way of carrying out proofs is the (standard) Isabelle-way!

- Refinement style means we work from goals to axioms
- metavariables used to delay commitments

Isabelle allows other refinements/alternatives too (see labs).
Outlook

• **Computer Supported Modeling and Reasoning** is about turning logic into a useful tool and bringing it to life.

• **We will cover:**
  - deductive aspects of logic (their proof systems)
  - metatheoretic aspects (their representation)
  - pragmatics (their use), and
  - case studies

• **This is an active, hands-on course**
  - The labs are as important as (if not more than!) the lectures
  - Individual projects are possible. Individual initiative desired!
More Detailed Explanations
What is Validity (of a Pattern of Reasoning)?

A and B are symbols whose meaning is not “hard-wired” into propositional logic. From if A then B and A it follows that B is valid because it is true regardless of what A and B “mean”, and in particular, regardless of whether A and B stand for true or false propositions.
An Invalid Pattern

From if A then B and B it follows that A is invalid because there is a counterexample: Let A be “Kim is a man” and B be “Kim is a person”.

Back to main referring slide
More Examples

1. If it is Sunday, then I don’t need to work.
   It is Sunday.
   Therefore I don’t need to work. VALID

2. It will rain or snow.
   It is too warm for snow.
   Therefore it will rain. VALID

3. The Butler is guilty or the Maid is guilty.
   The Maid is guilty or the Cook is guilty.
   Therefore either the Butler is guilty or the Cook is guilty. NOT VALID
More Detailed Explanations

More Examples (Which are Valid?)

1. If it is Sunday, then I don’t need to work.
   It is Sunday.
   Therefore I don’t need to work. VALID

2. It will rain or snow.
   It is too warm for snow.
   Therefore it will rain. VALID

3. The Butler is guilty or the Maid is guilty.
   The Maid is guilty or the Cook is guilty.
   Therefore either the Butler is guilty or the Cook is guilty. NOT VALID
Turning the Crank

By formalizing patterns of reasoning, we make it possible for such reasoning to be checked or even carried out by a computer. From known patterns of reasoning new patterns of reasoning can be constructed.
What does Formalization Mean?

At this stage, we are content with a formalization that builds on geometrical notions like “above” or “to the right of”. In other words, our formalization consists of geometrical objects like trees. We study formalization in more detail later.
Proof Systems

A proof system or deductive system is characterized by a particular set of rules plus the general principles of how rules are grafted together to trees in natural deduction. We will see this shortly, but note that natural deduction is just one style of proof systems. We call the rules in that particular set basic rules. Later we will see one can also derive rules.
Soundness and Completeness

A proof system is **sound** if only **valid** propositions can be derived in it.
A proof system is **complete** if all **valid** propositions can be derived in it.
What is a Metatheorem?

A metatheorem is a theorem about a proof system, as opposed to a theorem derived within the proof system. The statement “proof system XYZ is sound” is a metatheorem.
What is a Language?

By *language* we mean the language of formulae. We can also say that we define the (object) logic. Here “logic” is used in the narrower sense.
What is Semantics?

As we mentioned earlier, we will not say much about semantics in this lecture.

The standard semantics for propositional logic builds on the semantic domain of truth values \( \{ True, False \} \), i.e., each formula is interpreted as either \( True \) or \( False \). To interpret a formula, we need an assignment of the propositional variables. Each variable must be assigned one of the values \( True \) or \( False \). For each syntactic construct of propositional logic, it is specified how it must be interpreted as a function from truth values to truth values.

We go into more detail later.

Two formulae are equivalent if they yield the same truth value for any assignment of the propositional variables.
What does Open Mean?

For example, all assumptions in

\[
A \rightarrow (B \rightarrow C) \quad A \\
\frac{B \rightarrow C}{\rightarrow -E} \\
\frac{C}{\rightarrow -E}
\]

are open. For the moment, it suffices to know that when an assumption is made, it is initially an open assumption.
What is ⊢?

For the moment, the way to understand it is as follows: by writing $A \rightarrow (B \rightarrow C), A, B \vdash C$, we assert that $C$ can be derived in this proof system under the assumptions $A \rightarrow (B \rightarrow C), A, B$.

We will say more about the $\vdash$ notation later.
Why is this Example Abstract?

Natural deduction is not just about propositional logic! We explain here the general principles of natural deduction, not just the application to propositional logic.

In order to emphasize that applying natural deduction is a completely mechanical process, we give an example that is void of any intuition. It is important that you understand this process. Applying rules mechanically is one thing. Understanding why this process is semantically justified is another.
How to Read these Rules

The first rule reads: if at some root of a tree in the forest you have constructed so far, there is a ♦, then you are allowed to draw a line underneath that ♦ and write ♣ underneath that line.

The third rule reads: if the forest you have constructed so far contains two neighboring trees, where the left tree has root ♣ and the right tree has root ♠, then you are allowed to draw a line underneath those two roots and write ♥ underneath that line.
How to Read these Rules (2)

The last rule reads: if at some root of a tree in the forest you have constructed so far, there is a ♥, then you are allowed to draw a line underneath that ♥ and write ♦ underneath that line. Moreover you are allowed to discharge (eliminate, close) 0 or more occurrences of ♦ at the leaves of the tree.

Discharging is marked by writing [] around the discharged formula. Note that generally, the tree may contain assumptions other than ♦ at the leaves. However, these must not be discharged in this rule application. They will remain open until they might be discharged by some other rule application later.
Making Assumptions

In everyday language, “making an assumption” has a connotation of “claiming”. This is not the case here. By making an assumption, we are not claiming anything.

When interpreting a derivation tree, we must always consider the open assumptions. We must say: under the assumptions . . . , we derived . . . .

It is thus unproblematic to “make” assumptions.
Propositional Variables

In mathematics, logic and computer science, there are various notions of variable. In propositional logic, a variable stands for a proposition, i.e., a variable can be interpreted as True or False. This will be different in logics that we will learn about later.
What is a Formula?

In logic, the word “formula” has a specific meaning. **Formulæ** are a syntactic category, namely the expressions that stand for a statement. So formulas are syntactic expressions that are interpreted (on the semantic level) as *True* or *False*.

We will later learn about another syntactic category, that of **terms**.
Associativity and Precedences

To save brackets, we use standard associativity and precedences. All binary connectives are right-associative:

\[ A \circ B \circ C \equiv A \circ (B \circ C) \]

The precedences are \( \neg \) before \( \land \) before \( \lor \) before \( \rightarrow \). So for example

\[ A \rightarrow B \land \neg C \lor D \equiv A \rightarrow ((B \land (\neg C)) \lor D) \]
The Language of Propositional Logic

Strictly speaking, the definition of $L_P$ depends on $V$. A different choice of variables leads to a different language of propositional logic, and so we should not speak of the language of propositional logic, but rather of a language of propositional logic. However, for propositional logic, one usually does not care much about the names of the variables, or about the fact that their number could be insufficient to write down a certain formula of interest. We usually assume that there are countably infinitely many variables.

Later, we will be more fussy about this point.
Why Smallest Set?

The language of propositional logic is a set of formulae, defined by induction. Note the following points about the definition, which are important characteristics of any inductive definition:

• By the second item in the definition, $L_P$ is non-empty (also, one would usually have that $V$ is non-empty, since otherwise $L_P$ is not very interesting);

• $L_P$ is required to be the smallest set meeting the above conditions. Otherwise, anything (a number, a dog, the pope) could be a propositional formula.

• All conditions (or rules) defining $L_P$ have the form: if $\psi_1$ and $\ldots$ and $\psi_n$ are in $L_P$, then some formula built from $\psi_1$ and $\ldots$ and $\psi_n$ is in $L_P$. 
It is crucial that no negation is involved here. If for example, there was a rule stating: if $A$ is in $L_P$ then $A$ is not in $L_P$, then there could be no $L_P$ fulfilling such a rule.

More detail on inductive definitions can be found in an article by Aczel [Acz77].
Introduction and Elimination

It is typical that the basic rules of a proof system can be classified as introduction or elimination rules for a particular connective. This classification provides obvious names for the rules and may guide the search for proofs.

The rules for conjunction are pronounced and-introduction, and-elimination-left, and and-elimination-right.

Apart from the basic rules, we will later see that there are also derived rules.
Validity Revisited

A rule is valid if for any assignment under which the assumptions of the formula are true, the conclusion is true as well.

The notation $\mathcal{A} \models A \land B$ stands for: under the assignment $\mathcal{A}$, the formula $A \land B$ is interpreted as $True$.

This is consistent with the earlier intuitive explanation of validity of a formula. Details can be found in any textbook on logic [vD80].

Note that while the notation $\mathcal{A} \models \ldots$ will be used again later, there $\mathcal{A}$ will not stand for an assignment, but rather for a construct having an assignment as one constituent. This is because we will generalize, and in the new setting we need something more complex than just an assignment. But in spirit $\mathcal{A} \models \ldots$ will still mean the same thing.
Back to main referring slide
Schematic Rules

The letters $A$ and $B$ in the rules are not propositional variables. Instead, they can stand for arbitrary propositional formulas. One can also say that $A$ and $B$ are metavariabes, i.e., they are variables of the proof system as opposed to object variables, i.e., variables of the language that we reason about (here: propositional logic).

When a rule is applied, the metavariables of it must be replaced with actual formulae. We say that a rule is being instantiated.

We will see more about the use of metavariabes later.
Can we Prove Anything . . . ?

All three rules have a non-empty sequence of assumptions. Thus to build a tree using these rules, we must first make some assumptions. None of the rules involves discharging an assumption. We have said earlier that a proof is a derivation with no open assumptions. Consequently, the answer is no.
Object vs. Meta

In these examples, you may regard $A, B, C$ as propositional variables. On the other hand, the proofs are schematic, i.e., they go through for any formula replacing $A, B,$ and $C$. 
So you Find this Strange!

When we make the assumption $P$, we obtain a forest consisting of one tree. In this tree, $P$ is at the same time a leaf and the root. Thus the tree $P$ is a degenerate example of the schema $[A] \ldots \hat{B}$, where both $A$ and $B$ are replaced with $P$. Therefore we may apply rule $\rightarrow I$, similarly as in our abstract example.
The rule(s):

\[
[A] \\
\vdots \\
B \\
\hline
A \rightarrow B \rightarrow I
\]

A \rightarrow B \rightarrow A

The proof:

\[
[A]^1 \\
\hline
B \rightarrow A \rightarrow I \\
\hline
A \rightarrow B \rightarrow A \rightarrow I^1
\]

[Back to main referring slide]
\[(A \land (B \land C)) \rightarrow (A \land C)\]

The rules:

- \[\frac{A \land B}{A \land B} \quad \land-I\]
- \[\frac{A \land B}{A} \quad \land-EL\]
- \[\frac{A \land B}{B} \quad \land-ER\]
- \[\frac{[A]}{\vdots} \quad \land-I\]
- \[\frac{B}{A \rightarrow B} \quad \rightarrow-I\]

The proof:

\[\frac{[A \land (B \land C)]^1}{\vdots} \quad \land-EL\]
\[\frac{B \land C}{\quad \land-ER\frac{C}{\land-I\frac{A \land C}{(A \land (B \land C)) \rightarrow (A \land C) \rightarrow-1^1}}}\]

Back to main referring slide
\[(A → B → C) → (A → B) → A → C\]

The rules:

\[
\begin{align*}
[A] & \vdash B \\
B & \vdash A → B → -l \\
A → B & \vdash A → B → -E
\end{align*}
\]

\[
\begin{align*}
[(A → B → C)]^1 & \vdash [A]^3 \\
B → C & \vdash →-E \\
B & \vdash [A]^3 \\
B & \vdash →-E \\
C & \vdash →-l^3 \\
A → C & \vdash →-l^3 \\
(A → B) → A → C & \vdash →-l^2 \\
(A → B → C) → (A → B) → A → C & \vdash →-l^1
\end{align*}
\]
Falsity

The symbol $\bot$ stands for “false”.

[Back to main referring slide]
No Introduction Rule for \( \bot \)

The symbol \( \bot \) stands for “false”.

It should be intuitively clear that since the purpose of a proof system is to derive true formulae, there is no introduction rule for falsity. One may wonder: what is the role of \( \bot \) then? We will see this soon. The main role is linked to negation. We quote from [And02, p. 152]:

\[
\bot \text{ plays the role of a contradiction in indirect proofs.}
\]
Connectives

The connectives are called conjunction ($\land$), disjunction ($\lor$), implication ($\rightarrow$) and negation ($\neg$).

The connectives $\land, \lor, \rightarrow$ are binary since they connect two formulas, the connective $\neg$ is unary (most of the time, one only uses the word connective for binary connective).
Negation

“Officially”, negation does not exist in our language and proof system. Negation is only used as a shorthand, or syntactic sugar, for reasons of convenience. In paper-and-pencil proofs, we are allowed to erase any occurrence of \( \neg P \) and replace it with \( P \rightarrow \bot \), or vice versa, at any time. However, we shall see that when proofs are automated, this process must be made explicit.
Syntactic Sugar

For any formal language (programming language, logic, etc.), the term **syntactic sugar** refers to syntax that is provided for the sake of readability and brevity, but which does not affect the expressiveness of the language. It is usually a good idea to consider the language without the syntactic sugar for any theoretical considerations about the language, since it makes the language simpler and the considerations less error-prone. However, the correspondence between the syntactic sugar and the basic syntax should be stated formally.
The Rules for \( \neg \)

The rule

\[
\begin{array}{c}
\neg A \\
A \\
\hline
\bot
\end{array}
\]

is simply an instance of \( \rightarrow -E \) (since \( \neg A \) is shorthand for \( A \rightarrow \bot \)).

Likewise, the rule

\[
\begin{array}{c}
[A] \\
\vdots \\
\hline
\bot \\
\hline
\neg A
\end{array}
\]

is simply an instance of \( \rightarrow -I \). Therefore, we will not introduce these as special rules. But there is a special rule \( \neg -E \).
The Rule $\neg E$

For negation, it is common to have a rule

$$
\begin{array}{c}
\neg A \\
A
\end{array} \Rightarrow 
\begin{array}{c}
B \\
\neg E
\end{array}
$$

We have seen how this rule can be derived. The concept of deriving rules will be explained more systematically later.

This rule is also called ex falso quod libet (from the false whatever you like).
Peirce’s Law Valid?

Yes, simply check the truth table:

<table>
<thead>
<tr>
<th>$A$</th>
<th>$B$</th>
<th>$((A \rightarrow B) \rightarrow A) \rightarrow A$</th>
</tr>
</thead>
<tbody>
<tr>
<td>True</td>
<td>True</td>
<td>True</td>
</tr>
<tr>
<td>True</td>
<td>False</td>
<td>True</td>
</tr>
<tr>
<td>False</td>
<td>True</td>
<td>True</td>
</tr>
<tr>
<td>False</td>
<td>False</td>
<td>True</td>
</tr>
</tbody>
</table>
Peirce’s Law Provable?

In the proof system given so far, this is not provable. To prove that it is not provable requires an analysis of so-called normal forms of proofs. However, we do not do this here.
Intuitionistic versus Classical Logic

The proof system we have given so far is a proof system for intuitionistic logic. The main point about intuitionistic logic is that one cannot claim that every statement is either true or false, but rather, evidence must be given for every statement.

In classical reasoning, the law of the excluded middle holds. One also says that proofs in intuitionistic logic are constructive whereas proofs in classical logic are not necessarily constructive.

We quote the first sentence from [Min00]:

Intuitionistic logic is studied here as part of familiar classical logic which allows an effective interpretation and mechanical extraction of programs from proofs.

The difference between intuitionistic and classical logic has been the
topic of a fundamental discourse in the literature on logic [PM68] [Tho91, chapter 3]. Often proofs contain case distinctions, assuming that for any statement $\psi$, either $\psi$ or $\neg\psi$ holds. This reasoning is classical; it does not apply in intuitionistic logic.
Axiom of the Excluded Middle

\( A \lor \neg A \) is called \textit{axiom of the excluded middle}. 
Reductio ad absurdum

The rule

\[
\begin{array}{c}
\neg A \\
\vdots \\
\bot
\end{array}
\quad \frac{\bot}{A} \quad \text{RAA}
\]

is called reduction ad absurdum.
The classical rule in Isabelle

The rule

\[ \neg A \]
\[ \vdash \]
\[ A \]
\[ \frac{A}{A} \text{ classical} \]

corresponds to the formulation in Isabelle.
Sequent Notation

An object like $A \rightarrow (B \rightarrow C), A, B \vdash C$ is called a derivability judgement. We explained it earlier as simply asserting the fact that there exists a derivation tree with $C$ at its root and open assumptions $A \rightarrow (B \rightarrow C), A, B$.

However, it is also possible to make such judgements the central objects of the deductive system, i.e., have rules involving such objects.

The notation $\Gamma \vdash A$ is called sequent notation. However, this should not be confused with the sequent calculus (we will consider it later). The sequent calculus is based on sequents, which are syntactic entities of the form $A_1, \ldots, A_n \vdash B_1, \ldots, B_m$, where the $A_1, \ldots, A_n, B_1, \ldots, B_m$ are all formulae. You see that this definition is more general than the derivability judgements we consider here.

What we are about to present is a kind of hybrid between natural
deduction and the sequent calculus, which we might call natural deduction using a sequent notation.
Axioms vs. Rules

An axiom is a rule without premises. We call a rule with premises proper. One can write an axiom $A$ as

$$\overline{A}$$

to emphasise that it is a rule with an empty set of premises.

Note that the natural deduction rules for propositional logic contain no axioms. In the sequent style formalization, having the assumption rule (axiom) is essential for being able to prove anything, but in the natural deduction style we learned first, we can construct proofs without having any axioms.
Assumptions

The special rule for assumptions takes the role in this sequent style notation that the process of making and discharging assumptions had in natural deduction based on trees.

It is not so obvious that the two ways of writing proofs are equivalent, but we shall become familiar with this in the exercises by doing proofs on paper as well as in Isabelle.
Weakening

The rule *weaken* is

\[
\frac{\Gamma \vdash B}{A, \Gamma \vdash B}
\]

*weaken*

Intuitively, the soundness of rule *weaken* should be clear: having an additional assumption in the context cannot hurt since there is no proof rule that requires the absence of some assumption. We will see an application of that rule later.
Deriving $\land\!-E$

As an example, consider

$$
\frac{A, B, \Gamma \vdash C \quad \Gamma \vdash A \land B}{\Gamma \vdash C} \quad \land\!-E
$$

This rule can be derived as follows:

$$
\frac{A, B, \Gamma \vdash C}{A, \Gamma \vdash B \rightarrow C} \rightarrow\!-I
\quad \frac{\Gamma \vdash A \land B}{\Gamma \vdash A} \quad \land\!-EL
\quad \frac{\Gamma \vdash A \land B}{\Gamma \vdash B} \quad \land\!-ER
\quad \frac{\Gamma \vdash B \rightarrow C}{\Gamma \vdash C} \rightarrow\!-E
\quad \frac{\Gamma \vdash A \rightarrow B \rightarrow C}{\Gamma \vdash A \rightarrow B} \rightarrow\!-E
\quad \frac{\Gamma \vdash A \rightarrow B \rightarrow C}{\Gamma \vdash C} \rightarrow\!-E
$$

Back to main referring slide
Which Rule to Choose?

In general, statements about which rule to choose when building a proof are heuristics, i.e., they are not guaranteed to work. Building a proof means searching for a proof. However, there are situations where the choice is clear. E.g., when the topmost connective of a formula is $\rightarrow$, then $\rightarrow\text{-}I$ is usually the right rule to apply.

The question will be addressed more systematically later.
Goals to Axioms

As you saw in our animation, we worked from the root of the tree to the leaves.
Working on Assumptions

One aspect you might have noted in the proof is that the steps at the top, where \( \land-EL \) and \( \land-ER \) were used, required non-obvious choices, and those choices were based on the assumptions in the current derivability judgement.

In Isabelle, we will apply other rules and proof techniques that allow us to manipulate assumptions explicitly. These techniques make the process of finding a proof more deterministic.

But that is just one aspect. We will give a more theoretic account of the way Isabelle constructs proofs later.
Natural Deduction: Review
Overview

- Short review: ND Systems and proofs
- First-Order Logic
  - Overview
  - Syntax
  - Semantics
  - Deduction, some derived rules, and examples
How Are ND Proofs Built?

ND proofs build derivations under (possibly temporary) assumptions.
Natural Deduction: Review

**ND: Example for → / ∧ Fragment**

Rules:

- **∧-l**:
  \[
  \frac{A \quad B}{A \land B}
  \]

- **∧-EL**:
  \[
  \frac{A \land B}{A}
  \]

- **∧-ER**:
  \[
  \frac{A \land B}{B}
  \]

- **→-I**:
  \[
  \frac{A \land B}{A \rightarrow B}
  \]

- **→-E**:
  \[
  \frac{A \rightarrow B \quad A}{B}
  \]

Proof:

- **∧-EL**:
  \[
  \frac{[A \land B]^1}{B}
  \]

- **∧-ER**:
  \[
  \frac{[A \land B]^1}{A}
  \]

- **∧-I**:
  \[
  \frac{B \land A}{A \land B \rightarrow B \land A}
  \]

- **→-I**:
  \[
  \frac{A \land B}{B \land A}
  \]

Smaus: CSMR; WS05/06
Alternative Formalization Using Sequents

Rules (for → /∧ fragment). Here, Γ is a set of formulae.

\[ \Gamma \vdash A \quad (\text{where } A \in \Gamma) \]

\[ \frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \land B} \quad \land-I \]

\[ \frac{\Gamma \vdash A \land B}{\Gamma \vdash A} \quad \land-EL \]

\[ \frac{\Gamma \vdash A \land B}{\Gamma \vdash B} \quad \land-ER \]

\[ \frac{A, \Gamma \vdash B}{\Gamma \vdash A \rightarrow B} \quad \rightarrow-I \]

\[ \frac{\Gamma \vdash A \rightarrow B}{\Gamma \vdash B} \quad \rightarrow-E \]

Two representations equivalent. Sequent notation seems simpler in practice.
Example: Refinement Style with Metavariables

\[
\begin{align*}
A \land (B \land C) \vdash & A \land ?X \\
A \land (B \land C) \vdash & A \\
A \land (B \land C) \vdash & A \land C \\
\vdash & A \land (B \land C) \rightarrow A \land C
\end{align*}
\]

\[
\begin{align*}
A \land (B \land C) \vdash & ?Z \land (?Y \land C) \\
A \land (B \land C) \vdash & (?Y \land C) \\
A \land (B \land C) \vdash & C
\end{align*}
\]

Solution for \(?Z = A\), \(?Y = B\) and \(?X = (B \land C)\).

We went through this example in detail last lecture.
Comments about Refinement

This crazy way of carrying out proofs is the (standard) Isabelle-way!

- Refinement style means we work from goals to axioms
- Metavariables used to delay commitments

Isabelle allows other refinements/alternatives too (see labs).
More Detailed Explanations
What are ND Systems and Proofs?

ND stands for Natural Deduction. It was explained in the previous lecture.
What is Sequent Notation?

The judgement $(\Gamma \vdash \phi)$ means that we can derive $\phi$ from the assumptions in $\Gamma$ using certain rules. As, explained in the previous lecture, one can make such judgements the central objects of the deductive system.
Sequent Notation and Isabelle

In particular, the sequent style notation is more amenable to automation, and thus it is closer to what happens in Isabelle.
First-Order Logic
First-Order Logic: Overview

In propositional logic, formulae are Boolean combinations of propositions. This will remain important for modeling simple patterns of reasoning.

An atomic proposition is just a letter (variable). All one can say about it is that it is true or false. E.g. it is meaningless to say “\(A\) and \(B\) state something similar”. Also, infinity plays no role.
First-Order Logic: the Essence

In first-order logic, an atom (ic proposition) says that “things” have certain “properties”. Infinitely many “things” can be denoted, hence infinitely many atoms generated and distinguished. Comparisons of atoms become meaningful: “Tim is a boy” and “Carl is a boy” state something similar. Example reasoning: “Tim is a boy”; “boys don’t cry”; hence “Tim doesn’t cry”.

Further reading: [vD80], [Tho91, chapter 1].
Variables: Intuition

In first-order logic, we talk about “things” that have certain “properties”.

A variable in first-order logic stands for a “thing”.
Variables: Intuition

In first-order logic, we talk about “things” that have certain “properties”.

A variable in first-order logic stands for a “thing”. This is in contrast to propositional logic where variables stand for propositions.

It is common to use letters $x, y, z$ for variables.
Predicates: Intuition

A *predicate* denotes a property/relation.

\[ p(x) \equiv x \text{ is a prime number} \quad d(x, y) \equiv x \text{ is divisible by } y \]
Predicates: Intuition

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Propositional connectives are used to build statements

- \( x \) is a prime and \( y \) or \( z \) is divisible by \( x \)
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\[ p(x) \land (d(y, x) \lor d(z, x)) \]
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\[ p(x) \land (d(y, x) \lor d(z, x)) \]

- \( x \) is a man and \( y \) is a woman and \( x \) loves \( y \) but not vice versa
**Predicates: Intuition**

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\[ p(x) \land (d(y, x) \lor d(z, x)) \]

- \( x \) is a man and \( y \) is a woman and \( x \) loves \( y \) but not vice versa

\[ m(x) \land w(y) \land l(x, y) \land \lnot l(y, x) \]
Predicates: Intuition (2)

We can represent only “abstractions” of these in propositional logic, e.g., \( p \land (d_1 \lor d_2) \) could be an abstraction of \( p(x) \land (d(y, x) \lor d(z, x)) \).

Here \( p \) stands for “\( x \) is a prime” and \( d_1 \) stands for “\( y \) is divisible by \( x \)”.

But the sense in which \( p(x) \), \( d(y, x) \), \( d(z, x) \) state something similar is lost. What it means to be divisible or to be a prime cannot be expressed.
Functions: Intuition

- A constant stands for a “fixed thing” in a domain.
Functions: Intuition

- A **constant** stands for a “fixed thing” in a **domain**.
- More generally, a **function** of **arity** $n$ expresses an $n$-ary operation over some **domain**, e.g.
  
  Function **arity** expresses . . .
  
  $0$
  
  $s$
  
  $+$
Functions: Intuition

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| Function arity | expresses...
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>nullary</td>
</tr>
<tr>
<td>$s$</td>
<td>unary</td>
</tr>
<tr>
<td>$+$</td>
<td>binary</td>
</tr>
</tbody>
</table>
Functions: Intuition

• A constant stands for a “fixed thing” in a domain.

• More generally, a function of arity \( n \) expresses an \( n \)-ary operation over some domain, e.g.

  Function arity expresses . . .

  0 nullary number “0”

  \( s \) unary successor in \( \mathbb{N} \)

  + binary function plus in \( \mathbb{N} \)

Note special notations: infix, prefix, etc.
Quantifiers: Intuition

- A variable stands for “some thing” in a domain of discourse. Quantifiers $\forall, \exists$ are used to speak about all or some members of this domain.
Quantifiers: Intuition

- A variable stands for “some thing” in a domain of discourse. Quantifiers \( \forall, \exists \) are used to speak about all or some members of this domain.

- Examples: Are they satisfiable? valid?

\[
\forall x. \exists y. y \times 2 = x
\]
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true for rationals
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\[ \forall x. \exists y. y \ast 2 = x \quad \text{true for rationals} \]
\[ x < y \rightarrow \exists z. x < z \land z < y \quad \text{true for any dense order} \]
Quantifiers: Intuition

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- Examples: Are they satisfiable? valid?

  $\forall x. \exists y. y \cdot 2 = x$ true for rationals
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  $\exists x. x \neq 0$
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$$\forall x. \exists y. y \times 2 = x$$ true for rationals

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  $$\exists x. x \neq 0$$  true for domains with more than one element
  
  $$(\forall x. p(x, x)) \rightarrow p(a, a)$$
Quantifiers: Intuition

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  $(\forall x. p(x, x)) \rightarrow p(a, a)$ valid
First-Order Logic: Syntax

- Two syntactic categories: terms and formulae
- A first-order language is characterized by giving a finite collection of function symbols $\mathcal{F}$ and predicates $\mathcal{P}$ as well as a set $\mathit{Var}$ of variables.
First-Order Logic: Syntax

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- A first-order language is characterized by giving a finite collection of function symbols $\mathcal{F}$ and predicates $\mathcal{P}$ as well as a set $\text{Var}$ of variables.
- Sometimes write $f^i$ (or $p^i$) to indicate that function symbol $f$ (predicate $p$) has arity $i \in \mathbb{N}$. 
First-Order Logic: Syntax

• Two syntactic categories: terms and formulae

• A first-order language is characterized by giving a finite collection of function symbols $\mathcal{F}$ and predicates $\mathcal{P}$ as well as a set $\text{Var}$ of variables.

• Sometimes write $f^i$ (or $p^i$) to indicate that function symbol $f$ (predicate $p$) has arity $i \in \mathbb{N}$.

• One often calls the pair $\langle \mathcal{F}, \mathcal{P} \rangle$ a signature.
Terms in First-Order Logic

*Term*, the set of terms, is the smallest set where

1. $x \in \text{Term}$ if $x \in \text{Var}$, and

2. $f^n(t_1, \ldots, t_n) \in \text{Term}$ if $f^n \in \mathcal{F}$ and $t_j \in \text{Term}$, for all $1 \leq j \leq n$. 
Formulae in First-Order Logic

$Form$, the set of formulae, is the smallest set where

1. $\bot \in Form$,

2. $p^n(t_1, \ldots, t_n) \in Form$ if $p^n \in \mathcal{P}$ and $t_j \in Term$, for all $1 \leq j \leq n$,

3. $\neg \phi \in Form$ if $\phi \in Form$,

4. $(\phi \circ \psi) \in Form$ if $\phi \in Form$, $\psi \in Form$ and $\circ \in \{\land, \lor, \rightarrow\}$,

5. $Qx. \phi \in Form$ if $\phi \in Form$ and $x \in Var$ and $Q \in \{\forall, \exists\}$.

Formulae as in point 2 are called atoms.

Note quantifier scoping.
Variable Occurrences

• All occurrences of a variable in a formula are bound or free or binding.
  A variable $x$ in a formula $\phi$ is bound if $x$ occurs within a subformula of $\phi$ of the form $\exists x. \psi$ or $\forall x. \psi$.

• Example:
  
  $$(q(x) \lor \exists x. \forall y. p(f(x), z) \land q(y)) \lor \forall x. r(x, z, g(x))$$

  Which are bound?
Variable Occurrences

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Variable Occurrences

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  Which are **bound**? Which are **free**? Which are **binding**?

There will be an exercise.
A **structure** is a pair $\mathcal{A} = \langle U_\mathcal{A}, I_\mathcal{A} \rangle$ where $U_\mathcal{A}$ is an nonempty set, the **universe**, and $I_\mathcal{A}$ is a mapping where

1. $I_\mathcal{A}(f^n)$ is an $n$-ary (total) function on $U_\mathcal{A}$, for $f^n \in \mathcal{F}$,
2. $I_\mathcal{A}(p^n)$ is an $n$-ary relation on $U_\mathcal{A}$, for $p^n \in \mathcal{P}$, and
3. $I_\mathcal{A}(x)$ is an element of $U_\mathcal{A}$, for each $x \in \text{Var}$.

As shorthand, write $p^\mathcal{A}$ for $I_\mathcal{A}(p)$, etc.
The Value of Terms

Let $A$ be a structure. We define the value of a term $t$ under $A$, written $A(t)$, as

1. $A(x) = x^A$, for $x \in Var$, and
2. $A(f(t_1, \ldots, t_n)) = f^A(A(t_1), \ldots, A(t_n))$. 
The Value of Formulae

We define the (truth-)value of the formula $\phi$ under $A$, written $A(\phi)$, as

\[
A(\bot) = 0
\]

\[
A(p(t_1, \ldots, t_n)) = \begin{cases} 
1 & \text{if } (A(t_1), \ldots, A(t_n)) \in p^A \\
0 & \text{otherwise}
\end{cases}
\]

\[
A(\neg \phi) = \begin{cases} 
1 & \text{if } A(\phi) = 0 \\
0 & \text{otherwise}
\end{cases}
\]

\[
\vdots
\]
The Value of Formulae (2)

We define the (truth-)value of the formula $\phi$ under $\mathcal{A}$, written $\mathcal{A}(\phi)$, as

\[
\mathcal{A}(\forall x. \phi) = \begin{cases} 
1 & \text{if for all } u \in U_\mathcal{A}, \mathcal{A}[x/u](\phi) = 1 \\
0 & \text{otherwise}
\end{cases}
\]

\[
\mathcal{A}(\exists x. \phi) = \begin{cases} 
1 & \text{if for some } u \in U_\mathcal{A}, \mathcal{A}[x/u](\phi) = 1 \\
0 & \text{otherwise}
\end{cases}
\]
Models

• If $\mathcal{A}(\phi) = 1$, we write $\mathcal{A} \models \phi$ and say $\phi$ is true in $\mathcal{A}$ or $\mathcal{A}$ is a model of $\phi$. 
Models

- If $A(\phi) = 1$, we write $A \models \phi$ and say $\phi$ is true in $A$ or $A$ is a model of $\phi$.

- If every suitable structure is a model, we write $\models \phi$ and say $\phi$ is valid or $\phi$ is a tautology.
Models

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- If there is no model for $\phi$, then $\phi$ is contradictory.
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• If every suitable structure is a model, we write $\models \phi$ and say $\phi$ is valid or $\phi$ is a tautology.

• If there is at least one model for $\phi$, then $\phi$ is satisfiable.

• If there is no model for $\phi$, then $\phi$ is contradictory.

There is also more differentiated terminology.
An Example

\( \forall x. p(x, s(x)) \)
An Example

\( \forall x. p(x, s(x)) \)

A model:

\[
\begin{align*}
U_A &= \mathbb{N} \\
p^A &= \{(m, n) \mid m < n\} \\
s^A(x) &= x + 1
\end{align*}
\]
An Example

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A model:

\[
\begin{align*}
U_A &= \mathbb{N} \\
p^A &= \{(m, n) \mid m < n\} \\
s^A(x) &= x + 1
\end{align*}
\]

Not a model:

\[
\begin{align*}
U_A &= \{a, b, c\} \\
p^A &= \{(a, b), (a, c)\} \\
s^A &= \text{“the identity function”}
\end{align*}
\]
Towards a Deductive System

In natural language, quantifiers are often implicit: males don’t cry.
Towards a Deductive System

In natural language, quantifiers are often implicit: all males don’t cry.
Towards a Deductive System

In natural language, quantifiers are often implicit: all males don’t cry.

Some phrases in natural language proofs have the flavor of introduction rules.

Take “boys are males” and “males don’t cry” implies “boys don’t cry”: assume an arbitrary boy $x$; then $x$ is a male; hence $x$ doesn’t cry; hence “$x$ is a boy” implies “$x$ doesn’t cry” ; since $x$ was arbitrary, we can say this for all $x$.
Towards a Deductive System

In natural language, quantifiers are often *implicit*: all males don’t cry.

Some phrases in natural language proofs have the flavor of *introduction rules*.

Take “boys are males” and “males don’t cry” implies “boys don’t cry”: assume an arbitrary boy \( x \); then \( x \) is a male; hence \( x \) doesn’t cry; hence “\( x \) is a boy” implies “\( x \) doesn’t cry” (\( \rightarrow\text{-I} \)); since \( x \) was arbitrary, we can say this for all \( x \) (\( \forall\text{-I} \)). See later.
Towards a Deductive System

In natural language, quantifiers are often implicit: all males don’t cry.

Some phrases in natural language proofs have the flavor of introduction rules.

Take “boys are males” and “males don’t cry” implies “boys don’t cry”: assume an arbitrary boy \( x \); then \( x \) is a male; hence \( x \) doesn’t cry; hence “\( x \) is a boy” implies “\( x \) doesn’t cry” \((\rightarrow\text{-}I)\); since \( x \) was arbitrary, we can say this for all \( x \) \((\forall\text{-}I)\). See later.

Existential statements are proven by giving a witness.
First-Order Logic: Deductive System

First-order logic is a generalization of propositional logic. All the rules of propositional logic are “inherited”. But we must introduce rules for the quantifiers.
Universal Quantification ($\forall$): Rules

\[
\frac{P(x)}{\forall x. P(x)} \quad \forall-I^* \\
\frac{\forall x. P(x)}{P(t)} \quad \forall-E
\]

where side condition (also called: proviso or eigenvariable condition) $*$ means: $x$ must be arbitrary.
Universal Quantification (\(\forall\)): Rules

\[
\begin{align*}
P(x) & \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \]}
Universal Quantification: Side Condition

What does arbitrary mean? Consider the following “proof”

\[ x = 0 \]
Universal Quantification: Side Condition

What does arbitrary mean? Consider the following “proof”

$$\frac{x = 0}{\forall x. x = 0} \forall\neg I$$
Universal Quantification: Side Condition

What does arbitrary mean? Consider the following “proof”

\[
\begin{align*}
[x = 0]^1 \\
\frac{\forall x. x = 0}{\forall -l} \\
\frac{x = 0 \rightarrow \forall x. x = 0}{\rightarrow -l^1}
\end{align*}
\]
Universal Quantification: Side Condition

What does arbitrary mean? Consider the following “proof”

\[
\frac{[x = 0]^1}{\forall x. x = 0} \quad \forall\text{-}I
\]

\[
\frac{\forall x. x = 0}{x = 0 \rightarrow \forall x. x = 0} \quad \rightarrow\text{-}I^1
\]

\[
\frac{\forall x. (x = 0 \rightarrow \forall x. x = 0)}{\forall x.} \quad \forall\text{-}I
\]
Universal Quantification: Side Condition

What does arbitrary mean? Consider the following “proof”

\[
\begin{align*}
\text{[} x = 0 \text{]}^1 \\
\frac{\forall x. x = 0}{\forall x. x = 0} \quad \forall\text{-I} \\
x = 0 \rightarrow \forall x. x = 0 \quad \rightarrow\text{-I}^1 \\
\frac{\forall x. (x = 0 \rightarrow \forall x. x = 0)}{0 = 0 \rightarrow \forall x. x = 0} \quad \forall\text{-I} \\
\frac{0 = 0}{\forall x. x = 0} \quad \forall\text{-E}
\end{align*}
\]
Universal Quantification: Side Condition

What does arbitrary mean? Consider the following “proof”

\[
\begin{align*}
[x = 0]^1 & \\
\frac{[x = 0]^1}{\forall x. x = 0} & \text{-I} \\
\frac{\forall x. x = 0}{x = 0 \rightarrow \forall x. x = 0} & \rightarrow^-1 \\
\frac{x = 0 \rightarrow \forall x. x = 0}{\forall x. (x = 0 \rightarrow \forall x. x = 0)} & \text{-I} \\
\frac{\forall x. (x = 0 \rightarrow \forall x. x = 0)}{0 = 0 \rightarrow \forall x. x = 0} & \forall^-E \\
\frac{0 = 0 \rightarrow \forall x. x = 0}{0 = 0} & \text{refl}
\end{align*}
\]
Universal Quantification: Side Condition

What does **arbitrary** mean? Consider the following “proof”

\[
\begin{align*}
\forall x. x = 0 & \quad \text{∀-I} \\
x = 0 \rightarrow \forall x. x = 0 & \quad \rightarrow\text{-I} \\
\forall x. (x = 0 \rightarrow \forall x. x = 0) & \quad \forall\text{-I} \\
0 = 0 \rightarrow \forall x. x = 0 & \quad \forall\text{-E} \\
\forall x. x = 0 & \quad \text{refl} \\
\end{align*}
\]
Universal Quantification: Side Condition

What does arbitrary mean? Consider the following “proof”

\[
\begin{align*}
\frac{[x = 0]^1}{\forall x. x = 0} & \quad \forall-I \\
\frac{x = 0 \rightarrow \forall x. x = 0}{\forall x. x = 0 \rightarrow \forall x. x = 0} & \quad \rightarrow-I^1 \\
\frac{\forall x. (x = 0 \rightarrow \forall x. x = 0)}{0 = 0 \rightarrow \forall x. x = 0} & \quad \forall-E \\
\frac{0 = 0}{\forall x. x = 0} & \quad \text{refl} \\
\frac{\forall x. x = 0}{\forall x. x = 0} & \quad \rightarrow-E
\end{align*}
\]

Formal meaning of side condition: \( x \) not free in any open assumption on which \( P(x) \) depends. Violated!
Another Proof? (1)

Is the following a proof? Is the conclusion valid?

\[
\begin{align*}
[\forall x. \neg \forall y. x = y]^1 \\
\frac{\neg \forall y. y = y}{\lbrace \forall-E \rbrace} \\
\frac{(\forall x. \neg \forall y. x = y) \rightarrow \neg \forall y. y = y}{\rightarrow-I^1}
\end{align*}
\]
Another Proof? (1)

Is the following a proof? Is the conclusion valid?

\[
\frac{[\forall x. \neg \forall y. x = y]^1}{\neg \forall y. y = y \quad \forall-E}
\]

\[
\frac{\neg \forall y. y = y}{(\forall x. \neg \forall y. x = y) \to \neg \forall y. y = y \quad \rightarrow I^1}
\]

Conclusion is not valid.
The formula is false when $U_A$ has at least 2 elements.
Another Proof? (1)

Is the following a proof? Is the conclusion valid?

\[
\frac{[\forall x. \neg \forall y. x = y]^1}{\neg \forall y. y = y} \ \forall-E
\]

\[
\frac{(\forall x. \neg \forall y. x = y) \rightarrow \neg \forall y. y = y}{\rightarrow \neg I^1}
\]

Proof is incorrect.

Reason: Substitution must avoid capturing variables. Replacing \(x\) with \(y\) in \(\forall-E\) is illegal because \(y\) is bound in \(\neg \forall y. y = y\). This detail concerns substitution (and renaming of bound variables), not \(\forall-E\). Exercise
Another Proof? (2)

$$\forall x. A(x) \land B(x)$$
Another Proof? (2)

\[ \forall x. A(x) \land B(x) \]
\[
\begin{array}{c}
\frac{A(x) \land B(x)}{A(x) \land B(x)} \\
\forall-E
\end{array}
\]
Another Proof? (2)

\[ \forall x. A(x) \land B(x) \]
\[ \frac{\begin{array}{c} A(x) \land B(x) \\ \hline \end{array}}{A(x)} \text{ ^-EL} \]

\[ \frac{\begin{array}{c} \forall x. A(x) \land B(x) \\ \hline \end{array}}{A(x) \land B(x)} \text{ ^-E} \]

\[ \frac{\begin{array}{c} A(x) \land B(x) \\ \hline A(x) \end{array}}{\text{ ^-EL}} \]
Another Proof? (2)

\[
\forall x. A(x) \land B(x) \quad \forall-E
\]

\[
A(x) \land B(x) \quad \land-EL
\]

\[
A(x) \quad \land-EL
\]

\[
\forall x. A(x) \quad \forall-I
\]
Another Proof? (2)

\[
\begin{align*}
\forall x. A(x) \land B(x) & \quad \forall-E \\
A(x) \land B(x) & \quad \land-EL \\
A(x) & \quad \land-EL \\
\forall x. A(x) & \quad \forall-I
\end{align*}
\]

\[
\begin{align*}
\forall x. A(x) \land B(x) & \quad \forall-E \\
A(x) \land B(x) & \quad \land-ER \\
B(x) & \quad \land-ER \\
\forall x. B(x) & \quad \forall-I
\end{align*}
\]
Another Proof? (2)

\[
\begin{align*}
\forall x. A(x) \land B(x) & \quad \text{\textit{\(-E\)}} \\
A(x) \land B(x) & \quad \text{\textit{\(-EL\)}} \\
A(x) & \quad \text{\textit{\(-I\)}} \\
\forall x. A(x) & \quad \\
\exists x. A(x) \land B(x) & \quad \text{\textit{\(-E\)}} \\
A(x) \land B(x) & \quad \text{\textit{\(-EL\)}} \\
B(x) & \quad \text{\textit{\(-ER\)}} \\
\forall x. B(x) & \quad \text{\textit{\(-I\)}} \\
\exists x. A(x) \land B(x) & \quad \text{\textit{\(-I\)}} \\
\forall x. A(x) \land B(x) & \quad \text{\textit{\(-I\)}} \\
\exists x. A(x) \land B(x) & \quad \text{\textit{\(-I\)}}
\end{align*}
\]

(\exists x. A(x)) \land (\exists x. B(x))

Smaus: CSMR; WS05/06
Another Proof? (2)

\[ \forall x. A(x) \land B(x) \]

\[
\frac{\forall x. A(x) \land B(x)}{A(x) \land B(x)} \ \land\text{-}E
\]

\[
\frac{A(x)}{\forall x. A(x)} \ \land\text{-}E
\]

\[
\frac{\forall x. A(x) \land B(x)}{A(x) \land B(x)} \ \land\text{-}EL
\]

\[
\frac{A(x)}{\forall x. A(x)} \ \land\text{-}I
\]

\[
\frac{\forall x. A(x) \land B(x) \land \forall x. B(x)}{\forall x. A(x) \land \forall x. B(x)} \ \land\text{-}I
\]

\[
\frac{(\forall x. A(x)) \land (\forall x. B(x))}{(\forall x. A(x) \land B(x)) \rightarrow (\forall x. A(x)) \land (\forall x. B(x))} \rightarrow\text{-}I
\]
Another Proof? (2)

\[ \frac{\forall x. A(x) \land B(x)]^1}{A(x) \land B(x)} \quad \land\text{-}EL \]

\[ \frac{A(x)}{\forall x. A(x)} \quad \forall\text{-}I \]

\[ \frac{\forall x. A(x)}{\forall x. A(x) \land B(x)} \quad \forall\text{-}E \]

\[ \frac{B(x)}{\forall x. B(x)} \quad \forall\text{-}I \]

\[ \frac{(\forall x. A(x)) \land (\forall x. B(x))}{(\forall x. A(x) \land B(x)) \rightarrow (\forall x. A(x)) \land (\forall x. B(x))} \quad \rightarrow\text{-}I^1 \]

Yes (check side conditions of $\forall\text{-}I$).
Boys Don’t Cry

Let $\phi \equiv (\forall x. b(x) \rightarrow m(x)) \land (\forall x. m(x) \rightarrow \neg c(x))$.

\[
\begin{align*}
\frac{\phi}{\neg c(x)} &\quad \phi \\
\frac{\forall x. m(x) \rightarrow \neg c(x)}{\forall-E} &\quad \phi \\
\frac{m(x) \rightarrow \neg c(x)}{\neg-E} &\quad \phi \\
\frac{\forall x. m(x) \rightarrow \neg c(x)}{\forall-E} &\quad \phi \\
\frac{b(x) \rightarrow m(x)}{\neg-E} &\quad \phi \\
\frac{m(x)}{\neg-E} &\quad \phi \\
\frac{\neg c(x)}{\rightarrow-I^2} &\quad \phi \\
\frac{\forall x. b(x) \rightarrow \neg c(x)}{\forall-I} &\quad \phi \\
\frac{\phi \rightarrow (\forall x. b(x) \rightarrow \neg c(x))}{\rightarrow-I^1} &\quad \phi
\end{align*}
\]
Aside: \( A \leftrightarrow B \)

Define \( A \leftrightarrow B \) as \( A \rightarrow B \lor B \rightarrow A \).

The following rule can be derived (in propositional logic, actually):

\[
\begin{array}{c}
\frac{[A]}{B} \quad \frac{[B]}{A} \\
\hline
A \leftrightarrow B \quad \leftrightarrow -I
\end{array}
\]

You could do this as an exercise!
Proof?

\[
\frac{[A]^1}{\forall x. A} \quad \forall I \\
\frac{[\forall x. A]^1}{A} \quad \forall E
\]

\[
\frac{A \leftrightarrow \forall x. A}{\leftrightarrow - I^1}
\]
Proof?

\[
\frac{[A]^{1}}{\forall x. A} \quad \forall-I \\
\frac{[\forall x. A]^{1}}{A} \quad \forall-E
\]

\[
\frac{\text{A} \leftrightarrow \forall x. A}{\leftrightarrow-1^{1}}
\]

Yes, but only if \( x \) not free in \( A \).
Proof?

\[
\begin{align*}
[A]^1 & \\
\forall x. A & \quad [\forall x. A]^1 \\
\frac{}{\forall x. A} & \forall-I \\
\frac{}{A} & \forall-E \\
A \leftrightarrow \forall x. A & \quad \leftrightarrow-1
\end{align*}
\]

Yes, but only if \( x \) not free in \( A \).

Similar requirement arises in proving

\((\forall x. A \rightarrow B(x)) \leftrightarrow (A \rightarrow \forall x. B(x))\).
Side Conditions and Proof Boxes

We mentioned previously a style of writing derivations where subderivations based on temporary assumptions are enclosed in boxes.

These boxes are also handy for doing derivations in first-order logic, since one can use the very clear formulation: a variable occurs inside or outside of a box. See [HR04].
Existential Quantification

- We could define $\exists x. A$ as $\neg \forall x. \neg A$.
- Equivalence follows from our definition of semantics.

\[
A(\neg A) = \begin{cases} 
1 & \text{if } A(A) = 0 \\
0 & \text{otherwise} 
\end{cases}
\]

\[
A(\forall x. A) = \begin{cases} 
1 & \text{if for all } u \in U_A, A[x/u](A) = 1 \\
0 & \text{otherwise} 
\end{cases}
\]

\[
A(\exists x. A) = \begin{cases} 
1 & \text{if for some } u \in U_A, A[x/u](A) = 1 \\
0 & \text{otherwise} 
\end{cases}
\]

Conclude: $A(\exists x. A) = A(\neg \forall x. \neg A)$
Where do the Rules for $\exists$ Come from?

- We can use definition $\exists x. A \equiv \neg \forall x. \neg A$ and the given rules for $\forall$ to derive ND proof rules.
Where do the Rules for $\exists$ Come from?

- We can use definition $\exists x. A \equiv \neg \forall x. \neg A$ and the given rules for $\forall$ to derive ND proof rules.

- Alternatively, we can give rules as part of the deduction system and prove equivalence as a lemma, instead of by definition.

We will do the first here. The Isabelle formalisation follows the second approach.
\[ \exists x. A(x) \] as a Derived Rule

The rule:

\[ \frac{A(t)}{\exists x. A(x)} \] \( \exists \)-I

We want to have \( \exists x. A(x) \) as conclusion.
∃-I as a Derived Rule

The rule:

\[
\frac{A(t)}{\exists x. A(x)} \exists-I
\]

But by definition that’s \( \neg \forall x. \neg A(x) \).
$\exists$-I as a Derived Rule

The rule:

\[
\begin{array}{c}
A(t) \\
\hline
\exists x. A(x)
\end{array}
\]

\[
\begin{array}{c}
\forall x. \neg A(x) \\
\hline
\bot
\end{array}
\]

\[
\neg \forall x. \neg A(x)
\]

We aim for applying $\to$-I in the last step (recall $\neg$-definition).
∃-I as a Derived Rule

The rule:

\[
\begin{align*}
A(t) & \quad \Rightarrow \\
\exists x. A(x) & \quad \exists-I
\end{align*}
\]

We apply ∀-E.

\[
\begin{align*}
\forall x. \neg A(x) & \quad \Rightarrow \\
\neg A(t) & \quad \forall-E \\
\bot & \\
\neg \forall x. \neg A(x) & \quad \bot-E
\end{align*}
\]
∃-l as a Derived Rule

The rule:

\[
\frac{A(t)}{\exists x. A(x) \ \exists-I}
\]

Making assumption \( A(t) \) allows us to use \( \rightarrow-E \) (recall \( \neg- \) definition).

\[
\frac{\forall x. \neg A(x) \ \forall-E}{\neg A(t)}
\]

\[
\frac{\neg A(t) \ \rightarrow-E \ \ A(t)}{\bot}
\]

\[
\frac{\neg \forall x. \neg A(x)}{\neg \forall \ x. \neg A(x) \ \forall-E}
\]
∃-I as a Derived Rule

The rule:

\[
\frac{A(t)}{\exists x. A(x)} \text{ ∃-I}
\]

\[
\frac{[\forall x. \neg A(x)]^1}{\neg A(t)} \text{ ∀-E} \quad \frac{A(t)}{\bot} \text{ →-E}
\]

\[
\frac{\bot}{\neg \forall x. \neg A(x)} \text{ →-I}^1
\]

Finally we can apply →-I. Note that the assumption \( A(t) \) is still open.
∃-E as a Derived Rule

The rule:

\[
\begin{array}{c}
\exists x. A(x) \\
\vdots \\
A(x) \\
B
\end{array}
\]

\[\exists x. A(x) \quad B \quad \exists-E\]

We will use \(\exists x. A(x)\) as one assumption.
∃-E as a Derived Rule

The rule:

\[ \begin{array}{c}
[A(x)] \\
\vdots \\
\exists x. A(x) & B \\
B
\end{array} \]

\[ \exists-E \]

\[ \neg \forall x. \neg A(x) \]

But by definition that’s \( \neg \forall x. \neg A(x) \).
∃-E as a Derived Rule

The rule:

\[ \exists x. A(x) \quad B \]

\[ \frac{\exists x. A(x) \quad B}{\exists-E} \]

\[ \neg \forall x. \neg A(x) \]

We assume a hypothetical derivation.

\[ A(x) \quad \vdots \]

\[ B \]
\( \exists - E \) as a Derived Rule

The rule:

\[
\begin{array}{c}
\exists x. A(x) \\ [A(x)] \\
\vdots \\
B
\end{array}
\]

\[
\frac{\exists x. A(x) \quad B}{B} \quad \exists - E
\]

\[
\frac{\neg \forall x. \neg A(x)}{\neg \forall x. \neg A(x)}
\]

We make an additional assumption and apply \( \rightarrow - E \) (recall \( \neg \)-definition)
∃-E as a Derived Rule

The rule:

\[
\frac{\exists x. A(x) \quad B}{B} \quad \exists\!-E
\]

\[\vdash \neg \forall x. \neg A(x)\]

Now we can discharge the assumption \( A(x) \) made in the hypothetical derivation.
\( \exists\)-\(E \) as a Derived Rule

The rule:

\[
\frac{\exists x. A(x) \quad B}{[A(x)]^2 \quad \neg B \quad B \quad \bot \quad \neg A(x) \quad \forall x. \neg A(x) \quad \exists\neg I \quad \forall\neg I \quad \rightarrow E}
\]

\[
\frac{\exists x. A(x) \quad \exists\neg I \quad [A(x)]^2 \quad \forall\neg I}{\bot \quad \neg A(x) \quad \forall x. \neg A(x) \quad \exists\neg I \quad \forall\neg I}
\]

At this step, the side condition from \( \forall\neg I \) applies. \( \exists\)-\( E \) will inherit it!
\[\exists-E\] as a Derived Rule

The rule:

\[
\begin{array}{c}
\exists x. A(x) \\
\hline
\vdots \\
A(x) \\
\end{array}
\]

\[
\exists - E
\]

We apply \(\rightarrow E\).
We are done. Note that this proof uses classical reasoning.
Example Derivation Using $\exists$-E

Assumption: $x$ does not occur free in $B$

\[ \exists x. A(x) \]
\[ \forall x. A(x) \rightarrow B \]
\[ A(x) \rightarrow B \]
\[ \forall-E \]
\[ A(x) \]
\[ B \]
\[ \rightarrow-E \]
Example Derivation Using $\exists$-E

Assumption: $x$ does not occur free in $B$

$$\forall x. A(x) \rightarrow B$$

$$A(x) \rightarrow B$$

$$\forall$$-E [A(x)]$^3$

$$\exists x. A(x)$$

$$B$$

$$\exists$$-E$^3$

$$\rightarrow$$-E
Example Derivation Using $\exists$-E

Assumption: $x$ does not occur free in $B$

\[
\begin{align*}
[\forall x. A(x) \rightarrow B]^1 & \quad \forall-E
\frac{A(x) \rightarrow B}{A(x)}\quad [A(x)]^3 \\
[\exists x. A(x)]^2 & \quad \exists-E^3
\frac{B}{B} \quad \rightarrow-E
\frac{B}{(\exists x. A(x)) \rightarrow B} \quad \rightarrow-I^2
\frac{(\forall x. A(x) \rightarrow B) \rightarrow ((\exists x. A(x)) \rightarrow B)}{-(\forall x. A(x) \rightarrow B)} \quad \rightarrow-I^1
\end{align*}
\]
Conclusion on FOL

- Propositional logic is good for modeling simple patterns of reasoning like “if . . . then . . . else”.

Smaus: CSMR; WS05/06
Conclusion on FOL

- Propositional logic is good for modeling simple patterns of reasoning like “if . . . then . . . else”.
- In first-order logic, one has “things” and relations on / properties of “things”. Quantify over “things”. Powerful!
- Some people advocate intuitionistic, relevant, and other “deviant” logics.
- Limitation: cannot quantify over predicates.
- “A” world or “the” world is modeled in first-order logic using so-called first-order theories. This will be studied next lecture.
More Detailed Explanations
Boolean Functions

The set (or “type”) \( bool \) contains the two truth values \( True, False \). A propositional formula containing \( n \) variables can be viewed as a function \( bool^n \rightarrow bool \). For each combination of values \( True, False \) for the variables, the whole formula assumes the value \( True \) or \( False \).
Relations/Functions, Infinity

In propositional logic, there is no notation for writing “thing \( x \) has property \( p \)” or “things \( x \) and \( y \) are related as follows” or for denoting the “thing obtained from thing \( x \) by applying some operation”.

In particular, no statement about all elements of a possibly infinite domain can be expressed in propositional logic, since each formula involves only finitely many different variables, and up to equivalence and for a set containing \( n \) variables, there are only finitely many (to be precise \( 2^{(2^n)} \)) different propositional formulae.
What is a Domain?

For example, the set of integers, the set of characters, the set of people, you name it!

Any set of “things” that we want to reason about.
“Fixed Thing”? 
As opposed to a variable which also stands for a “thing”. This distinction will become clear soon.
Function Notation

So a function symbol $f$ denotes an operation that takes $n$ “things” and returns a “thing”. $f(t_1, \ldots, t_n)$ is a “thing” that depends on “things” $t_1, \ldots, t_n$.

The generic notation for function application is like this: $f(t_1, \ldots, t_n)$, but the brackets are omitted for nullary functions (≡ constants), and many common function symbols like + are denoted infix, so we write $0 + 0$ instead of $+(0, 0)$. Another common notation is prefix notation without brackets, as in $-2$. There are also other notations.
“Some Thing”? 

Just like a constant, a variable stands for a “thing”.

The most important difference between a constant and a variable is that one can quantify over a variable, so one can make statements such as “for all $x$ . . .” or “there exists $x$ such that . . .”.

Back to main referring slide
What is Satisfiability? Validity?

Intuitively, **satisfiable** means “can be made true” and **valid** means “always true”.

More formally, this will be defined **later**.
Syntactic Categories

We have already learned about the syntactic category of formulae last lecture.

A term is an expression that stands for a “thing”.

Intuitively, this is what first-order logic is about: We have terms that stand for “things” and formulae that stand for statements/propositions about those “things”.

But couldn’t a statement also be a “thing”? And couldn’t a “thing” depend on a statement?

In first-order logic: no!
Signatures

There isn’t simply the language of first-order logic! Rather, the definition of a first-order language is parametrised by giving a $\mathcal{F}$ and a $\mathcal{P}$. Each symbol in $\mathcal{F}$ and $\mathcal{P}$ must have an associated arity, i.e., the number of arguments the function or predicate takes. This could be formalised by saying that the elements of $\mathcal{F}$ are pairs of the form $f/n$, where $f$ is the symbol itself and $n$, and likewise for $\mathcal{P}$. All that matters is that it is specified in some unambiguous way what the arity of each symbols is.

One often calls the pair $\langle \mathcal{F}, \mathcal{P} \rangle$ a signature. Generally, a signature specifies the “fixed symbols” (as opposed to variables) of a particular logic language.

Strictly speaking, a first-order language is also parametrised by giving a set of variables $\text{Var}$, but this is inessential. $\text{Var}$ is usually assumed to be a countably infinite set of symbols, and the particular choice of names of
these symbols is not relevant.
A Language

*Term* and *Form* together make up a first-order language. Note that strictly speaking, *Term* and *Form* depend on the *signature*, but we always assume that the signature is clear from the context.
The Scope of a Quantifier

We adopt the convention that the scope of a quantifier extends as much as possible to the right, e.g.

$$\forall x. p(x) \lor q(x)$$

is

$$\forall x. (p(x) \lor q(x))$$

and not

$$(\forall x. p(x)) \lor q(x)$$

This is a matter of dispute and other conventions are around, but the one we adopt here corresponds to Isabelle.

Compare this to the precedences and associativity in propositional logic.
Free, Bound, and Binding Occurrences

All occurrences of a variable in a term or formula are bound or free or binding. These notions are defined by induction on the structure of terms/formulae. This is why the following definition is along the lines of our definition of terms and formulae.

1. The (only) occurrence of \( x \) in the term \( x \) is a free occurrence of \( x \) in \( x \);
2. the free occurrences of \( x \) in \( f(t_1, \ldots, t_n) \) are the free occurrences of \( x \) in \( t_1, \ldots, t_n \);
3. there are no free occurrences of \( x \) in \( \bot \);
4. the free occurrences of \( x \) in \( p(t_1, \ldots, t_n) \) are the free occurrences of \( x \) in \( t_1, \ldots, t_n \);
5. the free occurrences of \( x \) in \( \neg \phi \) are the free occurrences of \( x \) in \( \phi \);
6. the free occurrences of \( x \) in \( \psi \circ \phi \) are the free occurrences of \( x \) in \( \psi \).
and the free occurrences of $x$ in $\phi$ ($\circ \in \{\land, \lor, \to\}$);

7. the free occurrences of $x$ in $\forall y. \psi$, where $y \neq x$, are the free occurrences of $x$ in $\psi$; likewise for $\exists$;

8. $x$ has no free occurrences in $\forall x. \psi$; in $\forall x. \psi$, the (outermost) $\forall$ binds all free occurrences of $x$ in $\psi$; the occurrence of $x$ next to $\forall$ is a binding occurrence of $x$; likewise for $\exists$.

A variable occurrence is **bound** if it is not free and not binding.

We also define

$$FV(\phi) := \{x \mid x \text{ has a free occurrence in } \phi\}$$
Structures

As usual, there isn’t just one way of formalizing things, and so we now explain some other notions that you may have heard in the context of semantics for first-order logic.

A universe is sometimes also called domain.

As you saw, a structure gives a meaning to functions, predicates, and variables.

An alternative formalization is to have three different mappings for this purpose:

1. an algebra gives a meaning to the function symbols (more precisely, an algebra is a pair consisting of a domain and a mapping giving a meaning to the function symbols);

2. in addition, an interpretation gives a meaning also to the predicate
symbols;

3. a **variable assignment**, also called **valuation**, gives a meaning to the variables.

As **before**, we assume that the **signature** is clear from the context. Strictly speaking, we should say “structure for a particular signature”. Details can be found in any textbook on logic [vD80].
Omitted Cases

The following cases have been omitted:

\[
\mathcal{A}(\phi \land \psi) = \begin{cases} 
1 & \text{if } \mathcal{A}(\phi) = 1 \text{ and } \mathcal{A}(\psi) = 1 \\
0 & \text{otherwise}
\end{cases}
\]

\[
\mathcal{A}(\phi \lor \psi) = \begin{cases} 
1 & \text{if } \mathcal{A}(\phi) = 1 \text{ or } \mathcal{A}(\psi) = 1 \\
0 & \text{otherwise}
\end{cases}
\]

\[
\mathcal{A}(\phi \rightarrow \psi) = \begin{cases} 
1 & \text{if } \mathcal{A}(\phi) = 0 \text{ or } \mathcal{A}(\psi) = 1 \\
0 & \text{otherwise}
\end{cases}
\]

These cases are the same as in propositional logic. This can also be found in any textbook on logic [vD80].
In mathematics and computer science, the word \textit{or} is almost always meant to be \textit{inclusive}. If it is meant to be \textit{exclusive} \((A \text{ or } B \text{ hold but not both})\) this is usually mentioned explicitly.
The Notation $\mathcal{A}[x/u]$

$\mathcal{A}[x/u]$ is the structure $\mathcal{A}'$ identical to $\mathcal{A}$, except that $x^{\mathcal{A}'} = u$. 
Models

If you are happy with the definition of a model just given, this is fine. But if you are confused because you remember a different definition from your previous studies of logic, then these comments may help.

As explained before, it is common to distinguish an interpretation, which gives a meaning to the symbols in the signature, from an assignment, which gives a meaning to the variables. Let us use $\mathcal{I}$ to denote an interpretation and $A$ to denote an assignment.

Recall that we wrote $\mathcal{A}(\cdot)$ for the meaning of a term or formula. In the alternative terminology, we write $\mathcal{I}(A)(\cdot)$ instead. This makes sense since in the alternative terminology, $\mathcal{I}$ and $A$ together contain the same information as $\mathcal{A}$ in the original terminology. We define:

- For a given $\mathcal{I}$, we say that $\phi$ is **satisfiable in** $\mathcal{I}$ if there exists an $A$ so that $\mathcal{I}(A)(\phi) = 1$;
• for a given \( I \), we write \( I \models \phi \) and say \( \phi \) is true in \( I \) or \( I \) is a model of \( \phi \), if for all \( A \), we have \( I(A)(\phi) = 1 \);

• we say \( \phi \) is satisfiable if there exists an \( I \) so that \( \phi \) is satisfiable in \( I \);

• we write \( \models \phi \) and say \( \phi \) is valid if for every (suitable) \( I \), we have \( I \models \phi \).

Note that satisfiable (without “for . . .”) and valid mean the same thing in both terminologies, whereas true in . . . means slightly different things, since a structure is not the same thing as an interpretation.
Suitable Structures

A structure is suitable for $\phi$ if it defines meanings for the signature of $\phi$, i.e., for the symbols that occur in $\phi$. Of course, these meanings must also respect the arities, so an $n$-ary function symbols must be interpreted as an $n$-ary function. Without explicitly mentioning it, we always assume that structures are suitable.
\[ \mathbb{N} \]

\[ \mathbb{N} \] denotes the natural numbers.
Confusion of Syntax and Semantics?

In logic, we insist on the distinction between syntax and semantics. In particular, we set up the formalism so that the syntax is fixed first and then the semantics, and so there could be different semantics for the same syntax.

But the dilemma is that once we want to give a particular semantics, we can only do so using again some kind of language, hence syntax. This is usually natural language interspersed with usual mathematical notation such as $\lt$, $+$ etc.

Some people try to mark the distinction between syntax and semantics somehow, e.g., by saying $0$ is a constant that could mean anything, whereas $0$ is the number zero as it exists in the mathematical world.

When we give semantics, the symbols $\lt$, $+$, and $1$ have their usual mathematical meanings. The function that maps $x$ to $x + 1$ is also called
successor function. Of course, when we write \( m < n \), we assume that \( m, n \in \mathbb{N} \), in this context.
Why is this a Model?

It is true that for all numbers $n$, $n$ is less than $n + 1$. 
Why is this not a Model?

The identity function maps every object to itself.

It is **not** true that for every character $\alpha \in \{a, b, c\}$, $(\alpha, \alpha) \in \{(a, b), (a, c)\}$. E.g., $(a, a) \notin \{(a, b), (a, c)\}$.

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Implicit Quantifiers

In the statement

\[ \text{if } x > 2 \text{ then } x^2 > 4 \]

the \( \forall \)-quantifier is implicit. It should be

for all \( x \), if \( x > 2 \) then \( x^2 > 4 \).
Inheriting Rules

First-order logic inherits all the rules of propositional logic. Note however that the metavariables in the rules now range over first-order formulae.
Schematic Rules

Similarly as in the previous lecture, one should note that $P$ is not a predicate, but rather $P(x)$ is a schematic expression: $P(x)$ stands for any formula, possibly containing occurrences of $x$. In the context of $\forall$-E, $P(t)$ stands for a formula where all occurrences of $x$ are replaced by $t$. 
Reflexivity

When one has a predicate symbol $=$, it is usual to have a rule that says that $=$ is reflexive.

Don’t worry about it at this stage, just take it that we have such a rule. We will look at this later.
Side Condition Violated!

The side condition is violated in the proof since in the first $\forall$-I step, $x$ does occur free in $x = 0$. 
**Why is \((\forall x. \neg \forall y. x = y) \rightarrow \neg \forall y. y = y\) False?**

Here we assume that the predicate symbol \(=\) is interpreted by \(A\) as equality on \(U_A\). Suppose \(U_A\) contains two elements \(\alpha\) and \(\beta\) and \(I_A(x) = \alpha\) and \(I_A(y) = \beta\). Then \(A(x = y) = 0\), hence \(A(\forall y. x = y) = 0\), hence \(A(\neg \forall y. x = y) = 1\). Now one can see that \(A_{[x/u]}(\neg \forall y. x = y) = 1\) for all \(u \in U_A\), and hence \(A(\forall x. \neg \forall y. x = y) = 1\). On the other hand, \(A'(y = y) = 1\) for any \(A'\) and hence \(A(\forall y. y = y) = 1\) and hence \(A(\neg \forall y. y = y) = 0\). Therefore, \(A((\forall x. \neg \forall y. x = y) \rightarrow \neg \forall y. y = y) = 0\).
Substitutions in FOL

The notation $s[x \leftarrow t]$ denotes the term obtained by substituting $t$ for $x$ in $s$. However, a substitution $[x \leftarrow t]$ replaces only the free occurrences of $x$ in the term that it is applied to. A substitution is defined as follows:

1. $x[x \leftarrow t] = t$;
2. $y[x \leftarrow t] = y$ if $y$ is a variable other than $x$;
3. $f(t_1, \ldots, t_n)[x \leftarrow t] = f(t_1[x \leftarrow t], \ldots, t_n[x \leftarrow t])$ (where $f$ is a function symbol, $n \geq 0$);
4. $p(t_1, \ldots, t_n)[x \leftarrow t] = p(t_1[x \leftarrow t], \ldots, t_n[x \leftarrow t])$ (where $p$ is a predicate symbol, possibly $\bot$);
5. $(\neg \psi)[x \leftarrow t] = \neg(\psi[x \leftarrow t])$
6. $(\psi \circ \phi)[x \leftarrow t] = (\psi[x \leftarrow t] \circ \phi[x \leftarrow t])$ (where $\circ \in \{\land, \lor, \rightarrow\}$);
7. $(Qx.\psi)[x \leftarrow t] = Qx.\psi$ (where $Q \in \{\forall, \exists\}$);
8. \((Qy.\psi)[x \leftarrow t] = Qy.(\psi[x \leftarrow t])\) (where \(Q \in \{\forall, \exists\}\)) if \(y \neq x\) and \(y \notin FV(t)\);

9. \((Qy.\psi)[x \leftarrow t] = Qz.(\psi[y \leftarrow z][x \leftarrow t])\) (where \(Q \in \{\forall, \exists\}\)) if \(y \neq x\) and \(y \in FV(t)\) where \(z\) is a variable such that \(z \notin FV(t)\) and \(z \notin FV(\psi)\).
Avoiding Capture of Variables

A substitution (replacement of a variable by a term) must not replace bound occurrences of variables, and if we replace $x$ with $t$ in an expression $\phi$, then this replacement should not turn free occurrences of variables in $t$ into bound occurrences in $\phi$. It is possible to avoid this by renaming variables.

This is part of the standard definition of a substitution. The problem is not related to $\forall$-E in particular.

The definition can be found in any textbook on logic [vD80]. We will also give a formal definition later, in a different context.
Check Side Conditions

In both cases, $x$ does not occur free in $\forall x. A(x) \land B(x)$, which is the open assumption on which $A(x)$, respectively $B(x)$, depends.
Defining ↔

By defining we mean, use $A \leftrightarrow B$ as shorthand for $A \rightarrow B \land B \rightarrow A$, in the same way as we regard negation as a shorthand.
Defining $\exists$

By **defining** we mean, use $\exists x. A$ as shorthand for $\neg \forall x. \neg A$, in the same way as we regard **negation** as a shorthand.

However, we have already introduced $\exists$ as syntactic entity, and also its semantics. If we now want to treat it as being defined in terms of $\forall$, for the purposes of building a deductive system, we must be sure that $\exists x. A$ is semantically equivalent to $\neg \forall x. \neg A$, i.e., that $A(\exists x. A) = A(\neg \forall x. \neg A)$. 
Where Do the Rules for \( \exists \) Come from?

- We can use definition \( \exists x. A \equiv \neg \forall x. \neg A \) and the given rules for \( \forall \) to derive ND proof rules.

  In this case, the soundness of the derived rules is guaranteed since
  - the rules for \( \forall \) are sound;
  - we have proven the equivalence of \( \exists x. A \) and \( \neg \forall x. \neg A \) semantically.

- Alternative: give rules as part of the deduction system and prove the equivalence as a lemma, instead of by definition.

  In this case, the soundness must be proven by hand (however, proving rules sound is an aspect we neglect in this course). But once this is done, the equivalence of \( \exists x. A \) and \( \neg \forall x. \neg A \) can be proven within the deductive system, rather than by hand, provided that the deductive system is complete.
Hypothetical Derivation

We are constructing here a “schematic fragment” of a derivation tree. Within this construction, we assume a hypothetical derivation of $B$ from assumption $A(x)$. When we are done with the construction of this fragment, we will collapse the fragment by throwing away all the nodes in the middle and only keep the root and leaves.

Note two points:

- We assume a hypothetical derivation of $B$ from assumption $A(x)$. Somewhere in the middle of the constructed fragment, we will discharge the assumption $A(x)$. In the final rule $\exists$-$E$, this means an application of $\exists$-$E$ involves discharging $A(x)$. Therefore $\exists$-$E$ has brackets around the $A(x)$.

- The hypothetical derivation of $B$ may contain other assumptions than $A(x)$. These are not discharged in the constructed fragment, and so in
the final rule $\exists$-E, we must also read the notation

$$A(x) \quad \vdash \quad B$$

as a derivation of $B$ where one of the assumptions is $A(x)$. There may be other assumptions, but these are not discharged. This is no different from previous rules involving discharging.
Inheriting a Side Condition

∃-E will inherit the side condition from ∀-I. Hence, the side condition for ∃-E is:

$x$ must not be free in $B$ or in hypotheses of the subderivation of $B$ other than $A(x)$ (occurrences in $A(x)$ are allowed because the assumption $A(x)$ was discharged before the application of ∀-I).
Classical Reasoning

Defining $\exists x. A$ as $\neg \forall x. \neg A$ is only sensible in classical reasoning, since the derivation of the rule $\exists$-$E$ requires the RAA rule.
The Power of First-Order Logic

In first-order logic, one has “things” and relations/properties that may or may not hold for these “things”. Quantifiers are used to speak about “all things” and “some things”.

For example, one can reason:

All men are mortal, Socrates is a man, therefore Socrates is mortal.

The idea underlying first-order logic is so general, abstract, and powerful that vast portions of human (mathematical) reasoning can be modeled with it.

In fact, first-order logic is the most prominent logic of all. Many people know about it: not only mathematicians and computer scientists, but also linguists, philosophers, psychologists, economists etc. are likely to learn about first-order logic in their education.
While some applications in the fields mentioned above require other logics, e.g. modal logics, those can often be reduced to first-order logic, so that first-order logic remains the point of reference.

On the other hand, logics that are strictly more expressive than first-order logic are only known to and studied by few specialists within mathematics and computer science.

This example about Socrates and men is a very well-known one. You may wonder: what is the history of this example?

In English, the example is commonly given using the word “man”, although one also finds “human”. Like many languages (e.g., French, Italian), English often uses “man” for “human being”, although this use of language may be considered discriminating against women. E.g. [Tho95a]:

*man* [. . . ] 1 an adult human male, esp. as distinct from a woman
or boy. 2 a human being; a person (*no man is perfect*).

While the example does not, strictly speaking, imply that “man” is used in the meaning of “human being”, this is strongly suggested both by the content of the example (or should women be immortal?) and the fact that languages that do have a word for “human being” (e.g. “Mensch” in German) usually give the example using this word. In fact, the example is originally in Old Greek, and there the word ἀνθρωπος (anthropos = human being), as opposed to ἄνδρος (anér = human male), is used.

The example is a so-called *syllogism of the first figure*, which the scholastics called *Barbara*. It was developed by Aristotle [Ari] in an abstract form, i.e., without using the concrete name “Socrates”. In his terminology, ἀνθρωπος is the middle term that is used as subject in the first premise and as predicate in the second premise (this is what is called *first figure*). Aristotle formulated the syllogism as follows: If A of all B
and B is said of all C, then A must be said of all C.

And why “Socrates”? It is not exactly clear how it came about that this particular syllogism is associated with Socrates. In any case, as far it is known, Socrates did not investigate any questions of logic. However, Aristotle frequently uses **Socrates** and **Kallias** as standard names for individuals [Ari]. Possibly there were statutes of Socrates and Kallias standing in the hall where Aristotle gave his lectures, so it was convenient for him to point to the statutes whenever he was making a point involving two individuals.
Other Logics

There are still controversies about what the best logic is for reasoning about “things” and properties/relations, and scope (quantification). Some argue for intuitionistic, relevance, modal and other “deviant” logics.

An example where first-order logic is inappropriate might be:

From “a dollar buys a candy bar” and “a dollar buys an ice cream” we cannot normally conclude “a dollar buys a candy bar and an ice cream”.

However, such analogies should be treated with care. Depending on how ice-creams, candy bars, dollars and buying are modeled, first-order logic may very well be appropriate.

Modal logics are logics that have modality operators, usually $\square$ and $\Diamond$. 
Sometimes these denote **temporal** aspects, e.g., $\Box \phi$ means “$\phi$ always holds”. But many other interpretations are possible, e.g., $\Box_A \phi$ could mean “$A$ knows that $\phi$ holds” [HC68].

In relevance logics, it is not true that $A \rightarrow B$ holds whenever $A$ is false. Rather, $A$ must somehow be “relevant” for $B$. 

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Limitations of First-Order Logic

The idea underlying first-order logic seems so general that it is not so apparent what its limitations could be. The limitations will become clear as we study more expressive logics.

For the moment, note the following: in first-order logic, we quantify over variables (hence, domain elements), not over predicates. The number of predicates is fixed in a particular first-order language. So for example, it is impossible to express the following:

For all unary predicates $p$, if there exists an $x$ such that $p(x)$ is true, then there exists a smallest $x$ such that $p(x)$ is true,

since we would be quantifying over $p$. 

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First-Order Logic with Equality
Overview

Last lecture: first-order logic.

This lecture:
• first-order logic with equality and first-order theories;
• set-theoretic reasoning.

We extend language and deductive system to formalize and reason about the (mathematical) world.
FOL with Equality

Equality is a logical symbol rather than a mathematical one. Speak of first-order logic with equality rather than adding equality as “just another predicate”.
Syntax and Semantics

**Syntax:** $=\,$ is a binary infix predicate.

$$t_1 = t_2 \in Form \text{ if } t_1, t_2 \in Term.$$
Syntax and Semantics

**Syntax:** $=$ is a binary infix predicate.

$$t_1 = t_2 \in \text{Form} \text{ if } t_1, t_2 \in \text{Term}.$$  

**Semantics:** recall a **structure** is a pair $\mathcal{A} = \langle U_\mathcal{A}, I_\mathcal{A} \rangle$ and $I_\mathcal{A}(t)$ is the interpretation of $t$.

$$I_\mathcal{A}(s = t) = \begin{cases} 
1 & \text{if } I_\mathcal{A}(s) = I_\mathcal{A}(t) \\
0 & \text{otherwise}
\end{cases}$$

Note the three completely different uses of “$=$” here!
Rules

• Equality is an equivalence relation

\[\begin{align*}
\text{refl} &: x = x \\
\text{sym} &: x = y \Rightarrow y = x \\
\text{trans} &: x = y, y = z \Rightarrow x = z
\end{align*}\]
Rules

- Equality is an equivalence relation

\[
\frac{x = y}{x = x \quad \text{refl}} \quad \frac{y = x}{\text{sym}} \quad \frac{x = y \quad y = z}{x = z \quad \text{trans}}
\]

- Equality is also a congruence on terms and all relations

\[
\frac{x_1 = y_1 \cdots x_n = y_n}{t(x_1, \ldots, x_n) = t(y_1, \ldots, y_n) \quad \text{cong}_1}
\]

\[
\frac{x_1 = y_1 \cdots x_n = y_n}{A(x_1, \ldots, x_n) = A(y_1, \ldots, y_n) \quad \text{cong}_2}
\]
Soundness of Rules

Equality in $I_A$ is an equivalence relation and functions/predicates/logical-operators are “truth-functional”. Adding further rules gives us an equational theory, e.g. groups.
Congruence: Alternatives

One can specialize congruence rules to replace only some term occurrences.

\[
\begin{align*}
  x_1 &= y_1 \cdots x_n &= y_n \\
  t[z_1 \leftarrow x_1, \ldots, z_n \leftarrow x_n] &= t[z_1 \leftarrow y_1, \ldots, z_n \leftarrow y_n] \quad \text{cong}_1
\end{align*}
\]

\[
\begin{align*}
  x_1 &= y_1 \cdots x_n &= y_n \\
  A[z_1 \leftarrow y_1, \ldots, z_n \leftarrow y_n] \\
  A[z_1 \leftarrow x_1, \ldots, z_n \leftarrow x_n] \quad \text{cong}_2
\end{align*}
\]

One time the \( z \)'s are replaced with \( x \)'s and one time with \( y \)'s.
Examples

How many ways are there to choose some occurrences of $x$ in $x^2 + y^2 > 12 \cdot x$?
Examples

How many ways are there to choose some occurrences of $x$ in $x^2 + y^2 > 12 \cdot x$? 4, namely:

- $A = x^2 + y^2 > 12 \cdot x$,
- $A = z^2 + y^2 > 12 \cdot x$,
- $A = x^2 + y^2 > 12 \cdot z$,
- $A = z^2 + y^2 > 12 \cdot z$. 
Examples

How many ways are there to choose some occurrences of $x$ in $x^2 + y^2 > 12 \cdot x$? 4, namely:

- $A = x^2 + y^2 > 12 \cdot x$
- $A = z^2 + y^2 > 12 \cdot x$
- $A = x^2 + y^2 > 12 \cdot z$
- $A = z^2 + y^2 > 12 \cdot z$

We show two ways:

\[
x = 3 \quad x^2 + y^2 > 12 \cdot x
\]

\[
\frac{3^2 + y^2 > 12 \cdot x}{\text{with } A = z^2 + y^2 > 12 \cdot x}
\]

\[
x = 3 \quad x^2 + y^2 > 12 \cdot x
\]

\[
\frac{x^2 + y^2 > 12 \cdot 3}{\text{with } A = x^2 + y^2 > 12 \cdot z}
\]
Isabelle Rule

The Isabelle FOL rule is simply (using a tree syntax)

\[
\frac{x = y \quad P(x)}{P(y)} \quad \text{subst}
\]

or literally

\[
\left[ a = b; P(a) \right] \implies P(b)
\]
Proving $\exists x. t = x$

\[
\frac{t = t \text{ refl}}{\exists x. t = x \text{ } \exists\text{-I}}
\]
Proving $\exists x. t = x$

$$
\begin{align*}
\text{refl} & \quad t = t \\
\therefore \exists x. t = x & \quad \exists\text{-}l
\end{align*}
$$

In the rule $\exists x. A(x)$, “$A(x)$” is metanotation. In the example, $A(x) = (t = x)$. 
Proving $\exists x. t = x$

\[
\begin{align*}
\text{refl} & \quad t = t \\
\exists x. t &= x
\end{align*}
\]

In the rule $\exists x. A(x) \text{ } \exists\text{-I}$, “$A(x)$” is metanotation. In the example, $A(x) = (t = x)$.

Notational confusion avoided by a precise metalanguage.
More Detailed Explanations
Logical vs. Non-logical Symbols

In logic languages, it is common to distinguish between logical and non-logical symbols. We explain this for first-order logic.

Recall that there isn’t just the language of first-order logic, but rather defining a particular signature gives us a first-order language. The logical symbols are those that are part of any first-order language and whose meaning is “hard-wired” into the formalism of first-order logic, like $\land$ or $\forall$. The non-logical symbols are those given by a particular signature, and whose meaning must be defined “by the user” by giving a structure.

Above we say “mathematical” instead of “non-logical” because we assume that mathematics is our domain of discourse, so that the signature contains the symbols of “mathematics”.

Now what status should the equality symbol $=$ have? We will assume that $=$ is a symbol whose meaning is hard-wired into the formalism. One
then speaks of first-order logic with equality. Alternatively, one could regard $=$ as an ordinary (binary infix) predicate. However, even if one does not give $=$ a special status, anyone reading $=$ has a certain expectation. Thus it would be very confusing to have a structure that defines $=$ as a, say, non-reflexive relation.
Three Different Uses of Equality

\[ I_A(s = t) = \begin{cases} 
1 & \text{if } I_A(s) = I_A(t) \\
0 & \text{otherwise} 
\end{cases} \]

The first \( = \) is a predicate symbol.
Three Different Uses of Equality

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The second equality is a **definitional** occurrence: The expression on the left-hand side is **defined** to be equal to the value of the right-hand side.
Three Different Uses of Equality

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    1 & \text{if } I_A(s) = I_A(t) \\
    0 & \text{otherwise}
\end{cases} \]

The first \( = \) is a predicate symbol.

The second \( = \) is a **definitional** occurrence: The expression on the left-hand side is **defined** to be equal to the value of the right-hand side.

The third \( = \) is **semantic** equality, i.e., the identity relation on the domain.
Why Rules?

Since $=$ is a logical symbol in the formalism of first-order logic with equality, there should be derivation rules for $=$ to derive which formulas $a = b$ are true.
What is an Equivalence Relation?

In general mathematical terminology, a relation $\equiv$ is an equivalence relation if the following three properties hold:

**Reflexivity:** $a \equiv a$ for all $a$;

**Symmetry:** $a \equiv b$ implies $b \equiv a$;

**Transitivity:** $a \equiv b$ and $b \equiv c$ implies $a \equiv c$.

Example: being equal modulo 6.

“$a$ is equal $b$ modulo 6” is often written $a \equiv b \mod 6$. 

[Back to main referring slide]
What is a Congruence?

In general mathematical terminology, a relation $\sim$ is a **congruence w.r.t.** (or: **on**) $f$, where $f$ has arity $n$, if $a_1 \sim b_1, \ldots, a_n \sim b_n$ implies $f(a_1, \ldots, a_n) \sim f(b_1, \ldots, b_n)$.

**Example:** being equal modulo 6 is congruent w.r.t. multiplication. $14 \equiv 8 \text{ mod } 6$ and $15 \equiv 9 \text{ mod } 6$, hence $14 \cdot 15 \equiv 8 \cdot 9 \text{ mod } 6$.

This can be defined in an analogous way for a property (relation) $P$.

**Example:** being equal modulo 6 is congruent w.r.t. divisibility by 3. $15 \equiv 9 \text{ mod } 6$ and 15 is divisible by 3, hence 9 is divisible by 3. $14 \equiv 8 \text{ mod } 6$ and 14 is not divisible by 3, hence 8 is not divisible by 3.
What Does this Notation Mean?

Why did we use letters $t$ and $A$ here?

Recall the rules for building terms and atoms.

Is $t(x_1, \ldots, x_n)$ a term, and $A(x_1, \ldots, x_n)$ an atom, obtained by one application of such a rule, i.e.: is $t$ a function symbol in $F$, applied to $x_1, \ldots, x_n$, and is $A$ a predicate symbols in $P$, applied to $x_1, \ldots, x_n$?
What Does this Notation Mean?

Why did we use letters \( t \) and \( A \) here?

Recall the rules for building terms and atoms.

Is \( t(x_1, \ldots, x_n) \) a term, and \( A(x_1, \ldots, x_n) \) and atom, obtained by one application of such a rule, i.e.: is \( t \) a function symbol in \( \mathcal{F} \), applied to \( x_1, \ldots, x_n \), and is \( A \) a predicate symbols in \( \mathcal{P} \), applied to \( x_1, \ldots, x_n \)?

In general, no! The notations \( t(x_1, \ldots, x_n) \) and \( A(x_1, \ldots, x_n) \) are metanotations. \( t(x_1, \ldots, x_n) \) stands for any term in which \( x_1, \ldots, x_n \) occur, and \( A(x_1, \ldots, x_n) \) stands for any atom in which \( x_1, \ldots, x_n \) occur.

This is why we used letters \( t \) (term) and \( A \) (atom) here instead of \( f \) (function) and \( P \) (predicate).

And in this context, the notation \( t(y_1, \ldots, y_n) \) stands for the term obtained from \( t(x_1, \ldots, x_n) \) by replacing all occurrences of \( x_1 \) with \( y_1 \) and so forth. In analogy the notation \( A(y_1, \ldots, y_n) \) is defined.
Note that in the schematic formulation of the rule, we use letters $x$ and $y$ to suggest variables, but the rule applies to arbitrary terms.

This description is not very formal, but this is not too problematic since we will be more formal once we have some useful machinery for this at hand.
Soundness of Equivalence Rules

On the semantic level, two things are equal if they are identical. Semantic equality is an equivalence relation. This semantic fact is so fundamental that we cannot explain it any further.

So one can prove that $I_A(s = s) = 1$ for all terms $s$, because $I_A(s) = I_A(s)$ for all terms, and likewise for symmetry and transitivity.
Soundness of Congruence Rules

If $t(x)$ is a term containing $x$ and $t(y)$ is the term obtained from $t(x)$ by replacing all occurrences of $x$ with $y$, and moreover $I_A(x = y) = 1$, then $I_A(x) = I_A(y)$. One can show by induction on the structure of $t$ that $I_A(t(x)) = I_A(t(y))$.

So by “truth-functional” we mean that the value $I_A(t(x))$ depends on $I_A(x)$, not on $x$ itself.

This can be generalized to $n$ variables as in the rule.

An analogous proof can be done for rule $cong_2$. 
Replacing Some Occurrences

The notation $t[z_1 ← x_1, \ldots, z_n ← x_n]$ stands for the term obtained from $t$ by simultaneously replacing each $z_i$ $(i ∈ \{1, \ldots, n\})$ with $x_i$.

$[z_1 ← x_1, \ldots, z_n ← x_n]$ is called a substitution.

To have an unambiguous notation for “replacing some occurrences of $x_1, \ldots, x_n$”, we start from a term $t$ containing variable occurrences $z_1, \ldots, z_n$. On the LHS, these are replaced with $x_1, \ldots, x_n$, on the RHS they are replaced with $y_1, \ldots, y_n$. So on the RHS we have a term obtained from the one on the LHS by replacing some occurrences of $x_1, \ldots, x_n$ with $y_1, \ldots, y_n$.

One can say that the $z_1, \ldots, z_n$ are introduced to mark the occurrences of $x_1, \ldots, x_n$ that should be replaced by $y_1, \ldots, y_n$.

Note that in the schematic formulation of the rule, we use letters $x$ and $y$ to suggest variables, but the rule applies to arbitrary terms. The $z$’s
however are variables (substitutions replace variables, not arbitrary terms).
Example: $x^2 + y^2 > 12 \cdot x$

The atom $x^2 + y^2 > 12 \cdot x$ contains two occurrences of $x$. There are four ways to choose some occurrences of $x$ in $x^2 + y^2 > 12 \cdot x$. Each of those ways corresponds to an atom obtained from $x^2 + y^2 > 12 \cdot x$ by replacing some occurrences of $x$ with $z$. That is, there are four different $A$’s such that $A[x/z] = x^2 + y^2 > 12 \cdot x$. Now the atom above the line in the examples is obtained by substituting $x$ for $z$, and the atom below the line is obtained by substituting $y$ for $z$. 
Isabelle Rule

The Isabelle FOL rule is:

\[
\frac{x = y \quad P(x)}{P(y)} \quad \text{subst}
\]

In this rule, \( P \) is an Isabelle metavariable.

Why doesn’t the Isabelle rule contain a \( z \) to mark which occurrences should be replaced?

We cannot understand this yet, but think of \( P \) as a formula where some positions are marked in such a way that once we apply \( P \) to \( t \) (we write \( P(t) \)), \( t \) will be inserted into all those positions. This is why \( P(x) \) is a formula and \( P(y) \) is a formula obtained by replacing some occurrences of \( x \) with \( y \).
First-Order Theories
What Is a Theory?

Recall our intuitive explanation of theories. A theory involves certain function and/or predicate symbols for which certain “laws” hold. Depending on the context, these symbols may co-exist with other symbols. Technically, the laws are added as rules (in particular, axioms) to the proof system. A structure in which these rules are true is then called a model of the theory.
Example 1: Partial Orders

- The language of the theory of partial orders: $\leq$
Example 1: Partial Orders

• The language of the theory of partial orders: \( \leq \)

• Axioms

\[
\begin{align*}
\forall x, y, z. & \, x \leq y \land y \leq z \rightarrow x \leq z \\
\forall x, y. & \, x \leq y \land y \leq x \leftrightarrow x = y
\end{align*}
\]
Example 1: Partial Orders

- The language of the theory of partial orders: $\leq$

- Axioms

  \[
  \forall x, y, z. x \leq y \land y \leq z \rightarrow x \leq z
  \]

  \[
  \forall x, y. x \leq y \land y \leq x \leftrightarrow x = y
  \]

- Alternative to axioms is to use rules

  \[
  \frac{x \leq y \quad y \leq z}{\text{trans} \quad x \leq z}
  \]

  \[
  \frac{x \leq y \quad y \leq x}{\text{antisym} \quad x = y}
  \]

  \[
  \frac{x = y}{\text{\leq-refl} \quad x \leq y}
  \]

Such a conversion is possible since implication is the main connective.
A Second Transitivity Rule

One may also consider adding the rule

\[
x = y \\
y \leq x \leq \text{refl2}
\]

to the system. This rule can be derived as follows:

\[
x = y \\
y = x \text{sym} \\
y \leq x \leq \text{refl}
\]
More on Orders

• A partial order $\leq$ is a linear or total order when

$$\forall x, y. x \leq y \lor y \leq x$$

Note: no “pure” rule formulation of this disjunction.
More on Orders

• A partial order \( \leq \) is a linear or total order when

\[
\forall x, y. \ x \leq y \lor y \leq x
\]

Note: no “pure” rule formulation of this disjunction.

• A total order \( \leq \) is dense when, in addition

\[
\forall x, y. \ x < y \rightarrow \exists z. (x < z \land z < y)
\]

What does \(<\) mean?
Structures for Orders . . .

Give structures for orders that are . . .

1. not total:
Structures for Orders . . .

Give **structures** for orders that are . . .

1. not total: $\subseteq$-relation;

2. total but not dense:
Structures for Orders . . .

Give structures for orders that are . . .

1. not total: \subseteq -relation;

2. total but not dense: integers with \leq;

3. dense:
Structures for Orders . . .

Give structures for orders that are . . .

1. not total: $\subseteq$-relation;
2. total but not dense: integers with $\leq$;
3. dense: reals with $\leq$. 
Example 2: Groups

- **Language**: Function symbols \( \_ \cdot \_ \), \( \_^{-1} \), \( e \)
Example 2: Groups

- **Language:** Function symbols \(_ \cdot \_\), \(_{-1}\), \(e\)

- **A group is a model of**

\[
\forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)}
\]
\[
\forall x. x \cdot e = x \quad \text{(r-neutr)}
\]
\[
\forall x. x \cdot x^{-1} = e \quad \text{(r-inv)}
\]

It is an example of an **equational theory**.
Example 2: Groups

- **Language**: Function symbols \( \_ \cdot \_ \), \( \_^{-1} \), \( e \)

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It is an example of an **equational theory**.

**Two theorems**: (1) \( x^{-1} \cdot x = e \) and (2) \( e \cdot x = x \)

We will now prove them.
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad \text{(1)} \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad (1) \]
\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) \]
Theorem 1

\[ \forall x, y, z. \ (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]

\[ \forall x. \ x \cdot e = x \quad \text{(r-neutr)} \]

\[ \forall x. \ x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \]

(1)

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \]  \hspace{1cm} \text{(assoc)}

\[ \forall x. x \cdot e = x \]  \hspace{1cm} \text{(r-neutr)}

\[ \forall x. x \cdot x^{-1} = e \]  \hspace{1cm} \text{(r-inv)}

\[ x^{-1} \cdot x = e \]  \hspace{1cm} (1)

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1^{-1}})) \]
**Theorem 1**

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]

\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]

\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad (1) \]

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1-1})) \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad \text{(1)} \]

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1-1})) = \]
\[ x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1-1}) \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad \text{(1)} \]
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\[ x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1-1}) \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]

\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]

\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[
x^{-1} \cdot x = e \\
x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1}^{-1})) = x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1}^{-1}) = x^{-1} \cdot (e \cdot x^{-1}^{-1})
\]
Example 2: Groups

**Theorem 1**

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[
x^{-1} \cdot x = e \quad \text{(1)}
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\[
x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1-1})) =
\]
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x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1-1}) = x^{-1} \cdot (e \cdot x^{-1-1})
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Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \]  
(1)

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1-1})) = \]
\[ x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1-1}) = x^{-1} \cdot (e \cdot x^{-1-1}) = \]
\[ (x^{-1} \cdot e) \cdot x^{-1-1} \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad \text{(1)} \]

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1-1})) = \]
\[ x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1-1}) = x^{-1} \cdot (e \cdot x^{-1-1}) = \]
\[ (x^{-1} \cdot e) \cdot x^{-1-1} \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad (\text{assoc}) \]
\[ \forall x. x \cdot e = x \quad (\text{r-neutr}) \]
\[ \forall x. x \cdot x^{-1} = e \quad (\text{r-inv}) \]

\[ x^{-1} \cdot x = e \quad (1) \]

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1-1})) = \]
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Theorem 1

\[ \forall x, y, z. \ (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. \ x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. \ x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad \text{(1)} \]

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1-1})) = \]
\[ x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1-1}) = x^{-1} \cdot (e \cdot x^{-1-1}) = \]
\[ (x^{-1} \cdot e) \cdot x^{-1-1} = x^{-1} \cdot x^{-1-1} \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ x^{-1} \cdot x = e \quad (1) \]

\[ x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1})^{-1}) = \]
\[ x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1}) = x^{-1} \cdot (e \cdot x^{-1}) = \]
\[ (x^{-1} \cdot e) \cdot x^{-1} = x^{-1} \cdot x^{-1} = e \]
Theorem 1

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \]  \hspace{1em} (assoc)

\[ \forall x. x \cdot e = x \]  \hspace{1em} (r-neutr)

\[ \forall x. x \cdot x^{-1} = e \]  \hspace{1em} (r-inv)

\[
x^{-1} \cdot x = e \tag{1}
\]

\[
x^{-1} \cdot x = x^{-1} \cdot (x \cdot e) = x^{-1} \cdot (x \cdot (x^{-1} \cdot x^{-1}-1)) =
\]

\[
x^{-1} \cdot ((x \cdot x^{-1}) \cdot x^{-1}-1) = x^{-1} \cdot (e \cdot x^{-1}-1) =
\]

\[
(x^{-1} \cdot e) \cdot x^{-1}-1 = x^{-1} \cdot x^{-1}-1 = e.
\]
Theorem 2

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \] (assoc)

\[ \forall x. x \cdot e = x \] (r-neutr)

\[ \forall x. x \cdot x^{-1} = e \] (r-inv)

\[ e \cdot x = x \] (2)

\[ e \cdot x \]
Theorem 2

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \tag{assoc} \]
\[ \forall x. x \cdot e = x \tag{r-neutr} \]
\[ \forall x. x \cdot x^{-1} = e \tag{r-inv} \]

\[ e \cdot x = x \tag{2} \]
\[ e \cdot x = (x \cdot x^{-1}) \cdot x \]
Theorem 2

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ e \cdot x = x \quad \text{(2)} \]
\[ e \cdot x = (x \cdot x^{-1}) \cdot x \]
Example 2: Groups

Theorem 2

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]
\[ \forall x. x \cdot e = x \quad \text{(r-neutr)} \]
\[ \forall x. x \cdot x^{-1} = e \quad \text{(r-inv)} \]

\[ e \cdot x = x \]

\[ e \cdot x = (x \cdot x^{-1}) \cdot x = x \cdot (x^{-1} \cdot x) \]
Theorem 2

$$\forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)}$$

$$\forall x. x \cdot e = x \quad \text{(r-neutr)}$$

$$\forall x. x \cdot x^{-1} = e \quad \text{(r-inv)}$$

$$e \cdot x = x \quad \text{(2)}$$

$$e \cdot x = (x \cdot x^{-1}) \cdot x = x \cdot (x^{-1} \cdot x) \quad \text{(Theorem 1)}$$
Theorem 2

\[
\forall x, y, z. \ (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)}
\]

\[
\forall x. \ x \cdot e = x \quad \text{(r-neutr)}
\]

\[
\forall x. \ x \cdot x^{-1} = e \quad \text{(r-inv)}
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e \cdot x = (x \cdot x^{-1}) \cdot x = x \cdot (x^{-1} \cdot x) = x \cdot e
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Theorem 2

\[ \forall x, y, z. \ (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad \text{(assoc)} \]

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\[ \forall x. \ x \cdot x^{-1} = e \quad \text{(r-inv)} \]

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Theorem 2

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \quad (\text{assoc}) \]

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\[ e \cdot x = (x \cdot x^{-1}) \cdot x = x \cdot (x^{-1} \cdot x) = x \cdot e = x \]
Theorem 2

\[ \forall x, y, z. (x \cdot y) \cdot z = x \cdot (y \cdot z) \]  (assoc)

\[ \forall x. x \cdot e = x \]  (r-neutr)

\[ \forall x. x \cdot x^{-1} = e \]  (r-inv)

\[ e \cdot x = x \]  (2)

\[ e \cdot x = (x \cdot x^{-1}) \cdot x = x \cdot (x^{-1} \cdot x) = x \cdot e = x. \]
Lessons Learned from these Examples

Equational proofs are often tricky!

- Equalities used in different directions, “eureka” terms, etc.
- In some cases (the word problem is) decidable.
Equational versus ND Proofs

- Above proofs were of a particular, equational form.
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- Alternative is natural deduction:
  - requires explicit proofs using equality rules;
  - tedious in practice. Try it on above examples!
More Detailed Explanations
Partial Orders

A partial order is a binary relation that is reflexive, transitive, and anti-symmetric: \( a \leq b \) and \( b \leq a \) implies \( a = b \).
A Language Consisting of $\leq$?

$\leq$ is (by convention) a binary infix predicate symbol. The theory of partial orders involves only this symbol, but that does not mean that there could not be any other symbols in the context.
Antisymmetry and Reflexivity

Note that $\forall x, y. x \leq y \land y \leq x \iff x = y$ encodes both antisymmetry ($\rightarrow$) and reflexivity ($\leftarrow$). Recall that $A \iff B$ as shorthand for $A \rightarrow B \land B \rightarrow A$. 
Transitivity

The axiom $\forall x, y, z. x \leq y \land y \leq z \rightarrow x \leq z$ encodes transitivity.
Axioms vs. Rules

One can see that using →-I and →-E, one can always convert a proof using the axioms to one using the proper rules.

More generally, an axiom of the form $\forall x_1, \ldots, x_n. A_1 \land \ldots \land A_n \rightarrow B$ can be converted to a rule

$$\frac{A_1 \ldots A_n}{B}.$$

Do it in Isabelle!
Linear and Dense Orders

We define these notions according to usual mathematical terminology.

A partial order $\leq$ is a linear or total order if for all $a, b$, either $a \leq b$ or $b \leq a$.

A partial order $\leq$ is dense if for all $a, b$ where $a < b$, there exists a $c$ such that $a < b$ and $b < c$. 
“Pure” Rule Formulation

The axiom $\forall x, y. x \leq y \lor y \leq x$ cannot be phrased as a proper rule in the style of, for example, the transitivity axiom.
We use $s < t$ as shorthand for $s \leq t \land \neg s = t$.

We say that $<$ is the strict part of the partial order $\leq$. 
The ⊆-Relation

The ⊆-relation is partial but not total. As an example, consider the ⊆-relation on the set of subsets of \{1, 2\}.

\[
\begin{array}{c}
\{1, 2\} \\
\{1\} & \{2\} \\
\emptyset
\end{array}
\]

Depicting partial orders by a such a graph is quite common. Here, node \(a\) is below node \(b\) and connected by an arc if and only if \(a < b\) and there exists no \(c\) with \(a < c < b\).
In this example, we have the partial order

\[ \{(\emptyset, \emptyset), (\{1\}, \{1\}), (\{1\}, \{1\}), (\{1, 2\}, \{1, 2\}), (\emptyset, \{1\}), (\emptyset, \{1\}), (\{1\}, \{1, 2\}), (\{1\}, \{1, 2\})\} \]
Group Language

_ · _ is a binary infix function symbol (in fact, only · is the symbol, but the notation _ · _ is used to indicate the fact that the symbol stands between its arguments).

_⁻¹ is a unary function symbol written as superscript. Again, the _ is used to indicate where the argument goes.

e is a nullary function symbol (= constant).

Note that groups are very common in mathematics, and many different notations, i.e., function names and fixity (infix, prefix . . . ) are used for them.
Group

In general mathematical terminology, a group consists of three function symbols \( \cdot \), \( \cdot^{-1} \), \( e \), obeying the following laws:

**Associativity** \((a \cdot b) \cdot c = a \cdot (b \cdot c)\) for all \(a, b, c\),

**Right neutral** \(a \cdot e = a\) for all \(a\),

**Right inverse** \(a \cdot a^{-1} = e\) for all \(a\).
Equational Theory

An equational theory is a set of equations. Each equation is an axiom. Sometimes, each equation is surrounded by several ∀-quantifiers binding all the free variables in the equation, but often the equation is regarded as implicitly universally quantified.

More generally, a conditional equational theory consists of proper rules where the premises are called conditions [Höl90].

Note also that sometimes, one also considers the basic rules of equality as being part of every equational theory. Whenever one has an equational theory, one implies that the basic rules are present; whether or not one assumes that they are formally elements of the equational theory is just a technical detail.
A Model a Group?

A model of the group axioms is a structure in which the group axioms are true.

However, when we say something like, “this model is a group”, then this is a slight abuse of terminology, since there may be other function symbols around that are also interpreted by the structure.

So when we say “this model is a group”, we mean, “this model is a model of the group axioms for function symbols \( \cdot \), \( \cdot^{-1} \), and \( e \) clear from the context”.

“Eureka” terms

By “eureka” terms we mean terms that have to be guessed in order to find a proof. At least at first sight, it seems like these terms simply fall from the sky.

The Greek *heureka* is 1st person singular perfect of *heuriskō*, “to find”. It was exclaimed by Archimedes upon discovering how to test the purity of Hiero’s crown.
The Word Problem

The word problem w.r.t. an equational theory (here: the group axioms) is the problem of deciding whether two terms \( s \) and \( t \) are equal in the theory, that is to say, whether the formula \( s = t \) is true in any model of the theory.
Equational Proofs

An equational proof consists simply of a sequence of equations, written as \( t_1 = t_2 = \ldots = t_n \), where each \( t_{i+1} \) is obtained from \( t_i \) by replacing some subterm \( s \) with a term \( s' \), provided the equality \( s = s' \) holds. This style of proof can be justified by the rules given for equality, in particular the congruences. However, it looks very different from the natural deduction style.
Proof of Theorem 2 by Natural Deduction

Most steps use the congruence rule $cong_2$.

Each framed box in the derivation tree stands for a sub-tree consisting of a group axiom and possibly several applications of $\forall$-E.
Proof of Theorem 2 by Natural Deduction

\[ e \cdot x = x \]

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Proof of Theorem 2 by Natural Deduction

\[
x \cdot e = x \\
\hline
\]

\[
e \cdot x = x \cdot e \\
\hline
\]

\[
e \cdot x = x
\]

Most steps use the congruence rule \( cong_2 \).
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Proof of Theorem 2 by Natural Deduction

\[
\begin{array}{c}
\text{r-neutr} \\
\hline
x \cdot e = x & e \cdot x = x \cdot e \\
\hline
\phantom{e \cdot x = x} \\
e \cdot x = x
\end{array}
\]

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Proof of Theorem 2 by Natural Deduction

\[
\begin{align*}
\text{r-neutr} & \quad x^{-1} \cdot x = e \\
\hline
x \cdot e &= x \\
\end{align*}
\]

\[
\begin{align*}
e \cdot x &= x \cdot (x^{-1} \cdot x) \\
\hline
e \cdot x &= x \cdot e \\
\hline
e \cdot x &= x
\end{align*}
\]

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Proof of Theorem 2 by Natural Deduction

\[ \text{r-neutr} \]

\[ \begin{array}{c}
\text{Theorem 1} \\
\frac{x^{-1} \cdot x = e}{x \cdot e = x}
\end{array} \quad \frac{e \cdot x = x \cdot (x^{-1} \cdot x)}{e \cdot x = x \cdot e} \quad \frac{e \cdot x = x}{e \cdot x = x} \]

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More Detailed Explanations

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Proof of Theorem 2 by Natural Deduction

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\[
\begin{align*}
\text{r-neutr} & \quad & \text{assoc} & \quad & \text{r-inv} \\
(x \cdot x^{-1}) \cdot x &= x \cdot (x^{-1} \cdot x) & e \cdot x &= x \cdot (x^{-1} \cdot x) \\
x^{-1} \cdot x &= e & e \cdot x &= (x \cdot x^{-1}) \cdot x \\
\end{align*}
\]

Most steps use the congruence rule \textit{cong}_2.
Each framed box in the derivation tree stands for a sub-tree consisting of a group axiom and possibly several applications of \textit{\forall-E}. 

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Naïve Set Theory
Naïve Set Theory: Basics

- A set is a collection of objects where order and repetition are unimportant.

Sets are central in mathematical reasoning [Vel94]. E.g., set of prime numbers.
Naïve Set Theory: Basics

• A set is a collection of objects where order and repetition are unimportant.
  Sets are central in mathematical reasoning [Vel94]. E.g., set of prime numbers.

• In what follows we consider a simple, intuitive formalization: “naïve set theory”.
  We will be somewhat less formal than usual. Our goal is to understand standard mathematical practice.
  Later, in HOL, we will be completely formal.
Sets: Language

Assuming any first-order language with equality, we add:

- set-comprehension \( \{ x \mid P(x) \} \) and a binary membership predicate \( \in \).
Sets: Language

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- **Term/formula distinction inadequate**: need a syntactic category for sets.
Sets: Language

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- **set-comprehension** \( \{ x \mid P(x) \} \) and a binary membership predicate \( \in \).

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- **We will be more formal about syntax later** (HOL).
Sets: Language

Assuming any first-order language with equality, we add:

- **set-comprehension** \( \{ x \mid P(x) \} \) and a binary **membership predicate** \( \in \).
- **Term/formula distinction inadequate**: need a syntactic category for sets.
- We will be more formal about syntax later (HOL).
- Comprehension is a binding operator: \( x \) **bound in** \( \{ x \mid P(x) \} \).
Examples

- \( \forall x. x \in \{ y \mid y \mod 6 = 0 \} \rightarrow (x \mod 2 = 0 \land x \mod 3 = 0) \).
Examples

• \( \forall x. x \in \{ y \mid y \mod 6 = 0 \} \rightarrow (x \mod 2 = 0 \land x \mod 3 = 0) \).

• What does the following say?

\[
2 \in \{ w \mid 6 \not\in \{ x \mid x \text{ is divisible by } w \} \}
\]
Examples

- $\forall x. x \in \{y \mid y \bmod 6 = 0\} \rightarrow (x \bmod 2 = 0 \land x \bmod 3 = 0)$.

- What does the following say?

$$2 \in \{w \mid 6 \notin \{x \mid x \text{ divisible by } w\}\}$$

Answer: $6 \notin \{x \mid x \text{ divisible by } 2\}$ i.e., 6 not divisible by 2.
Proof Rules for Sets

Introduction, elimination, extensional equality

\[ P(t) \quad \frac{P(t)}{t \in \{x \mid P(x)\}} \quad \text{compr-}l \]

\[ t \in \{x \mid P(x)\} \quad \frac{t \in \{x \mid P(x)\}}{P(t)} \quad \text{compr-}E \]

\[ \forall x. x \in A \leftrightarrow x \in B \quad \frac{\forall x. x \in A \leftrightarrow x \in B}{A = B} \quad \text{=} \text{-}l \]

\[ A = B \quad \frac{A = B}{\forall x. x \in A \leftrightarrow x \in B} \quad \text{=} \text{-}E \]

The following equivalence is derivable:

\[ \forall x. P(x) \leftrightarrow x \in \{y \mid P(y)\} \]
Digression: Sorted Reasoning

• In mathematical arguments we often (implicitly) assume that variables are restricted to some universe of discourse. E.g., $x^2 < 9$ (universe either $\mathbb{R}$, $\mathbb{N}$, . . . )

• To avoid ambiguity we can include sort information in formulae:

  members $x$ of $U$ where $P(x) \equiv \{ x \in U \mid P(x) \}$

Formally

$$\{ x \in U \mid P(x) \} \equiv \{ x \mid U(x) \land P(x) \}.$$
Sorted Reasoning in an Unsorted Logic

We may introduce the additional set comprehension syntax \( \{ x \in U | P(x) \} \), but our logic is still unsorted. We have

\[
y \in \{ x \in U | P(x) \} \iff y \in \{ x | U(x) \land P(x) \} \iff U(y) \land P(y)
\]
Sorted Quantification

\[ \forall x \in U. P(x) \equiv \forall x. U(x) \rightarrow P(x) \]

\[ \exists x \in U. P(x) \equiv \exists x. U(x) \land P(x) \]
Operations on Sets

- Functions on sets

\[ A \cap B \equiv \{ x \mid x \in A \land x \in B \} \]
\[ A \cup B \equiv \{ x \mid x \in A \lor x \in B \} \]
\[ A \setminus B \equiv \{ x \mid x \in A \land x \notin B \} \]

- Predicates on sets

\[ A \subseteq B \equiv \forall x. x \in A \rightarrow x \in B \]
Examples of Operations on Sets

One often depicts sets as circles or bubbles. What are $A \cap B$, $A \cup B$, $A \setminus B$?
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Correspondence between Set-Theoretic and Logical Operators

\[
x \in A \cap B \iff x \in A \land x \in B
\]
\[
x \in A \cup B \iff x \in A \lor x \in B
\]
\[
x \in A \setminus B \iff x \in A \land x \notin B
\]

These correspondences follow from the definitions of the set-theoretic operators and \( \forall x. P(x) \iff x \in \{ y | P(y) \} \).
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These correspondences follow from the definitions of the set-theoretic operators and \( \forall x. P(x) \iff x \in \{ y | P(y) \} \).

Example: what is the logical form of \( x \in ((A \cap B) \cup (A \cap C)) \)?
Correspondence between Set-Theoretic and Logical Operators

\[ x \in A \cap B \iff x \in A \land x \in B \]
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These correspondences follow from the definitions of the set-theoretic operators and \( \forall x. P(x) \iff x \in \{y | P(y)\} \).

Example: what is the logical form of
\[ x \in ((A \cap B) \cup (A \cap C)) \]?
\[ (x \in A \land x \in B) \lor (x \in A \land x \in C) \]
Proof of \( A \cap (B \cup C) = (A \cap B) \cup (A \cap C) \)
**Proof of** \( A \cap (B \cup C) = (A \cap B) \cup (A \cap C) \) \( \text{(1)} \)

Venn diagram (Is this a proof?)
Proof of \( A \cap (B \cup C) = (A \cap B) \cup (A \cap C) \) (2)

Natural deduction (natural language)
Proof of $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$ \hfill (2)

Natural deduction (natural language)

By extensionality, suffices to show

$$\forall x. x \in A \cap (B \cup C) \iff x \in (A \cap B) \cup (A \cap C).$$
Proof of $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$ \hspace{1cm} (2)

Natural deduction (natural language)

By extensionality, suffices to show

$$\forall x. x \in A \cap (B \cup C) \leftrightarrow x \in (A \cap B) \cup (A \cap C).$$

For an arbitrary $x$, this is equivalent to establishing

$$(x \in A \land (x \in B \lor x \in C)) \leftrightarrow$$

$$(x \in A \land x \in B) \lor (x \in A \land x \in C)$$
Proof of \( A \cap (B \cup C) = (A \cap B) \cup (A \cap C) \) (2)

Natural deduction (natural language)

By extensionality, suffices to show

\[
\forall x. x \in A \cap (B \cup C) \leftrightarrow x \in (A \cap B) \cup (A \cap C).
\]

For an arbitrary \( x \), this is equivalent to establishing

\[
(x \in A \wedge (x \in B \vee x \in C)) \leftrightarrow (x \in A \wedge x \in B) \vee (x \in A \wedge x \in C)
\]

But that is a propositional tautology.
Same in Isabelle

Last proof carries over to Isabelle: extensionality, rewriting, tautology checking. Do it!
Prove: for all Sets $A$ and $B$, $((A \cup B) \setminus B) \subseteq A$

Let’s try a similar semi-formal proof:
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Prove: for all Sets $A$ and $B$, $((A \cup B) \setminus B) \subseteq A$

Let’s try a similar semi-formal proof:

Let $A$ and $B$ be arbitrary sets.
Let $x$ be element of $(A \cup B) \setminus B$.
So $(x \in A \lor x \in B) \land \neg x \in B$. 
Prove: for all Sets $A$ and $B$, $((A \cup B) \setminus B) \subseteq A$

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Let $A$ and $B$ be arbitrary sets.
Let $x$ be element of $(A \cup B) \setminus B$.
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Therefore $x \in A$. 
Prove: for all Sets $A$ and $B$, $((A \cup B) \setminus B) \subseteq A$

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Therefore $x \in A$.
Therefore $x \in (A \cup B) \setminus B \rightarrow x \in A$.
Therefore $((A \cup B) \setminus B) \subseteq A$. 
Prove: for all Sets $A$ and $B$, $((A\cup B)\setminus B) \subseteq A$

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- Let $A$ and $B$ be arbitrary sets.
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- Therefore $x \in A$.
- Therefore $x \in (A\cup B)\setminus B \rightarrow x \in A$.
- Therefore $((A\cup B)\setminus B) \subseteq A$.

Combination of forward reasoning with backward reasoning. This is common in practice and usually easy to unscramble.
Extending Set Comprehensions

Recall set comprehensions \( \{ x \mid P(x) \} \).
Extending Set Comprehensions

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Now what do you think this is?

\[ \{ f(x) \mid P(x) \} \]
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\[
\{ f(x) \mid P(x) \} \equiv \{ y \mid \exists x. P(x) \land y = f(x) \}
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Example: \( t \in \{ x^2 \mid x > 5 \} \) equivalent to
Extending Set Comprehensions

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\{ f(x) \mid P(x) \} \equiv \{ y \mid \exists x. P(x) \land y = f(x) \}
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Example: \( t \in \{ x^2 \mid x > 5 \} \) equivalent to \( \exists x. x > 5 \land t = x^2 \).

True for \( t \in \{ 36, 49, \ldots \} \)
Indexing

Sometimes, it is natural to denote a function $f$ applied to an argument $x$ as "$f$ indexed by $x$", so $f_x$, rather than $f(x)$.
Indexing

Sometimes, it is natural to denote a function $f$ applied to an argument $x$ as “$f$ indexed by $x$”, so $f_x$, rather than $f(x)$. Example: let $S =$ set of students and let $m_s$ stand for “the mother of $s$”, for $s$ a student. Call $S$ an index set.

$$x \in \{m_s \mid s \in S\} \iff x \in \{y \mid \exists s. \ s \in S \land y = m_s\} \iff \exists s. \ s \in S \land x = m_s \iff \exists s \in S. \ x = m_s$$

Uses extended comprehensions, indexing syntax, and sorted quantification.
Logical Forms of the New Notation

Question: what is the logical form of $\{x_i|i \in I\} \subseteq A$?
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\[
\forall x. x \in \{ x_i | i \in I \} \rightarrow x \in A, \quad \text{i.e.,}
\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A.
\]
Logical Forms of the New Notation

Question: what is the logical form of \( \{x_i | i \in I\} \subseteq A \)?

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\forall x. x \in \{x_i | i \in I\} \rightarrow x \in A, \quad \text{i.e.,}
\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A.
\]

Intuition suggests that \( \forall i \in I. x_i \in A \) is also correct, i.e.,

\[
(\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A) \leftrightarrow (\forall i \in I. x_i \in A).
\]

Proving this would be another exercise on using extended comprehensions, indexing syntax, and sorted quantification.
Powersets

\[ \wp(A) = \{ x \mid x \subseteq A \} \].

What is the logical form of:
1. \( x \in \wp(A) \)?
Powersets

\[ \wp(A) = \{ x | x \subseteq A \} . \]

What is the logical form of:

1. \( x \in \wp(A) \)?
   \[ x \subseteq A, \text{ i.e., } \forall y. (y \in x \rightarrow y \in A) \]

2. \( \wp(A) \subseteq \wp(B) \)?
**Powersets**

\[ \mathcal{P}(A) = \{ x \mid x \subseteq A \} . \]

What is the logical form of:

1. \( x \in \mathcal{P}(A) \)?
   
   \( x \subseteq A, \text{ i.e., } \forall y. (y \in x \rightarrow y \in A) \)

2. \( \mathcal{P}(A) \subseteq \mathcal{P}(B) \)?
   
   \( \forall x. x \in \mathcal{P}(A) \rightarrow x \in \mathcal{P}(B), \text{ i.e.,} \)
Powersets

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What is the logical form of:

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   \[ x \subseteq A, \text{ i.e., } \forall y. (y \in x \rightarrow y \in A) \]

2. \( \wp(A) \subseteq \wp(B) \)?
   \[ \forall x. x \in \wp(A) \rightarrow x \in \wp(B), \text{ i.e., } \]
   \[ \forall x. x \subseteq A \rightarrow x \subseteq B, \text{ i.e., } \]
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   \( x \subseteq A, \text{ i.e., } \forall y. (y \in x \rightarrow y \in A) \)

2. \( \wp(A) \subseteq \wp(B) \)?
   
   \( \forall x. x \in \wp(A) \rightarrow x \in \wp(B), \text{ i.e., } \forall x. x \subseteq A \rightarrow x \subseteq B, \text{ i.e., } \forall x. (\forall y. y \in x \rightarrow y \in A) \rightarrow (\forall y. y \in x \rightarrow y \in B) \)

Exercise: prove that the last answer is equivalent to \( A \subseteq B \), i.e., \( \forall x. x \in A \rightarrow x \in B \).
Outlook

Sets can have other sets as elements. Implicitly assume that universe of discourse is collection of all sets.
Russell’s Paradox

Suppose $U := \{ x \mid \top \}$. Then $U \in U$.

Quite strange but no contradiction yet.
Russell’s Paradox

Suppose \( U := \{ x \mid \top \} \). Then \( U \in U \).
Quite strange but no contradiction yet.
Now split sets into two categories:
1. unusual sets like \( U \) that are elements of themselves, and
2. more typical sets that are not.
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Now split sets into two categories:

1. unusual sets like \( U \) that are elements of themselves, and
2. more typical sets that are not.

Let \( R := \{ A \mid A \notin A \} \).

Using logical form we derive: \( \forall A. (A \in R \leftrightarrow A \notin A) \)
Russell’s Paradox

Suppose \( U := \{ x \mid \top \} \). Then \( U \in U \).

Quite strange but no contradiction yet.

Now split sets into two categories:
1. unusual sets like \( U \) that are elements of themselves, and
2. more typical sets that are not.

Let \( R := \{ A \mid A \not\in A \} \).

Using logical form we derive: \( \forall A. (A \in R \leftrightarrow A \not\in A) \)

Substituting \( R \) for \( A \) (\( \forall\)-E) yields \( R \in R \leftrightarrow R \not\in R \), which is a logical contradiction. What does this tell us about sets?
Where Do We Go from here?

- The $\lambda$-calculus as basis for a metalanguage to avoid notational confusion
Where Do We Go from here?

- The λ-calculus as basis for a metalanguage to avoid notational confusion
- Resolution and other deduction techniques: understanding Isabelle better and achieving a higher level of automation
Where Do We Go from here?

- The \( \lambda \)-calculus as basis for a metalanguage to avoid notational confusion
- Resolution and other deduction techniques: understanding Isabelle better and achieving a higher level of automation
- Higher-order logic: a formalism for (among other things) non-naive set theory
More Detailed Explanations
Set Comprehension

Set comprehension is a way of defining sets. \( \{x \mid P(x)\} \) stands for the set of elements of the universe for which \( P(x) \) (some formula usually containing \( x \)) holds.
Is a Set a Term?

It is more adequate to regard a set as a term than as a formula. A set is a “thing”, not a statement about “things”.

After all, we have the predicate $\in$ expecting a set on the RHS (and even the LHS may be a set!), and predicates take terms as arguments.

However, the syntax used in set comprehensions is not legal syntax for terms, since $P(x)$ is a formula.

This is why we introduce a special syntactic category for sets.
Extensional Equality

Two things are extensionally equal if they are “equal in their effects”. Thus two sets are equal if they have the same members, regardless of what syntactic expressions are used to define those sets. Note that extensional equality may be undecidable.
Deriving Equivalence for Comprehensions

\[ [P(x)]_1 \quad \text{compr-l} \quad \frac{P(x) \rightarrow x \in \{y \mid P(y)\}}{x \in \{y \mid P(y)\}} \rightarrow I^1 \]

\[ x \in \{y \mid P(y)\} \quad \text{compr-E} \quad \frac{P(x)}{\forall x. P(x) \leftrightarrow x \in \{y \mid P(y)\}} \forall I \]

Rules \( \land I \), \( \rightarrow I \), \( \forall I \) were defined in previous lectures. The step marked with \textit{iff} is not a proof step in the technical sense. We only make the expansion of a shorthand notation explicit.
Universes

We already know what a universe or domain is. To interpret a particular language, we have a structure interpreting all function symbols as functions on the universe.

However, it is often adequate to subdivide the universe into several “sub-universes”. Those are called sorts. Note that a sort is a set.

For example, in a usual mathematical context, one may distinguish \( \mathbb{R} \) (the real numbers) and \( \mathbb{N} \) (the natural numbers) to say that \( \sqrt{x} \) requires \( x \) to be of sort \( \mathbb{R} \) and \( x! \) requires \( x \) to be of sort \( \mathbb{N} \).
Avoiding Ambiguity

We want to make explicit the sort of the variable in question. So we do not want the set of all $x$ such that $P(x)$ holds, but only the ones of the right sort, so the ones for which $x \in U$ ($U$ being the sort/universe) holds. Note there is a certain confusion here, since we write $x \in U$ in one place (so $U$ should be a set) and $U(x)$ in another (so $U$ should be a predicate. This confusion is deliberate and quite common. One can identify a set (sort) $U$ with a unary predicate $U$ such that $U(t)$ is interpreted as $True$ iff $t$ is a member of $U$.

The whole expression $\{x \in U | P(x)\}$ is a special kind of syntax. Therefore, you must look at it as a whole: it makes no sense to see any meaning just in, say, the bit $x \in U$ in this expression. It is called set
comprehension, and it is defined by

\[ \{ x \in U | P(x) \} \equiv \{ x | U(x) \land P(x) \}. \]
Sorted Logic

In sorted logic, sorts are part of the syntax. So the signature contains a fixed set of sorts. For each constant, it is specified what its sort is. For each function symbol, it is specified what the sort of each argument is, and what the sort of the result is. For each predicate symbol, it is specified what the sort of each argument is.

Terms and formulas that do not respect the sorts are not well-formed, and so they are not assigned a meaning.

In contrast, our logic is unsorted. The special syntax we provide for sorted reasoning is just syntactic sugar, i.e., we use it as shorthand and since it has an intuitive reasoning, but it has no impact on how expressive our logic is.
Sorted Quantification

So $\forall x \in U. P(x)$ is simply a shorthand or syntactic sugar for $\forall x. x \in U \rightarrow P(x)$, and analogously for $\exists x \in U. P(x)$. 

Back to main referring slide
Set Functions

∩ is called intersection.
∪ is called union.
\ is called set difference.
⊆ is called inclusion.
The Logical Form

When we transform an expression containing set operators $\cap, \cup, \backslash, \subseteq$ into an expression using $\land, \lor, \neg, \rightarrow$, we call the latter the logical form of the expression.
Is a Venn Diagram a Proof?

A Venn diagram draws sets as bubbles. Intersecting sets are drawn as overlapping bubbles, and the overlapping area is meant to depict the intersection of the sets.

A Venn diagram is not a proof in the sense defined earlier. Moreover, it would not even be acceptable as a proof according to usual mathematical practice. If it is unknown whether two sets have a non-empty intersection, how are we supposed to draw them? Trying to make a case distinctions (drawing several diagrams depending on the cases) is error-prone.

Venn diagrams are useful for illustration purposes, but they are not proofs.
Natural Language

We intersperse formal notation with natural language here in order to give an intuitive and short proof.

We can also do this more formally in Isabelle.
Explanations for each Step

Let $A$ and $B$ be arbitrary sets. \hfill (\forall \bot)$
Explanations for each Step

Let $A$ and $B$ be arbitrary sets. \[(\forall - I)\]
Let $x$ be an element of $(A \cup B) \setminus B$ (temporary assumption)
Explanations for each Step

Let $A$ and $B$ be arbitrary sets. 

Let $x$ be an element of $(A \cup B) \setminus B$ 

So $(x \in A \lor x \in B) \land \neg x \in B$ 

($\forall$-I) 
(temporary assumption) 
(equivalent proposition)
Explanations for each Step

Let $A$ and $B$ be arbitrary sets. 

Let $x$ be an element of $(A \cup B) \setminus B$ 

So $(x \in A \lor x \in B) \land \lnot x \in B$ 

Therefore $x \in A$ 

($\forall$-I) 

(temporary assumption) 

(equivalent proposition) 

($P$ follows from $(P \lor Q) \land \lnot Q$)
Explanations for each Step

Let $A$ and $B$ be arbitrary sets.

Let $x$ be an element of $(A \cup B) \setminus B$  \hspace{1cm} (\forall\text{-}I)

So $(x \in A \lor x \in B) \land \neg x \in B$  \hspace{1cm} (temporary assumption)

Therefore $x \in A$  \hspace{1cm} (equivalent proposition)

Therefore $x \in (A \cup B) \setminus B \rightarrow x \in A$  \hspace{1cm} ($P$ follows from $(P \lor Q) \land \neg Q$)

$\rightarrow\text{-}I$
More Detailed Explanations

Explanations for each Step

Let $A$ and $B$ be arbitrary sets.

Let $x$ be an element of $(A \cup B) \setminus B$

So $(x \in A \lor x \in B) \land \neg x \in B$

Therefore $x \in A$

Therefore $x \in (A \cup B) \setminus B \rightarrow x \in A$

Therefore $((A \cup B) \setminus B) \subseteq A$

($\forall$-I)

(temporary assumption)

(equivalent proposition)

($P$ follows from $(P \lor Q) \land \neg Q$)

(→-I)

(def of $\subseteq$)
Explanations for each Step

Let $A$ and $B$ be arbitrary sets.

Let $x$ be an element of $(A \cup B) \setminus B$ \hfill $(\forall$-I) \hfill (temporary assumption)

So $(x \in A \lor x \in B) \land \neg x \in B$ \hfill (equivalent proposition)

Therefore $x \in A$ \hfill $(P$ follows from $(P \lor Q) \land \neg Q)$ \hfill (→-I)

Therefore $x \in (A \cup B) \setminus B \rightarrow x \in A$ \hfill (def of $\subseteq$)

Therefore $((A \cup B) \setminus B) \subseteq A$

Concerning forward and backwards reasoning, one may look at it as follows: we first construct the derivation step at the root of the proof tree ($\forall$-I), and then we jump to a leaf (by making the temporary assumption) and work downwards from there.
Definition of $\subseteq$

\[
\{x_i \mid i \in I\} \subseteq A \equiv \forall x. x \in \{x_i \mid i \in I\} \rightarrow x \in A
\]

follows from the definition of $\subseteq$. 
Details of Logical Form

We want to show

$$\forall x. x \in \{x_i | i \in I\} \rightarrow x \in A \equiv \forall x. (\exists i \in I. x = x_i) \rightarrow x \in A$$

- $x \in \{x_i | i \in I\}$
- $x \in \{y | \exists i. i \in I \land y = x_i\}$
- $\exists i. i \in I \land x = x_i$
- $\exists i \in I. x = x_i$

(Def. of notation) compr-l (Sorted quantification)
Intuition for Indexed Sets

It may be helpful to pronounce both forms out loud in natural language to get an intuitive feeling that they are equivalent.
Proof

Want to prove

\[(\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A) \leftrightarrow (\forall i \in I. x_i \in A)\]
Proof

Want to prove

$$(\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A) \leftrightarrow (\forall i \in I. x_i \in A)$$

• “⇒”

Let $i \in I$ be arbitrary. Now from assumption (for the instance $x_i$) we have $(\exists j \in I. x_i = x_j) \rightarrow x_i \in A$. But premise is true for $i = j$, so $x_i \in A$. 

Smaus: CSMR; WS05/06
Proof

Want to prove

$$(\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A) \iff (\forall i \in I. x_i \in A)$$

● “$\rightarrow$”

Let $i \in I$ be arbitrary. Now from assumption (for the instance $x_i$) we have $(\exists j \in I. x_i = x_j) \rightarrow x_i \in A$. But premise is true for $i = j$, so $x_i \in A$.

● “$\leftarrow$”

Let $x$ be arbitrary and assume $\exists i \in I. x = x_i$. So for some $i \in I$, we have $x = x_i$. Now $\forall i \in I. x_i \in A$. Hence $x \in A$. 

Smaus: CSMR; WS05/06
“→” in more detail: Want to prove

\[(\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A) \iff (\forall i \in I. x_i \in A)\]
“→” in more detail: Want to prove

\[
(\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A) \leftrightarrow (\forall i \in I. x_i \in A)
\]

We show \( \forall i \in I. x_i \in A \) assuming \( \forall x. (\exists i \in I. x = x_i) \rightarrow x \in A \).

So we show that for arbitrary \( i \in I \), assuming \( \forall x. (\exists i \in I. x = x_i) \rightarrow x \in A \), we have \( x_i \in A \). So let \( i \in I \) be arbitrary.

Since we have \( \forall x. (\exists i \in I. x = x_i) \rightarrow x \in A \), by rule \( \forall\text{-}E \) we can specialize to \( (\exists j \in I. x_i = x_j) \rightarrow x_i \in A \). But premise \( (\exists j \in I. x_i = x_j) \) is true for \( i = j \), and so \( x_i \in A \), which is what was to be proven.

This proof could be made more formal by drawing a proof tree or using Isabelle.

“←” in more detail: Want to prove

\[
(\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A) \leftrightarrow (\forall i \in I. x_i \in A)
\]
“→” in more detail: Want to prove

\[(\forall x.(\exists i \in I. x = x_i) \rightarrow x \in A) \leftrightarrow (\forall i \in I. x_i \in A)\]

We show \(\forall i \in I. x_i \in A\) assuming \(\forall x.(\exists i \in I. x = x_i) \rightarrow x \in A\).

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\(\forall x.(\exists i \in I. x = x_i) \rightarrow x \in A\), we have \(x_i \in A\). So let \(i \in I\) be arbitrary.

Since we have \(\forall x.(\exists i \in I. x = x_i) \rightarrow x \in A\), by rule \(\forall\text{-}E\) we can specialize to \((\exists j \in I. x_i = x_j) \rightarrow x_i \in A\). But premise \((\exists j \in I. x_i = x_j)\) is true for \(i = j\), and so \(x_i \in A\), which is what was to be proven.

This proof could be made more formal by drawing a proof tree or using Isabelle.

“←” in more Detail: Want to prove

\[(\forall x.(\exists i \in I. x = x_i) \rightarrow x \in A) \leftrightarrow (\forall i \in I. x_i \in A)\]
We show $\forall x. (\exists i \in I. x = x_i) \rightarrow x \in A$, assuming $\forall i \in I. x_i \in A$. So we show that for arbitrary $x$, assuming $\forall i \in I. x_i \in A$, we have $(\exists i \in I. x = x_i) \rightarrow x \in A$. So let $x$ be arbitrary.

To show $(\exists i \in I. x = x_i) \rightarrow x \in A$, assume $\exists i \in I. x = x_i$. So for some $i \in I$, we have $x = x_i$. Now by our earlier assumption $\forall i \in I. x_i \in A$, and so it follows that $x \in A$. thus we have shown $x \in A$ under the assumption $(\exists i \in I. x = x_i)$, thus we have shown $(\exists i \in I. x = x_i) \rightarrow x \in A$, which is what was to be proven.

This proof could be made more formal by drawing a proof tree or using Isabelle.
Collections and Sets

We speak of collection of all sets rather than set of all sets in order to pretend that we are being careful since we are not sure if there is such a thing as a set of all sets. Therefore we use the “neutral” word collection whose meaning is obvious. . .
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Is it?
Collections and Sets

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Is it?

Recall that we have defined set as collection of objects in the first place. So it is rather futile to suggest now that there should be some difference between collections and sets.

The fact of the matter is: the approach of allowing arbitrary collections of “objects” and regarding such collections as “objects” themselves is naïve. We will see this shortly.
Logical Characterization

Recall $R := \{A | A \notin A\}$ and recall the notion of logical form.

Let $A$ be arbitrary (for the formal reasoning applied here, arbitrary means: it could be a set, a number, a dog, the pope, anything whatsoever).

By the rules for set comprehension, we can prove $A \in \{A | A \notin A\} \rightarrow A \notin A$ and $A \notin A \rightarrow A \in \{A | A \notin A\}$, and so by definition of $\leftrightarrow$, we have $A \in R \leftrightarrow A \notin A$, and since $A$ was arbitrary, by $\forall$-I, we have $\forall A. (A \in R \leftrightarrow A \notin A)$. 

Back to main referring slide
What does this Tell us about Sets?

It tells us that there can be no such thing as the set of all sets. The fundamental flaw of naïve set theory is in saying that a set is a collection of “objects” without worrying what an object is. If we make no restriction as to what an object is, then a set is obviously also an object. But then we effectively base the definition of the new concept set on the existence of sets, so the definition is circular.

The intuition for the solution to this dilemma is not difficult: A set is a collection of objects of which we are already sure that they exist. In particular, since we are only just about to define sets, these objects may not themselves be sets.

Once we have such sets, we can introduce “sets of second order”, that is, sets that contain sets of the first kind. This process can be continued ad infinitum.
The formal details will come later.
Assume that $\top$ is syntactic sugar for a proposition that is always true, say $\top \equiv \bot \to \bot$. We have not introduced this, but it is convenient. So semantically, we have $I_A(\top) = 1$ for all $I_A$. 
A Strange Set Comprehension

Recall that a set comprehension has the form \( \{ x \mid P(x) \} \), where \( P(x) \) is a formula usually containing \( x \).

The set comprehension \( U := \{ x \mid \top \} \) is strange since \( \top \) does not contain \( x \).

But by the introduction rule for set comprehensions, this means that \( x \in U \) for any \( x \). Thus in particular, \( U \in U \).
Higher-Order Logic

Higher-order logic is a solution to the dilemma posed by Russell’s paradox.

It is a surprisingly simple formalism which can be extended conservatively: this means that it can be ensured that the extensions cannot compromise the truth or falsity of statements that were already expressible before the extension.
The $\lambda$-Calculus
The \( \lambda \)-Calculus: Motivation

A way of writing functions. E.g., \( \lambda x. x + 5 \) is the function taking any number \( n \) to \( n + 5 \). Theory underlying functional programming.

Turing-complete model of computation.

One of the most important formalisms of (theoretical) computer science!
The \( \lambda \)-Calculus: Motivation

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One of the most important formalisms of (theoretical) computer science!

Why is it interesting for us? The \( \lambda \)-calculus is used for representing object logics in Isabelle. It is the core of Isabelle’s metalogic!

Further reading: [Tho91, chapter 2], [HS86, chapter 1].
Outline of this Lecture

• The untyped λ-calculus
• The simply typed λ-calculus ($\lambda \rightarrow$)
• An extension of the typed λ-calculus
• Higher-order unification
Untyped λ-Calculus

From functional programming, you may be familiar with function definitions such as

\[ f \ x = x + 5 \]

The \( \lambda \)-calculus is a formalism for writing nameless functions. The function \( \lambda x. x + 5 \) corresponds to \( f \).
Untyped $\lambda$-Calculus

From functional programming, you may be familiar with function definitions such as

$$f \ x = x + 5$$

The $\lambda$-calculus is a formalism for writing nameless functions. The function $\lambda x. x + 5$ corresponds to $f$.

The application to say, 3, is written $(\lambda x. x + 5)(3)$. Its result is computed by substituting 3 for $x$, yielding $3 + 5$, which in usual arithmetic evaluates to 8.
Syntax

\((x \in \text{Var}, \ c \in \text{Const})\)

\[
e ::= x \mid c \mid (ee) \mid (\lambda x. e)
\]

The objects generated by this grammar are called \(\lambda\)-terms or simply terms.

Conventions: iterated \(\lambda\) & left-associated application

\[
(\lambda x. (\lambda y. (\lambda z. ((xz)(yz)))))) \equiv (\lambda xy z. ((xz)(yz)))
\equiv \lambda xyz. xz(yz)
\]

Is \(\lambda x. x + 5\) a \(\lambda\)-term?
Substitution

• **Reduction** based on substitutions

\[(\lambda x. g x 3)(5) = (g x 3)[x \leftarrow 5] = g 5 3\]

• Must respect **free** and **bound** variables,

\[(\lambda x. x(\lambda x. xy))(e) = ((x(\lambda x. xy))[x \leftarrow e] = e(\lambda x. xy)\]

• **Same problems as with quantifiers**

\[
\frac{\forall x. (P(x) \land \exists x. Q(x, y))}{P(e) \land \exists x. Q(x, y)} \quad \forall-E
\]

\[
\frac{\forall x. (P(x) \land \exists y. Q(x, y))}{P(y) \land \exists z. Q(y, z)} \quad \forall-E
\]
Bound, Free, Binding Occurrences

Recall the notions of bound, free, and binding occurrences of variables in a term. Same thing here:

\[
\begin{align*}
\text{\(\lambda\)-calculus} & \quad \text{FOL} \\
FV(x) & :=
\end{align*}
\]
Bound, Free, Binding Occurrences

Recall the notions of bound, free, and binding occurrences of variables in a term. Same thing here:

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<td>$FV(\lambda x. M) := FV(M) \setminus {x}$</td>
<td>$= FV(\forall x. M)$</td>
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Example: $FV(xyz(\lambda yz. xyz)) = \{x, y\}$
Definition of Substitution

$M[x \leftarrow N]$ means substitute $N$ for $x$ in $M$

1. $x[x \leftarrow N] =$

2. $a[x \leftarrow N] =$

3. $(PQ)[x \leftarrow N] =$

4. $(\lambda x. P)[x \leftarrow N] =$

5. $(\lambda y. P)[x \leftarrow N] =$

6. $(\lambda y. P)[x \leftarrow N] =$
Definition of Substitution

\[ M[x \leftarrow N] \] means substitute \( N \) for \( x \) in \( M \)

1. \( x[x \leftarrow N] = N \)
2. \( a[x \leftarrow N] = a \) if \( a \) is a constant or variable other than \( x \)
3. \( (PQ)[x \leftarrow N] = (P[x \leftarrow N]Q[x \leftarrow N]) \)
4. \( (\lambda x. P)[x \leftarrow N] = \lambda x. P \)
5. \( (\lambda y. P)[x \leftarrow N] = \lambda y. P[x \leftarrow N] \) if \( y \neq x \) and \( y \notin FV(N) \)
6. \( (\lambda y. P)[x \leftarrow N] = \lambda z. P[y \leftarrow z][x \leftarrow N] \) if \( y \neq x \) and \( y \in FV(N) \) where \( z \) is a variable such that \( z \notin FV(NP) \)
Definition of Substitution

$M[x \leftarrow N]$ means substitute $N$ for $x$ in $M$

1. $x[x \leftarrow N] = N$
2. $a[x \leftarrow N] = a$ if $a$ is a constant or variable other than $x$
3. $(PQ)[x \leftarrow N] = (P[x \leftarrow N]Q[x \leftarrow N])$
4. $(\lambda x. P)[x \leftarrow N] = \lambda x. P$
5. $(\lambda y. P)[x \leftarrow N] = \lambda y. P[x \leftarrow N]$ if $y \neq x$ and $y \notin \text{FV}(N)$
6. $(\lambda y. P)[x \leftarrow N] = \lambda z. P[y \leftarrow z][x \leftarrow N]$ if $y \neq x$ and $y \in \text{FV}(N)$ where $z$ is a variable such that $z \notin \text{FV}(NP)$

Cases similar to those for quantifiers: $\lambda$ binding is ‘generic’.
Substitution: Example

\[(x(\lambda x. xy))[x ← \lambda z. z]\]
Substitution: Example

\[(x(\lambda x. xy))[x ← \lambda z. z] \overset{3}{=} x[x ← \lambda z. z](\lambda x. xy)[x ← \lambda z. z] \overset{1,4}{=} (\lambda z. z)\lambda x. xy\]
Substitution: Example

\[(x(\lambda x. xy))[x \leftarrow \lambda z. z] \quad \overset{3}{=} \quad x[x \leftarrow \lambda z. z](\lambda x. xy)[x \leftarrow \lambda z. z] \quad \overset{1,4}{=} \quad (\lambda z. z)\lambda x. xy\]

\[(\lambda x. xy)[y \leftarrow x]\]
Substitution: Example

\[
(x(\lambda x. xy))[x \leftarrow \lambda z. z] \quad \Rightarrow^3 \quad x[x \leftarrow \lambda z. z](\lambda x. xy)[x \leftarrow \lambda z. z]
\]

\[
\quad \Rightarrow^{1,4} \quad (\lambda z. z)\lambda x. xy
\]

\[
(\lambda x. xy)[y \leftarrow x] \quad \Rightarrow^6 \quad \lambda z. ((xy)[x \leftarrow z][y \leftarrow x])
\]

\[
\quad \Rightarrow^{3,1,2} \quad \lambda z. (zy[y \leftarrow x])
\]

\[
\quad \Rightarrow^{3,2,1} \quad \lambda z. zx
\]

In the last example, clause 6 avoids capture, i.e., \(\lambda x. xx\).
Reduction: Intuition

Reduction is the notion of “computing”, or “evaluation”, in the \(\lambda\)-calculus.

\[
\begin{align*}
  f \; x &= x + 5 \quad \leadsto \quad f = \lambda x. x + 5 \\
  f \; 3 &= 3 + 5 \quad \leadsto \quad (\lambda x. x + 5)(3) \to_{\beta} (x + 5)[x \leftarrow 3] = 3 + 5
\end{align*}
\]

\(\beta\)-reduction replaces a parameter by an argument.

This should propagate into contexts, e.g.

\[
\lambda x.((\lambda x. x + 5)(3)) \to_{\beta} \lambda x.(3 + 5).
\]
Reduction: Definition

- **β-reduction**: 
  \[ (\lambda x. M) N \rightarrow_{\beta} M[x \leftarrow N] \]

- **Rules for contraction** (of redices) in contexts:

  \[
  \begin{align*}
  M \rightarrow_{\beta} M' & \quad \Rightarrow \quad NM \rightarrow_{\beta} NM' \\
  M \rightarrow_{\beta} M' & \quad \Rightarrow \quad MN \rightarrow_{\beta} M'N \\
  M \rightarrow_{\beta} M' & \quad \Rightarrow \quad \lambda z. M \rightarrow_{\beta} \lambda z. M'
  \end{align*}
  \]

- **Reduction** is reflexive-transitive closure

  \[
  \begin{align*}
  M \rightarrow_{\beta} N & \quad \Rightarrow \quad M \rightarrow^{*}_{\beta} N \\
  M \rightarrow^{*}_{\beta} N & \quad \Rightarrow \quad M \rightarrow^{*}_{\beta} M \\
  M \rightarrow_{\beta} N & \quad \Rightarrow \quad N \rightarrow_{\beta} P \\
  M \rightarrow^{*}_{\beta} P & \quad \Rightarrow \quad M \rightarrow^{*}_{\beta} P
  \end{align*}
  \]

- **A term without redices is in β-normal form.**
Reduction: Examples

$(\lambda x. \lambda y. g\, x\, y)\, a\, b \rightarrow_\beta$
Reduction: Examples

\[(\lambda x. \lambda y. g \, x \, y) \, a \, b \rightarrow_\beta (\lambda y. (g \, a \, y)) \, b \rightarrow_\beta\]
Reduction: Examples

\[ (\lambda x. \lambda y. g \, x \, y)\, a \, b \rightarrow_\beta (\lambda y. (g \, a \, y))\, b \rightarrow_\beta g \, a \, b \]

So \((\lambda x. \lambda y. g \, x \, y)\, a \, b \rightarrow^* g \, a \, b\)

Shows Currying
Reduction: Examples

\[(\lambda x. \lambda y. g \, x \, y) \, a \, b \rightarrow_\beta (\lambda y. (g \, a \, y)) \, b \rightarrow_\beta g \, a \, b\]

So \[(\lambda x. \lambda y. g \, x \, y) \, a \, b \rightarrow^* g \, a \, b\]

Shows Currying

\[(\lambda x. xx)(\lambda x. xx) \rightarrow_\beta\]
Reduction: Examples

\[(\lambda x. \lambda y. g \, x \, y) \, a \, b \rightarrow_\beta (\lambda y. (g \, a \, y)) \, b \rightarrow_\beta g \, a \, b\]

So \[(\lambda x. \lambda y. g \, x \, y) \, a \, b \rightarrow^* g \, a \, b\]

Shows **Currying**

\[(\lambda x. xx)(\lambda x. xx) \rightarrow_\beta (\lambda x. xx)(\lambda x. xx) \rightarrow_\beta \ldots\]

Shows **divergence**
Reduction: Examples

\[(\lambda x. \lambda y. g x y) a \ b \rightarrow_\beta (\lambda y. (g \ a \ y)) \ b \rightarrow_\beta g \ a \ b\]

So \( (\lambda x. \lambda y. g x y) a \ b \rightarrow^* g \ a \ b\)

Shows Currying

\[(\lambda x. xx)(\lambda x. xx) \rightarrow_\beta (\lambda x. xx)(\lambda x. xx) \rightarrow_\beta \ldots\]

Shows divergence

But \( (\lambda x y. y)((\lambda x. xx)(\lambda x. xx)) \rightarrow_\beta \lambda y. y\)
Conversion

- $\beta$-conversion: "symmetric closure" of $\beta$-reduction

\[
\begin{align*}
M & \rightarrow^* N \\
\hline
M =_\beta N & M =_\beta N \\
\hline
N =_\beta M & N =_\beta M
\end{align*}
\]
Conversion

- **β-conversion**: “symmetric closure” of β-reduction

\[
M \rightarrow^* \beta N \quad \quad M =_{\beta} N \\
\frac{M =_{\beta} N}{M \rightarrow^* \beta N} \\
\frac{N =_{\beta} M}{M =_{\beta} N}
\]

- **α-conversion**: bound variable renaming (usually implicitly)

\[
\lambda x. M =_{\alpha} \lambda z. M[x \leftarrow z] \quad \text{where } z \not\in FV(M)
\]
Conversion

- **β-conversion**: "symmetric closure" of β-reduction

\[ M \rightarrow^* _{\beta} N \quad \frac{M =_{\beta} N}{M = _{\beta} N} \quad \frac{M = _{\beta} N}{N = _{\beta} M} \]

- **α-conversion**: bound variable renaming (usually implicitly)

\[ \lambda x. M = _{\alpha} \lambda z. M[x \leftarrow z] \quad \text{where } z \notin FV(M) \]

- **η-conversion**: for normal-form analysis

\[ M = _{\eta} \lambda x. (M x) \quad \text{if } x \notin FV(M) \]
**λ-Calculus Meta-Properties**

Confluence (equivalently, Church-Rosser): reduction is order-independent.

For all $M, N_1, N_2$, if $M \rightarrow^* \beta N_1$ and $M \rightarrow^* \beta N_2$, then there exists a $P$ where $N_1 \rightarrow^* \beta P$ and $N_2 \rightarrow^* \beta P$. 

![Diagram showing confluence](image)
Uniqueness of Normal Forms

Corollary of the Church-Rosser property:

If $M \rightarrow^{*}_\beta N_1$ and $M \rightarrow^{*}_\beta N_2$ where $N_1$ and $N_2$ in normal form, then
Uniqueness of Normal Forms

Corollary of the Church-Rosser property:
If $M \rightarrow^* \beta N_1$ and $M \rightarrow^* \beta N_2$ where $N_1$ and $N_2$ in normal form, then $N_1 =_\alpha N_2$. 
**Uniqueness of Normal Forms**

Corollary of the Church-Rosser property:

If $M \rightarrow^\ast_\beta N_1$ and $M \rightarrow^\ast_\beta N_2$ where $N_1$ and $N_2$ in normal form, then $N_1 =_\alpha N_2$.

Example:

\[
(\lambda xy. y)((\lambda x. xx)a) \rightarrow_\beta (\lambda xy. y)(aa) \rightarrow_\beta \lambda y. y
\]

\[
(\lambda xy. y)((\lambda x. xx)a) \rightarrow_\beta \lambda y. y
\]
Turing Completeness

The $\lambda$-calculus can represent all computable functions.
Simple Type Theory $\lambda \to$

Motivation: Suppose you have constants 1, 2 with usual meaning. Is it sensible to write $1 \ 2$ ($1$ applied to $2$)?
Simple Type Theory $\lambda \rightarrow$

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$\lambda \rightarrow$ (simply typed $\lambda$-calculus, simple type theory) restricts syntax to “meaningful expressions”.

In untyped $\lambda$-calculus, we have syntactic objects called terms.
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We now introduce syntactic objects called types.
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$\lambda\rightarrow$ (simply typed $\lambda$-calculus, simple type theory) restricts syntax to “meaningful expressions”.

In untyped $\lambda$-calculus, we have syntactic objects called terms.

We now introduce syntactic objects called types.

We will say “a term has a type” or “a term is of a type”.
Two Syntaxes

• Syntax for types ($\mathcal{B}$ a set of base types, $T \in \mathcal{B}$)

$$\tau ::= T \mid \tau \to \tau$$
Two Syntaxes

• Syntax for types ($\mathcal{B}$ a set of base types, $T \in \mathcal{B}$)

\[ \tau ::= T \mid \tau \to \tau \]

Examples: $\mathbb{N}$, $\mathbb{N} \to \mathbb{N}$, $(\mathbb{N} \to \mathbb{N}) \to \mathbb{N}$, $\mathbb{N} \to \mathbb{N} \to \mathbb{N}$
Two Syntaxes

• Syntax for types ($B$ a set of base types, $T \in B$)

$$\tau ::= T \mid \tau \to \tau$$

Examples: $\mathbb{N}$, $\mathbb{N} \to \mathbb{N}$, $(\mathbb{N} \to \mathbb{N}) \to \mathbb{N}$, $\mathbb{N} \to \mathbb{N} \to \mathbb{N}$

• Syntax for (raw) terms: $\lambda$-calculus augmented with types

$$e ::= x \mid c \mid (ee) \mid (\lambda x^{\tau}.e)$$

($x \in \text{Var}, c \in \text{Const}$)
Signatures and Contexts

Generally (in various logic-related formalisms) a signature defines the “fixed” symbols of a language, and a context defines the “variable” symbols of a language.
Signatures and Contexts

Generally (in various logic-related formalisms) a signature defines the “fixed” symbols of a language, and a context defines the “variable” symbols of a language. In $\lambda \rightarrow$,

- a signature $\Sigma$ is a sequence ($c \in Const$)

$$
\Sigma ::= \langle \rangle \mid \Sigma, c : \tau
$$

- a context $\Gamma$ is a sequence ($x \in Var$)

$$
\Gamma ::= \langle \rangle \mid \Gamma, x : \tau
$$

What’s the difference to signatures you have seen so far?
Type Assignment Calculus

We now define type judgements: “a term has a type” or “a term is of a type”. Generally this depends on a signature $\Sigma$ and a context $\Gamma$. For example

$$\Gamma \vdash_\Sigma c \ x : \sigma$$

where $\Sigma = c : \tau \rightarrow \sigma$ and $\Gamma = x : \tau$. 
Type Assignment Calculus

We now define type judgements: “a term has a type” or “a term is of a type”. Generally this depends on a signature $\Sigma$ and a context $\Gamma$. For example

$$
\Gamma \vdash^\Sigma c \ x : \sigma
$$

where $\Sigma = c : \tau \to \sigma$ and $\Gamma = x : \tau$.

We usually leave $\Sigma$ implicit and write $\vdash$ instead of $\vdash^\Sigma$.

If $\Gamma$ is empty it is omitted.
Type Assignment Calculus: Rules

\[ \frac{c : \tau \in \Sigma}{\Gamma \vdash c : \tau} \quad assum \]

\[ \frac{\Gamma \vdash e : \sigma \rightarrow \tau \quad \Gamma \vdash e' : \sigma}{\Gamma \vdash ee' : \tau} \quad app \]

\[ \frac{\Gamma, x : \tau, \Delta \vdash x : \tau}{\Gamma \vdash \Delta \vdash x : \tau} \quad hyp \]

\[ \frac{\Gamma, x : \sigma \vdash e : \tau}{\Gamma \vdash \lambda x^\sigma. e : \sigma \rightarrow \tau} \quad abs \]
Type Assignment Calculus: Rules

\[
\frac{c : \tau \in \Sigma}{\Gamma \vdash c : \tau} \quad \text{assum} \quad \frac{\Gamma, x : \tau, \Delta \vdash x : \tau}{\Gamma \vdash x : \tau} \quad \text{hyp}
\]

\[
\frac{\Gamma \vdash e : \sigma \rightarrow \tau \quad \Gamma \vdash e' : \sigma}{\Gamma \vdash ee' : \tau} \quad \text{app} \quad \frac{\Gamma, x : \sigma \vdash e : \tau}{\Gamma \vdash \lambda x^\sigma. e : \sigma \rightarrow \tau} \quad \text{abs}
\]

Note analogy to minimal logic over →.

β-reduction defined as before, has subject reduction property and is strongly normalizing.
Example 1

\[ \vdash \lambda x^\sigma . \lambda y^\tau . x : \]
Example 1

\[ \vdash \lambda x^{\sigma}. \lambda y^{\tau}. x : \sigma \rightarrow (\tau \rightarrow \sigma) \]
Example 1

\[ \vdash \lambda x^\sigma . \lambda y^\tau . x : \sigma \rightarrow (\tau \rightarrow \sigma) \]
Example 1

\[
\begin{align*}
  x : \sigma & \vdash \lambda y^\tau. x : \tau \to \sigma \\
  \vdash \lambda x^\sigma. \lambda y^\tau. x : \sigma \to (\tau \to \sigma) & \quad \text{abs}
\end{align*}
\]
Example 1

\[
\begin{array}{c}
\frac{x : \sigma \vdash \lambda y^\tau . x : \tau \rightarrow \sigma}{\vdash \lambda x^\sigma . \lambda y^\tau . x : \sigma \rightarrow (\tau \rightarrow \sigma)}^\text{abs}
\end{array}
\]
Example 1

\[
\frac{x : \sigma, \ y : \tau \vdash x : \sigma}{x : \sigma \vdash \lambda y^\tau . x : \tau \to \sigma}^{\text{abs}}
\]

\[
\vdash \lambda x^\sigma . \lambda y^\tau . x : \sigma \to (\tau \to \sigma)^{\text{abs}}
\]
Example 1

\[ \vdash \lambda x^\sigma . \lambda y^\tau . x : \sigma \rightarrow (\tau \rightarrow \sigma) \]

1. \[x : \sigma, \ y : \tau \vdash x : \sigma \quad \text{hyp} \]
2. \[x : \sigma \vdash \lambda y^\tau . x : \tau \rightarrow \sigma \quad \text{abs} \]
3. \[\vdash \lambda x^\sigma . \lambda y^\tau . x : \sigma \rightarrow (\tau \rightarrow \sigma) \quad \text{abs} \]
Example 1

\[
\frac{x : \sigma, \ y : \tau \vdash x : \sigma}{x : \sigma \vdash \lambda y^\tau . x : \tau \rightarrow \sigma}^{\text{hyp}}
\]
\[
\frac{}{\vdash \lambda x^\sigma . \lambda y^\tau . x : \sigma \rightarrow (\tau \rightarrow \sigma)}^{\text{abs}}
\]

Note the use of schematic types!
Example 1

\[ x : \sigma, \ y : \tau \vdash x : \sigma \]

\[
\begin{array}{c}
x : \sigma \vdash \lambda y^\tau. x : \tau \rightarrow \sigma \\
\end{array}
\]

\[
\vdash \lambda x^\sigma. \lambda y^\tau. x : \sigma \rightarrow (\tau \rightarrow \sigma)
\]

Note the use of schematic types!

For simplicity, applications of \( hyp \) are usually not explicitly marked in proof.
Example 2

\( \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, x : \sigma \)

\( \vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau} \cdot \lambda x^{\sigma} \cdot f\ x\ x : \)
Example 2

\[ \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, x : \sigma \]

\[ \vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau}. \lambda x^{\sigma}. f \ x \ x : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau \]
Example 2

\[ \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, x : \sigma \]

\[ \vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau}. \lambda x^{\sigma}. f \; x \; x : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau \]
Example 2

\[ \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, x : \sigma \]

\[ f : \sigma \rightarrow \sigma \rightarrow \tau \vdash \lambda x^\sigma \cdot f \, x \, x : \sigma \rightarrow \tau \]

\[ \vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau} \cdot \lambda x^\sigma \cdot f \, x \, x : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau \]
Example 2

\[ \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, \ x : \sigma \]

\[
\frac{f : \sigma \rightarrow \sigma \rightarrow \tau \vdash \lambda x^\sigma. f \ x \ x : \sigma \rightarrow \tau}{\vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau}. \lambda x^\sigma. f \ x \ x : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau}
\]
Example 2

\[
\Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, \, x : \sigma
\]

\[
\Gamma \vdash f \, x \, x : \tau
\]

\[
f : \sigma \rightarrow \sigma \rightarrow \tau \vdash \lambda x^{\sigma} . f \, x \, x : \sigma \rightarrow \tau
\]

\[
\vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau} . \lambda x^{\sigma} . f \, x \, x : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau
\]
Example 2

\[ \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, x : \sigma \]

\[ \Gamma \vdash fx : \tau \]

\[ f : \sigma \rightarrow \sigma \rightarrow \tau \vdash \lambda x^\sigma. fxx : \sigma \rightarrow \tau \]

\[ \vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau}. \lambda x^\sigma. f xx : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau \]
Example 2

\[ \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, x : \sigma \]

\[\begin{align*}
\Gamma \vdash f x : \sigma & \rightarrow \tau & \Gamma \vdash x : \sigma \\
\hline
\Gamma \vdash f x x : \tau & \text{app} \\
\hline
f : \sigma \rightarrow \sigma \rightarrow \tau \vdash \lambda x^\sigma. f x x : \sigma \rightarrow \tau & \text{abs} \\
\hline
\vdash \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau}. \lambda x^\sigma. f x x : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau & \text{abs}
\end{align*}\]
Example 2

\[ \Gamma = f : \sigma \to \sigma \to \tau, x : \sigma \]

\[ \Gamma \vdash fx : \sigma \to \tau \]
\[ \Gamma \vdash x : \sigma \]
\[ \Gamma \vdash fx : \sigma \to \tau \]
\[ \Gamma \vdash fxx : \tau \]
\[ \Gamma \vdash \lambda x^\sigma. fxx : \sigma \to \tau \]
\[ \vdash \lambda f^{\sigma \to \sigma \to \tau}. \lambda x^\sigma. fxx : (\sigma \to \sigma \to \tau) \to \sigma \to \tau \]
Example 2

\[ \Gamma = f : \sigma \rightarrow \sigma \rightarrow \tau, x : \sigma \]

\[ \Gamma \vdash f : \sigma \rightarrow \sigma \rightarrow \tau \quad \Gamma \vdash x : \sigma \]

\[ \frac{\Gamma \vdash f : \sigma \rightarrow \sigma \rightarrow \tau \quad \Gamma \vdash x : \sigma}{\Gamma \vdash fx : \sigma \rightarrow \tau} \quad \text{app} \]

\[ \frac{\Gamma \vdash fx : \sigma \rightarrow \tau \quad \Gamma \vdash x : \sigma}{\Gamma \vdash fxx : \tau} \quad \text{app} \]

\[ \frac{f : \sigma \rightarrow \sigma \rightarrow \tau \mid \lambda x^\sigma. f xx : \sigma \rightarrow \tau}{\mid \lambda f^{\sigma \rightarrow \sigma \rightarrow \tau}. \lambda x^\sigma. f xx : (\sigma \rightarrow \sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \tau} \quad \text{abs} \]
Example 3

\[ \Sigma = f : \sigma \to \sigma \to \tau \]

\[ \Gamma = x : \sigma \]

\[ \Gamma \vdash f \, x \, x : \tau \]
Example 3

\[ \Sigma = f : \sigma \rightarrow \sigma \rightarrow \tau \]
\[ \Gamma = x : \sigma \]

\[ f : \sigma \rightarrow \sigma \rightarrow \tau \in \Sigma \]
\[ \frac{\Gamma \vdash f : \sigma \rightarrow \sigma \rightarrow \tau}{\text{assum}} \]

\[ \frac{\Gamma \vdash x : \sigma \quad \Gamma \vdash x : \sigma}{\text{app}} \]
\[ \frac{\Gamma \vdash f x : \sigma \rightarrow \tau \quad \Gamma \vdash x : \sigma}{\text{app}} \]
\[ \Gamma \vdash f x x : \tau \]

Note that this time, \( f \) is a constant.
Example 3

\[ \Sigma = f : \sigma \rightarrow \sigma \rightarrow \tau \]
\[ \Gamma = x : \sigma \]

\[ \Gamma \vdash f : \sigma \rightarrow \sigma \rightarrow \tau \]
\[ \Gamma \vdash x : \sigma \]

\[ \Gamma \vdash f \, x : \sigma \rightarrow \tau \]
\[ \Gamma \vdash x : \sigma \]

\[ \Gamma \vdash f \, x \, x : \tau \]

Note that this time, \( f \) is a constant.
We will often suppress applications of \textit{assum}. 
Type Assignment and $\alpha\beta\eta$-Conversion

Type construction:

- **Type construction** is decidable.
Type Assignment and $\alpha\beta\eta$-Conversion

Type construction:

- **Type construction** is decidable.
- There is a practically useful implementation for type-construction (Hindley-Milner algorithm $\mathcal{W}$ [Mil78, NN99]).

Term congruence $(e =_{\alpha\beta\eta} e')$ is decidable.
An Extension of the Typed $\lambda$-Calculus

We will now look at the typed $\lambda$-calculus extended by polymorphism and type classes. As we will see later, this is the universal representation for object logics in Isabelle.
Polymorphism: Intuition

In functional programming, the function \textit{append} for concatenating two lists works the same way on integer lists and on character lists: \textit{append} is \textbf{polymorphic}.

Type language must be generalized to include \textbf{type variables} (denoted by $\alpha, \beta \ldots$) and \textbf{type constructors}.

Example: \textit{append} has type $\alpha \text{list} \rightarrow \alpha \text{list} \rightarrow \alpha \text{list}$, and by type instantiation, it can also have type, say, $\text{int list} \rightarrow \text{int list} \rightarrow \text{int list}$.
Polymorphism: Two Syntaxes

- Syntax for polymorphic types ($\mathcal{B}$ a set of type constructors including $\to$), $T \in \mathcal{B}$, $\alpha$ is a type variable

$$\tau ::= \alpha \mid (\tau, \ldots, \tau)\, T$$
Polymorphism: Two Syntaxes

- Syntax for polymorphic types ($B$ a set of type constructors including $\rightarrow$), $T \in B$, $\alpha$ is a type variable

$$\tau ::= \alpha \mid (\tau, \ldots, \tau) \ T$$

Examples: $\mathbb{N}$, $\mathbb{N} \rightarrow \mathbb{N}$, $\alpha$ list, $\mathbb{N}$ list, $(\mathbb{N}, \text{bool})$ pair.
Polymorphism: Two Syntaxes

- Syntax for polymorphic types ($\mathcal{B}$ a set of type constructors including $\rightarrow$), $T \in \mathcal{B}$, $\alpha$ is a type variable)

$$\tau ::= \alpha \mid (\tau, \ldots, \tau) \ T$$

Examples: $\mathbb{N}$, $\mathbb{N} \rightarrow \mathbb{N}$, $\alpha \text{list}$, $\mathbb{N} \text{list}$, $(\mathbb{N}, \text{bool}) \text{pair}$.

- Syntax for (raw) terms as before:

$$e ::= x \mid c \mid (ee) \mid (\lambda x^\tau. e)$$

($x \in \text{Var}$, $c \in \text{Const}$)
Polymorphic Type Assignment Calculus

Type substitutions (denoted $\Theta$) defined in analogy to substitutions in FOL. Apart from application of $\Theta$ in rule *assum*, type assignment is as for $\lambda \rightarrow$:

\[
\begin{align*}
\frac{c : \tau \in \Sigma}{\Gamma \vdash c : \tau^{\Theta}}^{\text{assum}^*} & \quad \frac{\Gamma, x : \tau, \Delta \vdash x : \tau}{\text{hyp}} \\
\frac{\Gamma \vdash e : \sigma \rightarrow \tau \quad \Gamma \vdash e' : \sigma}{\Gamma \vdash ee' : \tau}^{\text{app}} & \quad \frac{\Gamma, x : \sigma \vdash e : \tau}{\Gamma \vdash \lambda x^{\sigma}. e : \sigma \rightarrow \tau}^{\text{abs}}
\end{align*}
\]

$^*$: $\Theta$ is any type substitution.
Type Classes: Intuition

Type classes are a way of “making ad-hoc polymorphism less ad-hoc” [HHPW96, WB89].

Type classes are used to group together types with certain properties, in particular, types for which certain symbols are defined.

We only sketch the formalisation here, and refer to [HHPW96, Nip93, NP93] for details.
Type Classes in Isabelle

- **Syntactic classes** (similarly as in Haskell): E.g., declare that there exists a class ord which is a subclass of class term, and that for any $\tau :: \text{ord}$, the constant $\leq$ is defined and has type $\tau \rightarrow \tau \rightarrow \text{bool}$. Isabelle has syntax for this.

- **Axiomatic classes**: Declare (axiomatize) that certain theorems should hold for a $\tau :: \kappa$ where $\kappa$ is a type class. E.g., axiomatize that $\leq$ is reflexive by an (Isabelle) theorem $"x \leq x"$. Isabelle has syntax for this.

To use a class, we can declare members of it, e.g., $\mathbb{N}$ is a member of ord.
Syntax: Classes, Types, and Terms

Based on

- a set of type classes, say $\mathcal{K} = \{ \text{ord}, \text{order}, \text{lattice}, \ldots \}$,
- a set of type constructors, say $\mathcal{B} = \{ \text{bool}, \_ \rightarrow \_, \text{ind}, \_ \text{list}, \_ \text{set} \ldots \}$,
- a set of constants $\text{Const}$ and a set of variables $\text{Var}$,

we define

- Polymorphic types: $\tau ::= \alpha \mid \alpha :: \kappa \mid (\tau, \ldots, \tau) \ T$
- Raw terms (as before): $e ::= x \mid c \mid (ee) \mid (\lambda x^\tau.e)$

($\alpha$ is type variable, $T \in \mathcal{B}$, $\kappa \in \mathcal{K}$, $x \in \text{Var}$, $c \in \text{Const}$)
Type Assignment Calculus with Type Classes

Assume some syntax for declaring $\tau :: \kappa$ and $\kappa \prec \kappa'$. In addition introduce the rule

$$\frac{\tau :: \kappa \quad \kappa \prec \kappa'}{\tau :: \kappa'}$$

subclass

Type assignment rules as before, but type substitution $\Theta$ in

$$\frac{c : \tau \in \Sigma}{\Gamma \vdash c : \tau\Theta}$$

assum

must respect class constraints: for each $\alpha :: \kappa$ occurring in $\tau$ where $\alpha\Theta = \sigma$, judgement $\sigma :: \kappa$ must hold.
Example

Suppose that by virtue of declarations, we have \( \mathbb{N} :: \text{order} \), \( \text{order} \prec \text{ord} \), and \( \leq : \alpha :: \text{ord} \rightarrow \alpha \rightarrow \text{bool} \in \Sigma \). Derive

\[
\frac{\mathbb{N} :: \text{order} \quad \text{order} \prec \text{ord}}{\mathbb{N} :: \text{ord}} \quad \text{subclass}
\]

and then \( (\Theta = [\alpha \leftarrow \mathbb{N}] ) \)

\[
\frac{(\leq : (\alpha :: \text{ord}) \rightarrow \alpha \rightarrow \text{bool}) \in \Sigma}{\vdash \leq : \mathbb{N} \rightarrow \mathbb{N} \rightarrow \text{bool}} \quad \text{assum}
\]

which respects the class constraint since the judgement \( \mathbb{N} :: \text{ord} \) was derived above.
Higher-Order Unification

The \( \lambda \)-calculus is “the” metalogic. Hence we now (sometimes) call its variables “metavariables” for emphasis and we precede them with “?”. E.g. they can stand for object-level formulae. Will be more precise later.
Higher-Order Unification

The $\lambda$-calculus is “the” metalogic. Hence we now (sometimes) call its variables “metavariables” for emphasis and we precede them with “?”.

E.g. they can stand for object-level formulae. Will be more precise later.

Two issues concerning metavariables are:

- suitable renamings of metavariables;
- unification before rule application.
What Is Higher-Order Unification?

Unification of terms $e, e'$: find substitution $\theta$ for metavariables such that $e\theta =_{\alpha\beta\eta} e'\theta$.

Examples:

\[ ?X + ?Y =_{\alpha\beta\eta} x + x \]
\[ ?P(x) =_{\alpha\beta\eta} x + x \]
\[ f(?X \ x) =_{\alpha\beta\eta} ?Y \ x \]
\[ ?F(?G \ x) =_{\alpha\beta\eta} f(g(x)) \]
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Examples:

\[
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f(?X x) &=_{\alpha\beta\eta} ?Y x \\
?F(?G x) &=_{\alpha\beta\eta} f(g(x))
\end{align*}
\]

Why higher-order? Metavariables may be instantiated to functions, e.g. $[?P \leftarrow \lambda y. y + y]$. 
Higher-Order Unification: Facts

- Unification modulo $\alpha\beta$ (HO-unification) is semi-decidable (in Isabelle: incomplete).
- Unification modulo $\alpha\beta\eta$ is undecidable (in Isabelle: incomplete).
Higher-Order Unification: Facts

- Unification modulo $\alpha \beta$ (HO-unification) is semi-decidable (in Isabelle: incomplete).
- Unification modulo $\alpha \beta \eta$ is undecidable (in Isabelle: incomplete).
- HO-unification is well-behaved for most practical cases.
- Important fragments (like HO-patterns) are decidable.
- HO-unification has possibly infinitely many solutions.

We will look at some of these issues again later.
Summary on λ-Calculus

λ-calculus is a formalism for writing functions. 

\(\beta\)-reduction is the notion of “computing” in λ-calculus.

λ-calculus is Turing-complete.

\(\lambda\rightarrow\) restricts syntax to “meaningful” λ-terms.

Extension of typed λ-calculus used to represent syntax of object logics. λ-terms stand for object terms/formulae, possibly containing “distinguished occurrences” of (object) variables. This will be explained thoroughly next lecture.

HO-unification important in constructing proofs.
More Detailed Explanations
$3 + 5 = 8$?

As you might guess, the formalism of the $\lambda$-calculus is not directly related to usual arithmetic and so it is not built into this formalism that $3 + 5$ should evaluate to 8. However, it may be a reasonable choice, depending on the context, to extend the $\lambda$-calculus in this way, but this is not our concern at the moment.
Var and $\text{Const}$

Similarly as for first-order logic, a language of the untyped $\lambda$-calculus is characterized by giving a set of variables and a set of constants.

One can think of $\text{Const}$ as a signature.

Note that $\text{Const}$ could be empty.

Note also that the word constant has a different meaning in the $\lambda$-calculus from that of first-order logic. In both formalisms, constants are just symbols.

In first-order logic, a constant is a special case of a function symbol, namely a function symbol of arity 0.

In the $\lambda$-calculus, one does not speak of function symbols. In the untyped $\lambda$-calculus, any $\lambda$-term (including a constant) can be applied to another term, and so any $\lambda$-term can be called a “unary function”. A constant being applied to a term is something which would contradict the
intuition about constants in first-order logic. So for the $\lambda$-calculus, think of constant as opposed to a variable, an application, or an abstraction.
How do We Call those Terms?

A $\lambda$-term can either be
- a variable (case $x$), or
- a constant (case $c$), or
- an application of a $\lambda$-term to another $\lambda$-term (case $(ee)$), or
- an abstraction over a variable $x$ (case $(\lambda x. e)$).
Backus-Naur Form

A notation like

\[
e ::= x \mid c \mid (ee) \mid (\lambda x. e)
\]

\[
\tau ::= T \mid \tau \rightarrow \tau
\]

\[
e ::= x \mid c \mid (ee) \mid (\lambda x^\tau. e)
\]

\[
P ::= x \mid \neg P \mid P \land P \mid P \rightarrow P \ldots
\]

for specifying syntax is called Backus-Naur form (BNF) for expressing grammars. For example, the first BNF-clause reads: a \(\lambda\)-term can be a variable, or a constant, or a \(\lambda\)-term applied to a \(\lambda\)-term, or a \(\lambda\)-abstraction, which is a \(\lambda\)-term of the form \(\lambda x. e\), where \(e\) is a \(\lambda\)-term. The BNF is a very common formalism for specifying syntax, e.g., of
programming languages. See here or here.
(\(\lambda\)-)Terms

So just like first-order logic, the \(\lambda\)-calculus has a syntactic category called terms. But the word “term” has a different meaning for the \(\lambda\)-calculus than for first-order logic, and so one can say \(\lambda\)-term for emphasis. Note that at this stage, we have no syntactic category called “formula” for the \(\lambda\)-calculus.
$\lambda$-Calculus: Notational Conventions

We write $\lambda x_1 x_2 \ldots x_n. e$ instead of $\lambda x_1. (\lambda x_2. (\ldots e) \ldots)$.

$e_1 e_2 \ldots e_n$ is equivalent to $(\ldots (e_1 e_2) \ldots e_n) \ldots$, not $(e_1 (e_2 \ldots e_n) \ldots)$.

Note that this is in contrast to the associativity of logical operators.

There are some good reasons for these conventions.
Infix Notation

Strictly speaking, $\lambda x. x + 5$ does not adhere to the definition of syntax of $\lambda$-terms, at least if we parse it in the usual way: $+$ is an infix constant applied to arguments $x$ and $5$.

If we parse $x + 5$ as $((x+)5)$, i.e., $x$ applied to (the constant) $+$, and the resulting term applied to (the constant) $5$, then $\lambda x. x + 5$ would indeed adhere to the definition of syntax of $\lambda$-terms, but of course, this is pathological and not intended here.

It is convenient to allow for extensions of the syntax of $\lambda$-terms, allowing for:

- application to several arguments rather than just one;
- infix notation.

Such an extension is inessential for the expressive power of the
\(\lambda\)-calculus. Instead of having a binary infix constant \(+\) and writing \(\lambda x. x + 5\), we could have a constant \textit{plus} according to the original syntax and write \(\lambda x. ((\textit{plus} x) 5)\) (i.e., write \(+\) in a \textit{Curried} way).
Reduction

Reduction is the notion of “computing”, or “evaluation”, in the \( \lambda \)-calculus.
Notations for Substitutions

Here we use the notation $e[x \leftarrow t]$ for the term obtained from $e$ by replacing $x$ with $t$. There is also the notation $e[t/x]$, and confusingly, also $e[x/t]$. We will attempt to be consistent within this course, but be aware that you may find such different notations in the literature.
λ Binding Is ‘Generic’

Recall the definition of substitution for first-order logic. We observe that binding and substitution are some very general concepts. So far, we have seen four binding operators: ∃, ∀ and λ, and set comprehensions. The λ operator is the most generic of those operators, in that it does not have a fixed meaning hard-wired into it in the way that the quantifiers do. In fact, it is possible to have it as the only operator on the level of the metalogic. We will see this later.
Avoiding Capture

If it wasn’t for clause 6, i.e., if we applied clause 5 ignoring the requirement on freeness, then \((\lambda x. xy)[y \leftarrow x]\) would be \(\lambda x. xx\).
Parameters and Arguments

In the $\lambda$-term $(\lambda x. M) N$, we say that $N$ is an argument (and the function $\lambda x. M$ is applied to this argument), and every occurrence of $x$ in $M$ is a parameter (we say this because $x$ is bound by the $\lambda$). This terminology may be familiar to you if you have experience in functional programming, but actually, it is also used in the context of function and procedure declarations in imperative programming.
Propagation into Contexts

In

\[ \lambda x.((\lambda x. x + 5)(3)), \]

the underlined part is a subterm occurring in a context. \( \beta \)-reduction should be applicable to this subterm.
Like a Proof System

As you see, $\beta$-reduction is defined using rules (two of them being axioms, the rest proper rules) in the same way that we have defined proof systems for logic before. Note that we wrote the first axiom defining $\beta$-reduction without a horizontal bar.
Redex

In a $\lambda$-term, a subterm of the form $$(\lambda x. M)N$$ is called a redex (plural redices). It is a subterm to which $\beta$-reduction can be applied.
Currying

You may be familiar with functions taking several arguments, or equivalently, a tuple of arguments, rather than just one argument. In the $\lambda$-calculus, but also in functional programming, it is common not to have tuples and instead use a technique called Currying (Schönfinkeln in German). So instead of writing $g(a, b)$, we write $g\ a\ b$, which is read as follows: $g$ is a function which takes an argument $a$ and returns a function which then takes an argument $b$.

Recall that application associates to the left, so $g\ a\ b$ is read $(g\ a)\ b$.

Currying will become even clearer once we introduce the typed $\lambda$-calculus.
Divergence

We say that a $\beta$-reduction sequence diverges if it is infinite.

Note that for $(\lambda xy. y)((\lambda x.xx)(\lambda x.xx))$, there is a finite $\beta$-reduction sequence

$$(\lambda xy. y)((\lambda x.xx)(\lambda x.xx)) \rightarrow_\beta \lambda y. y$$

but there is also a diverging sequence

$$(\lambda xy. y)((\lambda x.xx)(\lambda x.xx)) \rightarrow_\beta (\lambda xy. y)((\lambda x.xx)(\lambda x.xx)) \rightarrow_\beta \ldots$$
\(\alpha\text{-Conversion}\)

\(\alpha\)-conversion is usually applied implicitly, i.e., without making it an explicit step. So for example, one would simply write:

\[\lambda z. z =_\beta \lambda x. x\]
**η-Conversion**

η-conversion is defined as

\[ M \equiv \eta \lambda x. (M x) \quad \text{if} \quad x \not\in \text{FV}(M) \]

It is needed for reasoning about normal forms.

\[ g x = \eta \lambda y. g x y \quad \text{reflects} \quad g x b \equiv_\beta (\lambda y. g x y)b \]

More specifically: if we did not have the η-conversion rule, then \( g x \) and \( \lambda y. g x y \) would not be “equivalent” up to conversion. But that seems unreasonable, because they behave the same way when applied to \( b \). Applied to \( b \), both terms can be converted to \( g x b \). This is why it is reasonable to introduce a rule such that \( g x \) and \( \lambda y. g x y \) are “equivalent” up to conversion.
One also says that the $\eta$-conversion expresses the idea of extensionality [HS86, chapter 7].

Note that with the help of contraction and transitivity, $\eta$-conversion can be generalized to more than one variable, i.e. $M =_{\beta\eta} \lambda x_1 \ldots x_n. M x_1 \ldots x_n$. E.g. we can derive

\[
\lambda xyz. M x y z =_{\beta\eta} M:
\]

\[
\begin{align*}
\lambda z. M x y z & =_{\eta} M x y \\
\lambda y z. M x y z & =_{\beta\eta} \lambda y. M x y \\
\lambda y. M x y & =_{\eta} M x \\
\lambda y z. M x y z & =_{\beta\eta} \lambda y. M x \\
\lambda x y z. M x y z & =_{\beta\eta} \lambda x. M x \\
\lambda x. M x & =_{\eta} M
\end{align*}
\]

For any $n$, we call $\lambda x_1 \ldots x_n. M x_1 \ldots x_n$ an $\eta$-expansion of $M$. 
Confluence and Church-Rosser

A reduction $\rightarrow$ is called **confluent** if

for all $M, N_1, N_2$, if $M \rightarrow^* N_1$ and $M \rightarrow^* N_2$, then there exists a $P$ where $N_1 \rightarrow^* P$ and $N_2 \rightarrow^* P$.

A reduction is called **Church-Rosser** if

for all $N_1, N_2$, if $N_1 \leftrightarrow^* N_2$, then there exists a $P$ where $N_1 \rightarrow^* P$ and $N_2 \rightarrow^* P$.

Here, $\leftarrow:= (\rightarrow)^{-1}$ is the inverse of $\rightarrow$, and $\leftrightarrow:= \leftarrow \cup \rightarrow$ is the symmetric closure of $\rightarrow$, and $\leftrightarrow^*:= (\leftrightarrow)^*$ is the reflexive transitive symmetric closure of $\rightarrow$.

So for example, if we have
\[ M_1 \rightarrow M_2 \rightarrow M_3 \rightarrow M_4 \leftarrow M_5 \leftarrow M_6 \rightarrow M_7 \leftarrow M_8 \leftarrow M_9 \]

then we would write \( M_1 \leftrightarrow^* M_9 \).

Confluence is equivalent to the Church-Rosser property [BN98, page 10].
\textbf{λ-Calculus Metaproperties}

By metaproperties, we mean properties about reduction and conversion sequences in general.
Turing Completeness

The untyped $\lambda$-calculus is Turing complete. This is usually shown not by mimicking a Turing machine in the $\lambda$-calculus, but rather by exploiting the fact that the Turing computable functions are the same class as the $\mu$-recursive functions [HS86, chapter 4]. In a lecture on theory of computation, you have probably learned that the $\mu$-recursive functions are obtained from the primitive recursive functions by so-called unbounded minimalization, while the primitive recursive functions are built from the 0-place zero function, projection functions and the successor function using composition and primitive recursion [LP81]. The proof that the untyped $\lambda$-calculus can compute all $\mu$-recursive functions is thus based on showing that each of the mentioned ingredients can be encoded in the untyped $\lambda$-calculus. While we are not going to study this, one crucial point is that it should be possible to
encode the natural numbers and the arithmetic operations in the untyped λ-calculus.
Term Language

We also say that we have defined a term language. A particular language is given by a signature, although for the untyped $\lambda$-calculus this is simply the set of constants $Const$. 
**Type Language**

We can say that we define a *type language*, i.e., a language consisting of types. A particular type language is characterized by giving a set of base types $\mathcal{B}$. One might also call $\mathcal{B}$ a *type signature*.

A typical example of a set of base types would be $\{\mathbb{N}, \text{bool}\}$, where $\mathbb{N}$ represents the natural numbers and `bool` the Boolean values $\bot$ and $\top$.

All that matters is that $\mathcal{B}$ is some fixed set “defined by the user”.
Types: Intuition

The type $\mathbb{N} \rightarrow \mathbb{N}$ is the type of a function that takes a natural number and returns a natural number.

The type $(\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N}$ is the type of a function that takes a function, which takes a natural number and returns a natural number, and returns a natural number.
Types Are Right-Associative

To save parentheses, we use the following convention: types associate to the right, so \( \mathbb{N} \to \mathbb{N} \to \mathbb{N} \) stands for \( \mathbb{N} \to (\mathbb{N} \to \mathbb{N}) \).

Recall that application associates to the left. This may seem confusing at first, but actually, it turns out that the two conventions concerning associativity fit together very neatly.
Raw Terms

In the context of typed versions of the \( \lambda \)-calculus, raw terms are terms built ignoring any typing conditions. So raw terms are simply terms as defined for the untyped \( \lambda \)-calculus, possibly augmented with type superscripts.
Augmenting with Types

So far, this is just syntax!
The notation $(\lambda x^\tau. e)$ simply specifies that binding occurrences of variables in simple type theory are tagged with a superscript, where the use of the letter $\tau$ makes it clear (in this particular context) that the superscript must be some type, defined by the grammar we just gave.
**Var and Const**

*Var* and *Const* are the sets of variables and constants, respectively, as for the **untyped λ-calculus**.
Sequences

A sequence is a collection of objects which differs from sets in that a sequence contains the objects in a certain order, and there can be multiple occurrences of an object.

We write a sequence containing the objects $o_1, \ldots, o_n$ as $\langle o_1, \ldots, o_n \rangle$, or sometimes simply $o_1, \ldots, o_n$.

If $\Omega$ is the sequence $o_1, \ldots, o_n$, then we write $\Omega, o$ for the sequence $\langle o_1, \ldots, o_n, o \rangle$ and $o, \Omega$ for the sequence $\langle o, o_1, \ldots, o_n \rangle$.

An empty sequence is denoted by $\langle \rangle$. 
Type Binding

We call an expression of the form \( x : \tau \) or \( c : \tau \) a type binding. The use of the letter \( \tau \) makes it clear (in this particular context) that the superscript must be some type, defined by the grammar we just gave.
Signatures in Various Formalisms

For propositional logic, we did not use the notion of signature, although we mentioned that strictly speaking, there is not just the language of propositional logic, but rather a language of propositional logic which depends on the choice of the variables.

In first-order logic, a signature was a pair \((F, P)\) defining the function and predicate symbols, although strictly speaking, the signature should also specify the arities of the symbols in some way. Recall that we did not bother to fix a precise technical way of specifying those arities. We were content with saying that they are specified in “some unambiguous way”.

In sorted logic, the signature must also specify the sorts of all symbols. But we did not study sorted logic in any detail.

In the untyped \(\lambda\)-calculus, the signature is simply the set of constants.

Summarizing, we have not been very precise about the notion of a
signature so far.

For \( \lambda \rightarrow \), the rules for “legal” terms become more tricky, and it is important to be formal about signatures.

In \( \lambda \rightarrow \), a signature associates a type with each constant symbol by writing \( c : \tau \).

Usually, we will assume that \( Const \) is clear from the context, and that \( \Sigma \) contains an expression of the form \( c : \tau \) for each \( c \in Const \), and in fact, that \( \Sigma \) is clear from the context as well. Since \( \Sigma \) contains an expression of the form \( c : \tau \) for each \( c \in Const \), it is redundant to give \( Const \) explicitly. It is sufficient to give \( \Sigma \).
Type Judgement

The expression

\[ \Gamma \vdash_\Sigma c \, x : \sigma \]

is called a type judgement. It says that given the signature \( \Sigma = x : \tau \) and the context \( \Gamma = c : \tau \to \sigma \), the term

\( c \, x \) has type \( \sigma \) or

\( c \, x \) is of type \( \sigma \) or

\( c \, x \) is assigned type \( \sigma \).

Recall that you have seen other judgements before.
∈ for Sequences?

Recall that $\Sigma$ is a sequence. By abuse of notation, we sometimes identify this sequence with a set and allow ourselves to write $c : \tau \in \Sigma$. We may also write $\Sigma \subseteq \Sigma'$ meaning that $c : \tau \in \Sigma$ implies $c : \tau \in \Sigma'$. 
System of Rules

Type assignment is defined as a system of rules for deriving type judgements, in the same way that we have defined derivability judgements for logics, and $\beta$-reduction for the untyped $\lambda$-calculus.
**Minimal Logic over →**

Recall the **sequent rules** of the “→ ∧” fragment of propositional logic. Consider now only the “→” fragment. We call this fragment **minimal logic over →**.

If you take the rule

\[ \Gamma, x : \tau, \Delta \vdash x : \tau \quad hyp \]

of \( \lambda \to \) and throw away the terms (so you keep only the types), you obtain essentially the rule for assumptions

\[ \Gamma \vdash A \quad (where \ A \in \Gamma) \]

of propositional logic.
Likewise, if you do the same with the rule

\[
\Gamma \vdash e : \sigma \rightarrow \tau \quad \Gamma \vdash e' : \sigma \\
\hline
\Gamma \vdash ee' : \tau
\]

\[
\text{app}
\]

of \(\lambda\rightarrow\), you obtain essentially the rule

\[
\Gamma \vdash A \rightarrow B \quad \Gamma \vdash A \\
\hline
\Gamma \vdash B
\]

\[
\rightarrow\text{-}E
\]

of propositional logic.

Finally, if you do the same with the rule

\[
\Gamma, x : \sigma \vdash e : \tau \\
\hline
\Gamma \vdash \lambda x^\sigma. e : \sigma \rightarrow \tau
\]

\[
\text{abs}
\]
of $\lambda \to$, you obtain essentially the rule

$$
\frac{A, \Gamma \vdash B}{\Gamma \vdash A \to B} \rightarrow I
$$

of propositional logic.

Note that in this setting, there is no analogous propositional logic rule for

$$
\frac{c : \tau \in \Sigma}{\Gamma \vdash c : \tau} \text{ assum}
$$

So for the moment, we can observe a close analogy between $\lambda \to$, for $\Sigma$ being empty, and the $\to$ fragment of propositional logic, which is also called minimal logic over $\to$.

Such an analogy between a type theory (of which $\lambda \to$ is an example) and a logic is referred to in the literature as Curry-Howard isomorphism.
[Tho91]. One also speaks of propositions as types [GLT89]. The isomorphism is so fundamental that it is common to characterize type theories by the logic they represent, so for example, one might say: \( \lambda \to \) is the type theory of minimal logic over \( \to \).
Subject Reduction

Subject reduction is the following property: reduction does not change the type of a term, so if $\vdash_{\Sigma} M : \tau$ and $M \rightarrow_{\beta} N$, then $\vdash_{\Sigma} N : \tau$. 
(Strongly) Normalizing $\beta$-Reduction

The simply-typed $\lambda$-calculus, unlike the untyped $\lambda$-calculus, is normalizing, that is to say, every term has a normal form. Even more, it is strongly normalizing, that is, this normal form is reached regardless of the reduction order.
An Alternative for $hyp$

One could also formulate $hyp$ as follows:

$$
\frac{x : \tau \in \Gamma}{\Gamma \vdash x : \tau} \quad hyp
$$

That would be in close analogy to LF, a system not treated here.
Schematic Types

In this example, you may regard $\sigma$ and $\tau$ as base types (this would require that $\sigma, \tau \in B$), but in fact, it is more natural to regard them as metavariables standing for arbitrary types. Whatever types you substitute for $\sigma$ and $\tau$, you obtain a derivation of a type judgement. This is in analogy to schematic derivations in a logic.

Note also that $\Sigma$ is irrelevant for the example and hence arbitrary.
Constants vs. Variables

In Example 3, we have \( f : \sigma \rightarrow \sigma \rightarrow \tau \in \Sigma \), and so \( f \) is a constant.
In Example 2, we have \( f : \sigma \rightarrow \sigma \rightarrow \tau \in \Gamma \), and so \( f \) is a variable.

Looking at the different derivations of the type judgement \( \Gamma \vdash f \, x \, x : \tau \) in Examples 2 and 3, you may find that they are very similar, and you may wonder: What is the point? Why do we distinguish between constants and variables?

In fact, one could simulate constants by variables. When setting up a type theory or programming language, there are choices to be made about whether there should be a distinction between variables and constants, and what it should look like. There is a famous epigram by Alan Perlis:

One man’s constant is another man’s variable.
For our purposes, it is much clearer conceptually to make the distinction. For example, if we want to introduce the natural numbers in our $\lambda \to$ language, then it is intuitive that there should be constants $1, 2, \ldots$ denoting the numbers. If $1, 2, \ldots$ were variables, then we could write strange expressions like $\lambda 2^{\mathbb{N} \to \mathbb{N}} \cdot y$, so we could use $2$ as a variable of type $\mathbb{N} \to \mathbb{N}$. 
Type Construction

Type construction is the problem of given a $\Sigma$, $\Gamma$ and $e$, finding a $\tau$ such that $\Sigma, \Gamma \vdash e : \tau$.

Sometimes one also considers the problem where $\Gamma$ is unknown and must also be constructed.
Term Congruence

$\alpha\beta\eta$-conversion is defined as for $\lambda \rightarrow$. Given two (extended) $\lambda$-terms $e$ and $e'$, it is decidable whether $e =_{\alpha\beta\eta} e'$. 
(Parametric) Polymorphism

In functional programming, you will come across functions that operate uniformly on many different types. For example, a function `append` for concatenating two lists works the same way on integer lists and on character lists. Such functions are called polymorphic. More precisely, this kind of polymorphism, where a function does exactly the same thing regardless of the type instance, is called parametric polymorphism, as opposed to ad-hoc polymorphism.

In a type system with polymorphism, the notion of base type (which is just a type constant, i.e., one symbol) is generalized to a type constructor with an arity $\geq 0$. A type constructor of arity $n$ applied to $n$ types is then a type. For example, there might be a type constructor `list` of arity 1, and `int` of arity 0. Then, `int list` is a type.

Note that application of a type constructor to a type is written in postfix
notation, unlike any notation for function application we have seen. However, other conventions exist, even within Isabelle. See [Pau96, Tho95b, Tho99] for details on the polymorphic type systems of functional programming languages.
Ad-hoc Polymorphism

Ad-hoc polymorphism, also called overloading, refers to functions that do different (although usually similar) things on different types. For example, a function \( \leq \) may be defined as 'a' \( \leq \) 'b' . . . on characters and 1 \( \leq \) 2 . . . on integers. In this case, the symbol \( \leq \) must be declared and defined separately for each type.

This is in contrast to parametric polymorphism, but also somewhat different from type classes.

Type classes are a way of “making ad-hoc polymorphism less ad-hoc” [HHPW96, WB89].
Type Classes

Type classes are a way of “making ad-hoc polymorphism less ad-hoc” [HHPW96, WB89].

Type classes are used to group together types with certain properties, in particular, types for which certain symbols are defined. For example, for some types, a symbol $\leq$ (which is a binary infix predicate) may exist and for some it may not, and we could have a type class `ord` containing all types for which it exists.

Suppose you want to sort a list of elements (smaller elements should come before bigger elements). This is only defined for elements of a type for which the symbol $\leq$ exists.

Note that while a symbol such as $\leq$ may have a similar meaning for different types (for example, integers and reals), one cannot say that it means exactly the same thing regardless of the type of the argument to
which it is applied. In fact, $\leq$ has to be defined separately for each type in $\text{ord}$.

This is in contrast to \textit{parametric polymorphism}, but also somewhat different from \textit{ad-hoc polymorphism}: The types of the symbols must not be declared separately. E.g., one has to declare only once that $\leq$ is of type $(a :: \text{ord}, \alpha)$.
Polymorphic Type Language

As before, we define a type language, i.e., a language consisting of types, and a particular type language is characterized by a giving a certain set of symbols $\mathcal{B}$. But unlike before, $\mathcal{B}$ is now a set of type constructors. Each type constructor has an arity associated with it just like a function in first-order logic. The intention is that a type constructor may be applied to types.

Following the conventions of ML [Pau96], we write types in postfix notation, something we have not seen before. I.e., the type constructor comes after the arguments it is applied to.

It makes perfect sense to view the function construction arrow $\rightarrow$ as type constructor, however written infix rather than postfix.

So the $\mathcal{B}$ is some fixed set “defined by the user”, but it should definitely always include $\rightarrow$. 

Smaus: CSMR; WS05/06
Type Substitutions

A type substitution replaces a type variable by a type, just like in first-order logic, a substitution replaces a variable by a term.
Syntactic Classes

A syntactic class is a class of types for which certain symbols are declared to exist. Isabelle has a syntax for such declarations. E.g., the declaration

\begin{verbatim}
sort ord < term
cost <= : ['a::ord, 'a] => bool
\end{verbatim}

may form part of an Isabelle theory file. It declares a type class \textit{ord} which is a \textbf{subclass} (that’s what the \textless{} means; in mathematical notation it will be written \textless{}\textgreater{}) of a class \textit{term}, meaning that any type in \textit{ord} is also in \textit{term}. We will write the “\textit{class judgement}” \textit{ord} \textless{} \textit{term}. The class \textit{term} must be defined elsewhere.

The second line declares a symbol \textless{}. Such a declaration is preceded by the keyword \textit{const}. The notation \(\alpha :: \textit{ord}\) stands for a type variable \textbf{constrained} to be in class \textit{ord}. So \textless{} is declared to be of type
\[ \alpha :: \text{ord}, \alpha \Rightarrow \text{bool}, \] meaning that it takes two arguments of a type in the class \textit{ord} and returns a term of type \textit{bool}. The symbol \( \Rightarrow (\Rightarrow) \) is the function type arrow in Isabelle. Note that the second occurrence of \( \alpha \) is written without :: \text{ord}. This is because it is enough to state the class constraint once.

Note also that \( \alpha :: \text{ord}, \alpha \Rightarrow \text{bool} \) is in fact just another way of writing \( \alpha :: \text{ord} \Rightarrow \alpha \Rightarrow \text{bool} \), similarly as for goals.

Haskell [HHPW96] has type classes but ML [Pau96] hasn’t.
Axiomatic Classes

In addition to declaring the syntax of a type class, one can axiomatize the semantics of the symbols. Again, Isabelle has a syntax for such declarations. E.g., the declaration

\[
\text{axclass } \text{order } < \text{ ord} \\
\text{order_refl: } ' 'x \leq x ' ' \\
\text{order_trans: } ' '\left[ | x \leq y; y \leq z | \right] \implies x \leq z ' '\]
\[
\ldots
\]

may form part of an Isabelle theory file. It declares an axiomatic type class \textit{order} which is a subclass of \textit{ord} defined above. The next two lines are the axioms. Here, \texttt{order_refl} and \texttt{order_trans} are the names of the axioms. Recall that \( \implies \) is the implication symbol in Isabelle (that is to say, the metalevel implication).
Whenever an Isabelle theory declares that a type is a member of such a class, it must prove those axioms. The rationale of having axiomatic classes is that it allows for proofs that hold in different but similar mathematical structures to be done only once. So for example, all theorems that hold for dense orders can be proven for all dense orders with one single proof.
Members of a Type Class

One also speaks of a type being an instance of a type class, but this is slightly confusing, since we also say that a type can be an instance of another type, e.g., \( \mathbb{N} \to \mathbb{N} \) is an instance of \( \alpha \), since \( \alpha[\alpha \leftarrow (\mathbb{N} \to \mathbb{N})] = \mathbb{N} \to \mathbb{N} \). So it is better to speak of a member of a type class.

Isabelle provides a syntax for declaring that a type is a member of a type class, e.g.

\[
\text{instance nat :: ord}
\]

declares that type nat is a member of class ord.

If the class \( \kappa \) is a syntactic class, such a declaration must come with a definition of the symbols that are declared to exist for \( \kappa \).

In addition, if \( \kappa \) is an axiomatic class, such a declaration must come with a proof of the axioms.
If a type $\tau$ is (by declaration) a member of class $\kappa$, we write the “class judgement” $\tau :: \kappa$. 
Renaming

Whenever a rule is applied, the metavariables occurring in it must be renamed to fresh variables to ensure that no metavariable in the rule has been used in the proof before.

The notion fresh is often casually used in logic, and it means: this variable has never been used before. To be more precise, one should say: never been used before in the relevant context.
Unification

The mechanism to instantiate metavariables as needed is called (higher-order) unification. Unification is the process of finding a substitution that makes two terms equal.

We will now see more formally what it is and later also where it is used.
Type Class Syntax

The set $\mathcal{K}$ we gave is incomplete and just exemplary. So the set of type classes involved in an Isabelle theory is a finite set of names (written lower-case), typically including ord, order, and lattice. We have seen some Isabelle syntax for declaring the type classes previously. In grammars and elsewhere, $\kappa$ is the letter we use for “type class”.
Type Constructor Syntax

As before, the set $B$ we gave is is **incomplete** (there are “…”’) and just **exemplary**. We might call $B$ a **type signature**.

Note also that an _ is used to denote the **arity of a type constructor**.

- _ list means that list is unary type constructor;
- _ → _ means that → is a binary infix type constructor.

The notation using _ is slightly abusive since the _ is not actually part of the type constructor. _ list is not a type constructor; list is a type constructor.

So the set of type constructors involved in an Isabelle theory is a finite set of names (written lower-case) with each having an arity associated, typically including bool, →, and list. Note however that bool is fundamental (since object level predicates are modeled as functions
taking terms to a Boolean), and so is $\rightarrow$, the constructor of the function space between two types.

In grammars and elsewhere, $T$ is the letter we use for “type constructor”.
→ as Type Constructor

In $\lambda \to$, types were built from base types using a "special symbol" $\to$. When we generalize $\lambda \to$ to a $\lambda$-calculus with polymorphism, this "special symbol" becomes a type constructor. However, the syntax is still special, and it is interpreted in a particular way.
Polymorphic Types Syntax

\[ \tau ::= \alpha \mid \alpha :: \kappa \mid (\tau, \ldots, \tau) \ T \quad (\alpha \text{ is type variable}) \]

is a grammar defining what polymorphic types are (syntactically). As before, \( \tau \) is the non-terminal we use for (now: polymorphic) types. This grammar is not exemplary but generic, and it deserves a closer look.

A type variable is a variable that stands for a type, as opposed to a term. We have not given a grammar for type variables, but assume that there is a countable set of type variables disjoint from the set of term variables. We use \( \alpha \) as the non-terminal for a type variable (abusing notation, we often also use \( \alpha \) to denote an actual type variable).

First, note that a type variable may be followed by a class constraint \( :: \kappa \) (recall that \( \kappa \) is the non-terminal for type classes). However, a type variable is not necessarily followed by such a constraint, for example if
the type variable already occurs elsewhere and is constrained in that place. *We have already seen this.*

Moreover, a polymorphic type is obtained by preceding a type constructor with a tuple of types. The arity of the tuple must be equal to the declared arity of the type constructor.

It is not shown here that for some special type constructors, such as →, the argument may also be written infix.
Solutions for Unification Problems

A solution for \(?X + ?Y =_{\alpha\beta\eta} x + x\) is \([?X \leftarrow x, ?Y \leftarrow x]\).

A solution for \(?P(x) =_{\alpha\beta\eta} x + x\) is \([?P \leftarrow (\lambda y. y + y)]\).

A solution for \(f(?X x) =_{\alpha\beta\eta} ?Y x\) is \([?X \leftarrow (\lambda z. z), ?Y \leftarrow (\lambda z. f z)]\).

Three solutions for \(?F(?G x) =_{\alpha\beta\eta} f(g(x))\) are

\[
\begin{align*}
?F & \leftarrow f, ?G \leftarrow g, \\
?F & \leftarrow (\lambda x. f(g x)), ?G \leftarrow (\lambda x. x), \\
?F & \leftarrow (\lambda x. x), ?G \leftarrow (\lambda x. f(g x))
\end{align*}
\]
Unification Modulo

Unification of terms $e, e'$ modulo $\alpha \beta$ means finding a substitution $\theta$ for metavariables such that $\theta(e) =_{\alpha \beta} \theta(e')$.

Likewise, unification of terms $e, e'$ modulo $\alpha \beta \eta$ means finding a substitution $\sigma$ for metavariables such that $\sigma(e) =_{\alpha \beta \eta} \sigma(e')$. 

Back to main referring slide
Encoding Syntax
Metatheory: Motivation

Previously, we have seen the (polymorphically) typed \( \lambda \)-calculus (with type classes).

Now, we will see how the typed \( \lambda \)-calculus can be used as a metalanguage for representing the syntax of an object logic, e.g. first-order logic.
**Metatheory: Motivation**

Previously, we have seen the (polymorphically) typed $\lambda$-calculus (with type classes).

Now, we will see how the typed $\lambda$-calculus can be used as a metalanguage for representing the syntax of an object logic, e.g. first-order logic.

Idea: An object-level proposition is a meta-level term.

Metalogic type $o$ for propositions.

The terms of type $o$ encode object level propositions: $\phi \in Prop$ iff $\Gamma \vdash \phi : o$. 
Metatheory: Motivation

Previously, we have seen the (polymorphically) typed \( \lambda \)-calculus (with type classes).

Now, we will see how the typed \( \lambda \)-calculus can be used as a metalanguage for representing the syntax of an object logic, e.g. first-order logic.

Idea: An object-level proposition is a meta-level term.

Metalogic type \( o \) for propositions.

The terms of type \( o \) encode object level propositions:

\[ \phi \in Prop \iff \Gamma \vdash \phi : o. \]

Later: How do we represent the proofs/provability?
Why Have a Metalogic?

Why should we have a meta- or framework logic rather than implementing provers for each object logic individually?

+ Implement ‘core’ only once

+ Shared support for automation

+ Conceptual framework for exploring what a logic is

But

+/− Metalayer between user and logic

− Makes assumptions about structure of logic
\( \lambda \rightarrow : \) Review

\( \lambda \rightarrow \) is sufficient for presentation here (no polymorphism, type classes).

- Syntax for types (\( \mathcal{B} \) a set of base types, \( T \in \mathcal{B} \))

\[
\tau ::= T \mid \tau \to \tau
\]

Examples: \( \mathbb{N}, \mathbb{N} \rightarrow \mathbb{N}, (\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N}, \mathbb{N} \rightarrow \mathbb{N} \rightarrow \mathbb{N} \)

- Syntax for terms: \( \lambda \)-calculus augmented with types

\[
e ::= x \mid c \mid (ee) \mid (\lambda x^\tau . e)
\]

\((x \in \text{Var}, c \in \text{Const})\)
Type Assignment

- Signature \( \Sigma ::= \varnothing | \Sigma, c : \tau. \)
- Context \( \Gamma ::= \varnothing | \Gamma, x : \tau. \)
- Type assignment rules

\[
\frac{c : \tau \in \Sigma}{\Gamma \vdash c : \tau} \quad \text{assum} \quad \frac{\Gamma, x : \tau, \Delta \vdash x : \tau}{\Gamma \vdash x : \tau} \quad \text{hyp}
\]

\[
\frac{\Gamma \vdash e : \sigma \rightarrow \tau \quad \Gamma \vdash e' : \sigma}{\Gamma \vdash ee' : \tau} \quad \text{app} \quad \frac{\Gamma, x : \sigma \vdash e : \tau}{\Gamma \vdash \lambda x^\sigma . e : \sigma \rightarrow \tau} \quad \text{abs}
\]
Representing Syntax of Propositional Logic

Let the following fragment of propositional logic, which we call $\textit{Prop}$, be our object logic:

$$P ::= \, x \mid \neg P \mid P \land P \mid P \rightarrow P$$
Representing Syntax of Propositional Logic

Let the following fragment of propositional logic, which we call \( \text{Prop} \), be our object logic:

\[
P ::= x \mid \neg P \mid P \wedge P \mid P \rightarrow P
\]

Let \( \lambda \rightarrow \) be our metalogic. Declare

- \( \mathcal{B} = \{ o \} \).
- **Signature** assigns types to constants:

\[
\Sigma = \langle \text{not} : \quad \text{and} : \quad \text{imp} : \rangle
\]
Representing Syntax of Propositional Logic

Let the following fragment of propositional logic, which we call $Prop$, be our object logic:

$$P ::= x \mid \neg P \mid P \land P \mid P \rightarrow P$$

Let $\lambda \rightarrow$ be our metalogic. Declare

- $\mathcal{B} = \{o\}$.
- **Signature** assigns types to constants:

$$\Sigma = \langle not : o \rightarrow o, and : o \rightarrow o \rightarrow o, imp : o \rightarrow o \rightarrow o \rangle$$

- **Context** assigns types to variables.
Digression: Programming Languages

\( \lambda \to \) is the theory underlying typed functional programming. Our declaration of \( B \) and \( \Sigma \) on the previous slide corresponds to the declaration of an algebraic datatype in a functional programming language [Pau96]:

\[
\text{datatype } Prop = \\
\quad \text{VarInject of Variable} \quad | \quad \text{not of Prop} \\
\quad | \quad \text{and of Prop} \times \text{Prop} \quad | \quad \text{imp of Prop} \times \text{Prop}
\]
Example of First-Order Syntax

\[ a : o \vdash \text{imp} (\text{not } a) \ a : o \]
Example of First-Order Syntax

\[ a : o \vdash \text{imp} \ (\text{not} \ a) \ a : o \]

\[ a : o \vdash \text{imp} : o \rightarrow o \rightarrow o \quad \frac{a : o \vdash \text{not} : o \rightarrow o}{a : o \vdash a : o} \]

\[ a : o \vdash \text{imp} \ (\text{not} \ a) : o \rightarrow o \quad \frac{a : o \vdash \text{not} a : o}{a : o \vdash a : o} \]

\[ a : o \vdash \text{imp} \ (\text{not} \ a) \ a : o \]

Applications of \textit{hyp} and \textit{assum} suppressed. Otherwise always rule \textit{app}. 
Non-example of First-Order Syntax

\[ a : o \vdash \text{not} (\text{imp} \ a) \ a : o \]
Non-example of First-Order Syntax

\[ a : o \vdash \neg (\text{imp } a) \quad a : o \]

\[ a : o \vdash \neg : o \rightarrow o \]

\[ a : o \vdash \text{imp} : o \rightarrow o \rightarrow o \quad a : o \vdash a : o \]

\[ a : o \vdash \text{imp} a : o \rightarrow o \]

\[ ??? \]
Non-example of First-Order Syntax

\[ a : o ⊢ \text{not} (\text{imp} \ a) \ a : o \]

\[ \frac{a : o \vdash \text{imp} : o \rightarrow o \rightarrow o \quad a : o \vdash a : o}{\vdash a : o \rightarrow o} \]

\[ a : o \vdash \text{imp} a : o \rightarrow o \]

No proof possible! (Requires analysis of normal forms.)
Bijection between $Prop$ and $o$

We desire bijection $⌜·⌝ : Prop → o$ that is

- **adequate**: each proposition in $Prop$ can be represented by a $\lambda\rightarrow$-term of type $o$:

\[ P ∈ Prop \text{ then } Γ ⊢ ⌜P⌝ : o \]
**Bijection between $\mathit{Prop}$ and $o$**

We desire bijection $\lbrack \cdot \rbrack : \mathit{Prop} \rightarrow o$ that is

- **adequate**: each proposition in $\mathit{Prop}$ can be represented by a $\lambda \rightarrow$-term of type $o$:

  $$P \in \mathit{Prop} \text{ then } \Gamma \vdash \lbrack P \rbrack : o$$

- **faithful**: each $\lambda \rightarrow$ term of type $o$ represents a proposition in $\mathit{Prop}$:

  $$\Gamma \vdash t : o \text{ then } \lbrack t \rbrack^{-1} \in \mathit{Prop}$$
Adequacy of Bijection

Example: \((\neg a) \rightarrow b \in Prop \) therefore \(imp \ (not \ a) \ b : o\)
Adequacy of Bijection

Example: \((\neg a) \rightarrow b \in Prop\) therefore \(imp\ (not\ a)\ b: o\)

Formalize mapping \(\llbracket \cdot \rrbracket:\)

\[
\begin{align*}
\llbracket x \rrbracket &= x & \text{for } x \text{ a variable} \\
\llbracket \neg P \rrbracket &= \text{not } \llbracket P \rrbracket \\
\llbracket P \land Q \rrbracket &= \text{and } \llbracket P \rrbracket \llbracket Q \rrbracket \\
\llbracket P \rightarrow Q \rrbracket &= \text{imp } \llbracket P \rrbracket \llbracket Q \rrbracket
\end{align*}
\]
Adequacy of Bijection

Example: \((\neg a) \rightarrow b \in Prop\) therefore \(imp\ (not\ a)\ b: o\)

Formalize mapping \(\dashv\cdot\)\:

\[
\begin{align*}
\dashv x & = x \quad \text{for } x \text{ a variable} \\
\dashv \neg P & = not \dashv P \\
\dashv P \land Q & = and \dashv P \dashv Q \\
\dashv P \rightarrow Q & = imp \dashv P \dashv Q
\end{align*}
\]

Formal statement accounts for variables:

If \(P \in Prop\), and if for each propositional variable \(x\) in \(P\), we have \(x: o \in \Gamma\), then \(\Gamma \vdash \dashv P: o\).
Adequacy of Bijection

Example: \(( \neg a ) \rightarrow b \in \text{Prop} \) therefore \( \text{imp} ( \text{not} \ a ) \ b : o \)

Formalize mapping \( \vdash \cdot \vdash \):

\[
\begin{align*}
\vdash x \vdash &= x & \text{for } x \text{ a variable} \\
\vdash \neg P \vdash &= \text{not } \vdash P \vdash \\
\vdash P \land Q \vdash &= \text{and } \vdash P \vdash \vdash Q \vdash \\
\vdash P \rightarrow Q \vdash &= \text{imp } \vdash P \vdash \vdash Q \vdash 
\end{align*}
\]

Formal statement accounts for variables:

If \( P \in \text{Prop} \), and if for each propositional variable \( x \) in \( P \), we have \( x : o \in \Gamma \), then \( \Gamma \vdash \vdash P \vdash : o \). Proof by induction.
**Faithfulness of Bijection**

Define \( \Gamma \cdot \neg^{-1} \)

\[
\begin{align*}
\Gamma x^{-1} &= x & \text{for } x \text{ a variable} \\
\Gamma \text{ not } P^{-1} &= \neg \Gamma P^{-1} \\
\Gamma \text{ and } P \ Q^{-1} &= \Gamma P^{-1} \land \Gamma Q^{-1} \\
\Gamma \text{ imp } P \ Q^{-1} &= \Gamma P^{-1} \rightarrow \Gamma Q^{-1}
\end{align*}
\]
Faithfulness of Bijection

Define \( \gamma \cdot \neg^{-1} \)

\[
\gamma x^{-1} = x \\
\gamma \text{not } P^{-1} = \neg \gamma P^{-1} \\
\gamma \text{and } P^{-1} Q^{-1} = \gamma P^{-1} \land \gamma Q^{-1} \\
\gamma \text{imp } P^{-1} Q^{-1} = \gamma P^{-1} \rightarrow \gamma Q^{-1}
\]

For bijection, should have \( \gamma P^{-1} = P \) and \( \gamma t^{-1} = t \).
Former is trivial, but what about latter?
\( \Gamma t \vdash t^{-1} \) Is not Total

Example: For \( t = \text{not } ((\lambda x^o. x)a) \), we have \( a : o \vdash t : o \)

\[
\begin{align*}
  &a : o, x : o \vdash x : o \\
  &\frac{}{a : o \vdash \lambda x^o.x : o \rightarrow o} \text{abs} \\
  &\frac{a : o \vdash \lambda x^o.x : o \rightarrow o}{a : o \vdash a : o} \text{app} \\
  &\frac{a : o \vdash \text{not} : o \rightarrow o}{a : o \vdash (\lambda x^o.x) a : o} \text{app} \\
  &\frac{}{a : o \vdash \text{not } ((\lambda x^o.x) a) : o} \text{app}
\end{align*}
\]

But \( \Gamma t \vdash t^{-1} \) is undefined!
Normal Forms

If $t : o$, then there exists a $t'$ such that $t \equiv_{\beta\eta} t'$, where $t' : o$ and $t'$ is in canonical ($\beta\eta$-long) normal form, e.g.

\[
\begin{align*}
\text{not } ((\lambda x^o . x) a) & \equiv_{\beta\eta} \text{not } a \\
\text{not} & \equiv_{\beta\eta} \lambda x^o . \text{not } x \\
\text{imp } (\text{not } ((\lambda x^o . x) a)) & \equiv_{\beta\eta} \lambda x^o . \text{imp } (\text{not } a) \ x
\end{align*}
\]
Bijection Theorem

The encoding $\Gamma \cdot \neg$ is a bijection between propositional formulae with variables in $\Gamma$ and canonical terms $t'$, where $\Gamma \vdash t' : o$. 
Bijection Theorem

The encoding \( \Gamma \cdot \neg \) is a bijection between propositional formulae with variables in \( \Gamma \) and canonical terms \( t' \), where \( \Gamma \vdash t' : o \).

**Proof**: Based on normalization

\[
\begin{align*}
  x: \sigma & \vdash e: \tau \\
  \vdash \lambda x^\sigma.e: \sigma \rightarrow \tau & \text{\(abs\)} \\
  \vdash \lambda x^\sigma.e: \sigma \rightarrow \tau & \vdash e': \sigma \\
  \vdash (\lambda x^\sigma.e)e': \tau & \text{\(app\)} \\
  \vdash e[x \leftarrow e']: o & \Rightarrow \\
\end{align*}
\]
Bijection Theorem

The encoding $\Gamma \cdot \neg$ is a bijection between propositional formulae with variables in $\Gamma$ and canonical terms $t'$, where $\Gamma \vdash t' : o$.

**Proof:** Based on normalization

\[
\frac{x : \sigma \vdash e : \tau}{\vdash \lambda x^\sigma . e : \sigma \rightarrow \tau}^{abs}
\]

\[
\frac{\vdash e' : \sigma}{\vdash (\lambda x^\sigma . e)e' : \tau}^{app}
\]

$\Rightarrow \vdash e[x \leftarrow e'] : \tau$

**Corollary:** If $t : o$ then $t =_{\beta\eta} t'$ and $\Gamma t' \neg^{-1} \in Prop$ for some canonical $t'$. 
Representing Syntax of First-Order Logic

In $Prop$, we only have the **syntactic category** of formulae (propositions), represented in $\lambda \rightarrow$ by the type $o$. 
Representing Syntax of First-Order Logic

In Prop, we only have the syntactic category of formulae (propositions), represented in $\lambda \rightarrow$ by the type $o$. In first-order logic, we also have the syntactic category of terms. For representation in $\lambda \rightarrow$, we now introduce type $i$, so $\mathcal{B} = \{i, o\}$. 
Representing Syntax of First-Order Logic

In $Prop$, we only have the syntactic category of formulae (propositions), represented in $\lambda \to$ by the type $o$.
In first-order logic, we also have the syntactic category of terms. For representation in $\lambda \to$, we now introduce type $i$, so $\mathcal{B} = \{i, o\}$.

Just like $\Gamma \vdash a : o$ means that $a$ represents a proposition,
$\Gamma \vdash t : i$ means that $t$ represents a term.
Example: First-Order Arithmetic (FOA)

Following fragment of FOA is our object level language:

Terms \[ T ::= x \mid 0 \mid sT \mid T + T \mid T \times T \]

Formulae \[ F ::= T = T \mid \neg F \mid F \land F \mid F \rightarrow F \]
Example: First-Order Arithmetic (FOA)

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Terms \( T ::= x \mid 0 \mid sT \mid T + T \mid T \times T \)

Formulae \( F ::= T = T \mid \neg F \mid F \land F \mid F \rightarrow F \)

In \( \lambda \rightarrow \) (on metalevel), we define signature \( \Sigma = \Sigma_T \cup \Sigma_F \):

\[ \Sigma_T = \langle zero : i, succ : i \rightarrow i, plus : i \rightarrow i \rightarrow i, \]
\[ times : i \rightarrow i \rightarrow i \rangle \]

\[ \Sigma_F = \langle eq : i \rightarrow i \rightarrow o, not : o \rightarrow o, and : o \rightarrow o \rightarrow o, \ldots \rangle \]

Example: \( \lceil x + s 0 \rceil = \)
Example: First-Order Arithmetic (FOA)

Following fragment of FOA is our object level language:

Terms \( T ::= x \mid 0 \mid sT \mid T + T \mid T \times T \)

Formulae \( F ::= T = T \mid \neg F \mid F \land F \mid F \rightarrow F \)

In \( \lambda \rightarrow \) (on metalevel), we define signature \( \Sigma = \Sigma_T \cup \Sigma_F \):

\[
\Sigma_T = \langle \text{zero} : i, \text{succ} : i \rightarrow i, \text{plus} : i \rightarrow i \rightarrow i, \\
\text{times} : i \rightarrow i \rightarrow i \rangle
\]

\[
\Sigma_F = \langle \text{eq} : i \rightarrow i \rightarrow o, \text{not} : o \rightarrow o, \text{and} : o \rightarrow o \rightarrow o, \ldots \rangle
\]

Example: \( \llbracket x + s 0 \rrbracket = \text{plus} x (\text{succ} \text{ zero}) \).
Encoding FOL in General

In general, to encode some first-order language, we must define $\Sigma_F$ and $\Sigma_P$ so that for each $n$-ary $f \in \mathcal{F}$, $p \in \mathcal{P}$

$$f_{enc} : \underbrace{i \rightarrow \ldots \rightarrow i}_{n \text{ times}} \rightarrow i \in \Sigma_F,$$

$$p_{enc} : \underbrace{i \rightarrow \ldots \rightarrow i}_{n \text{ times}} \rightarrow o \in \Sigma_P,$$

and then $\llbracket f(t_1, \ldots t_n) \rrbracket = f_{enc} \llbracket t_1 \rrbracket \ldots \llbracket t_n \rrbracket$ and $\llbracket p(t_1, \ldots t_n) \rrbracket = p_{enc} \llbracket t_1 \rrbracket \ldots \llbracket t_n \rrbracket$.

Abusing notation, we might skip the subscript $enc$. 

Quantifiers in First-Order Syntax

Along the same lines, one might suggest

$$\text{all} : \text{var} \rightarrow o \rightarrow o,$$

so

$$\forall x. P \dashv \equiv \text{all } x \quad \text{⌜} P \text{⌝}$$

But this approach has some problems:
Quantifiers in First-Order Syntax

Along the same lines, one might suggest

\[ \text{all} : \text{var} \rightarrow \text{o} \rightarrow \text{o}, \quad \text{so} \quad \forall x. P \downarrow = \text{all} x \uparrow P \uparrow \]

But this approach has some problems:
- Variables are also terms, so “\text{var} \subseteq \text{i}”? No subtyping!
Quantifiers in First-Order Syntax

Along the same lines, one might suggest

\[
\text{all} : \text{var} \to o \to o, \quad \text{so} \quad \forall x. P \equiv \text{all } x \ P
\]

But this approach has some problems:

• Variables are also terms, so “\text{var} \subseteq i”? No subtyping!

• \text{all} is not a binding operator in \lambda \to. E.g.,

\[
(p(x) \land \forall x. q(x))[x \leftarrow a] \text{ cannot be modeled as } (\text{and} (p\ x)(\text{all} \ x \ (q\ x)))[x \leftarrow a].
\]
Higher-Order Abstract Syntax (HOAS)

Example, full FOA: \( F ::= \ldots \forall x. A \mid \exists x. A \)

\[ \Sigma = \Sigma_T \cup \Sigma_F \cup \Sigma_Q : \]

\[ \Sigma_Q = \langle all : (i \to o) \to o, exists : (i \to o) \to o \rangle \]
Higher-Order Abstract Syntax (HOAS)

Example, full FOA: \( F ::= \ldots \forall x. A \mid \exists x. A \)

\[ \Sigma = \Sigma_T \cup \Sigma_F \cup \Sigma_Q: \]

\[ \Sigma_Q = \langle \text{all}: (i \to o) \to o, \text{exists}: (i \to o) \to o \rangle \]

Extend the definition of \( \mathord{\neg} \):

\[
\neg \forall x. P \equiv \text{all} (\lambda x^i. \neg P)
\]

\[
\neg \exists x. P \equiv \text{exists} (\lambda x^i. \neg P)
\]

Faithfulness and adequacy as before.
Examples

\[ \forall x. x = x \]  
\[ \forall x. \exists y. \neg(x + x = y) \]  

\[ = \quad all(\lambda x^i. eq x x) \]  
\[ = \quad all(\lambda x^i. exists(\lambda y^i. not(eq(plus x x) y))) \]
Examples

\[
\forall x. x = x \ \ \ \ \ \ \ \ \ \ \ \ \ = \ \ all(\lambda x^i. eq \ x \ x)
\]

\[
\forall x. \exists y. \neg (x + x = y) \ \ \ \ \ \ =
\]

\[
all(\lambda x^i. \exists y^i. \neg (eq \ (plus \ x \ x) \ y))
\]

Example derivation (all but one steps use rule \textit{app}):

\[
\frac{x : i \vdash eq : i \rightarrow i \rightarrow o \quad x : i \vdash x : i}{x : i \vdash eq \ x : i \rightarrow o \quad x : i \vdash x : i}
\]

\[
\frac{x : i \vdash eq \ x \ x : o}{\vdash \lambda x^i. eq \ x \ x : i \rightarrow o \quad \text{abs}}
\]

\[
\vdash all : (i \rightarrow o) \rightarrow o
\]

\[
\vdash all(\lambda x^i. eq \ x \ x) : o
\]
Order

Order of a type: For type $\tau$ written $\tau_1 \rightarrow \ldots \rightarrow \tau_n$, right associated, $\tau_n \in \mathcal{B}$:

- $\text{Ord}(\tau) = 0$ if $\tau \in \mathcal{B}$, i.e., if $n = 1$;
- $\text{Ord}(\tau) = 1 + \max(\text{Ord}(\tau_i)),$
Order

Order of a type: For type \( \tau \) written \( \tau_1 \rightarrow \ldots \rightarrow \tau_n \), right associated, \( \tau_n \in B \):

- \( \text{Ord}(\tau) = 0 \) if \( \tau \in B \), i.e., if \( n = 1 \);
- \( \text{Ord}(\tau) = 1 + \max(\text{Ord}(\tau_i)) \),

Intuition: “functions as arguments”.

A type of order 1 is first-order, of order 2 second-order etc.

A type of order \( \geq 1 \) is called higher order.
Why “Higher Order”? 

Constants representing propositional operators (logical symbols) or non-logical symbols are first-order (hence first-order syntax):

$$\text{and} : o \rightarrow o \rightarrow o$$
Why “Higher Order”?

Constants representing propositional operators (logical symbols) or non-logical symbols are first-order (hence first-order syntax):

\[ \text{and} : o \rightarrow o \rightarrow o \]

Variable binding operators are higher-order (hence higher-order syntax):

\[ \text{all} : (i \rightarrow o) \rightarrow o \]
Exercise: Summation Operator

What is the order of the summation operator $\sum$?
Exercise: Summation Operator

What is the order of the summation operator $\sum$?

$$sum : i \rightarrow i \rightarrow (i \rightarrow i) \rightarrow i$$

$$\sum_{x=0}^{n} (x + 2) =$$
Exercise: Summation Operator

What is the order of the summation operator $\sum$?

$$\text{sum} : i \to i \to (i \to i) \to i$$

$$\sum_{x=0}^{n} (x + 2) = \text{sum zero n (} \lambda x^i . \text{plus} x (\text{succ succ zero}) \text{)}$$

So the order is 2.
Why “Abstract”?  
HOAS looks quite different from the concrete object level syntax and hence “abstracts” from this object level syntax. More specifically, different object level binding operators are represented by a combination of a constant \((all, exists)\) and the generic \(\lambda\)-operator. Thanks to this technique, standard operations on syntax need no special encoding, but are supported implicitly by \(\lambda\mapsto\). We will now see this.
Binding

Binding on the object level and metalevel coincide. So in $\forall x. P$, all occurrences of $x$ in $P$ are bound, and likewise, in $\forall \text{all}(\lambda x^i. \Box P \Box)$, all occurrences of $x$ in $\Box P \Box$ are bound.

This provides support for substitution.
Substitution

Recall rules for $\forall$:

$$\forall x. P(x) \quad \forall\text{-}E$$

$$\frac{\forall x. P(x)}{P(t)}$$
Substitution

Recall rules for $\forall$:

$$\frac{\forall x. P(x)}{P(t)} \forall\text{-}E$$

$$\rightsquigarrow \frac{all \ P}{P(t)} \forall\text{-}E$$
Substitution

Recall rules for $\forall$:

\[
\dfrac{\forall x. P(x)}{P(t)} \quad \forall\text{-E} \quad \leadsto \quad \dfrac{\text{all } P}{P(t)} \quad \forall\text{-E}
\]

\[
\dfrac{\forall x. x = x}{x = x[x \leftarrow 0]} \quad \forall\text{-E}
\]

Now apply substitution. . .
Substitution

Recall rules for $\forall$:

$$\frac{\forall x. \ P(x)}{P(t)} \ \forall-E$$

$$\frac{\forall x. x = x}{0 = 0} \ \forall-E$$

Now apply substitution...
Substitution

Recall rules for $\forall$:

$\forall x. P(x)$ $\Rightarrow \forall-E$

$P(t) \Rightarrow P(t)$ $\forall-E$

$\forall x. x = x$ $\Rightarrow \forall-E$

$0 = 0 \Rightarrow \forall-E$

Now apply substitution. . .

Now apply $\beta$-reduction. . .
Substitution

Recall rules for $\forall$:

$$\forall x. P(x) \quad \frac{\forall-E}{P(t)}$$

$$\forall x. x = x \quad \frac{\forall-E}{0 = 0}$$

$$\begin{align*}
\forall x. P(x) & \rightsquigarrow all P \\
(\lambda x^i. eq x x) & \rightsquigarrow eq zero zero
\end{align*}$$

Now apply substitution. . .
Now apply $\beta$-reduction. . .
We now understand “marked positions in a formula”.

Smaus: CSMR; WS05/06
Equivalence under Bound Variable Renaming

On the object level, formulae are equivalent under renaming of bound variables:

$$(\forall x. P \leftrightarrow \forall y. P[x \leftarrow y])$$
Equivalence under Bound Variable Renaming

On the object level, formulae are equivalent under renaming of bound variables:

\[(\forall x. P \leftrightarrow \forall y. P[x \leftarrow y])\]

Likewise, on the metalevel, formulae obtained by bound variable renaming are $\alpha$-equivalent:

\[\forall x. P \alpha \equiv \forall y. P[x \leftarrow y]\]
Summary of Encoding Syntax
<table>
<thead>
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<th>Metalanguage</th>
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<td>Term, Prop</td>
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Smaus: CSMR; WS05/06
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<td>Term, Prop</td>
<td>{i, o} = B</td>
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<td>( \land )</td>
<td>and : ( o \rightarrow o \rightarrow o )</td>
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<td><strong>Binding operator</strong></td>
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<tr>
<td>( \forall )</td>
<td>all : ( (i \rightarrow o) \rightarrow o )</td>
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<td><strong>Meaningful expr.</strong></td>
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<td>( a \land b \in Prop )</td>
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<tr>
<td><strong>Meaningful expr.</strong></td>
<td><strong>2nd-order constant</strong> ( \text{all} : (i \to o) \to o )</td>
</tr>
<tr>
<td><em>a \land b \in Prop</em></td>
<td><strong>Member of type</strong> ( (\text{and} \ a \ b) : o )</td>
</tr>
</tbody>
</table>
More Detailed Explanations
Representing Syntax and Semantics

In the following, we will distinguish between the object logic and the metalogic. We have already seen this kind of distinction before. The object logic, or user-defined theory if you like, has a syntax and has a notion of proof. Both must be represented in the metalogic. This is what this lecture and a later lecture are about.
Core

By the core we mean the syntax and proof rules of the metalogic. These should be simple, so that one can be reasonably confident that the implementation is correct.
Shared Support for Automation

There are some general techniques involved in automating the search for a proof that work for various object logics. It is therefore useful to implement these techniques on a higher level, rather than considering each object logic individually.
Conceptual Framework

By implementing various object logics within the same metalogic, we can compare the object logics in a more formal way.
Metalayer

Having a logic and a metalogic can be very mind-boggling. We already experienced that when working with Isabelle, it is sometimes confusing to know whether we are at the level of a particular theory, or at the level of general Isabelle syntax, or at the level of ML, the programming language that Isabelle is implemented in.
Assumptions

Designing a metalogic is a bold endeavor. How are we supposed to know that the metalogic is expressive enough to encode any object logic someone might invent? There is probably no general satisfactory answer to this question. In fact, we make assumptions that object logics are of a certain kind. This is related to the nature of implication. Roughly speaking, we assume logics and proof systems for which the deduction theorem holds, i.e., for which $A \vdash B$ ($B$ is derivable under assumption $A$) holds if and only if $\vdash A \rightarrow B$ ($A \rightarrow B$ is derivable without any assumption). There are logics (modal, relevance logics) for which the theorem does not hold [BM00].
Syntax Encoding

$\phi \in Prop$ iff $\vdash \phi \vec{} \in o$ means: The object level formula $\phi$ is a well-formed (according to the syntactic rules of the object logic) proposition if and only if its encoding in the metalogic, written $\vdash \phi \vec{}$, has type $o$. 

Back to main referring slide
Why First-Order?

We will now show an approach to representing the syntax an object logic in $\lambda \rightarrow$. This approach is called first-order syntax. For the moment, it is better not to worry about why the approach is called that. This will become clear later.
Which Fragment?

We consider here the fragment of propositional logic containing the logical symbols $\neg$, $\land$, $\rightarrow$, and we call it $Prop$. We chose this small fragment because it is sufficient for our purposes, namely to demonstrate how encoding syntax in $\lambda$ works. It would be trivial to adapt everything in the sequel to include $\lor$ or $\bot$. 
Metalevel Constants

Now the object/meta distinction starts becoming mind-boggling!
We declare

$$\Sigma = \langle \text{not} : o \rightarrow o, \text{and} : o \rightarrow o \rightarrow o, \text{imp} : o \rightarrow o \rightarrow o \rangle,$$

and so on the level of our metalogic $\lambda \rightarrow$, not, and, and imp are constants. However, these constants represent the logical symbols of the object logic.

Note the types of the constants:
not has type $o \rightarrow o$, so it takes a proposition and returns a proposition.
and and imp have type $o \rightarrow o \rightarrow o$, so each takes two propositions and returns a proposition.
Metalevel Variables

We identify metalevel variables and object level propositional variables. Hence $\Gamma$ should contain expressions of the form $a : o$, where $a$ is a $\lambda \rightarrow$ variable, representing a propositional variable. Note that under this agreement, $\Gamma$ should not contain expressions like, e.g., $a : o \rightarrow o$. 
Intuition for $a : o \vdash \text{imp} \ (\text{not} \ a) \ a : o$

$a : o \vdash \text{imp} \ (\text{not} \ a) \ a : o$ is a judgement in $\lambda \rightarrow$, which may or may not be provable.

If we set up everything correctly and if $a : o \vdash \text{imp} \ (\text{not} \ a) \ a : o$ is provable, then the judgement represents the fact $\neg a \rightarrow a$ is a proposition.

In this sense, we could then say that derivability in $\lambda \rightarrow$ captures the syntax of $Prop$, i.e., it can distinguish a legal proposition from a “non-proposition”.

Note that this has nothing to do with the question of whether it is a true proposition! So far, we are only talking about the representation of syntax.
**Intuition for** $a : o \vdash \text{not} \ (\text{imp} \ a) \ a : o$

$a : o \vdash \text{not} \ (\text{imp} \ a) \ a : o$ is a judgement in $\lambda \rightarrow$ which may or may not be provable.

If we set up everything correctly and if $a : o \vdash \text{not} \ (\text{imp} \ a) \ a : o$ is provable, then the judgement represents the fact that $(\rightarrow a) \neg a$ is a proposition.

However, you may observe that $(\rightarrow a) \neg a$ is gibberish. In fact, there is no formal sense whatsoever in saying that $\text{not} \ (\text{imp} \ a) \ a$ corresponds to $(\rightarrow a) \neg a$.

We will see that $a : o \vdash \text{not} \ (\text{imp} \ a) \ a : o$ isn’t provable, and this reflects the fact that there is no proposition represented by $\text{not} \ (\text{imp} \ a) \ a$. 
Non-existence of Proofs

Generally, it is difficult to prove that a proof of a given judgement within a given proof system does not exist, since there are infinitely many possible proofs and it is not obvious to predict how big an existing proof might be.

However, under certain conditions, there are techniques for simplifying proofs. In fact, there may be normal form proofs, i.e., proofs simplified as much as possible. One can then argue: if a proof of a certain judgement exists, it must be no bigger than a certain size. By searching through all proofs smaller than this size, one can prove that no proof exists.

In this lecture, we do not go into the details of this topic [GLT89, Pra65].
Bijection

In general mathematical terminology, a bijection between $A$ and $B$ is a mapping $f : A \rightarrow B$ such that for all $a, a' \in A$, where $a \neq a'$, we have $f(a) \neq f(a')$, and for each $b \in B$, there exists an $a \in A$ such that $f(a) = b$.

For a bijection $f$, the inverse $f^{-1}$ is always defined, and we have $f(f^{-1}(b)) = b$ for all $b \in B$ and $f^{-1}(f(a)) = a$ for all $a \in A$. 

Back to main referring slide
Proof of Adequacy

If \( P \in \text{Prop} \), and if for each propositional variable \( x \) in \( P \), we have \( x : o \in \Gamma \), then \( \Gamma \vdash \neg P : o \).

**Proof:** By structural induction on \( \text{Prop} \).

Base case: \( P \) is a propositional variable.

Then \( \neg P = P \), and so if \( P : o \in \Gamma \), then we have \( \Gamma \vdash \neg P : o \) by rule *hyp*.

Induction step: Suppose the claim holds for \( P \in \text{Prop} \) and \( Q \in \text{Prop} \).

Consider the propositional formula \( \neg P \). We have \( \neg P = \text{not } P \).

Assume that for each propositional variable \( x \) in \( P \), we have \( x : o \in \Gamma \). By the induction hypothesis, \( \Gamma \vdash \neg P : o \). Moreover \( \Gamma \vdash \text{not } : o \to o \) by rule *assum*, and so \( \Gamma \vdash \text{not } P : o \) by rule *app*.

Now consider the propositional formula \( P \land Q \). We have \( P \land Q = \text{and } P \land Q \). Assume that for each propositional variable \( x \)
in $P$ or $Q$, we have $x : o \in \Gamma$. By the induction hypothesis, $\Gamma \vdash \neg \neg P : o$ and $\Gamma \vdash \neg \neg Q : o$. Moreover $\Gamma \vdash \text{and} : o \to o \to o$ by rule $\textit{assum}$, and so $\Gamma \vdash \text{and} \neg \neg P \neg \neg Q : o$ by two applications of rule $\textit{app}$. The case $P \to Q$ is completely analogous.
Why $\lll P \lll^{-1} = P$?

By the definition of $Prop$ and the definition of $\lll \cdot \lll$, it is clear that $\lll P \lll$ is defined for all $P \in Prop$. It is very easy to show by induction on $Prop$ that $\lll\lll P \lll^{-1} = P$.

Here is an example of a proof by induction on $Prop$.

Obviously, everything we say here depends on the particular fragment of propositional logic, but in an inessential way. It would be trivial to adapt to other fragments.
A canonical $\beta\eta$-long normal form of a $\lambda$-term is obtained by applying first $\beta$-reduction as long as possible, and then computing the maximal $\eta$-expansion.

You may wonder: Why is there such a thing as a maximal $\eta$-expansion? Can’t I expand a $\lambda$-term to $\lambda x_1 \ldots x_n. M x_1 \ldots x_n$ for arbitrary $n$? In the untyped $\lambda$-calculus, this is indeed the case. But in the typed $\lambda$-calculus, the answer is no! Consider this example:

$not$ can be expanded to $\lambda x. not x$ since $not$ is of function type: it has type $o \rightarrow o$. Therefore, $not x$ can be assigned a type, which is an intermediate step in typing $\lambda x. not x$:
\[
\frac{\Gamma, x : o \vdash not : o \rightarrow o \quad \Gamma, x : o \vdash x : o}{\Gamma, x : o \vdash not \ x : o} \quad \text{app}
\]

\[
\frac{\Gamma, x : o \vdash not \ x : o}{\Gamma \vdash \lambda x. \, not \ x : o \rightarrow o} \quad \text{abs}
\]

But we cannot, say, expand \textit{not} to \(\lambda xy. \, not \ x \ y\) since it is impossible to assign a type to \textit{not} \(x \ y\).

Effectively, when a term of type \(\tau_1 \rightarrow \tau_n \rightarrow \tau\) is \(\eta\)-expanded, it will have the form \(\lambda x_1 x_2 \ldots x_n.e\).

Normal forms are \textit{unique}.
Variables in $\Gamma$

Saying that a propositional formula has variables in $\Gamma$ is an abuse of terminology, i.e., it isn't exactly true, but it is trusted that the reader can guess the exact formulation.

What we mean is: a propositional formula such that for each propositional variable $x$ occurring in the formula, we have $x : o \in \Gamma$. 
Simplifying Proofs

What this picture says is that if the left hand side is a fragment from a proof tree, deriving the judgement \( \vdash (\lambda x^{\sigma}. e)e' : \tau \), then there exists a proof of the judgement \( \vdash e[x \leftarrow e'] : \tau \).

Be aware however that our argument here is very sketchy. We do not go into the details in this course.
Simply writing \( t : o \) is again a bit sloppy. We should write: \( \Gamma \vdash t : o \) for some \( \Gamma \) containing only expressions of the form \( x : o \), where \( x \) is a propositional variable in \( Prop \).
Two Times First-Order!

In the previous section, we have seen how we can use first-order syntax (of $\lambda \rightarrow$) to represent the syntax of an object logic, then $Prop$. We haven’t really understood yet why we speak of first-order syntax, but note that the notion “first-order” refers to $\lambda \rightarrow$, i.e., the metalevel.

We will now consider first-order logic as object language. So we will now attempt to represent the syntax of first-order logic (the object language) using first-order $\lambda \rightarrow$ syntax (the metalanguage). To avoid confusion, it is best to imagine that it is a mere coincidence that both the object and the metalanguage are described as “first-order”. Of course there are reasons why both languages are called like that, but it is best to understand this separately for both levels. We will come back to this.
Specifying a First-Order Language

With this grammar, we specify a certain language of a fragment (since quantifiers, ∨, and ⊥ are missing) of first-order logic. Alternatively, we could say that \( F = \{0, s, +, \times\} \) and \( P = \{=\} \). However, the way we defined first-order logic, the language thus obtained would also include quantifiers, ∨, and ⊥. For the moment we want to restrict ourselves to the fragment given by the grammar for FOA.
$s$

$s$ is a unary prefix function, so $s$ applied to $T$ is written $sT$. 
Some Intuition for FOA

We have defined

$$\Sigma_T = \langle \text{zero}: i, \text{succ}: i \rightarrow i, \text{plus}: i \rightarrow i \rightarrow i, \text{times}: i \rightarrow i \rightarrow i \rangle$$
Some Intuition for FOA

We have defined

$$\Sigma_T = \langle \text{zero : } i, \text{succ : } i \rightarrow i, \text{plus : } i \rightarrow i \rightarrow i, \text{times : } i \rightarrow i \rightarrow i \rangle$$

\text{zero : } i \text{ means: viewed on the object level, 0 is a term.}

\text{plus : } i \rightarrow i \rightarrow i \text{ means: viewed on the object level, plus is a function that takes two terms and returns a term. eq : } i \rightarrow i \rightarrow o \text{ means: viewed on the object level, = is a predicate that takes two terms and returns a proposition.}

On the metalevel (level of } \lambda \rightarrow), \text{ zero, plus and eq are constants. Note that we could also formalize them as variables.}

\text{Recall that we encoded the non-logical symbols of an object logic as constants. It would however be possible to set up the encoding in such a}
way that the non-logical symbols are encoded as variables, so we would have a context $\Gamma_T$ instead of our $\Sigma_T$. This is in line with Perlis’ epigram. We will sometimes take this approach in the exercises as the encoding of $\lambda \rightarrow$ in Isabelle makes it more straightforward to play around with different $\Gamma$’s than with different $\Sigma$’s.
Definition of ⌜·⌝

We extend the definition of ⌜·⌝ as follows:

\[
\begin{align*}
\langle x \rangle & \ = \ x \\
\langle 0 \rangle & \ = \ zero \\
\langle s \ t \rangle & \ = \ succ \ \langle t \rangle \\
\langle r + t \rangle & \ = \ plus \ \langle r \rangle \ \langle t \rangle \\
\langle r \times t \rangle & \ = \ times \ \langle r \rangle \ \langle t \rangle 
\end{align*}
\]

Note that here, on the object level, \( x \) is a first-order variable (a variable is a term), and hence on the metalevel, it has type \( i \).
Subtypes?

In first-order logic, variables are not a syntactic category of their own, but rather they are a “sub-category” of terms. Therefore one should expect that var should be a “subtype” of i, that is to say, every term of type var is automatically also of type i. However, there is no such notion in $\lambda \rightarrow$. 
\[(\text{and } (p \ x)(\text{all } x \ (q \ x)))[x \leftarrow a]\]

There is a notion of substitution in $\lambda \rightarrow$, hence on the metalevel. But all is just a constant like any other on the level of $\lambda \rightarrow$, and hence $(\text{and } (p \ x)(\text{all } x \ (q \ x)))[x \leftarrow a] = (\text{and } (p \ a)(\text{all } a \ (q \ a)))$, and not $(\text{and } (p \ a)(\text{all } x \ (q \ x)))$ as one should expect.

That is to say, the standard operation of substitution, which exists on the metalevel, is of no use for implementing substitution on the object level. Instead, substitution on the object level must be “programmed explicitly”.

Note that the following question arises: on the $\lambda \rightarrow$ level, should the terms of type $\text{var}$ be variables or constants?

One could imagine that they are variables. This means that the signature $\Sigma$ would not contain any constants of type $\text{var}$ or $\ldots \rightarrow \text{var}$. The only terms of type $\text{var}$ would be variables. In this case, a $\lambda \rightarrow$ term like
\((\text{and } (p \ x)(\text{all } x \ (q \ x)))\) could only be typed in a context \(\Gamma\) containing \(x : \text{var}\).

Alternatively, one could imagine that they are constants. The signature \(\Sigma\) would contain expressions of the form \(x : \text{var}\), where \(x\) would be a \(\lambda\to\) constant. One thing that isn’t nice about this approach is that \(\Sigma\) cannot be an infinite sequence, and so we would have to fix a finite set of variables that can be represented in \(\lambda\to\).

In either case, the operation of substitution on the metalevel is of no use for implementing substitution on the object level.
\( all(\lambda x^i. eq \, x \, x : i \to o) \)

Some intuition: a proposition is represented by a term of type \( o \). Now a term of type \( i \to o \) represents a proposition where some positions are marked in a special way. For example, in \( \lambda x^i. eq \, x \, x \), the positions where \( x \) occurs are marked in a special way, by virtue of the fact that the \( \lambda \) in front of the expression binds the \( x \). This “marking” allows us to “insert” other terms in place of \( x \). We will see this soon.

\( all \) is a constant which can be applied to a term of type \( i \to o \).
Faithfulness and Adequacy
Terms and formulae are represented by (canonical) members of $i$ and $o$. The principle is similar as for $Prop$. 
Intuition for Order

A term of first-order type is a function taking (an arbitrary number of) arguments all of which must be of base type.

A term of second-order type is a function taking (an arbitrary number of) arguments some of which may be functions (of first order type).

A term of third-order type is a function taking (an arbitrary number of) arguments some of which may be functions, which again take functions (of first order type) as arguments.

... Obviously, it would be wrong to think of the order as “number of arrows in a type”. Instead, one can think of order as the “nesting depth of arrows in a type”.

Sometimes, the notion “second-order” is used in the context of type theories for quite a different concept, but we will avoid that other use...
here.
Propositional vs. First-Order Variables

Although propositional variables and first-order variables are quite different concepts, for both the representation in $\lambda \rightarrow$ used $\lambda \rightarrow$ variables. Technically however, there is a difference between the representations of propositional variables and first-order variables. In particular, propositional variables are represented as $\lambda \rightarrow$ variables of type $o$, and first-order variables are represented as $\lambda \rightarrow$ variables of type $i$. 

Resolution
Three Sections on Deduction Techniques

After encoding syntax, the next topic in the theory is encoding proofs.

But before, we look at some more practical issues:

- Resolution
- Proof search
- Term rewriting

We will explain many techniques relevant for Isabelle, but not in extreme detail and rigor. We want to understand better how Isabelle works, but not provide a formal proof that she works correctly, or be able to rebuild her.
Resolution

Resolution is the basic mechanism for transforming proof states in Isabelle in order to construct a proof. It involves unifying a certain part of the current goal (state) with a certain part of a rule, and replacing that part of the current goal.

We have already explained this in the labs and you have been working with it all the time, but now we want to understand it more thoroughly (in the next lecture, we will look at it more abstractly).

We look at several variants of resolution.
Resolution (\texttt{rtac}, as in Prolog)

\[ \phi_1 \ldots \phi_i \ldots \phi_n \]

\[ \overline{\psi} \]

\[ \psi \]

\[ \phi_1, \ldots, \phi_n \text{ are current sub-goals and } \psi \text{ is original goal. Isabelle displays} \]

Level \ldots (n subgoals)

\[ \psi \]

1. \( \phi_1 \)

\[ \vdots \]

\[ n. \ \phi_n \]
Resolution \((\text{rtac, as in Prolog})\)

\[ \phi_1, \ldots, \phi_n \text{ are current sub-goals and } \psi \text{ is original goal.} \]

Isabelle displays

\[ \text{Level } \ldots (n \text{ subgoals)} \]

\[ \psi \]

1. \(\phi_1\)

\[ \vdots \]

\(n. \phi_n\)

\[ [\alpha_1; \ldots; \alpha_m] \implies \beta \text{ is rule.} \]
Resolution (rtac, as in Prolog)

Simple scenario where $\phi_i$ has no premises. Now $\beta$ must be unifiable with selected subgoal $\phi_i$. 

$\psi$

$\alpha_1 \ldots \alpha_m$

$\beta$

$\phi_1 \ldots \phi_i \ldots \phi_n$
**Resolution (rtac, as in Prolog)**

Simple scenario where $\phi_i$ has no premises. Now $\beta'$ must be unifiable with selected subgoal $\phi_i$.

We apply the unifier ($'$)
Resolution (rtac, as in Prolog)

Simple scenario where $\phi_i$ has no premises. Now $\beta$ must be unifiable with selected subgoal $\phi_i$.

We apply the unifier ($'$)

We replace $\phi'_i$ by the premises of the rule.
Resolution (with Lifting over Parameters)

\[ \phi_1 \quad \cdots \quad \land x.\phi_i \quad \cdots \quad \phi_n \]

Now suppose the \(i\)'th (selected) subgoal is preceded by \(\land\) (metalevel universal quantifier).
Resolution (with Lifting over Parameters)

\[ \begin{align*}
\alpha_1 & \quad \cdots \quad \alpha_m \\
\beta \\
\phi_1 & \quad \cdots \quad \bigwedge x.\phi_i & \quad \cdots & \quad \phi_n \\
\psi
\end{align*} \]

Rule
Resolution (with Lifting over Parameters)

\[ \bigwedge x.\alpha_1[x] \cdots \bigwedge x.\alpha_m[x] \]

\[ \bigwedge x.\beta[x] \]

\[ \phi_1 \quad \cdots \quad \bigwedge x.\phi_i \quad \cdots \quad \phi_n \]

\[ \psi \]

Rule is lifted over \( x \): Apply \([?X \leftarrow ?X(x)]\).
Resolution (with Lifting over Parameters)

\[
\land x. \alpha_1[x] \cdots \land x. \alpha_m[x] \\
\land x. \beta[x]
\]

\[
\phi_1 \ \cdots \ \land x. \phi_i \ \cdots \ \phi_n
\]

\[
\psi
\]

Rule is lifted over \(x\): Apply \([?X \leftarrow ?X(x)]\).

As before, \(\beta\) must be unifiable with \(\phi_i\);
Resolution (with Lifting over Parameters)

\[ \land x.\alpha'[x] \land x.\alpha'[x] \]

\[ \land x.\beta'[x] \]

\[ \phi'_1 \land \ldots \land x.\phi'_i \land \ldots \land \phi'_n \]

\[ \psi' \]

Rule is lifted over \( x \): Apply \([?X \leftarrow ?X(x)]\).

As before, \( \beta \) must be unifiable with \( \phi_i \); apply the unifier.
Resolution (with Lifting over Parameters)

\[ \phi'_1 \cdots \land x.\alpha'_1[x] \cdots \land x.\alpha'_m[x] \cdots \phi'_n \]

\[ \psi' \]

Rule is lifted over \( x \): Apply \([?X \leftarrow ?X(x)]\).

As before, \( \beta \) must be unifiable with \( \phi_i \); apply the unifier.

We replace \( \phi'_i \) by the premises of the rule. \( \alpha'_1, \ldots, \alpha'_m \) are preceded by \( \land x \).
Resolution (with Lifting over Assumptions)

\[
\begin{bmatrix}
\phi_{i1} & \cdots & \phi_{ik_i}
\end{bmatrix}
\]

\[
\vdots
\]

\[\phi_1 \quad \cdots \quad \phi_i \quad \cdots \quad \phi_n\]

\[\psi\]

Now, suppose the \(i\)'th (selected) subgoal has assumptions \(\phi_{i1}, \ldots, \phi_{ik_i}\).
Resolution (with Lifting over Assumptions)

As before, we have a rule. In general \( \beta \) is not unifiable with the \( i \)'th subgoal, even assuming that \( \beta \) is unifiable with \( \phi_i \).
Resolution (with Lifting over Assumptions)

\[
\begin{align*}
\phi_1 & \quad \cdots \quad \phi_i & \quad \cdots & \quad \phi_n \\
\vdots & & & & \vdots \\
\end{align*}
\]

\[\alpha_1 \quad \cdots \quad \alpha_m\]

\[\left[\phi_{i1} \cdots \phi_{ik_i}\right] \quad \left[\phi_{i1} \cdots \phi_{ik_i}\right] \quad \vdots \quad \vdots \quad \vdots \]

\[\psi\]

Rule must be lifted over assumptions. No unification so far!
Resolution (with Lifting over Assumptions)

\[ [\phi_1 \cdots \phi_{ik_i}] \quad [\phi_1 \cdots \phi_{ik_i}] \]
\[ \vdots \quad \vdots \quad \vdots \]
\[ \alpha_1 \quad \cdots \quad \alpha_m \]

\[ [\phi_{i1} \cdots \phi_{ik_i}] \quad [\phi_{i1} \cdots \phi_{ik_i}] \]
\[ \vdots \quad \vdots \quad \vdots \]
\[ \beta \]

\[ \psi \]

Now, subgoal and rule conclusion (below the bar) are unifiable.
Resolution (with Lifting over Assumptions)

\[
\left[ \phi_{i1} \cdots \phi_{ik_i} \right] \quad \left[ \phi_{i1} \cdots \phi_{ik_i} \right] \\
\vdots \quad \vdots \quad \vdots \\
\alpha_1 \quad \cdots \quad \alpha_m \\
\quad \quad \quad \quad \quad \\
\left[ \phi_{i1} \cdots \phi_{ik_i} \right] \\
\]

\[ \psi \]

Now, subgoal and rule conclusion (below the bar) are unifiable. Non-trivially, \( \beta \) must be unifiable with \( \phi_i \).
Resolution (with Lifting over Assumptions)

\[
\begin{align*}
&\psi' \\
= &\ \phi_1' \cdots \phi_i' \cdots \phi_n' \\
&\mathbf{\alpha}_1' \cdots \mathbf{\alpha}_m' \\
\end{align*}
\]

We apply the unifier.
Resolution (with Lifting over Assumptions)

\[
\begin{bmatrix}
\phi'_{i_1} \cdots \phi'_{i_{k_i}} \\
\vdots \\
\phi'_{1} \cdots \phi'_{i-1} \; \alpha'_1 \cdots \alpha'_m \; \phi'_{i+1} \cdots \phi'_n
\end{bmatrix}
\]

\[\psi'\]

We replace the subgoal.
Rule Premises Containing $\implies$

$$[\phi'_1 \cdots \phi'_{ik_i}]$$

$$\vdots$$

$$\phi'_1 \cdots \alpha'_j \cdots \phi'_n$$

$$\psi'$$

What if some $\alpha'_j$ has the form $[\gamma_1; \ldots; \gamma_l] \implies \delta$?
Rule Premises Containing \[ \Rightarrow \]
\[
[\phi'_{i1} \cdots \phi'_{ik_i}]
\]

\[ \vdash \]
\[ \phi'_1 \cdots [\gamma_1; \ldots; \gamma_l] \Rightarrow \delta \cdots \phi'_n \]

\[ \psi' \]

What if some \( \alpha'_j \) has the form \([\gamma_1; \ldots; \gamma_l] \Rightarrow \delta\)?

Is this what we get?
**Rule Premises Containing**

\[
[\phi'_1 \ldots \phi'_{ik_i} ; \gamma'_1 \ldots \gamma'_l]
\]

\[
\vdots
\]

\[
\phi'_1 \ldots \delta' \ldots \phi'_n
\]

\[
\psi'
\]

What if some \( \alpha'_j \) has the form \([\gamma_1 ; \ldots ; \gamma_l] \Rightarrow \delta\)?

Is this what we get?

Well, we write : for \( \Rightarrow \), and use

\[
A \Rightarrow B \Rightarrow C \equiv [A; B] \Rightarrow C.
\]
Elimination-Resolution

\[ \begin{bmatrix} \phi_{i1} & \cdots & \phi_{il} & \cdots & \phi_{ik_i} \end{bmatrix} \]

\[
\begin{array}{cccc}
\phi_1 & \cdots & \phi_i & \cdots & \phi_n \\
\end{array}
\]

Same scenario as before
Elimination-Resolution

\[
[\phi_{i1} \cdots \phi_{il} \cdots \phi_{ik_i}]\]

\[\phi_1 \quad \cdots \quad \phi_i \quad \cdots \quad \phi_n\]

Same scenario as before, but now \(\beta\) must be unifiable with \(\phi_i\), and \(\alpha_1\) must be unifiable with \(\phi_{il}\), for some \(l\).
Same scenario as before, but now $\beta$ must be unifiable with $\phi_i$, and $\alpha_1$ must be unifiable with $\phi_{il}$, for some $l$. Apply the unifier.
Elimination-Resolution

\[
\begin{array}{c}
\phi'_i \ldots \phi'_{i,l-1}, \phi'_{i,l+1} \ldots \phi'_{ik_i} \\
\vdots \\
\phi'_1 \ldots \phi'_{i-1} \alpha'_2 \\
\hline
\psi' \\
\end{array}
\]

\[
\begin{array}{c}
\phi'_i \ldots \phi'_{i,l-1}, \phi'_{i,l+1} \ldots \phi'_{ik_i} \\
\vdots \\
\alpha'_m \phi'_{i+1} \ldots \phi'_n
\end{array}
\]

Same scenario as before, but now $\beta$ must be unifiable with $\phi_i$, and $\alpha_1$ must be unifiable with $\phi_{il}$, for some $l$.

Apply the unifier.

We replace $\phi'_i$ by the premises of the rule except the first. $\alpha'_2, \ldots, \alpha'_m$ inherit the assumptions of $\phi'_i$, except $\phi'_{il}$.
Destruct-Resolution

\[
\begin{array}{c}
\frac{\alpha}{\beta}
\end{array}
\]

\[
[\phi_{i1} \cdots \phi_{il} \cdots \phi_{ik_i}]
\]

\[
\vdots
\]

\[
\phi_1 \cdots \phi_i \cdots \phi_n
\]

\[
\psi
\]

Simple rule
**Destruct-Resolution**

\[
\begin{array}{c}
\text{[ } \phi_{i_1} \cdots \phi_{i_l} \cdots \phi_{i_k_1} \text{ ]}
\end{array}
\]

\[\alpha \frac{\beta}{\psi} \]

\[\phi_1 \cdots \phi_i \cdots \phi_n \]

Simple rule, and \( \alpha \) must be unifiable with \( \phi_{i_l} \), for some \( l \).
Destruct-Resolution

\[
\begin{array}{c}
\begin{array}{c}
\phi_1' \\
\vdots \\
\phi_i' \\
\phi_{i1}' \\
\cdots \\
\phi_{il}' \\
\cdots \\
\phi_{ik_i}'
\end{array}
\end{array}
\]

\[
\begin{array}{c}
\frac{\phi_i' \\
\vdots \\
\phi_i' \\
\alpha'}{\beta'}
\end{array}
\]

\[
\psi'
\]

Simple rule, and \( \alpha \) must be unifiable with \( \phi_{il} \), for some \( l \).
We apply the unifier.
Destruct-Resolution

\[
\left[ \phi_{i1}' \cdots \beta' \cdots \phi_{ik_i}' \right]
\vdots
\phi'_1 \cdots \phi_i' \cdots \phi'_n
\]

\[ \psi' \]

Simple rule, and \( \alpha \) must be unifiable with \( \phi_{il} \), for some \( l \).
We apply the unifier.
We replace premise \( \phi_{il}' \) with the conclusion of the rule.
Summary on Resolution

- Build proof resembling sequent style notation;
- technically: replace goals with rule premises, or goal premises with rule conclusions;
- metavariables and unification to obtain appropriate instance of rule, delay commitments;
- lifting over parameters and assumptions;
- various techniques to manipulate premises or conclusions, as convenient: rtac, etac, dtac.
More Detailed Explanations
Prolog

Prolog is a logic programming language [Apt97].

The computation mechanism of Prolog is resolution of a current goal (corresponding to our $\phi_1, \ldots, \phi_n$) with a Horn clause (corresponding to our $[\alpha_1; \ldots; \alpha_m] \implies \beta$).
Simple $\phi_i$

$\phi_i$ is the selected subgoal. In Isabelle, the number $i$ of the selected subgoal is always one of the arguments of a tactic. One writes:

by \((tactic\ rule\ i)\);

We assume here that $\phi_i$ is a formula, i.e., it contains no $\Rightarrow$ (metalevel implication). The form of the other subgoals $\phi_1, \ldots, \phi_{i-1}, \phi_{i+1}, \ldots, \phi_n$ is arbitrary.
Prime (′)

In all illustrations that follow, we use ′ to suggest the application of the appropriate unifier.
Metalevel Universal Quantification

\( \forall \) is the metalevel universal quantification (also written \( !! \)). If a goal is preceded by \( \forall x \), this means that Isabelle must be able to prove the subgoal in a way which is independent from \( x \), i.e., without instantiating \( x \).
Lifting over Parameters

The metavariables of the rule are made dependent on $x$. That is to say, each metavariable $?X$ is replaced by a $?X(x)$. You may also say that $?X$ is now a Skolem function of $x$.

This process is called lifting the rule over the parameter $x$.

We denote by $\rho[x]$ the result of lifting $\rho$ over $x$. 

[Back to main referring slide]
Non-unifiability

The selected subgoal is \([\phi_{i1}, \ldots, \phi_{ik_i}] \implies \phi_i\) where \(\phi_{i1}, \ldots, \phi_{ik_i}, \phi_i\) are object-level formulae. So the selected subgoal is not an object-level formula, but it has \(\implies\) as “top-level constructor” and is hence a formula in the metalogic.

Moreover, \(\beta\) is a formula. It is clear that an object-level formula cannot be unifiable with a formula in the metalogic having \(\implies\) as ‘top-level constructor’.
Lifting over Assumptions

Each premise of the rule, as well as the conclusion of the rule, are preceded by the assumptions $[\phi_{i1}, \ldots, \phi_{ik_i}]$ of the current subgoals. Actually, the rule

$$
\begin{array}{c}
[\phi_{i1} \cdots \phi_{ik_i}] & [\phi_{i1} \cdots \phi_{ik_i}] \\
\vdots & \vdots \\
\alpha_1 & \cdots & \alpha_m \\
\hline
[\phi_{i1} \cdots \phi_{ik_i}] \\
\vdots \\
\beta
\end{array}
$$

may look different from any rules you have seen so far, but it can be formally derived from the rule:
The derived rule should be read as: If for all $j \in \{1, \ldots, m\}$, we can derive $\alpha_j$ from $\phi_{i1}, \ldots, \phi_{ik}$, then we can derive $\beta$ from $\phi_{i1}, \ldots, \phi_{ik}$. 
Unifiability

Still assuming that $\phi_i$ and $\beta$ are unifiable.
A Trivial Unification

Both the subgoal and the conclusion of the lifted rule are preceded by assumptions $\phi_{i1}, \ldots, \phi_{ik_i}$. Hence the assumption list of the subgoal and the assumption list of the rule are trivially unifiable since they are identical.
Folding Assumptions

Generally, Isabelle makes no distinction between

$$[\psi_1; \ldots; \psi_n] \Longrightarrow [\mu_1; \ldots; \mu_k] \Longrightarrow \phi$$

and

$$[\psi_1; \ldots; \psi_n; \mu_1; \ldots; \mu_k] \Longrightarrow \phi$$

and displays the second form. Semantically, this corresponds to the equivalence of $A_1 \land \ldots \land A_n \rightarrow B$ and $A_1 \rightarrow \ldots \rightarrow A_n \rightarrow B$.

We have seen this in the exercises.
Same as Resolution

So the scenario looks as for resolution with lifting over assumptions. However, this time we do not show the lifting over assumptions in our animation.
The Rationale of Elimination-Resolution

Elimination-resolution is used to eliminate a connective in the premises. For example, if the current goal is

\[ [A \land B] \]
\[ \vdots \]
\[ B \]
\[ A \land B \rightarrow B \]

and the rule is

\[ [P; Q] \]
\[ \vdots \]
\[ P \land Q \]
\[ R \]
\[ R \]
\[ \land-E \]
then the result of elimination resolution is

\[
\begin{align*}
[A; B] \\
\therefore \\
B \\
\hline
A \land B \rightarrow B
\end{align*}
\]

Effectively, the interplay between elimination rules and elimination-resolution is such that one “does not throw any information away”. Before we had the assumption \( A \land B \). This was replaced by the components \( A \) and \( B \) as separate assumptions.
The Rationale of Destruct-Resolution

Destruct-resolution is used to eliminate a connective in the premises. The difference compared to elimination-resolution can be seen in the following example. Unlike elimination-resolution, destruct-resolution “throws information away”.

For example, if the current goal is

\[
\begin{array}{c}
[A \land B] \\
\vdots \\
B \\
\hline \\
A \land B \rightarrow B
\end{array}
\]

and the rule is

\[
\frac{P \land Q}{\text{conjunct2}}
\]
then the result of destruct-resolution is

\[
\begin{array}{c}
[B] \\
\vdots \\
B
\end{array}
\]

\[
\frac{B}{A \land B \rightarrow B}
\]

If we had instead used rule

\[
\frac{P \land Q}{P \quad \text{conjunct2}}
\]

the result would have been

\[
\begin{array}{c}
[A] \\
\vdots \\
B
\end{array}
\]

\[
\frac{B}{A \land B \rightarrow B}
\]
and we would be stuck. We accidentally “threw away” the assumption \( B \).
Automation by Proof Search
Outline of this Part

- Proof search (à la tableau proving) and backtracking
- Classifying rules
- Proof procedures
Proof Search and Backtracking

- Need for more automation
- Some aspects in proof construction are highly non-deterministic:
  - unification: which unifier to choose?
  - resolution: where to apply a rule (which ’subgoal’)?
  - which rule to apply?
- How to organize proof-search technically?
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).
A sketch of an exemplary proof search:
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

\[ \phi \Rightarrow \phi \]

Goal \( \phi \) will create the proof state \( \phi \Rightarrow \phi \).
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

φ \rightarrow φ

(ε \Rightarrow η) \Rightarrow φ

One tactic step (by ...) transforms into proof state (ε \Rightarrow η) \Rightarrow φ.
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

\[ \phi \Rightarrow \phi \]

\[ (\epsilon \Rightarrow \eta) \Rightarrow \phi \]

\[ \ldots \]

Next tactic step yields dead-end (no tactic application possible).
Organizing Proof Search Conceptually

Organize proof search as a **tree of theorems (thm’s)**.

A sketch of an exemplary proof search:

\[ \phi \Rightarrow \phi \]

\[ (\epsilon \Rightarrow \eta) \Rightarrow \phi \]

\[ (\epsilon \Rightarrow \epsilon) \Rightarrow \phi \]

\[ \cdots \]

\[ \text{back}() \]; tries an alternative successor of \((\epsilon \Rightarrow \eta) \Rightarrow \phi\).
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

\[
\phi \Rightarrow \phi \\
(\epsilon \Rightarrow \eta) \Rightarrow \phi \\
(\epsilon \Rightarrow \epsilon) \Rightarrow \phi \\
\phi
\]

Now \((\epsilon \Rightarrow \epsilon) \Rightarrow \phi\) is solvable using atac. qed.
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).
A sketch of an exemplary proof search:

\[ \phi \Rightarrow \phi \]
\[ (\epsilon \Rightarrow \eta) \Rightarrow \phi \]
\[ (\epsilon \Rightarrow \epsilon) \Rightarrow \phi \]

Use \texttt{undo()} three times to go to previous proof states.
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).
A sketch of an exemplary proof search:

Use undo(); three times to go to previous proof states.
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

Use undo(); three times to go to previous proof states.
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

Use \texttt{back()}; to try alternative successor. . . .
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

Summary:
back(); to try alternative successors (⇒ different unifiers).
Organizing Proof Search Conceptually

Organize proof search as a tree of theorems (thm’s).

A sketch of an exemplary proof search:

Summary:

- `back()`: to try alternative successors (⇒ different unifiers).
- `undo()`: to go to previous proof state.
**Problems**

The search space of proof search can be thought of as such a tree, but it cannot be implemented like this straightaway:

- Branching of the tree infinite in general (**HO-unification**).
- **Explicit tree representation** expensive in time and space.

As an aside, it is also possible to understand proof search more abstractly. But we are interested in the operational aspects.
Organizing Proof Search Operationally

Organize proof search as a function on theorems (thm’s)

\[
\text{type tactic} = \text{thm} \rightarrow \text{thm seq}
\]

where seq is the type constructor for infinite lists. This allows us to have tacticals:

- THEN
- ORELSE
- REPEAT
- INTLEAVE, BREADTHFIRST, DEPTHFIRST, …
Classifying Rules

How to Organize Proof Rules?

Observation: Some rules can always be applied blindly in backward reasoning, e.g. $\rightarrow\!-I$ or $\land\!-I$. Others are problematic, e.g. $\land\!-EL$ or $\land\!-ER$ (you do not know which to apply to get rid of a $\land$ in the premises.)
Classifying Rules

How to Organize Proof Rules?
Observation: Some rules can always be applied blindly in backward reasoning, e.g. $\rightarrow\neg$ or $\land\neg$. Others are problematic, e.g. $\land\neg EL$ or $\land\neg ER$ (you do not know which to apply to get rid of a $\land$ in the premises.

But proof rules can be tailored to be applied blindly. In the following we will explain this using sequent style notation.
Review: Sequent Notation

\[ \Gamma \vdash A \quad (\text{where } A \in \Gamma) \]

\[ \frac{\Gamma \vdash B}{A, \Gamma \vdash B} \quad \text{weaken} \]

\[ \frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \land B} \quad \land\text{-}I \]
\[ \frac{\Gamma \vdash A \land B}{\Gamma \vdash A} \quad \land\text{-}EL \]
\[ \frac{\Gamma \vdash A \land B}{\Gamma \vdash B} \quad \land\text{-}ER \]

\[ \frac{A, \Gamma \vdash B}{\Gamma \vdash A \rightarrow B} \quad \rightarrow\text{-}I \]
\[ \frac{\Gamma \vdash A \rightarrow B}{\Gamma \vdash A} \quad \rightarrow\text{-}E \]

\[ \frac{\Gamma \vdash A}{\Gamma \vdash A \lor B} \quad \lor\text{-}IL \]
\[ \frac{\Gamma \vdash B}{\Gamma \vdash A \lor B} \quad \lor\text{-}IR \]

\[ \frac{\Gamma \vdash A \lor B \quad \Gamma, A \vdash C \quad \Gamma, B \vdash C}{\Gamma \vdash C} \quad \lor\text{-}E \]
Example: $\land - E'$

In the sequent calculus, one writes $\land - E$ as:

$$
\frac{A, B, \Gamma \vdash C}{A \land B, \Gamma \vdash C}^{\land - E'}
$$

This mimics the effect of using $\land - E$ (conjE of Isabelle), here written in sequent style notation,

$$
\frac{\Gamma \vdash A \land B \quad A, B, \Gamma \vdash C}{\Gamma \vdash C}^{\land - E}
$$

in combination with etac. We now derive $\land - E'$. 
Deriving $\land^E'$ from $\land^E$

\[
\frac{
\Gamma \vdash A \land B \quad A, B, \quad \Gamma \vdash C
}{
\Gamma \vdash C}
\frac{
}{
\land^E
\}.
\]
Deriving $\lor \cdot E'$ from $\lor \cdot E$

$$
\frac{A \land B, \Gamma \vdash A \land B \quad A, B, A \land B, \Gamma \vdash C}{A \land B, \Gamma \vdash C} \lor \cdot E
$$

If we replace $\Gamma$ with $A \land B, \Gamma$ (just instantiation),
Deriving $\land\!-\!E'$ from $\land\!-\!E$

\[
\begin{array}{c}
A, B, A \land B, \Gamma \vdash C \\
\hline
A \land B, \Gamma \vdash C
\end{array}
\]

$\land\!-\!E$

If we replace $\Gamma$ with $A \land B, \Gamma$ (just instantiation), then one part holds by the assumption rule,
Deriving $\land\!-\!E'$ from $\land\!-\!E$

$$
\begin{align*}
A, B, \Gamma & \vdash C \\
\frac{\quad A \land B, A \land B, \Gamma \vdash C}{\quad A \land B, \Gamma \vdash C} & \text{weaken}
\end{align*}
$$

If we replace $\Gamma$ with $A \land B, \Gamma$ (just instantiation), then one part holds by the assumption rule, and we can apply weakening.
Deriving $\land\text{-}E'$ from $\land\text{-}E$

$$A, B, \Gamma \vdash C$$

$$\frac{A \land B, \Gamma \vdash C}{A \land B, \Gamma \vdash C} \land\text{-}E'$$
A Proof by Blind Rule Application

\[ \vdash (\rho \land \phi) \rightarrow \psi \rightarrow \phi \]

The topmost connective is \( \rightarrow \), which asks for \( \rightarrow \)-I.
A Proof by Blind Rule Application

\[
\frac{\rho \land \phi \vdash \psi \rightarrow \phi}{\vdash (\rho \land \phi) \rightarrow \psi \rightarrow \phi} \rightarrow -I
\]

The topmost connective is \(\rightarrow\), which asks for \(\rightarrow -I\).
Again \(\rightarrow -I\).
A Proof by Blind Rule Application

\[
\begin{align*}
\frac{\psi, \phi \vdash \phi}{\rho \land \phi \vdash \psi \rightarrow \phi} & \rightarrow \text{-I} \\
\frac{\rho \land \phi \vdash \psi \rightarrow \phi}{\vdash (\rho \land \phi) \rightarrow \psi \rightarrow \phi} & \rightarrow \text{-I}
\end{align*}
\]

The topmost connective is →, which asks for →-I.
Again →-I.
To decompose the assumption ρ ∧ φ, use ∧-E′.
A Proof by Blind Rule Application

\[
\frac{\rho, \phi, \psi \vdash \phi}{\rho \land \phi, \psi \vdash \phi} \land^{-E'} \\
\frac{\rho \land \phi \vdash \psi \rightarrow \phi}{\rightarrow^{-I}} \\
\frac{\rho \land \phi \vdash \psi}{\rightarrow^{-I}} \\
\frac{\vdash (\rho \land \phi) \rightarrow \psi \rightarrow \phi}{\rightarrow^{-I}}
\]

The topmost connective is \(\rightarrow\), which asks for \(\rightarrow^{-I}\).
Again \(\rightarrow^{-I}\).

To decompose the assumption \(\rho \land \phi\), use \(\land^{-E'}\).
The proof can now be completed by the assumption rule.
Safe and Unsafe Rules

Combined tactics rely on classification of rules, maintained in Isabelle data structure \texttt{claset}, and accessed by functions of type \texttt{claset * thm list \rightarrow claset}.

Class: 

To add use function:

- Safe introduction rules \texttt{addSIs}
- Safe elimination rules \texttt{addSEs}
- Unsafe introduction rules \texttt{addIs}
- Unsafe elimination rules \texttt{addEs}
Adapting Rules for Automated Proof Search

As seen for \( \land\)-E, rules must be suitably adapted in order to be useful in automated proof search.

\[
\vdash (\alpha \to \beta) \lor (\beta \to \alpha) \quad \lor\text{-}\text{\textit{swap}}
\]
Adapting Rules for Automated Proof Search

As seen for $\land$-$E$, rules must be suitably adapted in order to be useful in automated proof search.

\[
\neg(\alpha \rightarrow \beta) \vdash \beta \rightarrow \alpha \quad \rightarrow$-$I
\]

\[
\vdash (\alpha \rightarrow \beta) \lor (\beta \rightarrow \alpha) \quad \lor$-$swap
\]

Neither $\lor$-$IL$ nor $\lor$-$IR$ would work here. Uses classical logic.
Adapting Rules for Automated Proof Search

As seen for \( \land\)-E, rules must be suitably adapted in order to be useful in automated proof search.

\[
\begin{align*}
\neg(\alpha \rightarrow \beta), \beta \vdash \alpha & \quad \rightarrow\text{-swap}E \\
\neg(\alpha \rightarrow \beta) \vdash \beta \rightarrow \alpha & \quad \rightarrow\text{-I} \\
\vdash (\alpha \rightarrow \beta) \lor (\beta \rightarrow \alpha) & \quad \lor\text{-swap}
\end{align*}
\]
Adapting Rules for Automated Proof Search

As seen for $\land$-E, rules must be suitably adapted in order to be useful in automated proof search.

$$
\frac{\neg \alpha, \alpha, \beta \vdash \beta}{\vdash (\alpha \rightarrow \beta), \beta \vdash \alpha} \quad \rightarrow\text{-swapE}
$$

$$
\frac{\neg (\alpha \rightarrow \beta), \beta \vdash \alpha}{\vdash (\alpha \rightarrow \beta) \rightarrow \beta} \quad \rightarrow\text{-I}
$$

$$
\frac{\vdash (\alpha \rightarrow \beta) \lor (\beta \rightarrow \alpha)}{\neg (\alpha \rightarrow \beta) \vdash \beta \rightarrow \alpha} \quad \lor\text{-swap}
$$

Principle: **Emulate sequent calculus with derived rules.**
Handling Quantifiers

Can derive $\forall\text{-}E'$ ($\equiv \text{allE}$) using $\forall\text{-}E$ ($\equiv \text{spec}$):

$$
\forall x. A(x) \quad B
\overline{\text{[} A(x) \text{]} \quad B \quad \forall\text{-}E'}
$$

What is the difference to $\exists\text{-}E$?
Handling Quantifiers

Can derive $\forall-E'$ ($\equiv$ allE) using $\forall-E$ ($\equiv$ spec):

$$
\begin{align*}
\forall x.A(x) & \quad B \\
\frac{ \begin{array}{c} 
A(x) \\
\vdots \\
B \end{array} }{ B } & \quad \forall-E'
\end{align*}
$$

What is the difference to $\exists-E$?

Problem: $\forall x.A(x)$ may still be needed.
Handling Quantifiers

Can derive $\forall-E'$ ($\equiv \text{allE}$) using $\forall-E$ ($\equiv \text{spec}$):

\[
\begin{array}{c}
[A(x), \forall x. A(x)] \\
\forall x. A(x) \\
\vdash B \\
\hline
B \\
\end{array}
\]

What is the difference to $\exists-E$?

Problem: $\forall x. A(x)$ may still be needed.

Principle: Introduce duplicating rules. Turns search infinite!

Check out allE and all_duplicatedE in IFOL_lemmas.ML!
Proof Procedures (Simplified)

Tactics in Isabelle are performed in order:

1. REPEAT (rtac safe_I_rules ORELSE etac safe_E_rules)
2. canonize: propagate “$x = t$” throughout subgoal
3. rtac unsafe_I_rules ORELSE etac unsafe_E_rules
4. atac
Combined Proof Search Tactics

- **step_tac**: \( \text{claset} \to \text{int} \to \text{tactic} \)
  (just safe steps)
- **fast_tac**: \( \text{claset} \to \text{int} \to \text{tactic} \)
  (safe and unsafe steps in depth-first strategy)
- **best_tac**: \( \text{claset} \to \text{int} \to \text{tactic} \)
  (safe and unsafe steps in breadth-first strategy)
- **slow_tac**: \( \text{claset} \to \text{int} \to \text{tactic} \)
  (like fast_tac, but with backtracking atac’s)
- **blast_tac**: \( \text{claset} \to \text{int} \to \text{tactic} \)
  (like fast_tac, but often more powerful)
Summary on Automated Proof Search

- Proof search can be organized as a tree of theorems.
- Calculi can be set up to facilitate proof search (although this must be done by specialists).
- Combined with search strategies, powerful automatic procedures arise. Can prove well-known hard problems such as
  \[
  ((\exists y. \forall x. J(y, x) \lor \neg J(x, x)) \rightarrow \neg (\forall x. \exists y. \forall z. J(z, y) \lor \neg J(z, x)))
  \]
- Unfortunately, failure is difficult to interpret.
More Detailed Explanations
Sequent Calculus/Tableau

Tableau proving is a derivation system [Fit96].

It turns out that the language of tableaux is equivalent to the sequent calculus (recall our use of sequent style notation) [Pau97]. The techniques Isabelle uses for automating proofs can thereby be understood as tableau proving [Pau97].
Need for Automation

We have seen in the exercises that doing a proof step by step is very tedious and often involves difficult guessing or alternatively, backtracking. We cannot hope to prove anything about realistic systems if proving simple theorems is so tedious.

Efficiency considerations are important for automation. The non-determinacy in proof search obviously leads to inefficiencies as many possibilities have to be explored.
Which Subgoal?

We have seen in the exercises (and also in the lecture) that one can choose the subgoal to which one wants to apply a rule.
Technical Organization

We have seen in the previous lecture that resolution transforms a proof state into a new proof state. But how does one organize all those potential proof states in order to find proofs?
**A Tree of Theorems**

We have seen in the previous lecture that resolution transforms a proof state into a new proof state. Since in general, a proof state has several successor states (states that can be obtained by one resolution step), conceptually one obtains a tree where the children of a state are the successors.
The initial proof state is $\phi \implies \phi$. Isabelle will display this as

Level 1: (1 subgoal)

$\phi$

1. $\phi$

It might contradict your intuition and experience with Isabelle to think that the initial proof state is $\phi \implies \phi$. Shouldn’t it be just $\phi$? However, this seeming contradiction can be resolved. The way Isabelle displays the proof state focuses on **what has to be proven**, the subgoals. The proof state should be read as: if I have proven $\phi$ (the $\phi$ occurring after the 1.), I am done.

Technically, the proof state is an **Isabelle theorem** ($\text{thm}$), i.e. something which Isabelle regards as true. Now of course, she cannot initially regard
ϕ as true, as ϕ is what is to be proven. But she can regard ϕ → ϕ as true. The aim of a proof search is to transform ϕ → ϕ (ϕ can be shown if I assume ϕ) into ϕ (ϕ can be shown if I assume nothing).
Isabelle

For more details on Isabelle technicalities, you should consult the reference manual [Pau05].
Alternative Successors

Note that when there are no more successors (you cannot go down) anymore, `back()` will go to the previous proof state, i.e., go to the left one level (just like `undo()`), and then try alternative successors.
Isabelle Theorems

Technically, a proof state is an Isabelle theorem, (thm), i.e. something which Isabelle regards as true.
Explicit Tree Representation Expensive

Obviously, an infinite tree cannot be represented explicitly. But even if the tree is finite, it is generally expensive to represent it explicitly. In particular, the tree may contain many failing branches and only few successful ones, which begs the question if representing the unsuccessful branches cannot be avoided somehow.
Explicit Tree Representation not Abstract

The explicit tree representation is not very abstract in that each node has a defined order of the children (first successor, second successor, \ldots). This order is an artefact of the order in which unifiers are enumerated by the unification algorithm used. It is inessential for the proofs that are contained in the tree.

As a more abstract understanding of proof search, one can organize proof search as a relation on theorems (thm’s)

\[ \text{prooftrees} = \mathcal{P}(\text{thm} \times \text{thm}) \]

More precisely, one can look at a fragment of a tree of theorems as before, e.g.:
One could say that each tactic application (with a particular rule) gives rise to a relations on theorems. That is to say, $\phi$ and $\phi'$ are in the relation if $\phi'$ is a successor proof state of $\phi$.

This is abstract in that there is no order among the successors of a proof state.

Also, one does not represent a tree explicitly.

Advantage: we have an abstract algebra.

- $PT_1 \circ PT_2$: sequential composition ("then").

  Given two relations between thm's, $PT_1$ and $PT_2$, we define
composition $PT_1 \circ PT_2$ as the relation

$$\{(\phi, \psi) \mid \text{there is } \eta \text{ such that } (\phi, \eta) \in PT_1 \text{ and } (\eta, \psi) \in PT_2\}$$

- $PT_1 \cup PT_2$: alternative of proof attempts ("or")
  The union of two relations is defined as usual for sets. If $PT_1$ and $PT_2$ each model the application of a particular tactic, then $PT_1 \cup PT_2$ models the application of "first tactic or second tactic".

- $PT^*$: reflexive transitive closure ("repeat")
- $(\phi \Rightarrow \phi, \phi) \in PT^* \equiv \"there is a proof for \phi\"

$PT^*$ is inductively defined as the smallest set where

- $(\phi, \phi) \in PT^*$ for all $\phi$;
- if $(\phi, \eta) \in PT$ and $(\eta, \psi) \in PT^*$ then $(\phi, \psi) \in PT^*$.

So if $PT$ models the application of a particular tactic, then $PT^*$
models the application of that tactic arbitrarily many times. However, this also has some disadvantages:

- **Union** $\cup$ is difficult to implement (needs comparison with all previous results since one wants to avoid duplicates).

- More *operational*, strategic interpretations of union $\cup$ are desirable (try this — then that, interleave attempts in $PT_1$ with attempts in $PT_2$, and so forth).
A Function on Theorems

This way of understanding and organizing proof search is not so abstract, but rather operational. Instead of saying that $\phi$ and $\phi'$ are in a relation, one says that $\phi'$ is in the sequence returned by the tactic applied to $\phi$. There is an order among the successors of a proof state. One still does not represent a tree explicitly, although conceptually, proof search is about exploring this tree.

Back to main referring slide
Infinite Lists

For any type $\tau$, the type $\tau \text{ seq}$ (recall the notation) is the type of (possibly) infinite lists of elements of type $\tau$. This is of course an abstract datatype. There should be functions to return the head and the tail of such an infinite list.

An abstract datatype is a type whose terms cannot be represented explicitly and accessed directly, but only via certain functions for that type.
Tacticals

• THEN
• ORELSE
• REPEAT
• INTLEAVE, BREADTHFIRST, DEPTHFIRST, . . .

are called tacticals.

Tacticals are operations on tactics. They play an important role in automating proofs in Isabelle. The most basic tacticals are THEN and ORELSE. Both of those tacticals are of type tactic \* tactic \rightarrow tactic and are written infix: \textit{tac}_1 \text{ THEN } \textit{tac}_2 applies \textit{tac}_1 and then \textit{tac}_2, while \textit{tac}_1 \text{ ORELSE } \textit{tac}_2 applies \textit{tac}_1 if possible and otherwise applies \textit{tac}_2 [Pau05, Ch. 4].
Mimicking Isabelle

That is to say, $\land E'$ behaves for the sequent notation as $\text{conjE}$ behaves for Isabelle.
\( \wedge\text{-}E \)

In Isabelle notation, it looks as follows:

\[
[P \& Q; \ [P; Q] \Rightarrow R] \Rightarrow R
\]

(see IFOL_lemmas.ML).
**Blind Application of $\land$-E'$**

See now that we first derived the rule $\land$-E', which is a rule that can be used blindly to decompose a conjunction in the assumptions. This was not something ad-hoc to prove this particular formula. The rule $\land$-E' should be used generally instead of $\land$-EL or $\land$-EL, because it has the advantage that it can be applied blindly.

The essential point about being able to apply a rule blindly is that the application does not throw any information away. This is indeed the case for $\land$-E'. We remove the assumption $\phi \land \psi$, but we get the two conjuncts $\phi$ and $\psi$ as assumptions instead.

The rule $\land$-E' mimics the effect of using $\land$-E in combination with etac, which you can see by looking again at the exercises on etac.
claset

claset is an abstract datatype. Overloading notation, claset is also an ML unit function which will return a term of that datatype when applied to (), namely, the current classifier set. A classifier set determines which rules are safe and unsafe introduction, respectively elimination rules. The current classifier set is a classifier set used by default in certain tactics. The current classifier set can be accessed via special functions for that purpose.
Accessing the claset

The functions `addSIs`, `addSEs`, `addIs`, `addEs` are all of type `claset \times \text{thm list} \rightarrow \text{claset}`. They add rules to the current classifier set. For example, `addSIs` adds a rule as **safe introduction rule**.
Emulating the Sequent Calculus

The sequent calculus works with expressions of the form \(A_1, \ldots, A_n \vdash B_1, \ldots, B_m\) which should be interpreted as: under the assumptions \(A_1, \ldots, A_n\), at least one of \(B_1, \ldots, B_m\) can be proven. So as a formula, this would be \(A_1 \land \ldots \land A_n \rightarrow B_1 \lor \ldots \lor B_m\).

In Isabelle (and the proof trees we have seen, e.g., in this lecture), we only have sequents with one formula to the right of the \(\vdash\). We have said that we use sequent notation.

The important point to note here is that in the sequent calculus, one can shift a formula from left to right or vice versa, but one has to negate it, or more precisely, turn \(A\) into \(\neg A\) and \(\neg A\) into \(A\). This is called swapping and is an important technique for combined tactics.

The sequent calculus inherently relies on classical reasoning [Pau05, Ch. 11].
Deriving \texttt{allE}

You should do it in Isabelle. The rule is:

\[
[\forall x. P(x); P(x) \implies R] \implies R
\]
Name Confusion

As you may have noticed earlier, there is a confusion between the names of proof rules as we present them for the theory and the names used in Isabelle. For example, rule $\rightarrow\!-E$ is called $\mathtt{mp}$ in Isabelle. This confusion concerns elimination rules.

There is however a good reason for these choices. In traditional presentations of logic, one sets up the simplest possible elimination rules for the connectives which naturally arise from the meaning of those connectives. This is what we have done as well. However, as we see in this lecture, these rules cannot be applied blindly and are thus not very suitable for automation. Therefore, combined tactics in Isabelle use derived rules such as $\land\!-E$ (called $\mathtt{conjE}$ in Isabelle).

Since this is of such central importance for Isabelle, one prefers to have the obvious names $\mathtt{conjE}$, $\mathtt{allE}$ etc. for the rules that are actually used.
in “advanced” applications of Isabelle.
The rule
\[ \frac{\exists x. A(x) \quad B}{B} \exists-E \]

was derived previously (but in Isabelle, it is a basic rule in \texttt{IFOL.ML}). It is
\[ \llbracket \forall x. P(x); \square x. P(x) \Rightarrow R \rrbracket \Rightarrow R \]

Note that the rule \texttt{allE} ($\forall$-\texttt{E}$'$) is
\[ \llbracket \forall x. P(x); P(x) \Rightarrow R \rrbracket \Rightarrow R \]

The difference is that the former rule contains a metalevel universal quantifier. In terms of paper-and-pencil proofs, \(\exists\)-\texttt{E} has the side
condition that $x$ must not occur free in any assumption on which $B$ (see tree!) depends. There is no such side condition for $\forall\neg E'$. 
**Difference between $\forall-E'$ and $\exists-E$**

The difference between

\[
\begin{array}{c}
\exists x.A(x) \\
\vdots \\
B \\
\end{array}
\]

\[
\begin{array}{c}
\forall x. A(x) \quad B \\
\ldots \quad B \\
\sym{\exists-E} \\
\end{array}
\]

and

\[
\begin{array}{c}
\forall x. A(x) \\
\vdots \\
B \\
\end{array}
\]

\[
\begin{array}{c}
\forall x. A(x) \quad B \\
\ldots \quad B \\
\sym{\forall-E'} \\
\end{array}
\]

is that the first rule has a side condition: $x$ must not occur free in any assumption on which $B$ depends. See also what this means in terms of Isabelle.
The Rule \( \lor\text{-}swap \)

The rule \( \lor\text{-}swap \) is

\[
\neg A, \Gamma \vdash B \\
\frac{}{\Gamma \vdash A \lor B} \lor\text{-}swap
\]

To derive it you need classical reasoning, as the rule exploits the equivalence of \( A \rightarrow B \) and \( \neg A \lor B \).

This is a derived rule which is explicitly contained in the Isabelle classifier set as the classical introduction rule for \( \lor \). It is called \texttt{disjCI} (check out \texttt{FOL\_lemmas1.ML})!
The Rule $\rightarrow$-\textit{swapE}

The rule $\rightarrow$-\textit{swapE} is

$$
\begin{align*}
A, \neg C, \Gamma & \vdash B \\
\neg (A \rightarrow B), \Gamma & \vdash C
\end{align*}
\rightarrow$-\textit{swapE}

To derive it you need classical reasoning, as the rule exploits the equivalence of $\neg (A \rightarrow B)$ and $A \land \neg B$.

This is a standard technique in Isabelle, based on swapping. For dealing with negated formulas in the premises of the current subgoal, introduction rules are combined with swap using etac.

Generally, we have a formula $\neg (A \circ B)$ in the premises, where $\circ$ is some binary connective. Swapping will put $(A \circ B)$ in the conclusion and put the old conclusion into the premises after negating it. Afterwards, an introduction rule for $\circ$ will be used [Pau05, Section 11.2].
Duplicating Rules

You should recall that elimination rules are used in combination with \texttt{etac}. Using \texttt{allE} will eliminate the quantifier.

You should \textbf{try a proof} of the formula $(\forall x. P(x)) \rightarrow (P(a) \land P(b))$ in Isabelle to convince yourself that this is a problem since the quantified formula $\forall x. P(x)$ is needed twice as an assumption, with two different instantiations of $x$.

The duplicating rule $\forall$-\textit{dupE} has the effect that the universally quantified formula will still remain as an assumption.
Infinite Proof Search

Given only the rules so far (in combination with the appropriate tactics, `rtac` and `etac`, and `swapping`), excluding `∀-dupE`, the proof search would be finite. The rule `∀-dupE` is responsible for making the proof search infinite. This can be no surprise however, as first-order logic is undecidable [And02], and so there can be no automatic procedure for proving all true first-order formulas.
Isabelle Files

These files should be contained in your Isabelle distribution. In Freiburg they are located at:

```
/usr/local/share/provers/Isabelle/src/FOL/
```
Proof Procedures

Tactics in Isabelle are performed in order:

1. REPEAT (rtac safe_I_rules ORELSE etac safe_E_rules);
2. canonize: propagate "x = t" . . . throughout subgoal;
3. rtac unsafe_I_rules ORELSE etac unsafe_E_rules;
4. atac.

One elementary proof step consists of trying a safe introduction rule with rtac, or, if that is not possible, a safe elimination rule with etac. This will be repeated as long as possible.

Then in the current subgoal, any assumption of the form \( x = t \) (where \( x \) is a metavariable) will be propagated throughout the subgoal, i.e., all occurrences of \( x \) will be replaced by \( t \).

Then Isabelle will try one application of an unsafe introduction rule with
rtac, or, if that is not possible, an unsafe elimination rule with etac. Finally, she will use atac. Note that atac is unsafe. In general, there are several premises in a subgoal and atac may unify the conclusion of the subgoal with the wrong premise.
Failure in Classical Reasoning

`fast_tac`, `blast_tac` just tell you that the tactic failed, but not why. And it would be difficult to do that, since backtracking means that all attempts failed. This can have several reasons: a rule is missing, a rule has been classified wrongly, the search strategy was not adequate for the problem, enumeration of unifiers in a bad order. Or a combination thereof. Or it might be that too many unsafe steps are needed, since `fast_tac` limits their number.
Term Rewriting
Outline of this Part

- Higher-order rewriting
- Extensions: Ordered, pattern, congruence, splitting rewriting
- Organizing simplification rules

In this context, a term is a $\lambda$-term, since we use the $\lambda$-calculus to encode object logics.
Higher-Order Rewriting

Motivation:
- Simplification is a very important part of deduction, e.g.:
  \[ 0 + (x + 0) = x \]
  \[ [a, b, d] @ [a, b] = [a, b, d, a, b] \]
- Based on rewrite rules as in functional programming:
  \[ x + 0 = x, \quad 0 + x = x \]
  \[ [] @ X = X, \quad (x :: X) @ Y = x :: (X @ Y) \]
Term Rewriting: Foundation

- **Recall:** An equational theory consists of rules

\[
\begin{align*}
\text{refl} & : & x = x \\
\text{sym} & : & x = y \quad y = x \\
\text{trans} & : & x = y \quad y = z \quad x = z \\
\text{subst} & : & x = y \quad P(x) \quad \frac{P(y)}{P(x)}
\end{align*}
\]

- plus additional (possibly conditional) rules of the form

\[
\phi_1 = \psi_1, \ldots, \phi_n = \psi_n \Rightarrow \phi = \psi.
\]

The additional rules can be interpreted as rewrite rules, i.e. they are applied from **left** to **right**.
Incomplete Decision Procedure for Goal $e = e'$

To decide if $e = e'$ in an equational theory:
1. stop if the goal is solved, i.e., $e \equiv e'$ (syntactical equality)
**Incomplete Decision Procedure for Goal** \( e = e' \)

To decide if \( e = e' \) in an equational theory:

1. **stop** if the goal is **solved**, i.e., \( e \equiv e' \) (syntactical equality)
2. make a rewrite step:
   
   (a) pick a subterm \( t \) in \( e(t) \)
Incomplete Decision Procedure for Goal \( e = e' \)

To decide if \( e = e' \) in an equational theory:

1. **stop** if the goal is solved, i.e., \( e \equiv e' \) (syntactical equality)

2. make a rewrite step:
   (a) pick a subterm \( t \) in \( e(t) \)
   (b) for a rewrite rule \( \phi = \psi \), **match** (unify) \( \phi \) against \( t \), i.e., find \( \theta \) such that \( \phi \theta = t \)
Incomplete Decision Procedure for Goal $e = e'$

To decide if $e = e'$ in an equational theory:

1. **stop** if the goal is solved, i.e., $e \equiv e'$ (syntactical equality)

2. make a rewrite step:
   (a) pick a subterm $t$ in $e(t)$
   (b) for a rewrite rule $\phi = \psi$, match (unify)$\phi$ against $t$, i.e., find $\theta$ such that $\phi \theta = t$
   (d) replace $e(t)$ by $e(\psi \theta)$
Incomplete Decision Procedure for Goal $e = e'$

To decide if $e = e'$ in an equational theory:

1. **stop** if the goal is **solved**, i.e., $e \equiv e'$ (syntactical equality)

2. **make a rewrite step**:
   (a) pick a subterm $t$ in $e(t)$
   (b) for a rewrite rule $\phi = \psi$, match (unify) $\phi$ against $t$, i.e., find $\theta$ such that $\phi\theta = t$
   (d) replace $e(t)$ by $e(\psi\theta)$

3. **goto** 1
Incomplete Decision Procedure for Goal \( e = e' \)

To decide if \( e = e' \) in an equational theory:

1. **stop** if the goal is **solved**, i.e., \( e \equiv e' \) (syntactical equality)

2. make a rewrite step:
   (a) pick a subterm \( t \) in \( e(t) \) (resp. \( e'(t) \))
   (b) for a rewrite rule \( \phi = \psi \), **match** (unify)
       \( \phi \) against \( t \), i.e., find \( \theta \) such that \( \phi \theta = t \)
   (d) replace \( e(t) \) by \( e(\psi \theta) \) (resp. \( e'(t) \) by \( e'(\psi \theta) \))

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   (b) for a rewrite rule \( \phi_1 = \psi_1, \ldots, \phi_n = \psi_n \implies \phi = \psi \), match (unify) \( \phi \) against \( t \), i.e., find \( \theta \) such that \( \phi\theta = t \)

   (c) **solve** \( (\phi_1 = \psi_1, \ldots, \phi_n = \psi_n)\theta \)

   (d) replace \( e(t) \) by \( e(\psi\theta) \) (resp. \( e'(t) \) by \( e'(\psi\theta) \))

3. **goto 1**
Incomplete Decision Procedure for Goal $e = e'$

To decide if $e = e'$ in an equational theory:

1. **stop** if the goal is **solved**, i.e., $e \equiv e'$ (syntactical equality)

2. make a rewrite step:
   (a) pick a subterm $t$ in $e(t)$ (resp. $e'(t)$)
   (b) for a rewrite rule $\phi_1 = \psi_1, \ldots, \phi_n = \psi_n \Rightarrow \phi = \psi$, **match** (unify) $\phi$ against $t$, i.e., find $\theta$ such that $\phi\theta = t$
   (c) **solve** $(\phi_1 = \psi_1, \ldots, \phi_n = \psi_n)\theta$
   (d) replace $e(t)$ by $e(\psi\theta)$ (resp. $e'(t)$ by $e'(\psi\theta)$)

3. **goto** 1

This procedure + the rules define a **term rewriting system**.
Term Rewriting is Non-Trivial

- There are two major problems: this decision procedure may fail because:
  - it diverges (the rules are not terminating), e.g. $x + y = y + x$ or $x = y \implies x = y$;
**Term Rewriting is Non-Trivial**

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  - it diverges (the rules are *not terminating*), e.g. $x + y = y + x$ or $x = y \implies x = y$;
  - rewriting does not yield a unique normal form (the rules are not *confluent*), e.g. rules $a = b$, $a = c$. 

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Term Rewriting is Non-Trivial

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  - rewriting does not yield a unique normal form (the rules are not confluent), e.g. rules $a = b$, $a = c$.

- Providing criteria for terminating and confluent rule sets is an active research area (see [BN98, Klo93, RTA, ...]).
Extensions of Rewriting

- Symmetric rules are problematic, e.g. ACI:

\[
\begin{align*}
(x + y) + z &= x + (y + z) & \text{(A)} \\
x + y &= y + x & \text{(C)} \\
x + x &= x & \text{(I)}
\end{align*}
\]
Extensions of Rewriting

• Symmetric rules are problematic, e.g. ACI:

\[(x + y) + z = x + (y + z) \quad (A)\]
\[x + y = y + x \quad (C)\]
\[x + x = x \quad (I)\]

• Idea: apply only if replaced term gets smaller w.r.t. some term ordering. In example, if \((y + x)\theta\) is smaller than \((x + y)\theta\).

• Ordered rewriting solves rewriting modulo ACI, using derived rules (exercise).
Extension: HO-Pattern Rewriting

Rules such as $F(Gc) = \ldots$ lead to highly ambiguous matching and hence inefficiency.

Solution: restrict l.h.s. of a rule to higher-order patterns.
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Solution: restrict l.h.s. of a rule to higher-order patterns.
A term $t$ is a HO-pattern if
• it is in $\beta$-normal form; and
• any free $F$ in $t$ occurs in a subterm $Fx_1 \ldots x_n$ where the $x_i$ are $\eta$-equivalent to distinct bound variables.
Extension: HO-Pattern Rewriting

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Matching (unification) is decidable, unitary ('unique') and efficient algorithms exist.
A rule \( \Rightarrow \phi = \psi \) is a HO-pattern rule if:

- \( \phi \) is a HO-pattern;
- all free variables in \( \psi \) occur also in \( \phi \); and
- \( \phi \) is constant-head, i.e., of the form \( \lambda x_1 \ldots x_m . c \, p_1 \ldots p_n \) (where \( c \) is a constant, \( m \geq 0 \), \( n \geq 0 \)).
HO-Pattern Rewriting (Cont.)

A rule \( \Rightarrow \phi = \psi \) is a HO-pattern rule if:

- \( \phi \) is a HO-pattern;
- all free variables in \( \psi \) occur also in \( \phi \); and
- \( \phi \) is constant-head, i.e. of the form \( \lambda x_1 \ldots x_m . c p_1 \ldots p_n \) (where \( c \) is a constant, \( m \geq 0 \), \( n \geq 0 \)).

Example: \( (\forall x. P x \land Q x) = (\forall x. P x) \land (\forall x. Q x) \)

Result: HO-pattern allows for very effective quantifier reasoning.
Extensions Related to if \(\text{– then} \text{– else}\)

The if-then-else construct will play an important role later. It asks for special rewrite rules.
Extension: Congruence Rewriting

Problem:

\[
\text{if } A \text{ then } P \text{ else } Q = \text{ if } A \text{ then } P' \text{ else } Q
\]

where \( P = P' \) under condition \( A \)

is not a rule.

Solution in Isabelle: explicitly admit this extra class of rules (congruence rewriting)

\[
[A \Rightarrow P = P'] \Rightarrow \\
\text{if } A \text{ then } P \text{ else } Q = \text{ if } A \text{ then } P' \text{ else } Q
\]
Extension: Splitting Rewriting

Problem:

\[ P(\text{if } A \text{ then } x \text{ else } y) = \text{if } A \text{ then } (P \; x) \text{ else } (P \; y) \]

is not a HO-pattern rule (since it is not constant-head).

Solution in Isabelle: explicitly admit this extra class of rules (case splitting).
Organizing Simplification Rules

- Standard (HO-pattern conditional ordered rewrite) rules;
- congruence rules;
- splitting rules.

Isabelle data structure: simpset. Some operations:
- addsimps : simpset * thm list → simpset
- delsimps : simpset * thm list → simpset
- addcongs : simpset * thm list → simpset
- addsplits : simpset * thm list → simpset

Commutativity can be added without losing termination.
How to Apply the Simplifier?

Several versions of the simplifier:

- \texttt{simp\_tac: simpset \rightarrow int \rightarrow tactic}
- \texttt{asm\_simp\_tac: simpset \rightarrow int \rightarrow tactic}
  (includes assumptions into simpset)
- \texttt{asm\_full\_simp\_tac: simpset \rightarrow int \rightarrow tactic}
  (rewrites assumptions, and includes them into simpset)

Using \texttt{global} simplifier sets: \texttt{Simp\_tac}, \texttt{Asm\_simp\_tac}, \texttt{Asm\_full\_simp\_tac}.
Summary on Term Rewriting

Simplifier is a powerful proof tool for

- conditional equational formulas
- ACI-rewriting
- quantifier reasoning
- congruence rewriting
- automatic proofs by case splitting

Fortunately, failure is quite easy to interpret.
Summary on Last Three Sections

• Although Isabelle is an interactive proof construction, it is a flexible environment with powerful automated proof procedures.
• For classical logic and set theory, tableau-like procedures like blast_tac and fast_tac decide many tautologies.
• For equational theories (datatypes, evaluating functional programs, but also higher-order logic) simp_tac decides many tautologies (and is fairly easy to control).
More Detailed Explanations
\[ 0 + (x + 0) = x \]

Simplifying \(0 + (x + 0)\) to \(x\) is something you have learned in school. It is justified by the usual semantics of arithmetic expressions. Here, however, we want to see more formally how such simplification works, rather than why it is justified.
Lists

Lists are a common datatype in functional programming. \([a, b, d, a, b]\) is a list. Actually, this notation is syntactic sugar for \(a :: (b :: (d :: (a :: (b :: []))))\). Here, [] is the empty list and :: is a term constructor taking an element and a list and returning a list. @ stands for list concatenation.

Intuitively, it is clear that \([a, b, d]\) concatenated with \([a, b]\) yields \([a, b, d, a, b]\).

Term constructor is usual terminology in functional programming. In first-order logic, we would speak of a function symbol. In the \(\lambda\)-calculus, we would speak of a (special kind of) constant (this will become clear later).
Functional Programming

For example, the lines

\[
[] \@ X = X \\
(x :: X) \@ Y = x :: (X \@ Y)
\]

define the list concatenation function \(\@\).
Rewrite Rules

An equational theory is a formalism based on equational rules of the form \( \phi_1 = \psi_1, \ldots, \phi_n = \psi_n \implies \phi = \psi \).

A term rewriting system (to be defined shortly) is another formalism, based of rewrite rules. They also have the form \( \phi_1 = \psi_1, \ldots, \phi_n = \psi_n \implies \phi = \psi \), but they have a different flavor in that \( = \) must be interpreted as a directed symbol. One could also write \( \rightsquigarrow \) instead of \( = \) to emphasize this.
Matching

Given two terms $s$ and $t$, a unifier is a substitution $\theta$ such that $s\theta = t\theta$. A match is a substitution which only instantiates one of $s$ or $t$, so $s\theta = t$ or $s = t\theta$ (one should usually clarify in the given context which of the terms is instantiated).
Solve \((\phi_1 = \psi_1, \ldots, \phi_n = \psi_n)\theta\)

This means that the procedure is called recursively for the conditions of the rewrite rule.
Term Rewriting System

The procedure defines a term rewriting system [BN98, Klo93]. Equational theories, term rewriting systems, propositional logic, first-order logic, different versions of the $\lambda$-calculus — with all those different formalisms playing a role here, we must agree on some terminology. In particular, the words term, function, predicate, constant and variable are used somewhat differently in the different formalisms.

Our point of reference for the terminology is the $\lambda$-calculus as it is built into Isabelle for representing object logics. In particular:

- A term is a $\lambda$-term; object-level formulae (including equations) as well as object-level terms are all represented as $\lambda$-terms, and so for example, when we rewrite an equation, we rewrite a term.
- One could say that a function is any $\lambda$-term of functional type, i.e., of type containing at least one $\rightarrow$. Apart from that, there may be
function symbols in some object logic. On the metalevel (and hence also for the purpose of term rewriting), these would be constants.

• There may be predicate symbols in some object logic. On the metalevel (and hence also for the purpose of term rewriting), these would be constants.

• A constant is a $\lambda$-term consisting of just one symbol from a set $Const$. Constants of the $\lambda$-calculus may be used to represent connectives, quantifiers, functions, predicates or any other symbols that an object logic may contain.

• The notion of variable is that of the metalevel, and so we usually mean “variables including metavariables”.

Nevertheless, some confusion may arise wherever we use the terminology from the point of view of an object logic. See the following example:
The following is an example rewrite sequence, using the rules for lists. The picked subterm which is being replaced is underlined in each step:

\[
(a :: (b :: (d :: [])))) \odot (a :: (b :: [])) \quad = \quad [a, b, d, a, b] \quad \rightsquigarrow \\
a :: ((b :: (d :: [])) \odot (a :: (b :: []))) \quad = \quad [a, b, d, a, b] \quad \rightsquigarrow \\
a :: (b :: ((d :: []) \odot (a :: (b :: [])))) \quad = \quad [a, b, d, a, b] \quad \rightsquigarrow \\
a :: (b :: (d :: ([] \odot (a :: (b :: []))))) \quad = \quad [a, b, d, a, b] \quad \rightsquigarrow \\
a :: (b :: (d :: (a :: (b :: [])))) \quad = \quad [a, b, d, a, b] \quad \rightsquigarrow 
\]

Note the we are done now, as the right-hand side is identical to the left-hand side, modulo the use of syntactic sugar.

Note that generally, a term rewriting sequence rewrites arbitrary terms. Here we only rewrite equations. From the point of view of term rewriting, an equation is just a special case of a term.

One could also imagine that object-level function and predicate symbols
are represented as variables, as is done in LF. Recall Perlis’ epigram.
$a = b, a = c$  

For a rewriting system consisting of rules $a = b$, $a = c$, one cannot rewrite $b = c$ to prove the equality, although it holds:

$$
\frac{a = b}{b = a} \quad \text{sym}
\frac{a = c}{b = c} \quad \text{trans}
$$
Term Ordering

The biggest problem for term rewriting is (non-)termination. For some crucial rules, this problem is solved by ordered term rewriting. A term ordering is any partial order between ground (i.e., not containing free variables) terms.

One can define a term ordering by giving some function, called norm, from ground terms to natural numbers. Then a term is smaller than another term if the number assigned to the first term is smaller than the number assigned to the second term.
ACI

ACI stands for associative, commutative and idempotent. In

\[(x + y) + z = x + (y + z) \quad (A)\]
\[x + y = y + x \quad (C)\]
\[x + x = x \quad (I)\]

the constant \(+\) is written infix.
How Ordered Rewriting Solves ACI

Consider an equational theory consisting only of those rules (apart from \textit{refl, sym, trans, subst}). Apart from that, the language may contain arbitrary other constant symbols. For such a language, it is possible to give a term ordering that will assign more weight to the same term on the left-hand-side of a $+$ than on the right-hand side. We can base such a term ordering on a \textit{norm}. For example, the inductive definition of a norm $|\_|$ might include the line:

\[
|s + t| := 2|s| + |t|
\]

This means that if $|s| > |t|$, then $|s + t| = 2|s| + |t| > 2|t| + |s| = |t + s|$. This has two effects:

- Applications of (A) or (l) always decrease the weight of a term
(provided the weight of $s$ is $> 0$):

\[
| (s + t) + r | = 2|s + t| + |r| = 4|s| + 2|t| + |r| > 2|s| + 2|t| + |r| = 2|s| + |t + r| = |s + (t + r)|.
\]

- Applications of (C) are only possible if the left-hand side is heavier than the right-hand side.

We haven’t worked out here how the norm should be defined for the other symbols of the language. This would have to depend on that language.

The notation $|\_|$ (the argument is between the bars) is used in standard mathematics for the absolute value of a number and is standard for norms as well.
Ambiguous Matching

For higher-order rewriting, it is very problematic to have rules containing terms of the form $F(Gc)$ on the left-hand side, where $F$ and $G$ are free variables and $c$ is a constant or bound variable. The reason can be seen in an example: Suppose you want to rewrite the term $f(g(h(ic)))$ where $f$, $g$, $h$, $i$ are all constants. There are four unifiers of $F(Gc)$ and $f(g(h(ic)))$:

\[
\begin{align*}
[F &\leftarrow f, \quad G &\leftarrow (\lambda x.g(h(i \ x)))], \\
[F &\leftarrow (\lambda x.f(g \ x)), \quad G &\leftarrow (\lambda x.h(i \ x))], \\
(F &\leftarrow \lambda x.f(g(h \ x))), \quad G &\leftarrow (\lambda x.i \ x)], \\
((F &\leftarrow \lambda x.f(g(h(i \ x)))), \quad G &\leftarrow (\lambda x.x)).
\end{align*}
\]

This ambiguity makes such TRSs very inefficient.
\[ \forall, \exists \text{ is a Constant} \]

Further examples:

- \[(\exists x. P x \lor Q x) = (\exists x. P x) \lor (\exists x. Q x)\]
- \[(\exists x. P \rightarrow Q x) = P \rightarrow (\exists x. Q x)\]
- \[(\exists x. P x \rightarrow Q) = (\forall x. P x) \rightarrow Q\]

In these examples, you may assume that first-order logic is our object logic.

On the metalevel, and hence also for the sake of term rewriting, \(\forall, \exists\) are constants.

In the notation \((\forall x. P x \land Q x)\), the symbols \(P\) and \(Q\) are metavariables (as far as term rewriting is concerned, simply think: variables).

Actually, \((\forall x. P x \land Q x)\) mixes object and metalevel syntax in a way which is typical for Isabelle: \((\forall x. P x \land Q x)\) is a “pretty-printed” version
of ALL \((P \& Q)\).

You may want to look at a theory file (say, IFOL.thy) to get a flavor of this. The principle was explained thoroughly before.
**Nested**

Rewrite rules have the form $\phi_1 = \psi_1, \ldots, \phi_n = \psi_n \implies \phi = \psi$ (several equations imply one equation). It is not possible that any of the equations $\phi_1 = \psi_1, \ldots, \phi_n = \psi_n$ again depend on some condition, as in

$$
\text{if } A \text{ then } P \text{ else } Q = \text{if } A \text{ then } P' \text{ else } Q
$$

where $P = P'$ under condition $A$
simpset

The simpset is an abstract datatype and at the same time an ML unit function for returning the current simplifier set. This is in analogy to the classifier set.
Accessing the simpset

These function manipulate the simplifier set, in analogy to the classifier set.
Global simpset

Simp_tac, Asm_simp_tac, Asm_full_simp_tac work like their lower-case counterparts but use the current (global) simplifier set and hence do not take a simplifier set as first argument (e.g., Simp_tac has type \( \text{int} \to \text{tactic} \))

There are analogous capitalized versions for the tactics of the classical reasoner.
Failure in Simplifier

When you use simp_tac, usually you can just look at the term that you get to understand which simplification has not worked although you think that it should have worked.
Isabelle’s Metalogic
Representing Syntax and Proofs

- Previously, we have seen how the (polymorphically) typed $\lambda$-calculus can be used to represent the syntax of an object logic.

- Today, we will extend the $\lambda$-calculus to a logic (with formulae and inference rules): Isabelle’s metalogic, which goes under the names of $\mathcal{M}$, Pure, HOL.

This lecture is based on Paulson’s work [Pau89]. It is maybe the most challenging lecture of this course.
What Is Formality anyway?

- Ultimately, logic and formal reasoning have to resort to natural language. Proofs of, say, the soundness of a derivation system employ the usual mathematical rigor, but that’s all. Imagine this for the situation that we just want to do reasoning in propositional logic and nothing else.

- We will now introduce a logic $\mathcal{M}$. Its proof system is small!
Proof Techniques = Meta-Theorems

• When constructing proofs, there are
  ○ aspects that are specific to certain logics and its logical symbols: the proof rules;
  ○ aspects that reflect general principles of proof building: making and discharging assumptions, substitution, side conditions, resolution.

It seems that the latter must be justified by complicated (and thus error-prone) explanations in natural language.
Proof Techniques $\equiv$ Meta-Theorems

- When constructing proofs, there are
  - aspects that are specific to certain logics and its logical symbols: the proof rules;
  - aspects that reflect general principles of proof building: making and discharging assumptions, substitution, side conditions, resolution.

It seems that the latter must be justified by complicated (and thus error-prone) explanations in natural language.

- Using a metalogic such as $\mathcal{M}$ has two benefits:
  - Shared implementational support for the “general principles”;
  - to a wide extent, the “general principles” are formally derived in $\mathcal{M}$. This gives a high degree of confidence.
The Logic $\mathcal{M}$

We first introduce $\mathcal{M}$ just like any other logic, without considering its special role as metalogic. Nonetheless, we use the qualification “meta” to avoid confusion later. Some variations are possible (mainly: polymorphism/type classes or not), but those are not so important for us.
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So far, $\lambda \rightarrow$ is not a logic (no connectives, no formulae). We will now extend it to a logic.
Logic Based on $\lambda \to$

Assume some $B$ where $bool \in B$, and some signature $\Sigma$ where

- $\Rightarrow: bool \to bool \to bool \in \Sigma$,
- $\equiv_\sigma: \sigma \to \sigma \to bool \in \Sigma$ for all types $\sigma$, and
- $\bigwedge_\sigma: (\sigma \to bool) \to bool \in \Sigma$ for all types $\sigma$.

We usually omit type subscripts and write $\equiv$, $\bigwedge$. $\Rightarrow$, $\equiv$, and $\bigwedge$ are the logical symbols of $\mathcal{M}$. $\Rightarrow$ and $\equiv$ are written infix.

Terms of type $bool$ are called
Logic Based on $\lambda \to$

Assume some $B$ where $bool \in B$, and some signature $\Sigma$ where

- $\Rightarrow$: $bool \rightarrow bool \rightarrow bool \in \Sigma$,
- $\equiv_\sigma$: $\sigma \rightarrow \sigma \rightarrow bool \in \Sigma$ for all types $\sigma$, and
- $\land_\sigma$: $(\sigma \rightarrow bool) \rightarrow bool \in \Sigma$ for all types $\sigma$.

We usually omit type subscripts and write $\equiv$, $\land$.

$\Rightarrow$, $\equiv$, and $\land$ are the logical symbols of $\mathcal{M}$. $\Rightarrow$ and $\equiv$ are written infix.

Terms of type $bool$ are called (meta-)formulae: types generalize syntactic categories.
Folding Assumptions

Lists of (meta-)formulae are denoted by \( \Phi, \Psi, \Omega \). If \( \Phi \) is the list \([\phi_1, \ldots, \phi_n]\), then

\[
[\phi_1, \ldots, \phi_n] \Rightarrow \psi, \text{ i.e. } \Phi \Rightarrow \psi
\]

abbreviates the meta-formula \( \phi_1 \Rightarrow \ldots \Rightarrow \phi_n \Rightarrow \psi \).

You have seen this in the exercises.

Note that \([\phi_1, \ldots, \phi_n]\) on its own is not a term in \( \mathcal{M} \)!
Proof System for $\mathcal{M}$

The proof system will be presented in the style of natural deduction.

This is as formal as we get (for the metalogic): derivation trees in natural deduction style are authoritative.

The judgements, just like for natural deduction proofs in propositional logic or first-order logic, are formulae, i.e., terms of type $\text{bool}$. This is in contrast to derivability judgements or type judgements.
Rules for $\Rightarrow$

\[
\begin{align*}
\frac{[\phi]}{} & \Rightarrow -I \\
\vdots & \\
\psi & \Rightarrow -I \\
\phi \Rightarrow \psi & \Rightarrow -E
\end{align*}
\]

Just like rules for $\rightarrow$!
Rules for $\Rightarrow$

$$
\begin{align*}
\text{[\[\phi\]\ldots]} \\
\quad \downarrow \\
\psi \\
\hline
\phi \Rightarrow \psi & \Rightarrow -I \\
\hline
\phi \Rightarrow \psi \\
\hline
\phi \\
\quad \downarrow \\
\psi & \Rightarrow -E
\end{align*}
$$

Just like rules for $\rightarrow$!

For layout reasons we sometimes use

$$
\begin{align*}
\phi \\
\phi \Rightarrow \psi \\
\hline
\psi & \Rightarrow -E
\end{align*}
$$
Rules for $\forall$

Meta-universal-quantification is formalized in the style of higher-order abstract syntax; may write $\forall x.\phi$ as syntactic sugar for $\forall(\lambda x.\phi)$.

Note: quantification over terms of arbitrary type!
Rules for \( \land \)

Meta-universal-quantification is formalized in the style of higher-order abstract syntax; may write \( \land x.\phi \) as syntactic sugar for \( \land(\lambda x.\phi) \).

Note: quantification over terms of arbitrary type!

Rules:

\[
\begin{align*}
\phi & \quad \land x.\phi \\
\hline
\land x.\phi & \quad \land-\Im
\end{align*}
\]

\[
\begin{align*}
\land x.\phi & \quad \phi [x \leftarrow b] \\
\hline
\land x.\phi & \quad \land-E
\end{align*}
\]

Side (eigenvariable) condition \( \ast \): \( x \) is not free in any assumption on which \( \phi \) depends.

Just like rules for \( \forall \).
Rules for $\equiv$: Equivalence Relation

- $a \equiv a \equiv$-refl

- $a \equiv b \equiv$-symm

- $a \equiv b \quad b \equiv c \quad a \equiv c \equiv$-trans

Just like rules for $=$.
Rules for $\equiv$: $\lambda$ (i.e., $\alpha$, $\beta$, $\eta$) Conversions

\[
(\lambda x. a) \equiv (\lambda y. a[x \leftarrow y]) \quad \alpha^* \\
(\lambda x. a)b \equiv (a[x \leftarrow b]) \quad \beta \\
(\lambda x. f x) \equiv f \quad \eta^{**}
\]

Side condition $\ast$: $y$ is not free in $a$.
Side condition $\ast\ast$: $x$ is not free in $f$.
Just like rules for $=_{\alpha,\beta,\eta}$.
$\eta$ is equivalent to extensionality.
Rules for \( \equiv \): Abstraction, Combination

\[
\frac{a \equiv b}{(\lambda x.a) \equiv (\lambda x.b)} \equiv\text{-abstr}^* \\
\frac{f \equiv g}{f \ a \equiv g \ b} \equiv\text{-comb}
\]

Side (eigenvariable) condition \(*\): \( x \) is not free in any assumption on which \( a \equiv b \) depends.

As defined for \( \rightarrow_\beta \) before, \( \equiv \) is propagated into contexts.

Conversion is built into the proof system!

Recall that \( e \equiv e' \) is decidable in \( \lambda \rightarrow \) (\( \equiv\)-rules so far).

However, \( e \equiv e' \) is not decidable in \( \mathcal{M} \) (see next slide).
Rules for $\equiv$: Introduction and Elimination

\[
\begin{array}{c}
[\phi] \quad [\psi] \\
\vdots \quad \vdots \\
\psi \quad \phi \\
\hline
\phi \equiv \psi \equiv -I
\end{array} \quad \begin{array}{c}
\phi \equiv \psi \\
\hline
\psi \quad \phi \equiv -E
\end{array}
\]

What is the type of $\phi$ and $\psi$ here?
Rules for $\equiv$: Introduction and Elimination

\[
\begin{array}{c}
\varphi \\
\vdots \\
\varphi \\
\end{array} \quad \begin{array}{c}
\psi \\
\vdots \\
\psi \\
\end{array} \\
\frac{\varphi}{\varphi \equiv \psi} \equiv \text{-}I \\
\frac{\varphi \equiv \psi}{\psi} \equiv \text{-}E
\end{array}
\]

What is the type of $\varphi$ and $\psi$ here? $\varphi$ and $\psi$ are formulae, hence $\text{bool}$.

What object-level connective does $\equiv$ correspond to?
Rules for $\equiv$: Introduction and Elimination

$$[\phi] \quad [\psi]$$

$$\vdots \quad \vdots$$

$$\psi \quad \phi \quad \equiv \rightarrow I$$

$$\phi \equiv \psi \quad \phi \equiv \psi \quad \equiv \rightarrow E$$

What is the type of $\phi$ and $\psi$ here? $\phi$ and $\psi$ are *formulae*, hence *bool*.

What object-level connective does $\equiv$ correspond to? $\leftrightarrow$. 

We use FOL and its subset propositional logic (which we call here Prop) as exemplary object logic. We already know how to encode syntax. We will now see how to encode proof rules and mimic proofs of the object logic.

To encode a particular object logic $L$, we have to extend $\mathcal{M}$ by extending the type language, the term language (the signature) and the proof rules. The thus extended logic will be called $\mathcal{M}_L$.  

Smaus: CSMR; WS05/06
Encoding Syntax: Review

As before, $i, o \in B$. Previously:

$$\Sigma \supseteq \{ not : o \rightarrow o, and : o \rightarrow o \rightarrow o, imp : o \rightarrow o \rightarrow o, all : (i \rightarrow o) \rightarrow o, exists : (i \rightarrow o) \rightarrow o \}$$

Two types for truth values: $o$ and $\text{bool}$.

We now need a more concise (sweeter) syntax or things will become hopelessly unreadable.

But this is also quite demanding: you should always be able to “unsugar” the syntax.
Encoding Syntax Readably

\[ \Sigma \supseteq \langle \bot : o, \land, \lor, \to: o \to o \to o, \forall, \exists : (i \to o) \to o, \text{true} : o \to \text{bool} \rangle. \]

→ is both a constant declared in \( \Sigma \) and the function type arrow.

\( \land, \lor, \to \) will be written infix, and we may write \( \forall x.\phi \) for \( \forall(\lambda x.\phi) \), and likewise for \( \exists \).

\text{true} A \text{ is usually written } [A].
Encoding the Rules

The rules of the object logic are encoded as axioms of the metalogic. These axioms are added to the proof system of $\mathcal{M}$ (to obtain $\mathcal{M}_L$).

To avoid confusion, we will use distinctive terminology:

There is a meta-rule called $\Rightarrow$-E.

There is a similar object rule that we call the $\rightarrow$-E rule.

It is encoded as a meta-axiom that we call the $\rightarrow$-E axiom.
Encoding of the Rules of Propositional Logic

\[ \land AB. [A] \Rightarrow ([B] \Rightarrow [A \land B]) \]  \quad (\land-I)
\[ \land AB. [A \land B] \Rightarrow [A] \]  \quad (\land-EL)
\[ \land AB. [A \land B] \Rightarrow [B] \]  \quad (\land-ER)
\[ \land AB. [A] \Rightarrow [A \lor B] \]  \quad (\lor-IL)
\[ \land AB. [B] \Rightarrow [A \lor B] \]  \quad (\lor-IR)
\[ \land ABC. [A \lor B] \Rightarrow \]
\[ ([A] \Rightarrow [C]) \Rightarrow ([B] \Rightarrow [C]) \Rightarrow [C] \]  \quad (\lor-E)
\[ \land AB. ([A] \Rightarrow [B]) \Rightarrow [A \rightarrow B] \]  \quad (\rightarrow-I)
\[ \land AB. [A \rightarrow B] \Rightarrow [A] \Rightarrow [B] \]  \quad (\rightarrow-E)
\[ \land A. [\bot] \Rightarrow [A] \]  \quad (\bot-E)
Faithful Metalogics

For any object logic $L$, we define:

- $M_L$ is **sound for** $L$ if, for every proof of $[B]$ from assumptions $[A_1], \ldots, [A_m]$ in $M_L$, there is a proof of $B$ from assumptions $A_1, \ldots, A_m$ in $L$.

- $M_L$ is **complete for** $L$ if, for every proof of $B$ from assumptions $A_1, \ldots, A_m$ in $L$, there is a proof of $[B]$ from assumptions $[A_1], \ldots, [A_m]$ in $M_L$.

- $M_L$ is **faithful for** $L$ if $M_L$ is sound and complete for $L$.

Using concepts of Prawitz [Pra65, Pra71], one can show by structural induction that $M_{Prop}$ is faithful for $Prop$. 
An Example Proof

\[ \land AB. [A \land B] \quad \Rightarrow [A] \quad \land\text{-}EL \]
An Example Proof

\[
\begin{align*}
\land AB. [A \land B] & \quad \Rightarrow [A] \\
\land B. [P \land B] & \quad \Rightarrow [P]
\end{align*}
\]

\(\land-EL\)

\(\land-E\)
An Example Proof

\[
\begin{align*}
\land AB. [A \land B] & \quad \Rightarrow [A] \\
\land B. [P \land B] & \quad \Rightarrow [P] \\
[P \land Q] & \Rightarrow [P]
\end{align*}
\]

\(-EL\)
\(-E\)
\(-E\)
An Example Proof

\[ \neg \square \neg \forall x (x \neq x) \]

\[ \forall x \forall y (x = y) \]

\[ \neg \neg \forall x (x \neq x) \]

\[ \forall x \forall y (x = y) \]

\[ \neg \neg \forall x (x \neq x) \]

\[ \forall x \forall y (x = y) \]
An Example Proof

\[
\begin{align*}
\wedge AB. [A \land B] & \Rightarrow [A] \quad \wedge-EL \\
\wedge B. [P \land B] & \Rightarrow [P] \quad \wedge-E \\
[[P \land Q]]^1 \quad [P \land Q] \Rightarrow [P] & \quad \wedge-E \\
[P] & \Rightarrow [-I]^1 \\
[P \land Q] \Rightarrow [P] & \quad \Rightarrow-E
\end{align*}
\]
An Example Proof

\[
\begin{align*}
\Lambda \ A B. ([A] \Rightarrow [B]) \quad & \quad \Rightarrow [A \rightarrow B] \\
\Lambda \ B. ([P \land Q] \Rightarrow [B]) \quad & \quad \Rightarrow [P \land Q \rightarrow B] \\
([P \land Q] \Rightarrow [P]) \quad & \quad \Rightarrow [P \land Q \rightarrow P]
\end{align*}
\]

\[
\begin{align*}
\Lambda \ AB. [A \land B] \Rightarrow [A] \\
\Lambda \ B. [P \land B] \Rightarrow [P] \\
\Lambda E
\end{align*}
\]

\[
\begin{align*}
[[P \land Q]]^1 \Rightarrow [P \land Q] \Rightarrow [P] \\
[P] \Rightarrow -I
\end{align*}
\]
An Example Proof

\[
\begin{array}{c}
\neg - I \\
\neg I \quad \neg - E \\
\neg E \\
\neg E \\
\neg E
\end{array}
\]

\[
\begin{array}{c}
\land AB. ([A] \Rightarrow [B]) \\
\Rightarrow [A \rightarrow B] \\
\land E \\
\land E \\
\land E \\
\land E
\end{array}
\]

\[
\begin{array}{c}
\left( [P \land Q] \Rightarrow [P] \right) \\
\Rightarrow [P \land Q \rightarrow P] \\
\neg - E
\end{array}
\]

\[
\begin{array}{c}
\left( [P \land Q] \Rightarrow [P] \right) \\
\Rightarrow [P \land Q \rightarrow P] \\
\neg - E
\end{array}
\]

\[
\begin{array}{c}
\neg - I \\
\neg I \quad \neg - E \\
\neg E \\
\neg E \\
\neg E
\end{array}
\]

\[
\begin{array}{c}
\left( [P \land Q] \Rightarrow [P] \right) \\
\Rightarrow [P \land Q \rightarrow P] \\
\neg - E
\end{array}
\]

\[
\begin{array}{c}
\neg - I \\
\neg I \quad \neg - E \\
\neg E \\
\neg E \\
\neg E
\end{array}
\]

\[
\begin{array}{c}
\left( [P \land Q] \Rightarrow [P] \right) \\
\Rightarrow [P \land Q \rightarrow P] \\
\neg - E
\end{array}
\]

\[
\begin{array}{c}
\neg - I \\
\neg I \quad \neg - E \\
\neg E \\
\neg E \\
\neg E
\end{array}
\]

\[
\begin{array}{c}
\left( [P \land Q] \Rightarrow [P] \right) \\
\Rightarrow [P \land Q \rightarrow P] \\
\neg - E
\end{array}
\]

\[
\begin{array}{c}
\neg - I \\
\neg I \quad \neg - E \\
\neg E \\
\neg E \\
\neg E
\end{array}
\]

\[
\begin{array}{c}
\left( [P \land Q] \Rightarrow [P] \right) \\
\Rightarrow [P \land Q \rightarrow P] \\
\neg - E
\end{array}
\]
An Example Proof

\[
\begin{align*}
\neg\text{-}I & \quad \land\ AB.([A] \Rightarrow [B]) \\
\neg\text{-}E & \quad \Rightarrow [A \rightarrow B] \\
\land\text{-}E & \quad \land B.([P \land Q] \Rightarrow [B]) \\
\land\text{-}E & \quad \Rightarrow [P \land Q \rightarrow B] \\
\land\text{-}E & \quad ( [P \land Q] \Rightarrow [P] ) \\
\land\text{-}E & \quad \Rightarrow [P \land Q \rightarrow P] \\
\Rightarrow & \quad [P \land Q \rightarrow P]
\end{align*}
\]
Example Proof Simplified

\[
\begin{align*}
\land \ AB. ([A] \Rightarrow [B]) & \Rightarrow [A \rightarrow B] \\
\land \ B. ([P \land Q] \Rightarrow [B]) & \Rightarrow [P \land Q \rightarrow B] \\
([P \land Q] \Rightarrow [P]) & \Rightarrow [P \land Q \rightarrow P] \\
\land \ AB. ([A] \Rightarrow [B]) & \Rightarrow [A \rightarrow B] \\
\land \ B. ([P \land Q] \Rightarrow [B]) & \Rightarrow [P \land Q \rightarrow B] \\
([P \land Q] \Rightarrow [P]) & \Rightarrow [P \land Q \rightarrow P] \\
\land \ AB. ([A] \Rightarrow [B]) & \Rightarrow [A \rightarrow B] \\
\land \ B. ([P \land Q] \Rightarrow [B]) & \Rightarrow [P \land Q \rightarrow B] \\
([P \land Q] \Rightarrow [P]) & \Rightarrow [P \land Q \rightarrow P] \\
\end{align*}
\]
Remarks about Example Proof

- \(\land\)-EL and \(\rightarrow\)-E are not object rules but meta-axioms!
- The first, more complicated proof corresponds to the construction one would use to show that \(\mathcal{M}_{\text{Prop}}\) is complete for \(\text{Prop}\).
- Proof fragments of the form

\[
\frac{\phi \Rightarrow \psi \quad [\phi]}{\psi} \Rightarrow\text{-I}
\]

\[
\frac{\phi \Rightarrow \psi \Rightarrow\text{-E}}{\phi \Rightarrow \psi} \Rightarrow\text{-I}
\]

are collapsed into \(\phi \Rightarrow \psi\): proof normalization.
Reasoning with Resolution

In Isabelle, we mainly use backwards reasoning: we construct a proof tree starting from the root working to the leaves.
Reasoning with Resolution

In Isabelle, we mainly use backwards reasoning: we construct a proof tree starting from the root working to the leaves. On the meta-level, this proof is in fact a forwards proof: working from the leaves to the root. This is achieved by starting the proof of $\psi$ with the trivial meta-theorem $\psi \Rightarrow \psi$ and using a technique called resolution.
The Resolution Rule

For any formulae $\psi_1, \ldots, \psi_n, \psi, \phi_1, \ldots, \phi_m, \phi$ where $FV(\phi_1, \ldots, \phi_m, \phi) \subseteq \{x_1, \ldots, x_k\}$, and $\phi\theta \equiv \psi_i$ for some $i \in \{1, \ldots, n\}$, resolution is the following rule:

\[
\begin{align*}
\bigwedge x_1 \ldots x_k \cdot [\phi_1, \ldots, \phi_m] \Rightarrow \phi & \quad [\psi_1, \ldots, \psi_n] \Rightarrow \psi \\
[\psi_1, \ldots, \psi_{i-1}, \phi_1\theta, \ldots, \phi_m\theta, \psi_{i+1}, \ldots, \psi_n] \Rightarrow \psi
\end{align*}
\]

Intuition: $\bigwedge x_1 \ldots x_k \cdot [\phi_1, \ldots, \phi_m] \Rightarrow \phi$ is a meta-axiom such as $\wedge$-$EL$, $[\psi_1, \ldots, \psi_n] \Rightarrow \psi$ is the current goal (proof state).

Compare to phrasing using $\lor$!

We will now derive the rule.
Resolution as Derived Meta-Rule

\[ \bigwedge x_1 \ldots x_k. \]
\[ [\phi_1, \ldots, \phi_m] \Rightarrow \phi \]
Resolution as Derived Meta-Rule

\[ \bigwedge x_1 \ldots x_k. \quad [\phi_1, \ldots, \phi_m] \Rightarrow \phi \]

\[ \frac{\text{[} \phi_1 \theta, \ldots, \phi_m \theta \text{] \Rightarrow \phi \theta}}{\text{[} \phi_1 \theta, \ldots, \phi_m \theta \text{] \Rightarrow \phi \theta} \quad \bigwedge -E } \]
Resolution as Derived Meta-Rule

\[
\begin{align*}
\phi_1 \theta & \quad \ldots \quad \phi_m \theta \\
\land x_1 \ldots x_k. \\
[\phi_1, \ldots, \phi_m] & \Rightarrow \phi \\
[\phi_1 \theta, \ldots, \phi_m \theta] & \Rightarrow \phi \theta \\
\end{align*}
\]
Resolution as Derived Meta-Rule

\[ \begin{align*}
\phi_1 \theta & \quad \ldots \quad \phi_m \theta \\
\frac{\bigwedge x_1 \ldots x_k \cdot [\phi_1, \ldots, \phi_m] \Rightarrow \phi}{\bigwedge \text{-}E} \\
\frac{\bigwedge \text{-}E}{\phi \theta} \\
\frac{\phi_1 \theta, \ldots, \phi_m \theta \Rightarrow \phi \theta}{\Rightarrow \text{-}E}
\end{align*} \]
Resolution as Derived Meta-Rule

\[
\begin{array}{c}
\phi_1 \theta \quad \ldots \quad \phi_m \theta \\
\hline
[\phi_1 \theta, \ldots, \phi_m \theta] \Rightarrow \phi \\
\hline
\phi \theta \\
\hline
\Rightarrow -E \\
\hline
\nl \quad \wedge \quad x_1 \ldots x_k.
\end{array}
\]

\[
\begin{array}{c}
\left[\psi_1, \ldots, \psi_n\right] \\
\hline
\Rightarrow \psi
\end{array}
\]

\[
\left[\begin{array}{c}
\phi_1, \ldots, \phi_m
\end{array}\right] \Rightarrow \phi
\]
Resolution as Derived Meta-Rule

\[
\begin{align*}
\phi_1 \theta & \quad \ldots \quad \phi_m \theta \\
\left[ \phi_1 \theta, \ldots, \phi_m \theta \right] \Rightarrow \phi \\
\phi \theta & \quad \left[ \psi_1, \ldots, \psi_{i-1} \right] \\
\Rightarrow -E & \\
\psi_1 & \quad \ldots \quad \psi_{i-1} \\
\left[ \psi_1, \ldots, \psi_n \right] & \Rightarrow \psi
\end{align*}
\]
Resolution as Derived Meta-Rule

\[
\begin{align*}
\phi_1 \theta & \quad \ldots \quad \phi_m \theta \\
\phi_1 \theta, \ldots, \phi_m \theta \Rightarrow \phi \\
\phi \theta & \Rightarrow \neg \phi \\
\psi_1 \ldots \psi_{i-1} & \quad \Rightarrow \psi \\
\psi_1, \ldots, \psi_n \Rightarrow \psi & \Rightarrow \neg \psi
\end{align*}
\]
Resolution as Derived Meta-Rule

\[
\begin{align*}
\phi_1 \theta & \quad \ldots \quad \phi_m \theta \\
\Delta x_1 \ldots x_k. & \\
[\phi_1, \ldots, \phi_m] \Rightarrow \phi & \\
\phi & \\
\implies -E & \\
[\phi_1 \theta, \ldots, \phi_m \theta] \Rightarrow \phi & \\
\psi_1 & \quad \ldots \quad \psi_{i-1} \quad \left[ \psi_1, \ldots, \psi_n \right] \Rightarrow \psi & \\
[\psi_i, \ldots, \psi_n] \Rightarrow \psi & \\
\implies -E & \\
[\psi_{i+1}, \ldots, \psi_n] \Rightarrow \psi & \\
\implies -E & 
\end{align*}
\]
Resolution as Derived Meta-Rule

\[
\begin{align*}
\land x_1 \ldots x_k. & \quad \phi \\
[\phi_1, \ldots, \phi_m] \Rightarrow & \quad \phi \\
\phi \theta & \\
\land-E \\
[\phi_1 \theta, \ldots, \phi_m \theta] \Rightarrow & \quad \phi \theta \\
\Rightarrow-E \\
[\phi_1 \theta, \ldots, \phi_m \theta] \Rightarrow & \quad \phi \theta \\
\land-E \\
[\psi_1, \ldots, \psi_{i-1}] & \Rightarrow \psi \\
[\psi_i, \ldots, \psi_n] \Rightarrow & \quad \psi \\
\Rightarrow-E \\
[\psi_{i+1}, \ldots, \psi_n] & \Rightarrow \psi \\
[\phi_1 \theta, \ldots, \phi_m \theta, \psi_{i+1}, \ldots, \psi_n] \Rightarrow & \quad \psi \\
\Rightarrow-I^2
\end{align*}
\]
Resolution as Derived Meta-Rule

\[
\begin{align*}
\left[\phi_1 \theta \right]^2 \ldots \left[\phi_m \theta \right]^2 & \quad \left[\phi_1 \theta, \ldots, \phi_m \theta \right] \Rightarrow \phi \\
\left[\phi_1 \theta, \ldots, \phi_m \theta \right] \Rightarrow \phi \theta & \quad \Rightarrow -E \quad \left[\psi_1^1 \ldots \psi_{i-1}^1 \psi_1, \ldots, \psi_n \right] \Rightarrow \psi \\
\phi \theta & \quad \Rightarrow -E \\
\left[\psi_{i+1}^1, \ldots, \psi_n \right] \Rightarrow \psi & \quad \Rightarrow -E \\
\left[\phi_1 \theta, \ldots, \phi_m \theta, \psi_{i+1}^1, \ldots, \psi_n \right] \Rightarrow \psi & \quad \Rightarrow -I^2 \\
\left[\psi_1, \ldots, \psi_{i-1}^1, \phi_1 \theta, \ldots, \phi_m \theta, \psi_{i+1}^1, \ldots, \psi_n \right] \Rightarrow \psi & \quad \Rightarrow -I^1
\end{align*}
\]
Deriving Resolution: Remarks

- We collapsed *iterated applications* of rules (denoted by *double* horizontal line).
Deriving Resolution: Remarks

• We collapsed iterated applications of rules (denoted by double horizontal line).

• This is not just a matter of simplicity. The derivation is schematic not just in the sense that the Greek letters could stand for arbitrary formulae; we don’t even know how many formulae are involved ($k, m, n, i$ could be any natural numbers).

• But for any concrete $\psi_1, \ldots, \psi_n, \psi, \phi_1, \ldots, \phi_m, \phi$, you could do the formal derivation in $\mathcal{M}$. 
Dropping Outer Quantifiers

We adopt the convention that outer quantifiers in meta-formulae are dropped. E.g. $[A] \Rightarrow [B] \Rightarrow [A \land B]$, instead of $\land AB. [A] \Rightarrow [B] \Rightarrow [A \land B]$. In addition: use renaming for freshness.

Then we can write the resolution rule as follows:

\[
\begin{align*}
[\phi_1, \ldots, \phi_m] &\Rightarrow \phi \\
[\psi_1, \ldots, \psi_n] &\Rightarrow \psi \\
[\psi_1, \ldots, \psi_{i-1}, \phi_1 \theta, \ldots, \phi_m \theta, \psi_{i+1}, \ldots, \psi_n] \Rightarrow \psi
\end{align*}
\]

\[\text{res}\]

where $\phi \theta \equiv \psi_i$.

We will now work with this schematic form.
**Proof of** \( A \land B \rightarrow C \rightarrow A \land C \) (1)

Let's prove \( A \land B \rightarrow (C \rightarrow A \land C) \) by resolution. We start by resolution with \( \rightarrow I \):

\[
\begin{align*}
([A_1] \Rightarrow [B_1]) & \quad [A \land B \rightarrow (C \rightarrow A \land C)] \\
\Rightarrow [A_1 \rightarrow B_1] & \quad \Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)] \\
\hline
([A \land B] \Rightarrow [C \rightarrow A \land C]) & \quad \Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)]
\end{align*}
\]

What to do next?
Proof of \( A \land B \rightarrow C \rightarrow A \land C \) (1)

Let’s prove \( A \land B \rightarrow (C \rightarrow A \land C) \) by resolution. We start by resolution with \( \rightarrow \text{-}I \):

\[
\begin{align*}
([A_1] \Rightarrow [B_1]) & \quad \quad [A \land B \rightarrow (C \rightarrow A \land C)] \\
\Rightarrow [A_1 \rightarrow B_1] & \quad \quad \Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)] \\
\hline
([A \land B] \Rightarrow [C \rightarrow A \land C]) & \quad \quad \Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)]
\end{align*}
\]

What to do next? Again resolution with \( \rightarrow \text{-}I \).

Problem: the conclusion of \( \rightarrow \text{-}I \) is not unifiable with \([A \land B] \Rightarrow [C \rightarrow A \land C]\).
Lifting over Assumptions

The rule for lifting an object rule (meta-axiom)

\[ [\phi_1, \ldots, \phi_m] \Rightarrow \phi \text{ over a list of assumptions } \Psi \text{ is} \]

\[
\frac{[\phi_1, \ldots, \phi_m] \Rightarrow \phi}{[\Psi \Rightarrow \phi_1, \ldots, \Psi \Rightarrow \phi_m] \Rightarrow (\Psi \Rightarrow \phi)} \quad \text{a-lift}
\]

We will now derive it for one assumption, so \( \Psi = [\psi] \).
Deriving Assumption Lifting for one Assumption

\[
\begin{align*}
\[\phi_1, \ldots, \phi_m]\Rightarrow \phi & \quad \frac{\psi \Rightarrow \phi_1}{\phi_1} \quad \frac{\psi}{\Rightarrow -E} \quad \frac{\psi \Rightarrow \phi_m}{\phi_m} \quad \frac{\psi}{\Rightarrow -E}
\end{align*}
\]
Deriving Assumption Lifting for one Assumption

\[
\frac{\psi \Rightarrow \phi_1 \quad \psi \Rightarrow \phi_m}{\phi_1 \quad \phi_m} \Rightarrow -E \quad \Rightarrow -E
\]

\[
\frac{[\phi_1, \ldots, \phi_m] \Rightarrow \phi}{\phi} \Rightarrow -E
\]
Deriving Assumption Lifting for one Assumption

\[
\begin{align*}
[\phi_1, \ldots, \phi_m] & \Rightarrow \phi \\
\psi \Rightarrow \phi_1 & \quad [\psi]^2 \quad \Rightarrow -E \\
\phi_1 & \quad \Rightarrow -E \\
\vdots & \\
\phi_m & \quad \Rightarrow -E \\
\phi & \quad \Rightarrow -I^2 \\
\psi \Rightarrow \phi & \quad \Rightarrow -I^2
\end{align*}
\]
Reasoning with Resolution

Deriving Assumption Lifting for one Assumption

\[
\begin{align*}
[\phi_1, \ldots, \phi_m] & \Rightarrow \phi \\
& \quad \frac{[\psi \Rightarrow \phi_1]^1 \quad [\psi]^2}{\phi_1} \Rightarrow \text{-E} \quad \ldots \quad \frac{[\psi \Rightarrow \phi_m]^1 \quad [\psi]^2}{\phi_m} \Rightarrow \text{-E} \\
& \quad \frac{\phi}{\psi \Rightarrow \phi} \Rightarrow \text{-I}^2 \\
& \quad \frac{[\psi \Rightarrow \phi_1, \ldots, \psi \Rightarrow \phi_m] \Rightarrow (\psi \Rightarrow \phi)}{\Rightarrow \text{-I}^1}
\end{align*}
\]

This process can be repeated for any number of assumptions to get the general rule.
Proof of $A \land B \rightarrow (C \rightarrow A \land C)$ (2)

We do resolution using the $\rightarrow$-I rule lifted over $A \land B$:

\[
\begin{align*}
([A \land B] \Rightarrow ([A_2] \Rightarrow [B_2])) \quad &\Rightarrow ([A \land B] \Rightarrow [A_2 \rightarrow B_2]) \\
([A \land B] \Rightarrow [C \rightarrow A \land C]) \quad &\Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)] \\
\hline
([A \land B] \Rightarrow [C] \Rightarrow [A \land C]) \quad &\Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)]
\end{align*}
\]
**Proof of** \( A \land B \rightarrow (C \rightarrow A \land C) \) \( (2) \)

We do resolution using the \( \rightarrow I \) rule lifted over \( A \land B \):

\[
\begin{align*}
([A \land B] \Rightarrow ([A_2] \Rightarrow [B_2])) & \quad \Rightarrow ([A \land B] \Rightarrow [A_2 \rightarrow B_2]) \\
([A \land B] \Rightarrow [C \rightarrow A \land C]) & \quad \Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)]
\end{align*}
\]

**res**

\[
([A \land B] \Rightarrow [C] \Rightarrow [A \land C]) \\
\Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)]
\]

Before we proceed, we introduce the abbreviations

\[
\omega = [A \land B \rightarrow (C \rightarrow A \land C)], \quad \Omega = [[A \land B], [C]]
\]
Proof of $A \land B \rightarrow (C \rightarrow A \land C)$ (2)

We do resolution using the $\rightarrow$-I rule lifted over $A \land B$:

\[
\begin{align*}
( [A \land B] \Rightarrow ( [A_2] \Rightarrow [B_2])) & \quad ( [A \land B] \Rightarrow [C \rightarrow A \land C]) \\
\Rightarrow ( [A \land B] \Rightarrow [A_2 \rightarrow B_2]) & \Rightarrow \omega \\
\Rightarrow \omega & \quad \text{res}
\end{align*}
\]

Before we proceed, we introduce the abbreviations

\[
\omega = [A \land B \rightarrow (C \rightarrow A \land C)], \quad \Omega = [[A \land B], [C]]
\]
Proof of \( A \land B \rightarrow (C \rightarrow A \land C) \) (3)

We do resolution using the \( \land\!/-I \) rule lifted over \( \Omega \):

\[
\begin{align*}
(\Omega \Rightarrow [A_3]) & \Rightarrow (\Omega \Rightarrow [B_3]) \\
\Rightarrow (\Omega \Rightarrow [A_3 \land B_3]) & \Rightarrow (\Omega \Rightarrow [A \land C]) \\
\Rightarrow \omega & \Rightarrow \omega
\end{align*}
\]

At this point, Isabelle would display \( \Omega \Rightarrow [A] \) and \( \Omega \Rightarrow [C] \) as two subgoals.

The next step is to solve \( \Omega \Rightarrow [C] \) by assumption, but this must be formalized.
The Assumption Axiom

The assumption axiom is: for any $i \in \{1, \ldots, m\}$

\[
\frac{[\phi_1, \ldots, \phi_m] \Rightarrow \phi_i}{assum}
\]

It has a simple (schematic) derivation:

\[
\frac{[\phi_i] \Rightarrow \phi_i}{\Rightarrow -1}
\]

\[
\frac{[\phi_{i+1}, \ldots, \phi_m] \Rightarrow \phi_i}{\Rightarrow -1^1}
\]

\[
\frac{[\phi_i, \ldots, \phi_m] \Rightarrow \phi_i}{\Rightarrow -1}
\]

\[
\frac{[\phi_1, \ldots, \phi_m] \Rightarrow \phi_i}{\Rightarrow -1}
\]
Proof of $A \land B \rightarrow (C \rightarrow A \land C)$ (4)

We do resolution using the assumption axiom:

$$
\vdots \\
\Omega \Rightarrow [C] \quad [\Omega \Rightarrow [A], \Omega \Rightarrow [C]] \Rightarrow \omega \\
(\Omega \Rightarrow [A]) \Rightarrow \omega
$$

We used the correct instance of the assumption axiom. Alternatively, we could have used the more generic $[A_4, B_4] \Rightarrow B_4$.

What to do next? (Recall that $\Omega = [[A \land B], [C]]$.)
Proof of $A \land B \rightarrow (C \rightarrow A \land C)$ (4)

We do resolution using the assumption axiom:

$$\begin{align*}
\Omega \Rightarrow [C] & \quad [\Omega \Rightarrow [A], \Omega \Rightarrow [C]] \Rightarrow \omega \\
\hline
(\Omega \Rightarrow [A]) \Rightarrow \omega
\end{align*}$$

We used the correct instance of the assumption axiom. Alternatively, we could have use the more generic $[A_4, B_4] \Rightarrow B_4$.

What to do next? (Recall that $\Omega = [[A \land B], [C]]$.)

Resolution with $\land$-EL.
Proof of \( A \land B \rightarrow (C \rightarrow A \land C) \) (5)

Magically, we guess the right instance of \( \land\)-EL and lift it over \( \Omega \):

\[
\begin{align*}
(\Omega \Rightarrow [A \land B]) & \Rightarrow (\Omega \Rightarrow [A]) & (\Omega \Rightarrow [A]) \Rightarrow \omega \\
\hline
(\Omega \Rightarrow [A \land B]) & \Rightarrow \omega
\end{align*}
\]

What to do next? (Recall that \( \Omega = [[A \land B], [C]] \).)
Proof of $A \land B \rightarrow (C \rightarrow A \land C)$ (5)

Magically, we guess the right instance of $\land$-EL and lift it over $\Omega$:

$$(\Omega \Rightarrow [A \land B]) \Rightarrow (\Omega \Rightarrow [A]) \quad (\Omega \Rightarrow [A]) \Rightarrow \omega$$

What to do next? (Recall that $\Omega = [[A \land B], [C]]$.) Prove the subgoal by assumption.
Proof of $A \land B \rightarrow (C' \rightarrow A \land C)$ (6)

We do resolution using the assumption axiom:

$$
\begin{align*}
\therefore \\
\Omega \Rightarrow [A \land B] & \quad (\Omega \Rightarrow [A \land B]) \Rightarrow \omega \\
\omega & \quad \text{res}
\end{align*}
$$

Recall that $\omega = [A \land B \rightarrow (C' \rightarrow A \land C)]$. Done!
Getting Rid of the Magic

In one step, we had to guess the right instance of \( \land-EL \). This is not practical.

Solutions:

- **Generalize** the resolution rule to allow for instantiation of the current proof state and not just of meta-axioms.
- **Derive**

\[
\land AB C. ([A \land B], ([A], [B]) \Rightarrow [C]) \Rightarrow [C]
\]

which encodes the \( \land-E \) object rule.
The Whole Proof at a Glance

Compare proof in $M_{Prop}$ with corresponding proof in $Prop$:

\[
\begin{align*}
\text{ΔEL} & \quad \boxed{\ldots \Rightarrow \omega} \\
\rightarrow\dashv & \quad \boxed{\omega \Rightarrow \omega} \\
\text{ΔEL} & \quad \boxed{\ldots \Rightarrow \omega} \\
& \quad \boxed{\ldots \Rightarrow \omega} \\
& \quad \boxed{\ldots \Rightarrow \omega}
\end{align*}
\]

\[
\begin{align*}
\text{ΔEL} & \quad \boxed{\ldots \Rightarrow \omega} \\
\rightarrow\dashv & \quad \boxed{\omega \Rightarrow \omega} \\
\text{ΔEL} & \quad \boxed{\ldots \Rightarrow \omega} \\
& \quad \boxed{\ldots \Rightarrow \omega} \\
& \quad \boxed{\ldots \Rightarrow \omega}
\end{align*}
\]

\[
\begin{align*}
\begin{cases} [A \land B]^1 \\ A \end{cases} & \quad \text{ΔEL} \\
\begin{cases} A \land C \end{cases} & \quad [-\dashv] \quad \boxed{\ldots \Rightarrow \omega} \\
\begin{cases} C \rightarrow A \land C \end{cases} & \quad [-\dashv] \quad \boxed{\ldots \Rightarrow \omega} \\
\begin{cases} A \land B \rightarrow (C \rightarrow A \land C) \end{cases} & \quad [-\dashv] \quad \boxed{\ldots \Rightarrow \omega}
\end{cases}
\end{align*}
\]
The Whole Proof at a Glance

Compare proof in $\mathcal{M}_{Prop}$ with corresponding proof in $Prop$:

\[
\frac{\rightarrow -l}{\omega \Rightarrow \omega}
\]

\[
\frac{\rightarrow -l}{\ldots \Rightarrow \omega}
\]

\[
\frac{\land -l}{\ldots \Rightarrow \omega}
\]

\[
\frac{\land -l}{a. \ldots \Rightarrow \omega}
\]

\[
\frac{\land -EL}{\omega}
\]

\[
\frac{[A \land B]^1}{A}
\]

\[
\frac{\land -EL}{C \rightarrow A \land C \rightarrow -l^2}
\]

\[
\frac{A \land C}{C \rightarrow A \land C \rightarrow -l^2}
\]

\[
\frac{A \land B \rightarrow (C \rightarrow A \land C')}{-l^1}
\]

“The meta-level proof is the object level proof upside-down.”
Direction of the Implication

Is the direction of the implication reversed just because we go from the object to the meta-level?
Direction of the Implication

Is the direction of the implication reversed just because we go from the object to the meta-level?

No! The direction is reversed because we start from the trivial meta-theorem \( \omega \Rightarrow \omega \), and the resolution steps modify the left-hand side of this meta-theorem.
How Can One Turn a Tree Upside-Down?

A proper tree has nodes where it branches. Also, in Isabelle proofs, we frequently have to prove several subgoals. So how is this branching reflected in the meta-proof?
How Can One Turn a Tree Upside-Down?

A proper tree has nodes where it branches. Also, in Isabelle proofs, we frequently have to prove several subgoals. So how is this branching reflected in the meta-proof?

A meta-formula of the form $\psi_1 \Rightarrow \ldots \Rightarrow \psi_n \Rightarrow \psi$ corresponds to a branching point in the object level proof. It means that there are subgoals $\psi_1, \ldots, \psi_n$. But in the derivation tree in $\mathcal{M}_{Prop}$, there is no branching.
How Can One Turn a Tree Upside-Down?

A proper tree has nodes where it branches. Also, in Isabelle proofs, we frequently have to prove several subgoals. So how is this branching reflected in the meta-proof?

A meta-formula of the form $\psi_1 \Rightarrow \ldots \Rightarrow \psi_n \Rightarrow \psi$ corresponds to a branching point in the object level proof. It means that there are subgoals $\psi_1, \ldots, \psi_n$. But in the derivation tree in $\mathcal{M}_{Prop}$, there is no branching.

In the construction of a meta-proof (just like in Isabelle), one is always free to choose which subgoal to solve next. Interleaving is possible.
We have to add the following meta-axioms to obtain $\mathcal{M}_{\text{FOL}}$:

\[
\begin{align*}
\forall F. \left( \forall x. [Fx] \right) & \Rightarrow [\forall x. Fx] \quad (\forall-I) \\
\forall Fy. [\forall x. Fx] & \Rightarrow [Fy] \quad (\forall-E) \\
\forall Fy. [Fy] & \Rightarrow [\exists x. Fx] \quad (\exists-I) \\
\forall FB. [\exists x. Fx] & \Rightarrow (\forall x. [Fx \Rightarrow [B]]) \Rightarrow [B] \quad (\exists-E)
\end{align*}
\]

Similarly as for $Prop$, one can show that $\mathcal{M}_{\text{FOL}}$ is faithful for FOL.

Side condition checking is shifted to the meta-level.

We now consider resolution proofs for FOL.
Proof of \((∀z.G \, z) \rightarrow (∀z.G \, z ∨ H \, z)\) (1)

\[
([A_1] \Rightarrow [B_1]) \Rightarrow [A_1 \rightarrow B_1] \Rightarrow \text{res}
\]

What to do next?
Proof of \((\forall z. G z) \rightarrow (\forall z. G z \lor H z)\) (1)

\[
\begin{align*}
([A_1] \Rightarrow [B_1]) & \Rightarrow [A_1 \rightarrow B_1] & \Rightarrow [(\forall z. G z) \rightarrow (\forall z. G z \lor H z)] \\
\end{align*}
\]

\[\text{res}\]

\[
\begin{align*}
([\forall z. G z] & \Rightarrow [\forall z. G z \lor H z]) \\
\Rightarrow [(\forall z. G z) \rightarrow (\forall z. G z \lor H z)] \\
\end{align*}
\]

What to do next? Resolution with \(\forall I\) lifted over assumption \([\forall z. G z]\).
**Proof of** \((\forall z. G\ z) \rightarrow (\forall z. G\ z \lor H\ z)\) \((2)\)

\[
\begin{align*}
(\forall z. G\ z) & \Rightarrow (\exists x. [F_1\ x]) \\
\Rightarrow ((\forall z. G\ z) \Rightarrow (\forall x. F_1\ x)) & \Rightarrow ((\forall z. G\ z) \Rightarrow (\forall z. G\ z \lor H\ z)) \\
\Rightarrow (\forall z. G\ z) & \Rightarrow (\forall z. G\ z \lor H\ z)
\end{align*}
\]

The substitution \(\theta\) is \([F_1 \leftarrow \lambda w. G\ w \lor H\ w]\).

We suppress conversion, assuming terms are in normal form.

What to do next?
Proof of \((\forall z. G \ z) \rightarrow (\forall z. G \ z \lor H \ z)\) (2)

\[
\begin{align*}
& (\forall z. G \ z) \implies (\forall x. [F_1 x]) \\
\implies & (\forall z. G \ z) \implies (\forall x. F_1 x) \\
\implies & (\forall z. G \ z) \implies (\forall z. G \ z \lor H \ z) \\
\end{align*}
\]

\(\text{res}\)

The substitution \(\theta\) is \([F_1 \leftarrow \lambda w. G \ w \lor H \ w]\).

We suppress conversion, assuming terms are in normal form.

What to do next? Resolution with \(\lor-IL\) after lifting over assumption. Problem: the conclusion of \(\lor-IL\) is not unifiable with \(\forall z. [G \ z \lor H \ z]\).
Lifting over Parameters

Lifting over parameters seems easier to explain if outer $\land$’s are not dropped. The rule for lifting a meta-axiom

$\land y_1 \ldots y_k.[\phi_1, \ldots, \phi_m] \Rightarrow \phi$ over a parameter $z$ is

$$
\land y_1 \ldots y_k.[\phi_1, \ldots, \phi_m] \Rightarrow \phi
\]

where $'$ stands for application of the substitution

$[y_1 \leftarrow f_1 z, \ldots, y_k \leftarrow f_k z]$.  

We will now derive it.
Deriving Parameter Lifting for one Parameter

' stands for application of \([y_1 ← f_1(z), \ldots, y_k ← f_k(z)]\).

\[
\begin{align*}
\land y_1 \ldots y_k [\phi_1, \ldots, \phi_m] &\Rightarrow \phi \\
[\phi'_1, \ldots, \phi'_m] &\Rightarrow \phi' \\
\land z.\phi'_1 &\land-E \\
\phi'_1 &\land-E \\
\ldots &\land-E \\
\land z.\phi'_m &\land-E \\
\phi'_m &\land-E \\
\Rightarrow -E
\end{align*}
\]
Deriving Parameter Lifting for one Parameter

′ stands for application of \( [y_1 \leftarrow f_1(z), \ldots, y_k \leftarrow f_k(z)] \).

\[
\begin{align*}
\land y_1 \ldots y_k \cdot [\phi_1, \ldots, \phi_m] & \Rightarrow \phi \\
& \quad \quad \land-E \quad [\land z.\phi'_1]^1 \\
& \quad \quad \phi'_1 \quad \land-E \quad \ldots \quad [\land z.\phi'_m]^1 \\
& \quad \quad \phi'_m \quad \land-E \\
& \Rightarrow-E \\
& \quad \phi' \\
& \quad \land-I \\
[\land z.\phi'_1, \ldots, \land z.\phi'_m] & \Rightarrow \land z.\phi' \\
& \land z.\phi' \\
\land f_1 \ldots f_k \cdot [\land z.\phi'_1, \ldots, \land z.\phi'_m] & \Rightarrow \land z.\phi' \\
& \land-I
\end{align*}
\]
Deriving Parameter Lifting for one Parameter

' stands for application of $[y_1 \leftarrow f_1(z), \ldots, y_k \leftarrow f_k(z)]$.

\[
\begin{align*}
\text{\texttt{\Mapboxmath{\bigwedge} y_1 \ldots y_k}} \cdot \text{[\phi_1, \ldots, \phi_m]} & \Rightarrow \phi \\
[\phi'_1, \ldots, \phi'_m] & \Rightarrow \phi' \\
\text{\texttt{\Mapboxmath{\bigwedge}}} \phi' & \Rightarrow -E \\
[\text{\texttt{\Mapboxmath{\bigwedge}} z.}\phi'_1]^{\textup{1}} & \Rightarrow -E \\
& \ldots \\
[\text{\texttt{\Mapboxmath{\bigwedge}}} z.\phi'_m]^{\textup{1}} & \Rightarrow -E \\
\phi'_1 & \Rightarrow -E \\
\text{\texttt{\Mapboxmath{\bigwedge}}} z.\phi' & \Rightarrow -I \\
\text{\texttt{\Mapboxmath{\bigwedge}}} z.\phi'_{1, \ldots, m} & \Rightarrow -I^{\textup{1}} \\
\text{\texttt{\Mapboxmath{\bigwedge}}} z.\phi'_{1, \ldots, m} & \Rightarrow \text{\texttt{\Mapboxmath{\bigwedge}}} z.\phi' \\
\end{align*}
\]

After parameter lifting, we drop outer quantifiers again.
Lifting $\vee$-IL

Lifting $\bigwedge AB. [A] \Rightarrow [A \vee B] \ (\vee$-IL$)$ over $z$ gives

$$\bigwedge G_2 H_2. (\bigwedge z. [G_2 z]) \Rightarrow (\bigwedge z. [G_2 z \vee H_2 z]).$$
**Lifting** $\lor$-**IL**

Lifting $\land AB. [A] \Rightarrow [A \lor B]$ ($\lor$-**IL**) over $z$ gives

$$(\land z.[G_2 z]) \Rightarrow (\land z.[G_2 z \lor H_2 z]).$$

We drop outer quantifiers and lift over assumption $[\forall z. G z]$ to obtain

$$( [\forall z. G z] \Rightarrow \land z.[G_2 z] ) \Rightarrow ( [\forall z. G z] \Rightarrow \land z.[G_2 z \lor H_2 z] )$$

This rule will be applied in the next step.
Proof of \((\forall z. G z) \rightarrow (\forall z. G z \lor H z)\) (3)

\[
(\forall z. G z) \Rightarrow \bigwedge z. [G z] \Rightarrow (\forall z. G z) \Rightarrow \bigwedge z. [G z \lor H z] \Rightarrow [(\forall z. G z) \rightarrow (\forall z. G z \lor H z)]
\]

What to do next?
Proof of \((\forall z. G z) \rightarrow (\forall z. G z \lor H z)\) \((3)\)

\[
\begin{align*}
([\forall z. G z] \Rightarrow \bigwedge z. [G_2 z]) & \Rightarrow \quad ([\forall z. G z] \Rightarrow \bigwedge z. [G z \lor H z]) \\
([\forall z. G z] \Rightarrow \bigwedge z. [G_2 z \lor H_2 z]) & \Rightarrow \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \qua
Lifting of $\forall$-E over $z$

Lifting $\land Fy. [\forall x. F x] \Rightarrow [F y]$ ($\forall$-E) over parameter $z$ gives

$$\land G_3 f_3. (\land z. [\forall x. (G_3 z) x]) \Rightarrow (\land z. [G_3 z(f_3 z)]).$$

We drop outer quantifiers and lift over assumption $[\forall z. G z]$ to obtain

$$( [\forall z. G z] \Rightarrow \land z. [\forall x. (G_3 z) x] ) \Rightarrow$$

$$( [\forall z. G z] \Rightarrow \land z. [G_3 z(f_3 z)] )$$

This rule will be applied in the next step.
Proof of \((\forall z. G z) \rightarrow (\forall z. G z \lor H z)\) \((4)\)

\[
\begin{align*}
(\forall z. G z) & \Rightarrow \bigwedge z. (\forall x. (G_3 z) x) \\
(\forall z. G z) & \Rightarrow \bigwedge z. [G_3 z (f_3 z)]
\end{align*}
\]

\[
\begin{align*}
(\forall z. G z) & \Rightarrow \bigwedge z. [G z] \\
[(\forall z. G z) \rightarrow (\forall z. G z \lor H z)] & \Rightarrow \\
[(\forall z. G z) \rightarrow (\forall z. G z \lor H z)] & \Rightarrow
\end{align*}
\]

The substitution \(\theta\) is \([f_3 \leftarrow \lambda w. w, \ G_3 \leftarrow \lambda \nu w. G w]\). We suppress conversion, assuming terms are in normal form. What to do next?
Proof of \((\forall z. G z) \rightarrow (\forall z. G z \lor H z)\) (4)

\[
\frac{\left(\forall z. G z \Rightarrow \bigwedge z. \forall x. (G_3 z)x\right)}{\left(\forall z. G z \Rightarrow \bigwedge z. [G_3 z(f_3 z)]\right)} \quad \text{res}
\]

The substitution \(\theta\) is \([f_3 \leftarrow \lambda w.w, \ G_3 \leftarrow \lambda uvw.G w]\).

We suppress conversion, assuming terms are in normal form.

What to do next? Since \(z \notin FV(\forall x. G x)\), we can use a modified assumption axiom.
**Modified Assumption Axiom**

\[
\left[ \phi_1, \ldots, \phi_m \right] \Rightarrow \bigwedge z. \phi_i \quad \text{assum}
\]

where \( z \notin FV(\phi_i) \).

It has the following derivation:

\[
\frac{\left[ \phi_i \right]^1}{\bigwedge z. \phi_i} \Rightarrow -l
\]

\[
\frac{\left[ \phi_{i+1}, \ldots, \phi_m \right] \Rightarrow \bigwedge z. \phi_i}{\Rightarrow -l}
\]

\[
\frac{\left[ \phi_i, \ldots, \phi_m \right] \Rightarrow \bigwedge z. \phi_i}{\Rightarrow -l^1}
\]

\[
\frac{\left[ \phi_1, \ldots, \phi_m \right] \Rightarrow \bigwedge z. \phi_i}{\Rightarrow -l}
\]
Instance of Modified Assumption Axiom

In the next step, we will use the instance

$$[\forall z. G z] \Rightarrow \bigwedge z. [\forall x. G x]$$

of

$$[\phi_1, \ldots, \phi_m] \Rightarrow \bigwedge z. \phi_i.$$

We identified $\forall z. G z$ and $\forall x. G x$ by conversion.
Proof of \((\forall z.G\ z) \rightarrow (\forall z.G\ z \lor H\ z)\) \((5)\)

\[
\begin{align*}
\vdash & \quad [(\forall z.G\ z) \rightarrow (\forall z.G\ z \lor H\ z)] \\
\quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \text{res}
\end{align*}
\]

Done!
Remark on Step 2

Recall Step 2:

\[
\begin{align*}
([\forall z. G z] & \Rightarrow (\bigwedge x. [F_1 x])) \\
\Rightarrow ([\forall z. G z] & \Rightarrow [\forall x. F_1 x]) \\
& \Rightarrow (([\forall z. G z] \Rightarrow ([\forall z. G z] \lor H z]))
\end{align*}
\]

One could have obtained \(\bigwedge z. ([\forall z. G z] \Rightarrow ([G z \lor H z]))\) instead of \(([\forall z. G z] \Rightarrow (\bigwedge z. [G z \lor H z]))\) by lifting \(\forall\)-I in a different way. There will be an exercise.
Checking Side Conditions

To demonstrate how side conditions are checked, we show a proof attempt that fails due to a side condition.

Take $\exists y. \forall x. x = y$ in FOL with equality, so assume we have a meta-axiom for reflexivity:

$$\forall z. [z = z] \ (refl)$$
Failed Proof Attempt of $\exists y. \forall x. x = y$

\[ (\bigwedge x. [F_2 x]) \Rightarrow [\exists x. F_1 x] \]
\[ \Rightarrow [\exists y. \forall x. x = y] \]
\[ \Rightarrow [\exists y. \forall x. x = y] \]
\[ \Rightarrow [\exists y. \forall x. x = y] \]

Substitution? $[F_1 \leftarrow , F_2 \leftarrow ]$. 
Failed Proof Attempt of $\exists y. \forall x. x = y$

\[
\begin{align*}
F_1 y_1 & \Rightarrow \exists y. \forall x. x = y \\
\exists x. F_1 x & \Rightarrow \exists y. \forall x. x = y \\
\forall x. x = y_1 & \Rightarrow \exists y. \forall x. x = y \\
\end{align*}
\]

$\Rightarrow$ $\exists y. \forall x. x = y$

Substitution? $[F_1 \leftarrow \lambda v. \forall x. x = v, F_2 \leftarrow \lambda v. v = y_1]$

What to do next?
Failed Proof Attempt of $\exists y. \forall x. x = y$

\[
\begin{align*}
(\land x. [F_2 x] ) & \Rightarrow [\forall x. F_2 x]
\end{align*}
\]

\[
\begin{align*}
[F_1 y_1] & \Rightarrow [\exists y. \forall x. x = y] \\
[\exists x. F_1 x] & \Rightarrow [\exists y. \forall x. x = y] \\
[\forall x. x = y_1] & \Rightarrow [\exists y. \forall x. x = y]
\end{align*}
\]

\[
\begin{align*}
(\land x. [x = y_1]) & \Rightarrow [\exists y. \forall x. x = y]
\end{align*}
\]

Substitution? $[F_1 \leftarrow \lambda v. \forall x. x = v, F_2 \leftarrow \lambda v. v = y_1]$. 

What to do next? Resolution with $refl$ lifted over parameter $x$: $\land x. [g_3 x = g_3 x]$. But $\land x. [x = y_1]$ and $\land x. [g_3 x = g_3 x]$ are not unifiable. Proof fails!
Free Variables in Goals

The resolution rule can be generalized to allow for instantiation of variables in goals:

\[
\begin{array}{c}
[\phi_1, \ldots, \phi_m] \Rightarrow \phi \\
[\psi_1, \ldots, \psi_n] \Rightarrow \psi
\end{array}
\]

\[
(\left[\psi_1, \ldots, \psi_{i-1}, \phi_1, \ldots, \phi_m, \psi_{i+1}, \ldots, \psi_n\right] \Rightarrow \psi) \theta
\]

where \( \phi \theta \equiv \psi_i \theta \).

But then we must distinguish the status of the free variables. Denote the universal closure of \( \psi \) by \( \bigwedge \_ \_ \_ \psi \). Then . . .
Instantiation of the Initial Goal

Previously, when we proved \( \psi \) we in fact proved \( \land \neg \psi \).

\[
\psi \Rightarrow \psi \\
\vdots \quad \vdots \\
\psi
\]
Free Variables in Goals

Instantiation of the Initial Goal

Previously, when we proved $\psi$ we in fact proved $\land \neg \psi$.

$$\begin{align*}
\land \neg \psi & \Rightarrow \psi \\
\downarrow & \\
\psi & \Rightarrow \psi \\
\downarrow & \\
\psi & \\
\downarrow & \\
\land \neg \psi & \land \neg \psi
\end{align*}$$

$\land$-E

$\land$-I

Smaus: CSMR; WS05/06
Instantiation of the Initial Goal

Previously, when we proved $\psi$ we in fact proved $\land \_.\psi$. Now, allowing for instantiation of $\psi$, we in fact prove $\land \_.\psi\theta$.

\[
\begin{align*}
\land \_.\psi & \Rightarrow \psi \\
\psi & \Rightarrow \psi \\
\vdots & \vdots \\
\psi\theta & \\
\land \_.\psi\theta & \land-I
\end{align*}
\]
Free Variables in Goals

Instantiation of the Initial Goal

Previously, when we proved \( \psi \) we in fact proved \( \bigwedge \ldots \psi \).

Now, allowing for instantiation of \( \psi \), we in fact prove \( \bigwedge \ldots \psi \theta \).

\[
\begin{align*}
\bigwedge \ldots \psi & \Rightarrow \psi \\
\psi & \Rightarrow \psi \quad \text{\( \bigwedge\text{-}E \)} \\
\vdots & \vdots \\
\psi \theta & \bigwedge \ldots \psi \theta \quad \text{\( \bigwedge\text{-}I \)}
\end{align*}
\]

This may not be what we want.

Problem: more unifiers, hence bigger search space.
Two Kinds of Free Variables

In Isabelle, control over instantiation is given by having two kinds of free variables:

- ordinary variables must not become instantiated;
- metavariables (unknowns, schematic variables) may become instantiated.

In goals we can have both kinds, in rules we have metavariables. Try it out in Isabelle!

Once a theorem is proven, any free variables will be made metavariables, and the reading is as for rules: The theorem is implicitly universally quantified over the free variables.
Conclusion on Isabelle’s Metalogic

The logic $\mathcal{M}$ and its proof system are small. What makes $\mathcal{M}$ powerful enough to encode a large variety of object logics?

- The $\lambda$-calculus is very powerful for expressing syntax and syntactic manipulations ($\rightarrow$ substitution). $\mathcal{M}$ must be extended by appropriate signature for an object logic.
- Rules of the object logic can be encoded and added to $\mathcal{M}$ as axioms.
Conclusion (2)

General principles of proof building (e.g. resolution, proving by assumption, side condition checking) are not something that must be justified by complicated (and thus error-prone) explanations in natural language — they are formal derivations in the metalogic.

This has two big advantages: shared support and high degree of confidence.
More Detailed Explanations
The Names of the Metalogic

In Isabelle jargon, the metalogic is called Pure.

In this course, we will avoid calling the Isabelle metalogic HOL, although you may find such uses in the literature.

In the literature and in Isabelle formalisations, we find various definitions of higher-order logic (HOL) that differ more or less substantially.

But the important point to remember here is this: The Isabelle metalogic $\mathcal{M}$ we study here is not identical to the logic we will study during the entire second half of this course. And the most important difference between $\mathcal{M}$ and HOL is not in the logics themselves, but in the way we use them:

$\mathcal{M}$ is a (the) metalogic!

HOL is an object logic!
Formalising Propositional Logic

We would formalise the language and the proof system as we did in the first lecture. Any proofs of soundness and completeness or other meta-properties should be rigorous, but they still resort to natural language.
Σ Contains these Symbols

Σ contains ⇒, ≡ and \( \land \), but in addition, Σ may specify other symbols.
Alternative: Polymorphism

Alternatively, we could define that

• $\equiv_\alpha: \alpha \rightarrow \alpha \rightarrow bool \in \Sigma$, and

• $\land_\alpha: (\alpha \rightarrow bool) \rightarrow bool \in \Sigma$,

where $\alpha$ is a type variable.
The names of \( \Rightarrow \), \( \equiv \), and \( \wedge \) is called meta-implication, \( \equiv \) is called meta-equality, and \( \wedge \) is called meta-universal-quantification.
The Judgements

We define our proof system for $\mathcal{M}$ using natural deduction. The judgements are formulae, i.e., term of type $\text{bool}$. This means that a node $\phi$ in a derivation tree, as in

$$
\begin{array}{c}
\ldots \\
\phi \\
\ldots 
\end{array}
$$

must be a term of type $\text{bool}$. It cannot be a derivability judgement or type judgement or a term of type, say $\text{bool} \rightarrow \text{bool}$. 

Back to main referring slide
Extensionality

Extensionality is the rule

\[
\frac{f \, x \equiv g \, x}{f \equiv g}
\]

where the side condition is that \( x \) must not be free in \( f \) or \( g \) or any assumption on which the proof of \( f \, x \equiv g \, x \) depend. It is equivalent to the \( \eta \)-axiom [HS86, pages 72-74].

Recall that we have used the notion of extensionality before, for sets. The idea is the same here.
Shorthand for Writing Signatures

We write

\[
\langle \bot : o, \\
\land, \lor, \rightarrow : o \rightarrow o \rightarrow o, \\
\forall, \exists : (i \rightarrow o) \rightarrow o, \\
\text{true} : o \rightarrow \text{bool} \rangle
\]

as shorthand for

\[
\langle \bot : o, \\
\land : o \rightarrow o \rightarrow o, \\
\lor : o \rightarrow o \rightarrow o, \\
\rightarrow : o \rightarrow o \rightarrow o, \\
\forall : (i \rightarrow o) \rightarrow o, \\
\exists : (i \rightarrow o) \rightarrow o \\
\text{true} : o \rightarrow \text{bool} \rangle
\]
Two Types for Truth Values

So we have truth values in the metalogic (type bool) and in the object logic (type o). To distinguish them clearly there are two different types for them.
The constant $true$

So we have truth values in the metalogic (type $bool$) and in the object logic (type $o$).

Paulson [Pau89] says: “the meta-formula $[A]$ abbreviates $true \ A$ and means that $A$ is true”. More precisely, we can say that $[A]$ is a meta-formula that may or may not be derivable in $\mathcal{M}_L$, and that this should reflect derivability of $A$ in $L$.

In the file IFOL.thy in your Isabelle distribution, you find

$$Trueprop :: "o => prop"$$

$Trueprop$ corresponds to $true$. 

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ψ ⇒ ψ

We have seen this before as a proof in propositional logic.

\[
\frac{[\psi]^1}{\psi \rightarrow \psi \Rightarrow -1^1}
\]
Resolution Using ∨

You may have seen the following formulation of the resolution rule:

\[
\begin{array}{c}
A_1 \lor \ldots \lor A_n & B_1 \lor \ldots \lor B_m \\
(A_1 \lor \ldots \lor A_{i-1}, A_{i+1} \lor \ldots \lor A_n \lor B_1 \lor \ldots \lor B_{j-i}, B_{j+1} \lor \ldots \lor B_m) \theta
\end{array}
\]

where either \( A_i \theta = \neg B_j \theta \) or \( \neg A_i \theta = B_j \theta \).

You can see the correspondence to the rule given here by recalling that in first-order logic, \( \phi_1 \rightarrow \ldots \rightarrow \phi_m \rightarrow \phi \) is equivalent to \( \phi_1 \land \ldots \land \phi_m \rightarrow \phi \), which is in turn equivalent to \( \neg \phi_1 \lor \ldots \lor \neg \phi_m \lor \phi \).

You may still be wondering though why in the rule res, we only allow instantiation of \([\phi_1, \ldots, \phi_m] \Rightarrow \phi\). This restriction will in fact be lifted later.
Why Is $\Rightarrow -E$ Applicable?

Recall that $\phi \theta \equiv \psi_i$. 
Schematic Resolution Rule

The schematic form of the resolution rule is:

\[
\begin{align*}
[\phi_1, \ldots, \phi_m] & \Rightarrow \phi & [\psi_1, \ldots, \psi_n] & \Rightarrow \psi \\
[\psi_1, \ldots, \psi_{i-1}, \phi_1\theta, \ldots, \phi_m\theta, \psi_{i+1}, \ldots, \psi_n] & \Rightarrow \psi
\end{align*}
\]

where $\phi\theta \equiv \psi$.

We will work with this schematic form, but remember: if necessary, you could construct an actual derivation in $\mathcal{M}$.

In this schematic form, it is always assumed that the free variables in $[\phi_1, \ldots, \phi_m] \Rightarrow \phi$ are fresh,

i.e. $FV([\phi_1, \ldots, \phi_m] \Rightarrow \phi) \cap FV([\psi_1, \ldots, \psi_n] \Rightarrow \psi) = \emptyset$.

This assumption may be justified considering the formal derivation of the resolution rule. Suppose that the free variables in $[\phi_1, \ldots, \phi_m] \Rightarrow \phi$ are not all fresh, and consider $\bigwedge x'_1 \ldots x'_k.[\phi'_1, \ldots, \phi'_m] \Rightarrow \phi'$, obtained from
\[ \bigwedge x_1 \ldots x_k. [\phi_1, \ldots, \phi_m] \Rightarrow \phi \] by replacing each \( x_i \) with \( x'_i \), where the \( x'_i \) are fresh.

It is easy to see that in the formal derivation of the resolution rule, one can replace

\[
\begin{align*}
\bigwedge x_1 \ldots x_k. [\phi_1, \ldots, \phi_m] \Rightarrow \phi \\
[\phi_1 \theta, \ldots, \phi_m \theta] \Rightarrow \phi \theta
\end{align*}
\]

with

\[
\begin{align*}
\bigwedge x'_1 \ldots x'_k. [\phi'_1, \ldots, \phi'_m] \Rightarrow \phi' \\
[\phi_1 \theta, \ldots, \phi_m \theta] \Rightarrow \phi \theta
\end{align*}
\]

Therefore we can assume without loss of generality that the free variables in \( [\phi_1, \ldots, \phi_m] \Rightarrow \phi \) are fresh.

The next question is: why do we want fresh variables? Maybe this is clear intuitively: A rule is always meant to be schematic and the choice of variables names in a rule should be irrelevant. More concretely, one
may say that if one does not rename the variables in a rule and hence there is some variable, say $A$, that occurs in the current subgoal, then resolution may lead to a subgoal containing occurrences of $A$ originating from the goal and others originating from the rule, and these are inadvertently identified, leading to a proof state that is more instantiated than it should be.
A Hint

On the one hand, we want to resolve

\[
([A \land B] \Rightarrow [C \rightarrow A \land C]) \Rightarrow [A \land B \rightarrow (C \rightarrow A \land C)],
\]

i.e., we have to match \([A \land B] \Rightarrow [C \rightarrow A \land C]\) against the conclusion of some meta-axiom.

On the other hand, think what Isabelle would display in this situation. The (only) subgoal would be

1. \(A \land B \Rightarrow C \rightarrow A \land C\),

so we have to show \(C \rightarrow A \land C\) (using assumption \(A \land B\)). So you should look at \(C \rightarrow A \land C\) to guess which meta-axiom should be used now.
Resolution not Applicable

In our current situation, Isabelle would display:

Level 1 (1 subgoal)
\[ A \land B \rightarrow (C \rightarrow A \land C) \]
1. \[ A \land B \implies C \rightarrow A \land C \]

From your experience with Isabelle, it is clear that since the top-level symbol in \( C \rightarrow A \land C \) is \( \rightarrow \), you would use \( \rightarrow \text{I} \).

But look at the resolution rule again. We would take a fresh instance of \( \rightarrow \text{I} \), say \( ([A_2] \Rightarrow [B_2]) \Rightarrow [A_2 \rightarrow B_2] \). The problem is that \( [A_2 \rightarrow B_2] \) is not unifiable with \( [A \land B] \Rightarrow [C \rightarrow A \land C] \), and so \( \text{res} \) is not applicable.
The Lifted $\rightarrow$-I

$([A \land B] \Rightarrow ([A_2] \Rightarrow [B_2])) \Rightarrow ([A \land B] \Rightarrow [A_2 \rightarrow B_2])$

is the $\rightarrow$-I-rule (meta-axiom) lifted over the assumption $A \land B$. 

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The Lifted $\land$-I

$$(\Omega \Rightarrow [A_3]) \Rightarrow (\Omega \Rightarrow [B_3]) \Rightarrow (\Omega \Rightarrow [A_3 \land B_3])$$

is the $\land$-I-rule (meta-axiom) lifted over the assumption list $\Omega$. Recall that $\Omega$ was an abbreviation for $[[A \land B], [C]]$, but this is obviously irrelevant for the process of lifting.
Why Is the Assumption Axiom Schematic?

The assumption axiom

\[
[\phi_1, \ldots, \phi_m] \Rightarrow \phi_i
\]

is schematic is two senses:

• the Greek letters could stand for arbitrary formulae;
• just like for resolution rule, we don’t even know how many formulae are involved \((m, i)\) could be any natural numbers).

However, one could also write the axiom as

\[
[A_1, \ldots, A_m] \Rightarrow A_i
\]

where the \(A\)’s are variables (of type \text{bool}) and instantiate it later when it is used in some resolution step.
Discharging Is Optional

Recall here that the rule $\Rightarrow -$, just like $\rightarrow -$, allows you to discharge zero or more assumptions. In the present derivation, we discharge the assumption $\phi_i$ at some point but we do not discharge any other assumptions.
Using the more Generic Assumption Axiom

As explained previously, we could use a more generic variant of the assumption axiom, in that we have variables in it that may become instantiated upon resolution. As in previous proof steps we assume that these variables are suitably renamed; for this purpose we index them by $4$. Note however that the variant is still specific in the sense that $m = 2$. Like in meta-axioms used before, we use letters from the beginning of the alphabet, so the variant of the assumption axiom that we use is $[A_4, B_4] \Rightarrow B_4$. The proof fragment would then look as follows:

$$
\begin{array}{c}
\vdots \\

[A_4, B_4] \Rightarrow B_4 \\
[\Omega \Rightarrow [A], \Omega \Rightarrow [C]] \Rightarrow \omega \\
(\Omega \Rightarrow [A]) \Rightarrow \omega \\
\end{array}
$$

where $\theta = \{A_4 \leftarrow [A \land B], B_4 \leftarrow [C]\}$. 

Smaus: CSMR; WS05/06
Turning Trees Upside-Down?

Intuitively, as far as the order in which the object rules, resp. meta-axioms, are applied, the proof in $M_{\text{Prop}}$ is the proof in $\text{Prop}$ turned upside-down.

However, this may seem suspicious for two reasons:

- In derivation trees, the direction of implication (forgetting about whether it is meta- or object implication) is “downwards”: whatever is above implies whatever is below. So it seems strange that this order should be reversed just because we go from the object to the meta-level.

- In general, a derivation tree in the object level is a proper tree, i.e., there are nodes where it branches. So what sense does it make to “turn it upside-down”? The result would not be any tree at all.

These points will now be addressed.
More Detailed Explanations

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Interleaving Proofs

If one pictures the object level proof and how it is modeled in $\mathcal{M}_{Prop}$, one intuitive way of thinking of it is as follows: Each rule application in the object level proof must also be performed at the meta-level. Now, starting at the root of the object level proof, we may do any rule application that is the child of a rule application we have done previously. Take for example the following object level proof:

\[
\frac{[A \land (B \land C)]}{A} \quad \text{\raisebox{1pt}{$\land$}-EL}^3
\]

\[
\frac{B \land C}{C} \quad \text{\raisebox{1pt}{$\land$}-ER}^{4}
\]

\[
\frac{A \land C}{\lor-\text{I}^2}
\]

\[
\frac{[A \land (B \land C)]}{A \land (B \land C)} \quad \text{\raisebox{1pt}{$\land$}-ER}^{5}
\]

\[
\frac{A \land (B \land C) \rightarrow A \land C}{\rightarrow\text{I}^1}
\]
Then in the meta-proof, the meta-axioms might be applied in the following orders:

- $\rightarrow -I_1 \land -I_2 \land -ER^4 \land -ER^5 \land -EL^3$, or
- $\rightarrow -I_1 \land -I_2 \land -EL^3 \land -ER^4 \land -ER^5$, or
- $\rightarrow -I_1 \land -I_2 \land -ER^4 \land -EL^3 \land -ER^5$.

But this is not new to you: In Isabelle, you are always free to choose the subgoal that you want to work on next, and so you can interleave the proofs of the different subgoals.

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A Different Way of Lifting ∀-I

In our proof, we lifted ∀-I over assumption $[\forall z. G z]$ as follows:

$$([\forall z. G z] \Rightarrow (\bigwedge x. [F_1 x])) \Rightarrow ([\forall z. G z] \Rightarrow [\forall x. F_1 x])$$

It would have been possible to derive (formally, in $\mathcal{M}$) the following rule instead:

$$(\bigwedge x. [\forall z. G z] \Rightarrow [F_1 x]) \Rightarrow ([\forall z. G z] \Rightarrow [\forall x. F_1 x])$$

This is essentially so since $z \notin FV[\forall z. G z]$. If we had done it like that,
step 2 would have looked as follows

\[
\begin{align*}
& (\wedge x. [\forall z. G z] \Rightarrow [F_1 x]) \\
\Rightarrow & (\forall z. G z) \Rightarrow (\forall x. F_1 x) \\
& (\forall z. G z) \Rightarrow (\forall z. G z \lor H z) \\
\Rightarrow & [(\forall z. G z) \rightarrow (\forall z. G z \lor H z)]
\end{align*}
\]

The rest of the proof would then have looked slightly differently due to the different scope of the \(\wedge\). For example, it would have been necessary to lift \(\lor\)-\textit{IL} over assumptions \textit{before} lifting it over parameters. In fact, if we denote a vector of variables by overlining, then we can
derive the following rule for lifting over assumptions:

\[ \left[ (\land \bar{x}_1.\phi_1), \ldots, (\land \bar{x}_m.\phi_m) \right] \Rightarrow \phi \]

\[ \left[ (\land \bar{x}_1.\Psi \Rightarrow \phi_1), \ldots, (\land \bar{x}_1.\Psi \Rightarrow \phi_m) \right] \Rightarrow (\Psi \Rightarrow \phi) \]

where \( \bar{x}_1, \ldots, \bar{x}_m \notin FV(\Psi) \). Compare this to rule \( a\text{-}lift \). Using the more complicated rule, where the assumption list \( \Psi \) is pulled into the scope of \( \land \)’s surrounding each rule premise \( \phi_i \), would probably have made the presentation here somewhat more complicated. On the other hand, this is indeed what happens in Isabelle (try to do the proof of \( (\forall z.G\ z) \rightarrow (\forall z.G\ z \lor H\ z) \) in Isabelle).
Lifting \( \text{refl} \)

Note that lifting \( \text{refl} \)

\[
\forall z. (z = z)
\]

over \( x \) gives

\[
\forall g_3. \forall x. (g_3 \cdot x = g_3 \cdot x).
\]

Here the variable \( z \) in \( \text{refl} \) was replaced by the variable \( g_3 \) that depends on \( x \). However, we drop the outer quantification \( \forall g_3 \). In this particular case, \( \forall x \) is also an outer quantification, but we keep it, since obtaining this quantification was the very purpose of lifting (recall that lifting is done to achieve unifiability).
Unifying $\bigwedge x. [x = y_1]$ and $\bigwedge x. [g_3 x = g_3 x]$.

Recall that $\bigwedge x. \phi$ is syntactic sugar for $\bigwedge x. (\lambda x. \phi)$.

So we have to unify $\lambda x. [x = y_1]$ and $\lambda x. [g_3 x = g_3 x]$.

It turns out that this task can be decomposed into having to unify $\lambda x. x$ and $\lambda x. g_3 x$ on the one hand, and $\lambda x. y_1$ and $\lambda x. g_3 x$ on the other hand.

Unification of $\lambda x. x$ and $\lambda x. g_3 x$ forces $g_3$ to be $\lambda x. x$, so we are left with having to unify $\lambda x. y_1$ and $\lambda x. x$. But these terms are not unifiable!

This was just a semi-formal argument that $\bigwedge x. [x = y_1]$ and $\bigwedge x. [g_3 x = g_3 x]$ are not unifiable, but it gives you the idea.
The Universal Closure

The universal closure of a meta-formula $\psi$ is the formula $\bigwedge x_1 \ldots x_n.\psi$ where $FV(\psi) = \{x_1 \ldots x_n\}$.

As might be expected, the same concept is also used for FOL formulae where it is defined in analogy using $\forall$ instead of $\bigwedge$. 
Proving what We Want

Suppose we want to prove \(((A \rightarrow B) \rightarrow A) \rightarrow A\). If we allow for instantiation of the free variables \(A\) and \(B\), we could easily end up proving \(((A \rightarrow A) \rightarrow A) \rightarrow A\). This is probably not what we want. In fact the proof has little to do with the proof of \(((A \rightarrow B) \rightarrow A) \rightarrow A\) that is schematic in \(A\) and \(B\).

In terms of \(\mathcal{M}_{\text{prop}}\), we want to prove \(\text{\lor AB} \cdot [((A \rightarrow B) \rightarrow A) \rightarrow A]\)

Recall that \(((A \rightarrow B) \rightarrow A) \rightarrow A\) is Peirce’s law.
Too many Unifiers

The more free variables in the goal we allow Isabelle to instantiate, the more unifiers there are. This may increase the search space to the extent of making it impossible to find a proof.
Test the Difference

To understand the difference, try proving $A \land B \rightarrow P$ and $A \land B \rightarrow ?P$ in Isabelle. The first won’t succeed while the second may succeed in various ways.
See how Variables Are Turned into Metavariabes

Prove $A \land B \rightarrow ?P$ in Isabelle and save (qed) it as a theorem and then have a look at the theorem.
The Inference Rules of $\mathcal{M}$ Are not Enough

In some course on propositional logic, you may have learned that the connective $\rightarrow$ is not really necessary since $A \rightarrow B$ is equivalent to $\neg A \lor B$. Likewise, we considered $\neg A$ as syntactic sugar for $A \rightarrow \bot$.

Therefore, when we introduce a logic $\mathcal{M}$ that is so extremely simple as far as the number of logical symbols is concerned (just $\Rightarrow$, $\equiv$, $\land$), one might think that the idea is that all the other logical symbols one usually needs are just syntactic sugar. This is not the case!

To encode propositional logic or FOL in $\mathcal{M}$, we must add their rules as axioms.

Later, we will be working with a logic just slightly richer than $\mathcal{M}$ but still quite simple, and there the idea is indeed that all the other logical symbols one usually needs are just syntactic sugar.
HOL: Foundations
Overview

HOL is expressive foundation for

- **Mathematics**: analysis, algebra, . . .
- **Computer science**: program correctness, hardware verification, . . .
Overview

HOL is expressive foundation for
• Mathematics: analysis, algebra, . . .
• Computer science: program correctness, hardware verification, . . .

HOL is very similar to $\mathcal{M}$, but it “is” an object logic!
• HOL is classical.
• Still important: modeling of problems/domains (now within HOL).
• Still important: deriving relevant reasoning principles.
Isabelle/HOL vs. Alternatives

We will use Isabelle/HOL.

- Could forgo the use of a metalogic and employ alternatives, e.g., HOL system or PVS, or constructive provers such as Coq, Nuprl.

- Choice depends on culture and application.
Safety through Strength

Safety via conservative (definitional) extensions:

- Small kernel of constants and rules;
- extend theory with new constants and types defined using existing ones;
- derive properties/theorems.

Contrast with:

- Weak logics (e.g., propositional logic): can’t define much;
- axiomatic extensions: can lead to inconsistency.

Bertrand Russel once likened the advantages of postulation over definition to the advantages of theft over honest toil!
Set Theory as Alternative?

Set theory is the logician’s choice as basis for modern mathematics.

- **ZFC** (in Isabelle): impressive applications!
- Bernays-Gödel: used for resolution since finitely axiomatizable.

Set theories (both) distinguish between sets and classes.

- Consistency maintained as some collections are “too big” to be sets, e.g., class of all sets $V$ is not a set.
- A class cannot belong to another class (let alone a set)!
Finally: We Choose HOL!

HOL developed by [Chu40, Hen50] and rediscovered by [And02, GM93].

- **Rationale:** one usually works with typed entities.
- Reasoning is then easier with support for types.

HOL is classical logic based on $\lambda \rightarrow$.

- Isabelle/HOL also supports “mod cons” like polymorphism and type classes!

HOL is weaker than ZF set theory, but for most applications this does not matter. If you prefer ML to Lisp, you will probably prefer HOL to ZF.  

(Paulson)
## What Does Higher-Order Mean?

<table>
<thead>
<tr>
<th>“Type” order</th>
<th>Logic order</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Example</strong></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td>$A \land B \rightarrow B \land A$</td>
</tr>
<tr>
<td>+ quantification</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>$\forall x, y. R(x, y) \rightarrow R(y, x)$</td>
</tr>
<tr>
<td>+ quantification</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>$False \equiv \forall P. P$</td>
</tr>
<tr>
<td></td>
<td>$P \land Q \equiv \forall R. (P \rightarrow Q \rightarrow R)$</td>
</tr>
<tr>
<td>2</td>
<td></td>
</tr>
<tr>
<td>+ quantification</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>$\forall X. (X(R, S') \leftrightarrow (\forall x. R(x) \rightarrow S(x))) \rightarrow X(R', S') \equiv subrel(R', S')$</td>
</tr>
</tbody>
</table>
HOL = Union of All Finite Orders

$\omega$-order logic, also called finite-type theory or higher-order logic (HOL), includes logics of all finite orders.
Syntax

Syntactically, HOL is a polymorphic (although not necessarily) variant of $\lambda \to$ with certain default types and constants.

Default constants can be called **logical symbols**.
Types (Review)

Given a set of type constructors, say $B = \{bool, \_ \to \_, ind, \_ \times \_, \_ list, \_ set, \ldots\}$, polymorphic types are defined by $\tau ::= \alpha \mid (\tau, \ldots, \tau) T$, where $\alpha$ is type variable.

- $bool$ is also called $o$ in literature [Chu40, And02], but avoid confusion.
- $bool$ and $\to$ always present in HOL; $ind$ will also play a special role; other type constructors may be defined.

- Note polymorphism!
Terms

Reminder:  \( e ::= x \mid c \mid (ee) \mid (\lambda x^\tau. e) \)

Typing rules as in polymorphic \( \lambda \)-calculus, with \( \Sigma \) defining and typing constants.

Terms of type \( \text{bool} \) are called (well-formed) formulae.

In HOL, \( \Sigma \) always includes:

\[
\begin{align*}
\text{True}, \text{False} & : \text{bool} \\
\equiv & : \alpha \rightarrow \alpha \rightarrow \text{bool} \quad (\text{polymorphic, or set}) \\
\rightarrow & : \text{bool} \rightarrow \text{bool} \rightarrow \text{bool} \\
\epsilon & : (\alpha \rightarrow \text{bool}) \rightarrow \alpha \quad (\text{in Isabelle: Eps or SOME})
\end{align*}
\]
Semantics

Intuitively: many-sorted semantics + functions

- FOL: structure is domain and functions/relations.

\[ A = \langle D, I_A \rangle \]
Semantics

Intuitively: many-sorted semantics + functions

• FOL: structure is domain and functions/relations.
  Many-sorted FOL: domains are sort-indexed

\[ \mathcal{A} = \langle D_1, \ldots, D_n, I_A \rangle \]
Intuitively: many-sorted semantics + functions

- FOL: structure is domain and functions/relations. Many-sorted FOL: domains are sort-indexed

\[ A = \langle D_1, \ldots, D_n, I_A \rangle \]

- HOL extends idea: \( D \) indexed by (infinitely many) types.
- Complications due to polymorphism [GM93].
- We only give a monomorphic variant of semantics here!
Model Based on Universe of Sets $\mathcal{U}$

$\mathcal{U}$ is a collection of sets (domains), fulfilling closure conditions:

**Inhab:** Each $X \in \mathcal{U}$ is a nonempty set

**Sub:** If $X \in \mathcal{U}$ und $Y \neq \emptyset \subseteq X$, then $Y \in \mathcal{U}$

**Prod:** If $X, Y \in \mathcal{U}$ then $X \times Y \in \mathcal{U}$.

**Pow:** If $X \in \mathcal{U}$ then $\wp(X) = \{Y \mid Y \subseteq X\} \in \mathcal{U}$

**Infty:** $\mathcal{U}$ contains a distinguished infinite set $I$

**Choice:** There is a function $ch \in \Pi_{X \in \mathcal{U}}.X$. 

Smaus: CSMR; WS05/06
**Prod: Encoding** $X \times Y$

$X \times Y$ is the Cartesian product.

One can actually encode a tuple $(x, y)$ without explicitly postulating the "existence of tuples". E.g.:

$$(x, y) \equiv \{\{x\}, \{x, y\}\}$$
Choice: Picking a Member

The function $ch$ takes a set $X \in \mathcal{U}$ as argument and returns a member of $X$.

We hence write $ch \in \Pi_{X \in \mathcal{U}} X$, i.e., $ch$ is of dependent type. Essentially, the constant $\epsilon$ will be interpreted as $ch$, but you will see the technical details later.
Function Space in $\mathcal{U}$

Define set $X \rightarrow Y$ as (graph of) functions from $X$ to $Y$.

- For nonempty $Y$, this set is nonempty and is a subset of $\mathcal{P}(X \times Y)$.
- From closure conditions: $X, Y \in \mathcal{U}$ then $X \rightarrow Y \in \mathcal{U}$.
Distinguished Sets

From

**Infty:** \( \mathcal{U} \) contains a distinguished infinite set \( I \)

**Sub:** If \( X \in \mathcal{U} \) and \( Y \neq \emptyset \subseteq X \), then \( Y \in \mathcal{U} \)

it follows that there is (at least one) set

**Unit:** A distinguished 1-element set \( \{1\} \)

**Bool:** A distinguished 2-element set \( \{T, F\} \).
Frame

For semantics, we neglect polymorphism. \( \tau \) and \( \sigma \) range over types.

A frame is a collection \( \{ \mathcal{D}_\tau \}_{\tau} \) of non-empty sets (domains) \( \mathcal{D}_\tau \in \mathcal{U} \), one for each type \( \tau \), where:

- \( \mathcal{D}_{\text{bool}} = \{ T, F \} \);
- \( \mathcal{D}_{\tau \rightarrow \sigma} \subseteq \mathcal{D}_\tau \rightarrow \mathcal{D}_\sigma \), i.e., some collection of functions from \( \mathcal{D}_\tau \) to \( \mathcal{D}_\sigma \).
- \( \mathcal{D}_{\text{ind}} = I \).

Note: for fundamental reasons discussed later, one cannot simply define \( \mathcal{D}_{\tau \rightarrow \sigma} = \mathcal{D}_\tau \rightarrow \mathcal{D}_\sigma \) at this stage.
Interpretations

An interpretation $\mathcal{M} = \langle \{D_\tau\}_\tau, \mathcal{J} \rangle$ is a frame $\{D_\tau\}_\tau$ and a denotation function $\mathcal{J}$ mapping each constant of type $\tau$ to an element of $D_\tau$ where:

- $\mathcal{J}(\text{True}) = T$ and $\mathcal{J}(\text{False}) = F$;
- $\mathcal{J}(\rightarrow)$ is identity on $D_\tau$;
- $\mathcal{J}(\rightarrow)$ is implication function over $D_{\text{bool}}$. For $b, b' \in \{T, F\}$,

$$\mathcal{J}(\rightarrow)(b, b') = \begin{cases} F & \text{if } b = T \text{ and } b' = F \\ T & \text{otherwise} \end{cases}$$
Interpretations (Cont.)

• $\mathcal{J}(\epsilon_{(\tau \rightarrow \text{bool}) \rightarrow \tau})$ is defined by (for $f \in (\mathcal{D}_\tau \rightarrow \mathcal{D}_{\text{bool}})$):

\[
\mathcal{J}(\epsilon_{(\tau \rightarrow \text{bool}) \rightarrow \tau})(f) = \begin{cases} 
ch(f^{-1}(\{T\})) & \text{if } f^{-1}(\{T\}) \neq \emptyset \\
ch(\mathcal{D}_\tau) & \text{otherwise}
\end{cases}
\]

Note: If a frame $\{\mathcal{D}_\tau\}_\tau$ does not contain all of the functions used above, then $\{\mathcal{D}_\tau\}_\tau$ cannot belong to any interpretation.
A Terminological Note

The terminology is slightly different from FOL:
In FOL, “⟨\{D_\tau\}_\tau, J⟩” is called structure and “J” is called interpretation.
In HOL, ⟨\{D_\tau\}_\tau, J⟩ is called interpretation and J is called denotation function.
The Value of Terms (Naive)

In analogy to FOL, given an interpretation \( m = \langle \{ D_\tau \}_\tau, J \rangle \) and a type-indexed collection of assignments \( A = \{ A_\tau \}_\tau \), define \( V^m_A \) such that \( V^m_A(t_\rho) \in D_\rho \) for all \( t \), as follows:

1. \( V^m_A(x_\tau) = A(x_\tau) \);
2. \( V^m_A(c) = J(c) \) for \( c \) a constant;
3. \( V^m_A(s_\tau \rightarrow_\sigma t_\tau) = (V^m_A(s))(V^m_A(t)) \), i.e., the value of the function \( V^m_A(s) \) at the argument \( V^m_A(t) \);
4. \( V^m_A(\lambda x_\tau . t_\sigma) \) = the function from \( D_\tau \) into \( D_\sigma \) whose value for each \( e \in D_\tau \) is \( V^m_A[x \leftarrow e](t) \).

What is the problem?
The Value of Terms (Naive)

In analogy to FOL, given an interpretation \( m = \langle \{ D_\tau \}_\tau, J \rangle \) and a type-indexed collection of assignments \( A = \{ A_\tau \}_\tau \), define \( V_A^m \) such that \( V_A^m(t_\rho) \in D_\rho \) for all \( t \), as follows:

1. \( V_A^m(x_\tau) = A(x_\tau) \);
2. \( V_A^m(c) = J(c) \) for \( c \) a constant;
3. \( V_A^m(s_\tau \rightarrow_\sigma t_\tau) = (V_A^m(s))(V_A^m(t)) \), i.e., the value of the function \( V_A^m(s) \) at the argument \( V_A^m(t) \);
4. \( V_A^m(\lambda x_\tau . t_\sigma) = \) the function from \( D_\tau \) into \( D_\sigma \) whose value for each \( e \in D_\tau \) is \( V_A^m[x \leftarrow e](t) \).

What is the problem? Condition 4!
**Condition 4 Is Critical**

For $\mathcal{V}_A^m$ to be well-defined, the function from $D_\tau$ into $D_\sigma$ in condition 4 must live:

- in some domain of $\mathcal{U}$ (since it is required that $\mathcal{V}_A^m(t_\rho) \in D_\rho$ for all $t$, and $D_\rho \in \mathcal{U}$): this is guaranteed by closure conditions on $\mathcal{U}$;
**Condition 4 Is Critical**

For $V_A^m$ to be well-defined, the function from $D_\tau$ into $D_\sigma$ in condition 4 must live

- in some domain of $\mathcal{U}$ (since it is required that $V_A^m(t_\rho) \in D_\rho$ for all $t$, and $D_\rho \in \mathcal{U}$): this is guaranteed by closure conditions on $\mathcal{U}$;

- in a certain domain of $\mathcal{U}$, namely $D_{\tau\rightarrow\sigma}$; for this, $D_{\tau\rightarrow\sigma}$ must be big enough.

If $V_A^m$ is well-defined, we call $m = \langle D_\tau, \mathcal{I} \rangle$ a (general) model.
Models

Hence: Not all interpretations are general models, but we restrict our attention to the general models.

If $D_{τ→σ}$ is the set of all functions from $D_τ$ to $D_σ$, then it is certainly “big enough”. In this case, we speak of a standard model. Important for completeness.

If $V^m_A$ is a general model and $A$ an assignment, then $V^m_A$ is uniquely determined.

$V^m_A(t)$ is value of $t$ in $V^m_A$ wrt. $A$.

Note that in contrast to first-order logic, “model” does not mean “an interpretation that makes a formula true”.

Smaus: CSMR; WS05/06
Satisfiability and Validity

A formula (term of type \( \text{bool} \)) \( \phi \) is **satisfiable** wrt. a model \( \mathcal{M} \) if there exists an assignment \( A \) such that \( \mathcal{V}^{\mathcal{M}}_A(\phi) = T \).

A formula \( \phi \) is **valid** wrt. a model \( \mathcal{M} \) if for all assignments \( A \), we have \( \mathcal{V}^{\mathcal{M}}_A(\phi) = T \).

A formula \( \phi \) is valid in **the general sense** if it is valid in every general model.

A formula \( \phi \) is valid in **the standard sense** if it is valid in every standard model.
Existence of Values

Closure conditions for general models guarantee every well-formed term has a value under every assignment, and this means that certain values must exist, e.g.,

- Closure under functions: since $\forall^m_V (\lambda x^\tau. x)$ is defined, the identity function from $\mathcal{D}_\tau$ to $\mathcal{D}_\tau$ must always belong to $\mathcal{D}_{\tau \rightarrow \tau}$.

- Closure under application: if $\mathcal{D}_\mathbb{N}$ is natural numbers, and $\mathcal{D}_{\mathbb{N} \rightarrow \mathbb{N} \rightarrow \mathbb{N}}$ contains addition function $p$ where $p \ x \ y = x + y$, then $\mathcal{D}_{\mathbb{N} \rightarrow \mathbb{N}}$ must contain $k$ where $k \ x = 2x + 5$, since $k = \forall^m_V (\lambda x^\mathbb{N}. f(f x x) y)$ where $A(f) = p$ and $A(y) = 5$. 
Basic Rules

We now give the core calculus of HOL. Its rules can be stated using only the constants $=$, $\rightarrow$, and $\epsilon$. However, there will be one rule, \texttt{tof} ("true or false"), which would be hard to read if we did that.

So we allow ourselves to "cheat" and also use constants \texttt{True}, \texttt{False}, $\lor$ to write rule \texttt{tof}.

Later we will define those constants, i.e., regard them as syntactic sugar.
Basic Rules in Sequent Notation

\[
\begin{align*}
\Gamma \vdash \phi &= \phi & \text{refl} \\
\Gamma \vdash \phi x &= \eta x & \text{ext}^* \\
\Gamma \vdash \phi &= \eta & \\
\Gamma \vdash \phi \rightarrow \eta & \quad \Gamma \vdash \phi & \quad \text{mp} \\
\Gamma \vdash \eta & \\
\Gamma \vdash (\phi \rightarrow \eta) \rightarrow (\eta \rightarrow \phi) \rightarrow (\phi = \eta) & \text{iff} \\
\phi = True \lor \phi = False & \text{tof} \\
\Gamma \vdash \phi \epsilon x.\phi x & \text{selectl}
\end{align*}
\]
Axiom of Infinity

There is one additional rule (axiom) that will give us the existence of infinite sets:

\[ \exists f(\text{ind} \to \text{ind}). \text{injective } f \land \neg \text{surjective } f \]

Has special role. Interesting to look at HOL with or without infinity. Won’t consider infinity today.

Note “cheating” (use of \( \exists \)).

These eight (nine) rules are the entire basis!
Soundness and Completeness

**Soundness** is straightforward [And02, p. 240]. **Completeness** only follows w.r.t. general models, as opposed to standard models. Recall that a **standard model** is one where $D_{\tau \rightarrow \sigma}$ is always the set of all functions from $D_{\tau}$ to $D_{\sigma}$. There are formulas that are valid in all standard models, but not in all general models, and which cannot be proven in our calculus. Our calculus can prove the formulas that are true in all general models including non-standard ones. This reconciles HOL with Gödel’s incompleteness theorem.

If we consider a version of HOL without infinity, then every model is a standard model and so completeness holds.
We now look at a particular instance of HOL (given by defining certain types and constants) which essentially corresponds to the HOL theory of Isabelle. We present language and rules using “mathematical” syntax, but also comparing with Isabelle (concrete/HOAS) syntax. We take polymorphism back on board.
(Central Parts of the) Language

\[ \Sigma_0 = \{
  \begin{array}{ll}
    \text{True, False} & : \text{bool}, \\
    \neg & : \text{bool} \rightarrow \text{bool}, \\
    \_ \land \_ & : \text{bool} \rightarrow \text{bool} \rightarrow \text{bool}, \\
    \forall \_ & : (\alpha \rightarrow \text{bool}) \rightarrow \text{bool}, \\
    \exists \_ & : (\alpha \rightarrow \text{bool}) \rightarrow \alpha, \\
    \epsilon \_ & : \text{bool} \rightarrow \alpha \rightarrow \alpha \rightarrow \alpha, \\
    \text{if} \_ \text{then} \_ \text{else} \_ & : \alpha \rightarrow \alpha \rightarrow \text{bool}
  \end{array}
\]
Basic Rules in Isabelle Notation

refl: "t = t"

subst: "[| s = t; P(s) |] ==> P(t)"

ext: "(!!x. (f x) = g x) ==> (%x. f x) = (%x. g x)"

impI: "(P ==> Q) ==> P --> Q"

mp: "[| P --> Q; P |] ==> Q"

iff: "(P-->Q) --> (Q-->P) --> (P=Q)"

True_or_False: "(P=True) | (P=False)"

selectI: "P (x) ==> P (@x. P x)"

See HOL.thy.
Basic Rules in Mixed Notation

\[
\frac{\phi = \phi}{\text{refl}}
\]

\[
\frac{\phi x = \eta x}{\phi = \eta \quad \text{ext}^*}
\]

\[
\frac{\phi \rightarrow \eta \quad \phi}{\eta \quad \text{mp}}
\]

\[
\frac{(\phi \rightarrow \eta) \rightarrow (\eta \rightarrow \phi) \rightarrow (\phi = \eta)}{\text{iff}}
\]

\[
\frac{\phi = \text{True} \lor \phi = \text{False}}{\text{tob}}
\]

\[
\frac{\phi x}{\phi(\epsilon x. \phi x) \quad \text{selectl}}
\]

\[
\frac{\phi = \eta \quad P(\phi)}{P(\eta) \quad \text{subst}}
\]

\[
\frac{\phi \Rightarrow \eta}{\phi \rightarrow \eta \quad \text{impl}}
\]

Smaus: CSMR; WS05/06
No more “Cheating”: The Definitions

\[ True = (\lambda x^{bool}. x = \lambda x.x) \]
\[ \forall = \lambda \phi^{\alpha \rightarrow bool}. (\phi = \lambda x. True) \]
\[ False = \forall \phi^{bool}. \phi \]
\[ \vee = \lambda \phi \eta. \forall \psi. (\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi \]
\[ \land = \lambda \phi \eta. \forall \psi. (\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi \]
\[ \neg = \lambda \phi. (\phi \rightarrow False) \]
\[ \exists = (\lambda \phi. \phi(\epsilon x. \phi x)) \]
\[ If = \lambda \phi^{bool} xy. \epsilon z. (\phi = True \rightarrow z = x) \land (\phi = False \rightarrow z = y) \]
Note: Different Syntaxes

Mathematical vs. Isabelle, e.g.

\[ \neg \phi \]
\[ \lambda x^{\text{bool}}. P \]

\text{Not Phi}
\text{%x :: bool. P}

HOAS vs. concrete, e.g.

\[ \forall (\lambda x^T. (\land p(x) \land q(x))) \]
\[ \epsilon (P) \]

\[ \forall x^T. p(x) \land q(x) \]
\[ \epsilon x. P(x) \]

We use all those forms as convenient. For displaying Isabelle files, we will sometimes use a style where some ASCII words (e.g. \%) are replaced with mathematical symbols (e.g. \lambda).
Conclusions on HOL

- HOL generalizes semantics of FOL:
  - \textit{bool} serves as type of propositions;
  - Syntax/semantics allows for higher-order functions.

- Logic is rather minimal: 8 or 9 rules, based on 3 constants, \textit{soundness} straightforward.

- Logic \textit{complete} (w.r.t. general models, but not \textit{standard} models).

- Next lecture we will see how all well-known inference rules can be derived.
More Detailed Explanations
HOL Applications

Theorem proving in higher-order logic is an active research area with some impressive applications.
HOL “Is” an Object Logic

The differences between $\mathcal{M}$ and HOL are subtle and the matter is further complicated by the fact that there are some variations in the way in which the Isabelle metalogic $\mathcal{M}$ on the one hand and the object logic HOL on the other hand are presented.

But what matters for us here is that HOL is an object logic, i.e., it is one of the object logic that can be represented by $\mathcal{M}$, just like propositional logic or first-order logic. That is to say, we use HOL as object logic.
Modeling of Problems/Domains in HOL

We have previously looked at metatheory, i.e., how can one logic be represented/modelled in a metalogic.

In particular, we have seen how general reasoning principles can be derived in the metalogic.

We now set aside the issue of metalogics, but there is still an issue of modeling one system within another: how do we model problems/domains within HOL? How do we derive reasoning principles?
Classical Reasoning

Recall the distinction between classical and intuitionistic logics. There is a particular rule in HOL from which the rule of the excluded middle can be derived. This is in contrast to constructive (intuitionistic) logics.
Not just HOL, but Isabelle/HOL

We use Isabelle/HOL, and this means that HOL is an object logic represented by the metalogic $\mathcal{M}$. 
Forgoing Metalogic

There are theorem proving systems that have no metalogic, but rather have a particular logic hard-wired into them, e.g. a HOL system or PVS.
Constructive Provers

Constructive provers are based on intuitionistic logic. The rationale is that one has to give evidence for any statement. Coq and Nuprl are examples of such systems.
Safety

The principle is simple: the smaller a system is, the easier it is to check that it is correct, and the more confident one can be about it. We have seen this before when we argued for the use of metalogics. However, in that context, we still had to add further axioms to $M$. Here this is not the case.

Safety through strength means: HOL is strong enough to model interesting systems without having to add further axioms – that’s what makes it safe.
No Axiomatic Extensions

What we attempt to do here has similarities to the process of representing an object logic in a metalogic. But an important difference must be noted.

We will see many extensions of the HOL kernel by constants (and types). The definitions of those constants and types involve axioms that must be added according to a strict discipline. Other than that, we will not add any axioms!
ZFC

ZFC stands for Zermelo-Fränkel set theory with choice [Dev93, Ebb94].
Mod Cons

“Mod cons” stands for “modern conveniences”.
Type Order

Recall the definition of an order on types. Assume here, as we did in the lecture on representing syntax, that there is a type $i$ of individuals and a type $o$ for truth values. These objects are of 0th-order type.

A predicate symbol is a function taking individuals to a truth value, so it is an object of first-order type. A function symbol is a function taking individuals to an individual, so it is also an object of first-order type.

In the table, we classify logics by the order of the non-logical symbols (e.g., for first-order logic: variables, function symbols, predicate symbols).

A hierarchy of logics is obtained by the following alternation:

- admit an additional order for the non-logical symbols in the logic;
• admit quantification over symbols of that order.

If one only admits symbols of type $o$ (propositional variables), one obtains **propositional logic**. At this stage, one also admits symbols of type $i$, although this is still degenerate since one cannot form any formulas with them (without any function or predicate symbols). One can now admit quantification over individuals, although one can still not do much with that since one cannot form any formulas.

Now, if one admits symbols of first-order type (function symbols, predicate symbols), one obtains **first-order logic**. Quantification is allowed only over individuals.

Now, if one admits quantification over symbols of first-order type, one obtains **second-order logic**.

Now, if one admits symbols of second-order type (symbols taking predicate/function symbols as arguments), one obtains **third-order logic**.
Now, if one admits quantification over symbols of second-order type, one obtains **fourth-order** logic.

Hence quantification over $n$th-order variables corresponds to $(2n)$th-order logic.

This particular terminology is due to [And02, §50] and in the end, one will never bother to discuss, say, $7$th-order logic, since higher-order logic is the **union** of all logics of finite order, and this is what we will be working with.

You may find that especially below first-order logic, there are some oddities in this hierarchy (e.g., should propositional logic be called “$-1$th”-order logic?). However, once you take higher-order logic as your point of reference and not propositional or first-order logic, which can just be viewed as special cases, you will probably not find this bothering anymore.
Consider the binary predicate \textit{subrel} which takes two unary relations as arguments. \textit{subrel}(R, S) is defined as true whenever \( R \) is a subrelation of \( S \), i.e. when \( \forall x. R(x) \rightarrow S(x) \).

Now instead of defining such a predicate and writing, say, a formula \textit{subrel}(R', S'), one could abstract from that name and write

\[
\forall X. (X(R, S) \leftrightarrow (\forall x. R(x) \rightarrow S(x))) \rightarrow X(R', S')
\]

The subformula \( X(R, S) \leftrightarrow (\forall x. R(x) \rightarrow S(x)) \) is true if and only if \( X \) is indeed the predicate \textit{subrel} and so the entire formula is true if \( R' \) is indeed a subrelation of \( S' \).
The Type signature of HOL

As before, we use the letter $\mathcal{B}$ to denote a particular set of type constructors.

Note that this set is not hard-wired into HOL, but can be specified as part of a particular HOL language. One can therefore speak of $\mathcal{B}$ as a type signature.

$\mathcal{B}$ is some fixed set “defined by the user”. In Isabelle, there is a syntax provided for this purpose.

However, some type constructors are always present.
$ind$

$ind$ ("indefinite") is a type constructor which stands for a type with infinitely many members, a concept which is central in HOL, as we will see later.
Pair Type

For any two types $\tau$ and $\sigma$, we write $\tau \times \sigma$ for the type of pairs where the first component is of type $\tau$ and the second component is of type $\sigma$. The infix syntax is in analogy to $\to$.

The pair type is not in the core of HOL, but it can be defined in it.
Variable Augmented with Type?

Strictly speaking, a variable should be augmented with a type in the term $\lambda x. e$. The type $\tau$ in $\lambda x^\tau. e$ is often omitted if it is clear from the context. Here, “clear from the context” does not only refer to a human reader, but also to the formal Isabelle syntax. It is possible to give an explicit type to a variable and also specify the class of that type (one can impose type and class constraints), but often, Isabelle can infer the type of a variable.
Generalizing \( \lambda \rightarrow \) to Polymorphism

We have seen the generalization of \( \lambda \rightarrow \) to polymorphism. Note that in order to simplify the presentation, we neglect polymorphism in the section on semantics. In that section, \( \tau \) and \( \sigma \) will be metavariables (used in the description of the formalism) ranging over types, rather than type variables of a polymorphic type system.
The Type of $\equiv$

The type of $\equiv$ can either be declared to be polymorphic (then $\alpha$ would be a type variable), or one can, conceptually, assume that there is an infinite set containing a constant $\equiv_\tau$ for each type $\tau$. 

Back to main referring slide
Intuition for the Constants

We will give the formal semantics later, but now some intuition!

*True*, *False*, *≡* and *→* have the meanings you would expect although *≡* is more general than in first-order logic since for any type *τ*, there is the *≡* symbols for terms of type *τ*. This is just like in *ℳ*.

*True* and *False* are intuitive but not strictly necessary.

The constant *ε* (also called Hilbert operator) denotes a function which takes a set and picks a member from that set. We give a more detailed intuitive explanation later.

Note that the derivation rules can be formulated without using *True* and *False*.

[Back to main referring slide]
Isabelle Syntax for $\epsilon$

The Hilbert operator is written $\text{Eps}$ in Isabelle.
Now similarly as for quantifiers $\forall, \exists$, Isabelle provides a syntax $\text{SOME } x. P$ that stands for $\text{Eps}.\lambda x. P$.
In older versions of Isabelle, $\text{SOME}$ was written '@$'.
Prod: Encoding \( X \times Y \)

According to usual mathematical practice, one would argue that if two sets \( A \) and \( B \) are well-defined, then the set \( A \times B \) of pairs (tuples) \((a, b)\) where \( a \in A \) and \( b \in B \) is also well-defined.
Inhabitation

It is crucial in the semantics that any type is inhabited, i.e., has an element. The function space $X \rightarrow Y$ is empty if $X$ is empty.

This means that $D_{\tau \rightarrow \sigma}$ would necessarily be empty if $\tau$ is empty. This in turn would lead to a very nasty behavior of $\beta$-reduction: for any types $\tau, \sigma$ and a constant $c$ of type $\sigma$, we expect $(\lambda x^\tau. c)x = c$. But this wouldn’t hold if we cannot give a semantics to $(\lambda x^\tau. c)$ since $D_{\tau \rightarrow \sigma}$ is empty.

Therefore: inhabitation.

We will also see two more specific points where inhabitation is crucial, one concerning the $\epsilon$-operator and one concerning sets.
Dependent Type

When we write $ch \in \Pi_{X \in U}.X$, i.e., $ch$ is of dependent type, then this is a statement on the semantic level. The expression $\Pi_{X \in U}.X$ is not part of the formal syntax of HOL (unlike in LF, a system we have not treated here), and its meaning is only described in plain English, by saying that $ch$ takes a set $X \in U$ as argument and returns a member of $X$. 
What Are Functions?

In any basic math course on algebra, we learn that a binary relation between $X$ and $Y$ is set of a pairs of tuples of the form $(x, y)$ where $x \in X$ and $y \in Y$. One also calls such a set a graph since one can view pairs $(x, y)$ as edges.

We also learn that a relation $R$ is called a function from $X$ to $Y$ if for each $x \in X$, there exists exactly one $y \in Y$ such that $(x, y) \in R$. Provided that $Y$ is nonempty, a function from $X$ to $Y$ always exists.

Thus the set of functions from $X$ to $Y$, denoted $X \rightarrow Y$, is a nonempty subset of the set of relations on $X$ and $Y$, i.e., $\varnothing(X \times Y)$. Since $X \rightarrow Y$ is nonempty, by Prod we have that $X \rightarrow Y \in U$. 

Back to main referring slide
Why \{1\} and \{T, F\}? 

Of course, the conditions on \( \mathcal{U} \) do not per se enforce the existence of sets containing the elements 1 or \( T \) or \( F \). Just as well, one could say that they enforce the existence of sets containing elements ☕ or ☕ or ☕. It is only because the name of a semantic element is ultimately irrelevant that we claim, without loss of generality, that there is a 1-element set \{1\} and a 2-element set \{T, F\}. We say that these sets are distinguished because they play a special role in the setup of the semantics.
**Standard and General Models**

*General* models must be distinguished from *standard* models, as well see later.

We sometimes omit the word “general” in *general model.*
Type Subscript

For $=$ and $\epsilon$, we give type subscripts in the presentation of the semantics since we assume, conceptually, that there are infinitely many copies of those constants, one for each type. We do this to avoid explicit polymorphism in this presentation.
Intuition for $\epsilon$ and $ch$

We have

$$J(\epsilon(\tau \rightarrow \text{bool}) \rightarrow \tau)(f) = \begin{cases} \text{ch}(f^{-1}(\{T\})) & \text{if } f^{-1}(\{T\}) \neq \emptyset \\ \text{ch}(D_\tau) & \text{otherwise} \end{cases}$$

$ch$ is a (semantic) function which takes a nonempty set and returns an element from that set. $f$ is a semantic function from $D_\tau$ to $D_{\text{bool}}$. However, $f$ can be interpreted as set. This is done in all formality here: we write $f^{-1}(\{T\})$. One says that $f$ is the characteristic function of the set $f^{-1}(\{T\})$.

Now the type of $\epsilon$ is $\tau \rightarrow \text{bool} \rightarrow \tau$ (for any $\tau$), so $\epsilon$ expects a function as argument, which can be interpreted as a set as just stated. This set can be empty or nonempty. In case it is nonempty, an element is picked from the set non-deterministically. If the set is empty, an element from
the type $\tau$ (which must be nonempty since each type is interpreted as nonempty set). Note the importance of inhabitation.
Type-Indexed Assignments

An assignment (previously called valuation) maps variables to elements of a domain.

A type-indexed collection of assignments is an assignment that respects the types: a variable of type $\tau$ will be assigned to a member of $D_{\tau}$ [GM93]. Note that a variable has a type by virtue of a context $\Gamma$, which is suppressed in our presentation of models.
Type Subscript

In the presentation of models, we give type subscripts for the cases $V^m_A(s_\tau \to \sigma t_\tau)$ and $V^m_A(\lambda x^\tau. t_\sigma)$ to indicate the types of $s$ and $t$ in those definitions. Note that a term has a type in a certain context $\Gamma$, which is suppressed in our presentation of models. The semantics is only defined for well-formed terms, in particular, applications and abstractions having types of the indicated forms.
\[ A[x \leftarrow e] \]

\( A[x \leftarrow e] \) denotes the assignment that is identical to \( A \) except that \( A(x) = e \).
Condition 4 Violated

In condition 4, the semantics of $\lambda x^\tau. t_\sigma$ is defined unambiguously as a certain function. But in general, there is no guarantee that this function is actually in $\mathcal{D}_{\tau \rightarrow \sigma}$, and in this case, $\mathcal{M} = \langle \{\mathcal{D}_\tau\}_\tau, \mathcal{J}\rangle$ would not be a model.
Completeness

This is a standard trick when faced with the problem that a deductive system is not complete. One can either enlarge the set of axioms, or one can weaken the models by permitting more models. If we allow more models, then fewer theorems will be valid (i.e., hold in all models), and so fewer theorems will have to be provable in the derivation system.

Here, completeness is based on general models, and not standard models. This resolves the apparent contradiction with Gödel’s incompleteness theorem: HOL with infinity contains $I$, hence the natural numbers, hence arithmetic . . . ). By Gödel’s incompleteness theorem, there cannot be a consistent derivation system that can prove all valid theorems in the natural numbers.

A readable account on this problem can be found in [And02, ch. 7].
Finite Domains

We might consider a version of HOL without infinity, i.e., one where each domain is finite (note that \( \mathcal{U} \) is still infinite, since there are infinitely many types, e.g., \( \text{bool}, \text{bool} \to \text{bool}, \text{bool} \to \text{bool} \to \text{bool}, \ldots \)).

One can see that every function in such a finite domain is representable as a \( \lambda \)-term, and so for any \( \sigma \) and \( \tau \), we must have \( \mathcal{D}_{\tau \to \sigma} = \mathcal{D}_\tau \to \mathcal{D}_\sigma \).

For details consult [And02, §54].
Syntaxes for Rules

We will mix natural deduction (with discharging assumptions), natural deduction written in sequent style, and Isabelle syntax. For a thorough account of this, consult [SH84].

Some general remarks about the correspondence: A rule

\[
\frac{\psi}{\phi}
\]

in ND notation corresponds to an Isabelle rule \( \psi \Longrightarrow \phi \).

A rule

\[
\frac{[\rho]}{
\vdots
\psi
\phi}
\]
is written as
\[
\frac{\rho, \Gamma \vdash \psi}{\Gamma \vdash \phi}
\]

in sequent style or
\[
\frac{\rho \Rightarrow \psi}{\phi}
\]

using the Isabelle meta-implication \( \Rightarrow \).

A rule
\[
\frac{\psi}{\phi(x)}
\]

with side condition that \( x \) must not occur free in any undischarged assumption on which \( \psi \) depends is written as
\[
\frac{\Gamma \vdash \psi}{\Gamma \vdash \phi(x)}
\]
in sequent style, where the side condition reads: $x$ must not occur free in $\Gamma$. Using the Isabelle meta-universal quantification, the rule is written

$$\frac{\bigwedge x. \psi}{\phi(x)}$$

We will switch between the various ways of writing the rules! This means in particular that we will use $\Longrightarrow$ and $\bigwedge$ from Isabelle’s metalogic.
Readability of Rule \textit{tof}

Rule \textit{tof} can be written as follows:

\[
(\lambda \psi. \ (\phi = (\lambda x.x = \lambda x.x) \rightarrow \psi) \rightarrow \\
(\phi = ((\lambda \eta. \eta) = \lambda x.(\lambda x.x = \lambda x.x)) \rightarrow \psi) \rightarrow \psi) = \\
(\lambda x.(\lambda x.x = \lambda x.x))
\]

Our notation for rule \textit{tof} is thus based on the following definitions:

\[
\begin{align*}
\text{True} &= (\lambda x^{\text{bool}}. x = \lambda x.x) \\
\text{False} &= \forall \phi^{\text{bool}}. \phi \\
\forall &= \lambda \phi \eta. \forall \psi.(\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi
\end{align*}
\]
Intuition for $True$

$True = (\lambda x^{bool}. x = \lambda x.x)$

The term $\lambda x^{bool}. x = \lambda x.x$ evaluates to $T$, and so it is a suitable definition for the constant $True$.

Note that we give the type for $x$ once. The right-hand side $\lambda x.x$ will thereby also be forced to be of type $bool \rightarrow bool$.

This is necessary for reasons that will become clear later.

Note that $(\lambda x^{bool}. x = \lambda x.x)$ is closed. Definitions must always be closed.
Intuition for $\forall$

$$\forall = \lambda\phi.(\phi = \lambda x. True)$$

Note the use of HOAS here. $\forall$ should be a function that expects an argument $\phi$ of type $\alpha \rightarrow bool$ (generalizing the technique we used for encoding first-order $\forall$). So $\phi$ is such that when you pass it an argument $x$ of type $\alpha$, it will return a proposition (something of type $bool$).

The expected semantics of $\forall\phi$ wrt. a model $M$ and an assignment $A$ is: $\forall^M_A(\forall\phi) = T$ iff $\forall^M_{A[x\leftarrow e]}(\phi x) = T$ for any $e$ (from the domain of $x$’s type).

Now when does $\phi x$ hold for all $x$? This is the case exactly when $\phi x$ evaluates to $T$ for all $x$, which is the same (applying some HOL rules) as saying that $\phi$ is the function $\lambda x. True$. 

Smaus: CSMR; WS05/06
Here $\alpha$ could be arbitrarily instantiated to some type.
**Intuition for ∨**

\[ ∨ = \lambda \phi \eta. \forall \psi. (\phi \to \psi) \to (\eta \to \psi) \to \psi \]

First, observe the similarity of this definition with the \( \lor\)-E rule of propositional logic.

Secondly, just go through the cases:

- **If \( \phi \) is true, then:**
  - If \( \psi \) is false, then \( \phi \to \psi \) is false and so \( (\phi \to \psi) \to (\eta \to \psi) \to \psi \) is true;
  - If \( \psi \) is true, then \( (\eta \to \psi) \to \psi \) is true and hence \( (\phi \to \psi) \to (\eta \to \psi) \to \psi \) is true.

  Thus for all \( \psi \), we have that \( (\phi \to \psi) \to (\eta \to \psi) \to \psi \) is true.

- **Otherwise, if \( \eta \) is true, then:**
○ If $\psi$ is false, then $\eta \rightarrow \psi$ is false and so $(\eta \rightarrow \psi) \rightarrow \psi$ is true and so $(\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi$ is true.

○ If $\psi$ is true, then $(\eta \rightarrow \psi) \rightarrow \psi$ is true and hence $(\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi$ is true.

Thus for all $\psi$, we have that $(\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi$ is true.

• Otherwise (if both $\phi$ and $\eta$ are false), then for all $\psi$, both $\phi \rightarrow \psi$ and $\eta \rightarrow \psi$ are true, and so there exists a $\psi$, say $\psi \equiv False$, such that $(\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi$ is false.

Thus it is not the case that for all $\psi$, $(\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi$ is true.

So the definition of $\lor$ behaves exactly as it should.
Intuition for $\land$

\[ \land = \lambda \phi \eta. \forall \psi. (\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi \]

Similarly as for $\lor$, we can go through the cases:

- If $\eta$ is false, then there exists a $\psi$, namely $\psi \equiv False$, such that $\eta \rightarrow \psi$ is true, hence $\phi \rightarrow \eta \rightarrow \psi$ is true, hence $(\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi$ is false. Thus it is not the case that for all $\psi$, $(\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi$ is true.

- Otherwise, if $\phi$ is false, then $\phi \rightarrow \eta \rightarrow \psi$ is true, and there exists a $\psi$, namely $\psi \equiv False$, such that $(\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi$ is false. Thus it is not the case that for all $\psi$, $(\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi$ is true.

- Otherwise (if $\phi$ and $\eta$ are true), then:
  - If $\psi$ is false, then $\eta \rightarrow \psi$ is false, hence $\phi \rightarrow \eta \rightarrow \psi$ is false, hence $(\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi$ is true.
If $\psi$ is true, then $(\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi$ is true.

Thus for all $\psi$, we have that $(\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi$ is true.

So the definition of $\land$ behaves exactly as it should.
Intuition for $\neg$

$\neg = \lambda \phi. (\phi \rightarrow False)$

We know that one already from propositional logic.
Intuition for $\exists$

$$\exists = (\lambda \phi. \phi(\epsilon x. \phi x))$$

Using the abstract syntax for $\epsilon$, one could also write

$$\exists = (\lambda \phi. \phi(\epsilon \phi))$$

Recall first the definition of $\forall$ to understand the type of $\exists$.

The expected semantics of $\exists \phi$ wrt. a model $\mathcal{M}$ and an assignment $A$ is:

$$\mathcal{V}_{A}^{\mathcal{M}}(\forall \phi) = T \text{ iff } \mathcal{V}_{A[x\leftarrow e]}^{\mathcal{M}}(\phi x) = T \text{ for some } e \text{ (from the domain of } x\text{'s type).}$$

The semantics of $\epsilon$ is such that $\phi(\epsilon \phi)$ is true, if and only if a term $t$ exists for which $\phi(t)$ is true.

So this is exactly the expected semantics of $\exists \phi$. 

Smaus: CSMR; WS05/06
Intuition for $\text{If}$

$$\text{If} = \lambda\phi xy.\varepsilon z. (\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y)$$

The constant $\text{If}$ stands for the if-then-else construct. Note first that $\varepsilon z. (\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y)$ is $\eta$-equivalent to $\varepsilon z. (\lambda z. (\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y)) z$, which is written $\varepsilon (\lambda z. (\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y))$ in the “real” HOL syntax, which uses the concept of HOAS.

The expression $\varepsilon (\lambda z. (\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y))$ picks a term from the set of terms $z$ such that $(\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y)$ holds. But this means that $z = x$ if $\phi = \text{True}$, or $z = y$ if $\phi = \text{False}$.

Since $\text{If}$ should be a function which takes $\phi$, $x$ and $y$ as arguments, we
must abstract over those variables, giving
\[ \lambda \phi xy.ez. (\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y). \]
Definitions by $=$ or $\equiv$?

It is a design choice if we want to add these definitions at the level of the object logic (HOL) or at the level of the $\mathcal{M}$. In the first case, we would use $=$ and have axioms such as

$$\text{True} = (\lambda x^{\text{bool}}. x = \lambda x.x)$$

In the second case, we would have meta-axioms

$$\text{True} \equiv (\lambda x^{\text{bool}}. x = \lambda x.x)$$

This would mean that we would regard $\text{True}$ merely as syntactic sugar. The second way corresponds to what is done in Isabelle, see HOL.thy. It is technically more convenient since rewriting is based on meta-level equalities.
Logically, it is not a big difference which way one chooses. We will have an exercise on this.
Intuition for $False$

$False = \forall \phi. \phi$

The essence of $False$ is that anything can be derived from it. But this is exactly what $\forall \phi. \phi$ says.
Concrete Syntax for $\forall$

The HOL constant $\forall$ is defined first in the style of HOAS. But we also use concrete syntax, so we write $\forall x.\psi$ instead of $\forall(\lambda x.\psi)$. In the concrete syntax, one may also annotate the variable with a type.
Type Annotation for Variables

In HOL, the quantifiers, which one expects to be variable binders, are realized using $\lambda$ in the style of HOAS.

We have said binding occurrences of variables in a $\lambda$-term should, strictly speaking, be annotated with a type, but that this type can often be omitted.

Now whenever we use concrete quantifier syntax for convenience, so we write $\forall x.\psi$ instead of $\forall (\lambda x.\psi)$ (and likewise for $\exists$), we may annotate the variable in the obvious way: $\forall x^\tau.\psi$ is concrete syntax for $\forall(\lambda x^\tau.\psi)$.

Sometimes we will annotate variables for clarity, sometimes we trust that the type is clear from the context.
Side Condition of $\text{ext}$

The rule

\[
\Gamma \vdash \phi x = \eta x \\
\Gamma \vdash \phi = \eta
\]

$\text{ext}$

has the side condition that $x \notin FV(\Gamma)$.

Phrased like

\[
\phi x = \eta x \\
\phi = \eta
\]

$\text{ext}$

the rule has the side condition that $x$ must not occur freely in the derivation of $\phi x = \eta x$. 

Back to main referring slide
Why no \textit{selectE}? 

You may wonder why there is no rule for eliminating $\epsilon$. We will later see a rule derivation where an $\epsilon$ is effectively eliminated, and we will also see that this is done without requiring a rule explicitly for this purpose. Apart from that, the $\epsilon$-operator is used in HOL as basis for defining $\exists$ and the if-then-else constructs. Once we have derived the appropriate rules for those, we will not explicitly encounter $\epsilon$ anymore.
Concrete Syntax for $\epsilon$, $\forall$, $\exists$

For readability, we will frequently use a syntax that one is more used to than higher-order abstract syntax:

$ex.\phi x$ stands for $\epsilon(\phi)$.

$\forall x.\phi(x)$ stands for $\forall(\phi)$, and likewise for $\exists$.

We have done the same previously for $\mathcal{M}$. 

Infinity in HOL

The infinity axiom

\[ \exists f^{(ind \rightarrow ind)} . \text{injective } f \land \neg \text{surjective } f \]

says that there is a function from \( I \) to \( I \) (the postulated infinite set in \( U \)) which is injective (any two different elements \( e, e' \) of \( I \) have different images under \( f \)) but not surjective (there exists an element of \( I \) which is not the image of any element).

Such a function can only exist if \( I \) is infinite, and in fact the axiom expresses the very essence of infinity, as we will see later.

Think of the natural numbers and the successor function as an example: for any two different natural numbers, the successors are different, and the number 0 is not the successor of any number.
Injective – Surjective

A function is **injective** (also called **one-to-one**) if any two different elements $e, e'$ have different images under $f$.

A function is **surjective** (also called **onto**) if for any $e$ (in the function's range type, i.e. the type $\tau$ where $\sigma \rightarrow \tau$ is the type of the function), there exists an $e'$ whose image under the function is $e$.

Formally, the definitions are

\[
\text{injective} = \lambda f. \forall xy. f x = f y \rightarrow x = y \\
\text{surjective} = \lambda f. \forall y. \exists x. f x = y
\]
Just One Lambda!

Note that the $\lambda$-binder of the object logic HOL is not distinguished from the $\lambda$-binder of Isabelle’s metalogic $\mathcal{M}$. One could introduce an object level constant $\textit{lambda}$, but one quickly sees that it would be an unnecessary overhead.
Optional Type Superscript

As we have learned previously, \( \lambda \)-abstracted variables should have a type superscript, although this superscript is often omitted since the type can be inferred.

Since \( \forall x.p(x) \land q(x) \) is the “concrete syntax” version of \( \forall (\lambda x.(\land p(x) q(x))) \), it makes sense that we allow an optional superscript also for \( \forall \)-bound (and likewise for \( \exists \)-bound) variables.

In Isabelle the optional type annotation is written using :: instead of a superscript.
Gather Constants with Same Type

For convenience (and to save space, we write \( \ldots a : \tau, \ b : \tau \ \ldots \) as \( \ldots a, \ b : \tau \ \ldots \) in a signature. This is of course syntactic sugar.
Notation Using _

We use a notation with _ to indicate the arity and fixity of constants, as this has been done for type constructors before.

The whole matter of arity of fixity is one of notational convenience. For example, as the type of $\land$ indicates, we should write $(\land \phi) \psi$ (Curried notation), but we write $\phi \land \psi$ since it is more what we are used to.
HOL.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/HOL.thy

Moreover, in

/usr/local/share/provers/Isabelle/src/HOL/HOL_lemmas.ML

you find all the derivations of the rules presented in this lecture. However, the presentation of this lecture is still partly based on HOL.thy of Isabelle 98. E.g., the definition of Ex_def is now different from the one presented here.

Note also that here in the slides, we use a style of displaying Isabelle files which uses some symbols beyond the usual ASCII set.
HOL: Deriving Rules
Outline

Last lecture: Introduction to HOL
- Basic syntax and semantics
- Basic eight (or nine) rules
- Definitions of True, False, ∧, ∨, ∀ . . .

Today:
- Deriving rules for the defined constants
- Outlook on the rest of this course
Reminder: Different Syntaxes

Mathematical vs. Isabelle, e.g.

\neg \phi 
\lambda x^{bool}.P

HOAS vs. concrete, e.g.

\forall (\lambda x^\tau. (\wedge p(x) q(x)))
\epsilon (P)

\forall \tau. p(x) \land q(x)
\epsilon x. P(x)

We use all those forms as convenient. For displaying Isabelle files, we will sometimes use a style where some ASCII words (e.g. \%) are replaced with mathematical symbols (e.g. \lambda).
Reminder: Definitions

\[ \text{True} = (\lambda x^{bool}. x = \lambda x.x) \]
\[ \forall \phi^{\alpha \rightarrow bool}. (\phi = \lambda x. \text{True}) \]
\[ \text{False} = \forall \phi^{bool}. \phi \]
\[ \bigvee \phi \eta. \forall \psi. (\phi \rightarrow \psi) \rightarrow (\eta \rightarrow \psi) \rightarrow \psi \]
\[ \bigwedge \phi \eta. \forall \psi. (\phi \rightarrow \eta \rightarrow \psi) \rightarrow \psi \]
\[ \neg \phi = \lambda \phi. (\phi \rightarrow \text{False}) \]
\[ \exists \phi x. (\exists x. \phi x) \]
\[ \text{If} = \lambda \phi x y. \epsilon z. (\phi = \text{True} \rightarrow z = x) \land (\phi = \text{False} \rightarrow z = y) \]
Derived Rules

The definitions can be understood either semantically (checking if each definition captures the usual meaning of that constant) or by their properties (= derived rules).

We now look at the constants in turn and derive rules for them. We will present derivations in natural deduction style. We usually proceed as follows: first show a rule involving a constant, then replace the constant with its definition (if applicable), then show the derivation.
Equality

- Rule \( \text{sym} \)

\[
\frac{s = t}{t = s} \quad \text{sym}
\]
Equality

- Rule \textit{sym} and \textbf{ND derivation}

\[
\begin{array}{c}
  s = t \\
  \hline \\
  s = s \\
  \hline \\
  t = s
\end{array}
\]

- Isabelle rule $s=t \implies t=s$. Proof script:

Goal "s=t ==> t=s";
by (etac subst 1); (* P is \(\%x. x=s\) *)
by (rtac refl 1); (* s=s *)
qed "sym";

\textbf{Smaus: CSMR; WS05/06}
Equality: Transitivity and Congruences

- Rule \( \text{trans} \)

\[
\frac{s = t \quad r = s}{r = t} \quad \text{trans}
\]
Equality: Transitivity and Congruences

- Rule *trans* and ND derivation

\[
\frac{s = t \quad r = s}{r = t} \quad \text{subst}
\]

Isabelle rule \([ | r=s; s=t | ] \implies r=t\)
Equality: Transitivity and Congruences

- Rule *trans* and ND derivation

\[
\frac{s = t \quad r = s}{r = t} \quad \text{subst}
\]

Isabelle rule \[\begin{array}{|l}
| r=s; s=t | \end{array} \implies r=t\]

- Congruences (only Isabelle forms):
  
  \((f::'a=>'b) = g \implies f(x) = g(x)\) (\text{fun\_cong})
  
  \(x = y \implies f(x) = f(y)\) (\text{arg\_cong})

Isabelle proofs using *subst* and *refl*. 
Equality of Booleans (iffI)

Rule \textit{iffI}

\[
\begin{align*}
[P] & \quad Q \\
\vdots & \quad \ddots \\
Q & \quad [Q] \\
\end{align*}
\]

\[P = Q\]
Equality of Booleans ($\text{iff}$)

Rule $\text{iff}$ and ND derivation

\[
\frac{(P \to Q) \to (Q \to P) \to (P = Q)}{(Q \to P) \to (P = Q)} \quad \text{iff}
\]

\[
\begin{align*}
\frac{[P]}{\vdots} & \quad Q \\
\frac{[Q]}{\vdots} & \quad P
\end{align*}
\]

\[
\frac{P \to Q}{P \to Q} \quad \text{impl}
\]

\[
\frac{Q \to P}{Q \to P} \quad \text{impl}
\]

\[
\frac{P \to Q}{P = Q} \quad \text{mp}
\]

\[
\frac{Q \to P}{P = Q} \quad \text{mp}
\]

Isabelle rule $[\mid P \to Q; \ Q \to P \mid] \Longrightarrow P = Q$. 

Smaus: CSMR; WS05/06
Equality of Booleans (iffD2)

Rule iffD2

\[ P = Q \]

\[ \frac{Q}{P} \text{ iffD2} \]
Equality of Booleans (iffD2)

Rule iffD2 and ND derivation

\[ \frac{P = Q}{Q = P} \quad \text{sym} \]
\[ \frac{Q = P}{P} \quad \text{subst} \]

Isabelle rule \[\{ | P=Q; Q |\} \implies P.\]
True

\[ \text{True} = ((\lambda x^{\text{bool}}. x) = (\lambda x. x)) \]

• Rule \text{Truel}

\[
\begin{array}{c}
\text{True} \\
\hline
\text{Truel}
\end{array}
\]

Smaus: CSMR; WS05/06
True

True = ((\lambda x^{bool}. x) = (\lambda x . x))

• Rule Truel

\[
(\lambda x . x) = (\lambda x . x) \quad \text{Truel}
\]
True

\[ True = ((\lambda x^{bool}. x) = (\lambda x.x)) \]

- Rule Truel and ND derivation

\[
\frac{(\lambda x.x) = (\lambda x.x)}{refl}
\]
True

\[
\text{True} = ((\lambda x^{\text{bool}}. x) = (\lambda x.x))
\]

- Rule TrueI and ND derivation

\[
(\lambda x.x) = (\lambda x.x) \quad \text{refl}
\]

- Rule eqTrueE

\[
P = \text{True}
\]

\[
P \quad \text{eqTrueE}
\]
\[ True = ((\lambda x^{bool}.x) = (\lambda x.x)) \]

- Rule \textit{TrueI} and ND derivation
  \[
  \frac{\lambda x.x = \lambda x.x}{(\lambda x.x) = (\lambda x.x)} \text{ refl}
  \]

- Rule \textit{eqTrueE} and ND derivation
  \[
  \frac{P = \text{True} \quad \text{TrueI}}{P} \quad \frac{\text{True}}{P} \text{ iffD2}
  \]

Isabelle rule \( P = \text{True} \implies P \).
True (Cont.)

- Rule \( eqTrueI \)

\[
P = \text{True} \quad \text{eqTrueI}
\]
True (Cont.)

- Rule \textit{eqTrue} and ND derivation

\[
\begin{array}{c}
\text{True} \\
\text{True} \\
\end{array}
\begin{array}{c}
\text{Truel} \\
\hline
P \\
\end{array}
\begin{array}{c}
P = \text{True} \\
\hline
\text{iffI}
\end{array}
\]

Note that 0 assumptions were discharged.
Isabelle rule \( P \implies P=\text{True} \).
Universal Quantification

\[ \forall P = (P = (\lambda x. True)) \]

- Rule allI

\[ P(x) \]

\[ \begin{array}{c}
\forall P \\
\hline
P(x)
\end{array} \]

\[ \forall P \quad \text{allI} \]
Universal Quantification

\( \forall P = (P = (\lambda x. True)) \)

- Rule \textit{allI}

\[
P(x) \quad \text{allI}
\]

\[
P = \lambda x. True \quad \text{allI}
\]
Universal Quantification

∀P = (P = (λx. True))

- Rule alll and ND derivation

\[
\begin{align*}
P(x) & \quad \text{eqTrueI} \\
P(x) = \text{True} & \quad \text{ext} \\
P = \lambda x. \text{True} & \quad \text{ext}
\end{align*}
\]

Inherits the side condition of ext: \(x\) must not occur freely in the derivation of \(P(x)\).

Isabelle rule \((!!x. P(x)) \Rightarrow !x. P(x)\).
Example Illustrating Side Condition

\[
\frac{[r(x)]^1}{r(x) \rightarrow r(x)} \rightarrow [^1]
\]

\[
\frac{r(x) \rightarrow r(x)}{\forall x. r(x) \rightarrow r(x)} \text{ alll}
\]

Why is this correct?
Example Illustrating Side Condition

\[
\frac{[r(x)]^1}{r(x) \rightarrow r(x)} \rightarrow I^1
\]
\[
\frac{r(x) \rightarrow r(x)}{\forall x. r(x) \rightarrow r(x)} \text{ allI}
\]

Why is this correct? Let’s do it without using allI explicitly:

\[
\frac{[r(x)]^2}{r(x) \rightarrow r(x)} \rightarrow I^2
\]
\[
\frac{r(x) \rightarrow r(x)}{(r(x) \rightarrow r(x)) = True} \text{ eqTrueI}
\]
\[
\frac{\lambda x. (r(x) \rightarrow r(x)) = \lambda x. True}{\text{ext}}
\]

The side condition is respected.
Universal Quantification (Cont.)

• Rule *spec* (recall $\forall P$ means $\forall x. Px$)

\[
\forall P \\
\frac{\phantom{\forall P}}{P(t)} \quad spec
\]
Universal Quantification (Cont.)

- Rule $spec$ (recall $\forall P$ means $\forall x. Px$)

\[
P = \lambda x. True
\]

\[
P(t) \quad \text{spec}
\]
Universal Quantification (Cont.)

• Rule \( \text{spec} \) (recall \( \forall P \) means \( \forall x. P \, x \)) and ND derivation

\[
\begin{align*}
P &= \lambda x. \text{True} \\
P(t) &= \text{True} \\
P(t) &= \text{True}
\end{align*}
\]

Isabelle rule \( \exists x::'a. \ P(x) \Rightarrow P(x) \).

Note: Need universal quantification to reason about \( \text{False} \)
(since \( \text{False} = (\forall P. P) \)).
False

\[ False = (\forall P. P) \quad (= \forall (\lambda P. P)) \]

• Falsel:
False

False = (∀P.P)  (= ∀(λP.P))

- Falsel: No rule!
- Rule FalseE

\[
\frac{False}{P} \text{FalseE}
\]
False

\[ False = (\forall P. P) \quad (= \forall (\lambda P. P)) \]

- Falsel: No rule!
- Rule FalseE

\[ \frac{\forall P. P}{P} \quad \text{FalseE} \]
False

\[ False = (\forall P. P) \quad (= \forall (\lambda P. P)) \]

- Falsel: No rule!
- Rule FalseE and ND derivation

\[
\begin{align*}
\forall P. P & \\
\hline
P & \text{spec}
\end{align*}
\]

Isabelle rule False \(\implies\) P.
False (Cont.)

- Rule \( \text{False\_neq\_True} \)

\[ \text{False} = \text{True} \]

\[ \frac{}{P} \text{False\_neq\_True} \]
False (Cont.)

• Rule \texttt{False_neq_True} and ND derivation

\[
\begin{align*}
\text{False} &= \text{True} \\
\text{False} &= \text{False} \\
\text{P} &= \text{FalseE} \\
\end{align*}
\]

Isabelle rule \texttt{False=True ==> P}.

• Similar:

\[
\begin{align*}
\text{True} &= \text{False} \\
\text{P} &= \text{True_neq_False} \\
\end{align*}
\]
Negation

\[ \neg P = P \rightarrow False \]

- Rule \textit{notl}

\[
\begin{array}{c}
\vdots \\
False \\
\hline \\
\neg P
\end{array}
\]

\textit{notl}
Negation

\( \neg P = P \rightarrow False \)

- Rule \textit{notI}

\[
\begin{array}{c}
\text{[P]}
\\
\vdots
\\
False
\\
\hline
P \rightarrow False
\end{array}
\]

\textit{notI}
Negation

\[ \neg P = P \rightarrow False \]

- Rule notI and ND derivation

\[
\begin{array}{c}
[P] \\
\vdots \\
False \\
\hline \\
P \rightarrow False
\end{array}
\]

\[ impl \]

Isabelle rule \((P \implies False) \implies \neg P.\)
Negation (2)

- Rule $notE$

\[
\begin{array}{c}
\neg P \\
\hline
P
\end{array}
\]

\[
\begin{array}{c}
R \\
\hline
notE
\end{array}
\]
Negation (2)

- Rule \( \text{notE} \)

\[
P \rightarrow \text{False} \quad P
\]

\[
\frac{}{R \quad \text{notE}}
\]
Negation (2)

- Rule notE and ND derivation

\[
egin{align*}
P \rightarrow False & \quad P \quad \text{mp} \\
& \quad False \\
& \quad FalseE \\
& \quad R \\
\end{align*}
\]

Isabelle rule \[ [\lnot P; P] ] \implies R. \]
Negation (3)

- Rule $True_{\neg}False$

\[ \neg(\text{True} = \text{False}) \quad True_{\neg}False \]
Negation (3)

- Rule *True_Not_False*

\[
(\text{True} = \text{False}) \rightarrow \text{False} \quad \text{True_Not_False}
\]
Negation (3)

- Rule True_Not_False and ND derivation

\[
\frac{[\text{True} = \text{False}]^1}{\text{False}} \quad \text{True_neq_False}
\]

\[
\frac{\text{False}}{(\text{True} = \text{False}) \rightarrow \text{False}} \quad \text{not}^1
\]

Isabelle rule True \(\sim=\) False.
Existential Quantification

\[ \exists P = P(\epsilon x. P(x)) \]

- Rule \textit{existsI}

\[
\begin{array}{c}
P(x) \\
\hline
\exists P
\end{array} \quad \textit{existsI}
\]
Existential Quantification

$$\exists P = P(\epsilon x. P(x))$$

• Rule \textit{existsI}

$$\frac{P(x)}{P(\epsilon x. P(x))} \text{ existsI}$$
Existential Quantification

\[ \exists P = P(\epsilon x.P(x)) \]

- Rule \textit{existsI} and ND derivation

\[ \begin{array}{c}
P(x) \\
\hline
P(\epsilon x.P(x)) \end{array} \]

\textit{selectI}

Isabelle rule \( P(x) \Rightarrow ?x::'a.P(x). \)
Existential Quantification (Cont.)

- Rule \( \text{existsE} \)

\[
\exists P \quad \frac{[P(x)]}{Q} \quad \text{existsE}
\]

Inherits side condition from \( \text{allI} \) (just like in \( \text{FOL} \)).

Isabelle rule \([ | \ ?x.P(x); \ !!x.P(x) ==> Q | ] \) \( \Longrightarrow Q \).
Existential Quantification (Cont.)

- Rule \textit{existsE}

\[
\begin{align*}
\exists x. P(x) & \\
\Rightarrow & \\
Q
\end{align*}
\]

\[
\frac{P(\epsilon x. P(x))}{Q} \quad \text{existsE}
\]

Inherits side condition from \textit{allI} (just like in FOL).

Isabelle rule \[ | \ ?x. P(x); \ !!x. P(x) \Rightarrow Q | ] \Rightarrow Q. \]
Existential Quantification (Cont.)

- Rule \textit{existsE} and \textbf{ND} derivation

\[
\begin{array}{c}
P(x) \\
\vdots \\
Q \\
\hline
\end{array}
\]

\[
\frac{P(x) \rightarrow Q}{\forall x. (P(x) \rightarrow Q)}
\]

\[
\frac{P(\epsilon x. P(x))}{Q}
\]

Inherits side condition from \textit{allI} (just like in \textbf{FOL}).

\textit{Isabelle} rule \([ | \ ?x. P(x) ; \ ! ! x. P(x) \Longrightarrow Q \ | ] \Longrightarrow Q \).
Conjunction

\[ P \land Q = \forall R. (P \rightarrow Q \rightarrow R) \rightarrow R \]

- Rule \textit{conjI}

\[ \begin{array}{c}
\text{P} \\
\text{Q} \\
\hline
\text{P} \land Q
\end{array} \quad \text{\textit{conjI}} \]
Conjunction

\[ P \land Q = \forall R. (P \rightarrow Q \rightarrow R) \rightarrow R \]

- Rule *conjI*
Conjunction

\[ P \land Q = \forall R. (P \rightarrow Q \rightarrow R) \rightarrow R \]

- Rule *conjI* and ND derivation

\[
\frac{\frac{[P \rightarrow Q \rightarrow R]^1 \quad P}{Q \rightarrow R \quad P \quad mp}}{Q \quad mp \quad mp \quad \text{impl}^1} \quad \frac{(P \rightarrow Q \rightarrow R) \rightarrow R \quad \text{impl}^1}{\forall R. (P \rightarrow Q \rightarrow R) \rightarrow R \quad \text{allI}}
\]

Isabelle rule [ | P ; Q | ] ==> P & Q.
Conjunction (Cont.)

- Rule $\text{conjEL}$

\[
P \land Q \\
\hline
\]

$P \quad \text{conjEL} \quad P$
Conjunction (Cont.)

• Rule $\text{conjEL}$

$$\forall R. (P \rightarrow Q \rightarrow R) \rightarrow R$$

\[ \text{conjEL} \]

$P$
Conjunction (Cont.)

- Rule *conjEL* and ND derivation

\[ \forall R. (P \to Q \to R) \to R \]

\[ (P \to Q \to P) \to P \]

\[ P \]

\[ \frac{[P]^1}{impl^1} \]

\[ Q \to P \]

\[ P \to Q \to P \]

\[ P \]

Isabelle rule \( P \land Q \rightarrow P \).
Conjunction (Cont.)

- $P \land Q \Rightarrow Q$ (conjER)
- $[P \land Q; [P; Q] \Rightarrow R] \Rightarrow R$ (conjE) (rule analogous to disjE)
Disjunction

\[
P \lor Q = \forall R. (P \rightarrow R) \rightarrow (Q \rightarrow R) \rightarrow R
\]

- Rule \textit{disjIL}
Disjunction

\[ P \lor Q = \forall R. (P \rightarrow R) \rightarrow (Q \rightarrow R) \rightarrow R \]

- Rule disjIL

\[ \forall R. (P \rightarrow R) \rightarrow (Q \rightarrow R) \rightarrow R \]

\[ \frac{\phantom{\forall R. (P \rightarrow R) \rightarrow (Q \rightarrow R) \rightarrow R}}{\forall R. (P \rightarrow R) \rightarrow (Q \rightarrow R) \rightarrow R}^{\text{disjIL}} \]
Disjunction

\[ P \lor Q = \forall R. (P \to R) \to (Q \to R) \to R \]

- Rule \textit{disjIL} and ND derivation

\[
\begin{align*}
[P \to R]^{1} & \quad P & \text{mp} \\
& \quad R & \text{impl} \\
(Q \to R) & \to R & \text{impl}^{1} \\
(P \to R) & \to (Q \to R) & \to R & \text{allI} \\
\forall R. (P \to R) & \to (Q \to R) & \to R & \text{allI} \\
\end{align*}
\]

Isabelle rule \( P \implies P \mid Q \).
Disjunction (Cont.)

- $Q \implies P \lor Q$ (disjIR) similar
- Rule disjE

\[
P \lor Q
\]

\[
\begin{array}{c}
P \\
\vdots \\
R \\
\end{array}
\]

\[
\begin{array}{c}
Q \\
\vdots \\
R \\
\end{array}
\]

\[
\frac{\text{(disjE)} \quad R}{R}
\]
Disjunction (Cont.)

- $Q \implies P \lor Q$ (*disjIR*) similar
- Rule *disjE*

\[
\forall R. (P \rightarrow R) \rightarrow (Q \rightarrow R) \rightarrow R
\]

\[
\begin{array}{c}
[\ P \ ] \\
\vdots \\
R \\
\hline \\
[\ Q \ ] \\
\vdots \\
R
\end{array}
\]

$\ 
\hline 
\]
Disjunction (Cont.)

- $Q \rightarrow P \lor Q$ (disjIR) similar
- Rule disjE and ND derivation

\[
\begin{align*}
\forall R. (P \rightarrow R) & \rightarrow (Q \rightarrow R) \rightarrow R \\
(P \rightarrow R) & \rightarrow (Q \rightarrow R) \rightarrow R \\
(Q \rightarrow R) & \rightarrow R \\
\Rightarrow & R
\end{align*}
\]

Isabelle rule $[ | P | Q; P \Rightarrow R; Q \Rightarrow R | ] \Rightarrow R$. 

Smaus: CSMR; WS05/06
Disjunction (Cont.)

- $Q \to P \lor Q$ (disjIR) similar
- Rule $\text{disjE}$ and ND derivation

\[
\begin{align*}
\forall R. (P \to R) & \to (Q \to R) \to R & \text{spec} \\
(P \to R) & \to (Q \to R) \to R & \text{impl mp} \\
(Q \to R) & \to R & \\
R & & \\
\end{align*}
\]

Isabelle rule $[\ prer; P \to R; Q \to R ] \to R$.

- $P \lor \neg P$ (excluded middle). Follows using $\text{ttof}$. 
Miscellaneous Definitions

See HOL.thy!

Typical example (if-then-else):

\[
If = \lambda \phi^{bool} xy. \varepsilon z. (\phi = \text{True} \rightarrow z = x) \\
\quad \land (\phi = \text{False} \rightarrow z = y)
\]

The way rules are derived should now be clear. E.g.,

\[
\begin{align*}
P = \text{True} & \quad \Rightarrow (If \ P \ x \ y) = x \\
P = \text{False} & \quad \Rightarrow (If \ P \ x \ y) = y
\end{align*}
\]
Summary on Deriving Rules

HOL is very powerful in terms of what we can represent/derive:

- All well-known inference rules can be derived.
- Other “logical” syntax (e.g. if-then-else) can be defined.
- Rich theories can be obtained by a method we see next lecture.
Mathematics and Software Engineering in HOL

In coming weeks, we will see how Isabelle/HOL can be used as foundation for mathematics and software engineering.

Outline:

- The central method for making HOL scale up: conservative extensions (< 1 week)
- How the different parts of mathematics are encoded in the Isabelle/HOL library (several weeks)
- How software systems are embedded in Isabelle/HOL (several weeks)
Outlook on Mathematics

After some historical background, we will look at how central parts of mathematics are encoded as Isabelle/HOL theories:

- Orders
- Sets
- Functions
- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes
Outlook on Software Engineering

Some weeks from now, we will look at case studies of how HOL can be applied in software engineering, i.e. how software systems can be embedded in Isabelle/HOL:

- Foundations, functional languages and denotational semantics
- Imperative languages, Hoare logic
- Z and data-refinement, CSP and process-refinement
- Object-oriented languages (Java-Light . . . )

Of the last three items, we want to treat only one in depth, depending on the audience’s preferences.
Conservative Extensions: Motivation

But first, conservative extensions.

Stage of our course before studying HOL:
- fairly small theories,
- “intuitive” models, (e.g. naïve set theory),
- but inconsistent (due to foundational problems).

How can we use HOL to
- reason about a reasonably large part of mathematics and software engineering;
- prevent inconsistencies?
What Is Needed for Scaling up?

Several well-known structuring mechanisms are known.

Modularization: Isabelle supports (class) polymorphism and theories.
What Is Needed for Scaling up?

Several well-known structuring mechanisms are known.

**Modularization:** Isabelle supports (class) polymorphism and theories.

**Reuse:** Isabelle supports libraries and retrieval utilities.
What Is Needed for Scaling up?

Several well-known structuring mechanisms are known.

**Modularization**: Isabelle supports (class) polymorphism and theories.

**Reuse**: Isabelle supports libraries and retrieval utilities.

**Safe**, well-understood integration mechanisms: Isabelle supports conservative theory extensions.
What Is Needed for Scaling up?

Several well-known structuring mechanisms are known.

**Modularization**: Isabelle supports (class) polymorphism and theories.

**Reuse**: Isabelle supports libraries and retrieval utilities.

**Safe**, well-understood integration mechanisms: Isabelle supports conservative theory extensions.

Topic of next lecture.
More Detailed Explanations
Natural Deduction Derivation

We present most of those proofs by giving a derivation tree for it, but sometimes, we also give an Isabelle proof script. Note also the mix of syntaxes.
Z, CSP

Z and CSP are specification languages. CSP stands for communicating sequential processes.
Conservative Theory Extensions
In the previous lecture, we have derived all well-known inference rules. There is now the need to scale up. Today we look at conservative theory extensions, an important method for this purpose.
Outline

In the previous lecture, we have derived all well-known inference rules. There is now the need to scale up. Today we look at conservative theory extensions, an important method for this purpose.

In the weeks to come, we will look at how mathematics is encoded in the Isabelle/HOL library.
Conservative Theory Extensions: Basics

Some definitions [GM93, Hué]

**Definition 1 (theory):**
A (syntactic) theory $T$ is a triple $(\mathcal{B}, \Sigma, A)$, where $\mathcal{B}$ is a type signature, $\Sigma$ a signature and $A$ a set of axioms.

**Definition 2 (theory extension):**
A theory $T' = (\mathcal{B}', \Sigma', A')$ is an extension of a theory $T = (\mathcal{B}, \Sigma, A)$ iff $\mathcal{B} \subseteq \mathcal{B}'$ and $\Sigma \subseteq \Sigma'$ and $A \subseteq A'$. 
Definitions (Cont.)

Definition 3 (conservative extension):
A theory extension $T' = (B', \Sigma', A')$ of a theory $T = (B, \Sigma, A)$ is conservative iff for the set of derivable formulas $Th$ we have

$$Th(T) = Th(T') \mid_\Sigma,$$

where $\mid_\Sigma$ filters away all formulas not belonging to $\Sigma$.

Counterexample:

$$\forall f^{\alpha \rightarrow \alpha}. \ Y f = f(Y f)$$
Consistency Preserved

Corollary 1 (consistency):
If $T'$ is a conservative extension of $T$, then

$$False \notin \text{Th}(T) \Rightarrow False \notin \text{Th}(T').$$
Syntactic Schemata for Conservative Extensions

- Constant definition
- Type definition
- Constant specification
- Type specification

Will look at first two schemata now.
For the other two see [GM93].
Constant Definition

Definition 4 (constant definition):
A theory extension $T' = (B', \Sigma', A')$ of a theory $T = (B, \Sigma, A)$ is a constant definition, iff

- $B' = B$ and $\Sigma' = \Sigma \cup \{c : \tau\}$, where $c \notin \text{dom}(\Sigma)$;
- $A' = A \cup \{c = E\}$;
- $E$ does not contain $c$ and is closed;
- no subterm of $E$ has a type containing a type variable that is not contained in the type of $c$. 
Constant Definitions Are Conservative

Lemma 1 (constant definitions):
Constant definitions are conservative.

Proof Sketch:
- \( \text{Th}(T) \subseteq \text{Th}(T') |_{\Sigma} \) : trivial.
- \( \text{Th}(T) \supseteq \text{Th}(T') |_{\Sigma} \) : let \( \pi' \) be a proof for \( \phi \in \text{Th}(T') |_{\Sigma} \). We unfold any subterm in \( \pi' \) that contains \( c \) via \( c = E \) into \( \pi \). Then \( \pi \) must be a proof in \( T \), implying \( \phi \in \text{Th}(T) \).
Side Conditions

Where are those side conditions needed? What goes wrong?
Side Conditions

Where are those side conditions needed? What goes wrong?

Very simple example: Let $E \equiv \exists x^\alpha y^\alpha. x \neq y$ and suppose $\sigma$ is a type inhabited by only one term, and $\tau$ is a type inhabited by at least two terms. Then we would have:

$$c = c \quad \text{hols by } \text{refl}$$
$$\implies (\exists x^\sigma y^\sigma. x \neq y) = (\exists x^\tau y^\tau. x \neq y)$$
$$\implies \text{False} = \text{True}$$
$$\implies \text{False}$$

This explains definition of True. Other (standard) example later.
Constant Definition: Examples

Definitions of True, False, ∧, ∨, ∀ . . .

Here the original Isabelle syntax (Ex_def changed)

True_def: "True  == ((%x::bool. x) = (%x. x))"
All_def:  "All(P) == (P = (%x. True))"
Ex_def:  "Ex(P)  == P (SOME x. P x)"
False_def: "False == (!P. P)"
not_def: "~ P  == P-->False"
and_def: "P & Q  == !R. (P-->Q-->R) --> R"
or_def:  "P | Q  == !R. (P-->R) --> (Q-->R)
                        --> R"
More Constant Definitions in Isabelle

Function application (Let), if-then-else, unique existence:

consts
Let :: ['a, 'a => 'b] => 'b
If :: [bool, 'a, 'a] => 'a

defs
Let_def "Let s f == f(s)"
if_def "If P x y == @z::'a.(P=True-->z=x) &
(P=False-->z=y)"
Ex1_def "Ex1(P) == ?x. P(x) & (!y. P(y) --> y=x)"

Recall: => is function type arrow; also recall [] syntax.
Type Definitions

Type definitions, explained intuitively: we have

- an existing type $\rho$;
Type Definitions

Type definitions, explained intuitively: we have

- an existing type $\rho$;
- a predicate $S : \rho \rightarrow bool$, defining a non-empty "subset" of $\rho$;
Type Definitions

Type definitions, explained intuitively: we have

- an existing type $\rho$;
- a predicate $S : \rho \rightarrow bool$, defining a non-empty “subset” of $\rho$;
- axioms stating an isomorphism between $S$ and the new type $\tau$.

\[
\begin{align*}
\text{Abs}_\tau : & \rho \rightarrow \tau \\
\text{Rep}_\tau : & \tau \rightarrow \rho \\
\end{align*}
\]
Type Definition: Definition

Definition 5 (type definition):
Assume a theory $T = (B, \Sigma, A)$ and a type $\rho$ and a term $S$ such that $\Sigma \vdash S : \rho \rightarrow bool$.

A theory extension $T' = (B', \Sigma', A')$ of $T$ is a type definition for type $\tau$ (where $\tau$ fresh), iff

\[ B' = B \uplus \{ \tau \}, \]
\[ \Sigma' = \Sigma \cup \{ Abs_\tau : \rho \rightarrow \tau, Rep_\tau : \tau \rightarrow \rho \} \]
\[ A' = A \cup \{ \forall x. Abs_\tau(Rep_\tau x) = x, \]
\[ \forall x. S x \rightarrow Rep_\tau(Abs_\tau x) = x \} \]

Proof obligation $\exists x. S x$ can be proven inside HOL!
Type Definitions Are Conservative

Lemma 2 (type definitions):
Type definitions are conservative.
Proof see [GM93, pp.230].
HOL Is Rich Enough!

This may seem fishy: if a new type is always isomorphic to a subset of an existing type, how is this construction going to lead to a “rich” collection of types for large-scale applications?
HOL Is Rich Enough!

This may seem fishy: if a new type is always isomorphic to a subset of an existing type, how is this construction going to lead to a “rich” collection of types for large-scale applications?

But in fact, due to $\text{ind}$ and $\rightarrow$, the types in HOL are already very rich.
HOL Is Rich Enough!

This may seem fishy: if a new type is always isomorphic to a subset of an existing type, how is this construction going to lead to a “rich” collection of types for large-scale applications?

But in fact, due to $\text{ind}$ and $\to$, the types in HOL are already very rich.

We now give three examples to convince you.
Example: Typed Sets

General scheme,

\[ \mathcal{B}' = \mathcal{B} \uplus \{ \tau \}, \]
\[ \Sigma' = \Sigma \cup \{ \text{Abs}_\tau : \rho \rightarrow \tau, \]
\[ \text{Rep}_\tau : \tau \rightarrow \rho \} \]
\[ A' = A \cup \{ \forall x. \text{Abs}_\tau (\text{Rep}_\tau x) = x, \]
\[ \forall x. S x \rightarrow \text{Rep}_\tau (\text{Abs}_\tau x) = x \} \]
Example: Typed Sets

General scheme, substituting $\rho \equiv \alpha \rightarrow bool$ ($\alpha$ is any type variable),

$$
\begin{align*}
\mathcal{B}' &= \mathcal{B} \cup \{\tau\}, \\
\Sigma' &= \Sigma \cup \{Abs_\tau : (\alpha \rightarrow bool) \rightarrow \tau, \\
& \quad Rep_\tau : \tau \rightarrow (\alpha \rightarrow bool)\}, \\
A' &= A \cup \{\forall x. Abs_\tau (Rep_\tau x) = x, \\
& \quad \forall x. S x \rightarrow Rep_\tau (Abs_\tau x) = x\}
\end{align*}
$$
Example: Typed Sets

General scheme, substituting $\rho \equiv \alpha \rightarrow bool$ ($\alpha$ is any type variable), $\tau \equiv \alpha set$ (or set),

\[
\begin{align*}
B' &= B \uplus \{set\}, \\
\Sigma' &= \Sigma \cup \{Abs_{set} : (\alpha \rightarrow bool) \rightarrow \alpha set, \\
&\quad Rep_{set} : \alpha set \rightarrow (\alpha \rightarrow bool)\} \\
A' &= A \cup \{\forall x. Abs_{set}(Rep_{set} x) = x, \\
&\quad \forall x. S x \rightarrow Rep_{set}(Abs_{set} x) = x\}
\end{align*}
\]
Example: Typed Sets

General scheme, substituting $\rho \equiv \alpha \rightarrow \text{bool}$ ($\alpha$ is any type variable), $\tau \equiv \alpha \text{ set}$ (or set), $S \equiv \lambda x^{\alpha \rightarrow \text{bool}}. \text{True}$

$$B' = B \uplus \{ \text{set} \},$$
$$\Sigma' = \Sigma \cup \{ \text{Abs}_{\text{set}} : (\alpha \rightarrow \text{bool}) \rightarrow \alpha \text{ set},$$
$$\quad \text{Rep}_{\text{set}} : \alpha \text{ set} \rightarrow (\alpha \rightarrow \text{bool}) \}$$
$$A' = A \cup \{ \forall x. \text{Abs}_{\text{set}}(\text{Rep}_{\text{set}} x) = x,$$
$$\quad \forall x. \text{True} \rightarrow \text{Rep}_{\text{set}}(\text{Abs}_{\text{set}} x) = x \}$$
Example: Typed Sets

General scheme, substituting $\rho \equiv \alpha \rightarrow \text{bool}$ ($\alpha$ is any type variable), $\tau \equiv \alpha \text{ set}$ (or set), $S \equiv \lambda x^{\alpha \rightarrow \text{bool}}. \text{True}$

\[
B' = B \uplus \{ \text{set} \},
\]

\[
\Sigma' = \Sigma \cup \{ \text{Abs}_{\text{set}} : (\alpha \rightarrow \text{bool}) \rightarrow \alpha \text{ set}, \text{Rep}_{\text{set}} : \alpha \text{ set} \rightarrow (\alpha \rightarrow \text{bool}) \}
\]

\[
A' = A \cup \{ \forall x. \text{Abs}_{\text{set}}(\text{Rep}_{\text{set}} x) = x, \forall x. \text{Rep}_{\text{set}}(\text{Abs}_{\text{set}} x) = x \}
\]

Simplification since $S \equiv \lambda x. \text{True}$. Proof obligation: $(\exists x. Sx)$ trivial since $(\exists x. \text{True}) = \text{True}$. Inhabitation crucial!
Sets: Remarks

Any function \( r : \tau \rightarrow bool \) can be interpreted as a set of \( \tau \); \( r \) is called characteristic function. That’s what \( Abs_{set} r \) does; \( Abs_{set} \) is a wrapper saying “interpret \( r \) as set”.

Smaus: CSMR; WS05/06
Sets: Remarks

Any function $r : \tau \rightarrow bool$ can be interpreted as a set of $\tau$; $r$ is called characteristic function. That’s what $Abs_{set} r$ does; $Abs_{set}$ is a wrapper saying “interpret $r$ as set”.

$S \equiv \lambda x. True$ and so $S$ is trivial in this case.
More Constants for Sets

For convenient use of sets, we define more constants:

\[
\{ x \mid f \, x \} = \text{Collect } f = \text{Abs}_{\text{set}} f \\
x \in A = (\text{Rep}_{\text{set}} A) \, x \\
A \cup B = \{ x \mid x \in A \lor x \in B \} \\
\]

Consistent set theory adequate for most of mathematics and computer science.

In Isabelle/HOL however, sets are a special case.

Here, sets are just an example to demonstrate type definitions. Later we study them for their own sake.
Example: Pairs

Consider type $\alpha \rightarrow \beta \rightarrow \text{bool}$. We can regard a term $f : \alpha \rightarrow \beta \rightarrow \text{bool}$ as a representation of the pair $(a, b)$, where $a : \alpha$ and $b : \beta$, iff $f \, x \, y$ is true exactly for $x = a$ and $y = b$. Observe:

- For given $a$ and $b$, there is exactly one such $f$ (namely, $\lambda x^\alpha y^\beta. x = a \land y = b$).

- Some functions of type $\alpha \rightarrow \beta \rightarrow \text{bool}$ represent pairs and others don’t (e.g., the function $\lambda xy. \text{True}$ does not represent a pair). The ones that do are exactly the ones that have the form $\lambda x^\alpha y^\beta. x = a \land y = b$, for some $a$ and $b$. 
Type Definition for Pairs

This gives rise to a type definition where $S$ is non-trivial:

$$
\begin{align*}
\rho & \equiv \alpha \rightarrow \beta \rightarrow \text{bool} \\
S & \equiv \lambda f^{\alpha \rightarrow \beta \rightarrow \text{bool}}. \exists a b. f = \lambda x^{\alpha} y^{\beta}. x = a \land y = b \\
\tau & \equiv \alpha \times \beta
\end{align*}
$$

It is convenient to define a constant $\text{Pair}_\text{Rep}$ (not to be confused with $\text{Rep}_\times$) as $\lambda a^{\alpha} b^{\beta}. \lambda x^{\alpha} y^{\beta}. x = a \land y = b$. Then $\text{Pair}_\text{Rep} a b = \lambda x^{\alpha} y^{\beta}. x = a \land y = b$. 
Now in Isabelle

Isabelle has a special set-based syntax for type definitions:

\[
\text{typedef } (T) \\
\langle \text{typevars} \rangle "T"" \langle \text{fixity} \rangle \\
= "\{x.\phi\}"
\]
Now in Isabelle

Isabelle has a special set-based syntax for type definitions:

\[
\text{typedef (} T \text{)} \\
\langle \text{typevars} \rangle \ " T'" \langle \text{fixity} \rangle \\
= \" \{ x.\phi \}\" 
\]

How is this linked to our scheme:

- the new type is called \( T' \);
- \( \rho \) is the type of \( x \) (inferred);
- \( S \) is \( \lambda x.\phi \);
- constants \( \text{Abs}_T \) and \( \text{Rep}_T \) are automatically generated.
Isabelle Syntax for Pair Example

constdefs
  Pair_Rep :: ['a, 'b] => ['a, 'b] => bool
  "Pair_Rep == (%a b. %x y. x=a & y=b)"
typedef (Prod)
  ('a, 'b) "*" (infixr 20) =
  "{f.?a b. f=Pair_Rep(a::'a)(b::'b)}"

The keyword constdefs introduces a constant definition. The definition and use of Pair_Rep is for convenience. There are “two names” * and Prod.
See Product_Type.thy.
Example: Sums

An element of \((\alpha, \beta)\) sum is either \(\text{Inl } a\) where \(a : \alpha\) or \(\text{Inr } b\) where \(b : \beta\).

So think of \(\text{Inl } a\) and \(\text{Inr } b\) as syntactic objects that we want to represent.

Consider type \(\alpha \to \beta \to \text{bool} \to \text{bool}\). We can regard \(f : \alpha \to \beta \to \text{bool} \to \text{bool}\) as a representation of . . . iff \(f x y i\) is true for . . .

| \(\text{Inl } a\) | \(x = a, y\) arbitrary, and \(i = \text{True}\) |
| \(\text{Inr } b\) | \(x\) arbitrary, \(y = b\), and \(i = \text{False}\). |

Similar to pairs.
constdefs
  Inl_Rep :: ['a, 'a, 'b, bool] => bool
  "Inl_Rep == (%a. %x y p. x=a & p)"
  Inr_Rep :: ['b, 'a, 'b, bool] => bool
  "Inr_Rep == (%b. %x y p. y=b & ~p)"

typedef (Sum)
  ('a,'b)+" =
  "{f. (?a. f = Inl_Rep(a::'a)) | (?b. f = Inr_Rep(b::'b))}"

See Sum_Type.thy.

How would you define a type even based on nat?
Summary on Conservative Extensions

We have seen two schemata:

- **Constant definition**: new constant must be defined using old constants. No *recursion*! Subtle *side conditions* concerning types.

- **Type definition**: new type must be isomorphic to a “subset” $S'$ of an existing type $\rho$. Not possible to define any type that is “structurally” richer than the types one already has. But HOL is *rich enough*. ▶️
More Detailed Explanations
Axioms or Rules

Isabelle-technically, those axioms are `thm`'s, and they may include Isabelle’s metalevel implication $\implies$. For this reason, it is not required to mention `rules` explicitly.

But speaking more generally about HOL, not just its Isabelle implementation, one should better say “rules” here, i.e., objects with a horizontal line and zero or more `formulas` above the line and one `formula` below the line.
Derivable Formulas

The derivable formulas are terms of type bool derivable using the inference rules of HOL. We write $Th(T)$ for the derivable formulas of a theory $T$. 
Closed Terms

A term is **closed** or **ground** if it does not contain any **free** variables.
Definition of $\textit{True}$ Is Type-Closed

$\textit{True}$ is defined as $\lambda x^{\textit{bool}}. x = \lambda x.x$ and not $\lambda x^{\alpha}. x = \lambda x.x$. The definition must be type-closed.
We have never used unique existential quantification ($\exists!$) before. $\exists! x_1, \ldots, x_n \cdot \phi(x_1, \ldots, x_n)$ is defined as
$$\exists x_1, \ldots, x_n \cdot \phi(x_1, \ldots, x_n) \land (\forall y_1, \ldots, y_n \cdot \phi(y_1, \ldots, y_n) \rightarrow x_1 = y_1 \land \ldots \land x_n = y_n).$$

Note that in general $\exists! x \cdot (\exists! y \cdot \phi)$ is not the same as $\exists! xy \cdot \phi)$. 

Back to main referring slide
Fixpoint Combinator

Given a function $f : \alpha \to \alpha$, a fixpoint of $f$ is a term $t$ such that $ft = t$. Now $Y$ is supposed to be a fixpoint combinator, i.e., for any function $f$, the term $Yf$ should be a fixpoint of $f$. This is what the rule

$$\forall f : \alpha \to \alpha. Yf = f (Yf)$$

says. Consider the example $f \equiv \neg$. Then the axiom allows us to infer $Y(\neg) = \neg(Y(\neg))$, and it is easy to derive $False$ from this. This axiom is a standard example of a non-conservative extension of a theory. It is not surprising that this goes wrong: Not every function has a fixpoint, so there cannot be a combinator returning a fixpoint of any function.

Nevertheless, fixpoints are important and must be realized in some way,
as we will see later.
Side Conditions

By side conditions we mean

- $E$ does not contain $c$ and is closed;
- no subterm of $E$ has a type containing a type variable that is not contained in the type of $c$;

in the definition.

The second condition also has a name: one says that the definition must be type-closed.

The notion of having a type is defined by the type assignment calculus. Since $E$ is required to be closed, all variables occurring in $E$ must be $\lambda$-bound, and so the type of those variables is given by the type superscripts.
Domains of $\Sigma$, $\Gamma$

The domain of $\Sigma$, denoted $\text{dom}(\Sigma)$, is $\{c \mid c : A \in \Sigma \text{ for some } A\}$.
Likewise, the domain of $\Gamma$, denoted $\text{dom}(\Gamma)$, is $\{x \mid x : A \in \Gamma \text{ for some } A\}$.
Note the abuse of notation.
**constdefs**

In Isabelle theory files, `consts` is the keyword preceding a sequence of constant declarations (i.e., this is where the $\Sigma$ is defined), and `defs` is the keyword preceding the axioms that define these constants (i.e., this is where the $A$ is defined).

`constdefs` combines the two, i.e. it allows for a sequence of both constant declarations and definitions. When the `constdefs` syntax is used to define a constant $c$, then the identifier $c\_def$ is generated automatically. E.g.

```isabelle
constdefs
  id :: 'a => 'a
  "id == %x. x"
```

will bind $id\_def$ to $id \equiv \lambda x. x$. 

[Back to main referring slide]
A Predicate a Set?

Although a set is formally a different object than a predicate, it is standard to interpret a predicate a set: the set of terms for which the predicate returns true. We have done this before.
Here, $S$ is any “predicate”, i.e., term of type $\rho \rightarrow \text{bool}$, not necessarily a constant.
**Fresh** \( \forall \)

The type constructor \( \tau \) must not occur in \( \mathcal{B} \).
What Is $\tau$?

A type definition is supposed to define a type constructor (where the arity and fixity are indicated in some way). We abuse notation here: we use $\tau$ to denote a type constructor, but also the type obtained by applying the type constructor to a vector of different type variables (as many as the type constructor requires).

So think of $\tau$ as either being a type constructor or a “generic” type (just a type constructor being applied to type variables).

We do the same in examples.
The symbol $\uplus$ denotes disjoint union, so the expression $A \uplus B$ is well-formed only when $A$ and $B$ have no elements in common. One thus uses this notation to indicate this fact.
What Are $Abs_\tau$ and $Rep_\tau$?

Of course we are giving a schematic definition here, so any letters we use are metanotation.

Notice that $Abs_\tau$ and $Rep_\tau$ stand for new constants. For any new type $\tau$ to be defined, two such constants must be added to the signature to provide a generic way of obtaining terms of the new type. Since the new type is isomorphic to the “subset” $S$, whose members are of type $\rho$, one can say that $Abs_\tau$ and $Rep_\tau$ provide a type conversion between (the subset $S$ of) $\rho$ and $\tau$.

So we have a new type $\tau$, and we can obtain members of the new type by applying $Abs_\tau$ to a term $t$ of type $\rho$ for which $S\,t$ holds.
Isomorphism

The formulas
\[ \forall x. Abs_\tau(Rep_\tau x) = x \]
\[ \forall x. S x \to Rep_\tau(Abs_\tau x) = x \]
state that the "set" \( S \) and the new type \( \tau \) are isomorphic. Note that \( Abs_\tau \) should not be applied to a term not in "set" \( S \). Therefore we have the premise \( S x \) in the above equation.

Note also that \( S \) could be the "trivial filter" \( \lambda x. True \). In this case, \( Abs_\tau \) and \( Rep_\tau \) would provide an isomorphism between the entire type \( \rho \) and the new type \( \tau \).
Proof Obligation

We have said previously that $S$ should be a non-empty “subset” of $\tau$. Therefore it must be proven that $\exists x. S\, x$. This is related to the semantics.

Whenever a type definition is introduced in Isabelle, the proof obligation must be shown inside Isabelle/HOL. Isabelle provides the typedef syntax for type definitions, as we will see later. Using this syntax, the “author” of a type definition can either explicitly provide a proof (see Product_Type.thy), or the proof is so easy that Isabelle can do it automatically (see Sum_Type.thy).
Inhabitation in the set Example

We have \( S \equiv \lambda x^{\alpha \rightarrow \text{bool}}. \text{True} \), and so in \( (\exists x.Sx) \), the variable \( x \) has type \( \alpha \rightarrow \text{bool} \). The proposition \( (\exists x.Sx) \) is true since the type \( \alpha \rightarrow \text{bool} \) is inhabited, e.g. by the term \( \lambda x^{\alpha}. \text{True} \) or \( \lambda x^{\alpha}. \text{False} \).

Beware of a confusion: This does not mean that the new type \( \alpha \text{set} \), defined by this construction, is the type of non-empty sets. There is a term for the empty set: The empty set is the term \( \text{Abs}_{set} (\lambda x. \text{False}) \).

Recall a previous argument for the importance of inhabitation.
Trivial $S$

We said that in the general formalism for defining a new type, there is a term $S$ of type $\rho \rightarrow \text{bool}$ that defines a “subset” of a type $\rho$. In other words, it filters some terms from type $\rho$. Thus the idea that a predicate can be interpreted as a set is present in the general formalism for defining a new type.

Now we are talking about a particular example, the type $\alpha \text{set}$. Having the idea “predicates are sets” in mind, one is tempted to think that in the particular example, $S$ will take the role of defining particular sets, i.e., terms of type $\alpha \text{set}$. This is not the case!

Rather, $S$ is $\lambda x. \text{True}$ and hence trivial in this example. Moreover, in the example, $\rho$ is $\alpha \rightarrow \text{bool}$, and any term $r$ of type $\rho$ defines a set whose elements are of type $\alpha$; $\text{Abs}_{\text{set}} r$ is that set.
Collect

We have seen *Collect* before in the theory file *NSet.thy* (naïve set theory).

*Collect* $f$ is the set whose characteristic function is $f$. There is also a concrete (i.e., according to mathematical practice) syntax $\{x \mid fx\}$. It is called *set comprehension*. The correspondence between the HOAS *Collect* $f$ and the concrete syntax $\{x \mid fx\}$ also makes it clear that set comprehension is a binding operator, as we learned some time ago.

Note also that *Collect* is the same as $\text{Abs}_{\text{set}}$ here.

The file *Set.thy* should be contained in your Isabelle distribution. In Freiburg it is

```
/usr/local/share/provers/Isabelle/src/HOL/Set.thy
```

\[\text{Back to main referring slide}\]
The \( \in \)-Sign

We define

\[
x \in A = (\text{Rep}_{\text{set}} A) \ x
\]

Since \( \text{Rep}_{\text{set}} \) has type \( \alpha \text{ set} \rightarrow (\alpha \rightarrow \text{bool}) \), this means that \( x \) is of type \( \alpha \) and \( A \) is of type \( (\alpha \rightarrow \text{bool}) \). Therefore \( \in \) is of type \( \alpha \rightarrow (\alpha \text{ set}) \rightarrow \text{bool} \) (but written infix).

In the Isabelle theory file \texttt{Set.thy}, you will indeed find that the constant : (Isabelle syntax for \( \in \)) has type \( \alpha \rightarrow (\alpha \text{ set}) \rightarrow \text{bool} \).

However, you will not find anything directly corresponding to \( \text{Rep}_{\text{set}} \).
Consistent Set Theory

Typed set theory is a conservative extension of HOL and hence consistent.

Recall the problems with untyped set theory.
Sets in Isabelle/HOL

We presented a definition of $\alpha$ set according to the scheme of type definitions. However, in Isabelle/HOL (*Set.thy*), it is not done exactly like that. The reason will become clear later.

The type $\alpha$ set is defined in Isabelle/HOL in a way which essentially corresponds to the type definition scheme, but is different in the technical details. In particular, there are no constants $\text{Abs}_{\alpha \text{ set}}$ and $\text{Rep}_{\alpha \text{ set}}$. Instead, we have $\text{Collect}$ and the $\in$-sign. We will now explain how.

Concerning $\text{Abs}_{\alpha \text{ set}}$, there is no worry, since it corresponds exactly to $\text{Collect}$.

$\text{Rep}_{\alpha \text{ set}}$ is related to the $\in$-sign via

$$x \in A = (\text{Rep}_{\alpha \text{ set}} A) x$$
Let us see that this setup is equivalent to the scheme of type definitions. There are two axioms in Set.thy:

axioms

mem_Collect_eq [iff]: "(a : \{x. P(x)\}) = P(a)"
Collect_mem_eq [simp]: "\{x. x:A\} = A"

We translate these axioms using the definitions:

\[ a \in \{x \mid P \, x\} = P \, a \rightsquigarrow \]
\[ a \in (\text{Collect} \, P) = P \, a \rightsquigarrow \]
\[ a \in (\text{Abs}_{\text{set}} \, P) = P \, a \rightsquigarrow \]
\[ \text{Rep}_{\text{set}}(\text{Abs}_{\text{set}} \, P) \, a = P \, a \rightsquigarrow \]
\[ \text{Rep}_{\text{set}}(\text{Abs}_{\text{set}} \, P) = P \]

The last step uses extensionality.
Now the second one:

\[
\{ x \mid x \in A \} = A \sim \\
\{ x \mid (\text{Rep}_{\text{set}} A) x \} = A \sim \\
\text{Collect}(\text{Rep}_{\text{set}} A) = A
\]

Ignoring some universal quantifications (these are implicit in Isabelle), these are the \textbf{isomorphy axioms for set}. 

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“Exactly one” Term

When we say that there is “exactly one" $f$, this is meant modulo equality in HOL. This means that e.g. $\lambda x^\alpha y^\beta. y = b \land x = a$ is also such a term since $(\lambda x^\alpha y^\beta. x = a \land y = b) = (\lambda x^\alpha y^\beta. y = b \land x = a)$ is derivable in HOL.
$\text{Rep}_\times$

$\text{Rep}_\times$ would be the generic name for one of the two isomorphism-defining functions.

Since $\text{Rep}_\times$ looks funny, the definition scheme for type definitions in Isabelle is such that it provides two names for a type, one if the type is used as such, and one for the purpose of generating the names of the isomorphism-defining functions.
Funny Iteration of λ’s

We write $\lambda a^\alpha b^\beta . \lambda x^\alpha y^\beta . x = a \land y = b$ rather than $\lambda a^\alpha b^\beta x^\alpha y^\beta . x = a \land y = b$ to emphasize the idea that one first applies Pair_Repl to $a$ and $b$, and the result is a function representing a pair, which can then be applied to $x$ and $y$. 
typedef Is Based on set

The syntax ”\{x.\phi}\)” does not just look like a set comprehension, it is one!

So, since the typedef syntax is based on sets, sets themselves could not have been defined using that syntax. This is the reason why in Isabelle/HOL, sets are a special case of a type definition.

See Typedef.thy, which should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Typedef.thy
Product_Type.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Product_Type.thy
Sum Types

Idea of sum or union type: $t$ is in the sum of $\tau$ and $\sigma$ if $t$ is either in $\tau$ or in $\sigma$. To do this formally in our type system, and also in the type system of functional programming languages like ML, $t$ must be wrapped to signal if it is of type $\tau$ or of type $\sigma$.

For example, in ML one could define

$$\text{datatype } (\alpha, \beta) \text{ sum } = \text{Inl } \alpha \mid \text{Inr } \beta$$

So an element of $(\alpha, \beta) \text{ sum}$ is either $\text{Inl } a$ where $a : \alpha$ or $\text{Inr } b$ where $b : \beta$. 

Back to main referring slide
Sum_Type.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Sum_Type.thy
Defining even

Suppose we have a type nat and a constant + with the expected meaning. We want to define a type even of even numbers. What is an even number?
Defining `even`

Suppose we have a type `nat` and a constant `+` with the expected meaning. We want to define a type `even` of even numbers. What is an even number?

The following choice of $S$ is adequate:

$$S \equiv \lambda x. \exists n. x = n + n$$

Using the Isabelle scheme, this would be

```isabelle
typedef (Even)
  even = "\{x. ?y. x=y+y\}"
```

We could then go on by defining an operation `PLUS` on `even`, say as
follows:

\[
\begin{align*}
\text{constdefs} \\
\text{PLUS}::[\text{even}, \text{even}] & \Rightarrow \text{even} \quad \text{(infixl 56)} \\
\text{PLUS} \_ \text{def} & \ "\text{opPLUS} \equiv \" \\
& \quad \%xy. \ \text{Abs} \_ \text{Even} \ (\text{Rep} \_ \text{Even}(x)+\text{Rep} \_ \text{Even}(x))
\end{align*}
\]

Note that we chose to use names `even` and `Even`, but we could have used the same name twice as well.
Mathematics in the Isabelle/HOL Library: Introduction
Isabelle/HOL at Work

We have seen how the mechanism of conservative extensions works in principle.
For several lectures, we will now look at theories of the Isabelle/HOL library, all built by conservative extensions and modelling significant portions of mathematics.
Sets: The Basis of Principia Mathematica

Sets are ubiquitous in mathematics:

- 17th century: geometry can be reduced to numbers [Des16, vL16].
- 19th century: numbers can be reduced to sets [Can18, Pea18, Fre93, Fre03].
- 20th century: sets can be represented in logics [Zer19, Frä19, WR25, Göd31, Ber19, Chu40].

We call this the Principia Mathematica Structure [WR25].

The libraries of theorem provers follow this Principia Mathematica Structure — in reverse order!
The Roadmap

- Orders
- Sets
- Functions
- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes ▶
More Detailed Explanations
Why in Reverse Order?

It is not surprising that the logical built-up of theorem prover is reversed w.r.t. to the historical development of mathematics and logics. Research usually starts from applications and the intuition and works its way back to the foundations.
Orders
The Roadmap

We are looking at how the different parts of mathematics are encoded in the Isabelle/HOL library.

- Orders
- Sets
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The Roadmap

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Three Order Classes

We first define a syntactic class \( \text{ord} \). It is the class of types for which symbols \(<\) and \(\leq\) exist.
Three Order Classes

We first define a syntactic class ord. It is the class of types for which symbols $<$ and $\leq$ exist.

We then define two axiomatic classes order and linorder for which $<$ and $\leq$ are required to have certain properties, that of being a partial order, or a linear order, resp.
Orders (in HOL.thy)

axclass
  ord < type
consts
  "op <" :: ['a::ord, 'a] => bool
  "op <=" :: ['a::ord, 'a] => bool
constdefs
  min :: ['a::ord, 'a] => 'a
  "min a b == (if a <= b then a else b)"
  max :: ['a::ord, 'a] => 'a
  "max a b == (if a <= b then b else a)"
Recall constdefs syntax and note two uses of <.

Smaus: CSMR; WS05/06
Orders in HOL.thy (Cont.)

axclass order < ord
  order_refl  "x <= x"
  order_trans  "[|x <= y; y <= z|] ==> x <= z"
  order_antisym "[|x <= y; y <= x|] ==> x = y"
  order_less_le  "x < y = (x <= y & x ~= y)"
%
axclass linorder < order
  linorder_linear  "x <= y | y <= x"
Least Elements

In *Ord.thy*, least elements used to be defined as:

\[
\text{Least :: } (\forall a::\text{ord} \Rightarrow \text{bool}) \Rightarrow \text{'}a'
\]

\[
\text{Least_def } \text{"Least } P = \exists x. P(x) \& (\forall y. P(y) \Rightarrow x \leq y)"
\]

Now it is done without using the Hilbert operator.
Monotonicity

In `Ord.thy`, monotonicity used to be defined as:

```plaintext
mono :: ['a::ord => 'b::ord] => bool
mono_def "mono(f) == (!A B. A <= B --> f(A) <= f(B))"
```

Now it is done using a completely different syntax, but one can still use monotonicity as before.
Some Theorems about Orders

\begin{align*}
\text{monoI} & \quad (\bigwedge AB. A \leq B \implies f A \leq f B) \implies \text{mono } f \\
\text{monoD} & \quad \left[\text{mono } f; A \leq B\right] \implies f A \leq f B \\
\text{order_eq_refl} & \quad x = y \implies x \leq y \\
\text{order_less_irrefl} & \quad \neg x < x \\
\text{order_le_less} & \quad (x \leq y) = (x < y \lor x = y) \\
\text{linorder_less_linear} & \quad x < y \lor x = y \lor y < x \\
\text{linorder_neq_iff} & \quad (x \neq y) = (x < y \lor y < x) \\
\text{min_same} & \quad \text{min}_x x = x \\
\text{le_min_iff_conj} & \quad (z \leq \text{min}_x y) = (z \leq x \land z \leq y)
\end{align*}
Summary on Orders

Type classes are a structuring mechanism in Isabelle:

- **Syntactic classes** (e.g. $t :: \alpha :: ord$ as in Haskell [HHPW96]): merely a mechanism to structure visibility of operations.
Summary on Orders

Type classes are a structuring mechanism in Isabelle:

- **Syntactic classes** (e.g. \( t :: \alpha :: \text{ord} \) as in Haskell [HHPW96]): merely a mechanism to structure visibility of operations.

- **Axiomatic classes** (e.g. \( t :: \alpha :: \text{order} \)): a mechanism for structuring semantic knowledge in types (foundation to be discussed later).
More Detailed Explanations
Where Are Orders Defined?

In previous versions of Isabelle, there used to be a theory file Ord.thy. Nowadays orders are defined in HOL.thy.
Different uses of `<`

The line

\texttt{axclass order < ord}

in the theory file states that \textit{order} is a \textbf{subclass} of \textit{ord}.

The line

\texttt{"op <" :: ['a::ord, 'a] => bool ("(_ < _)" [50, 51] 50)}

in the theory file declares a constant `<` with a certain type.

\textit{type} is the class containing all types. In \textit{previous versions of Isabelle}, it used to be called \texttt{term}.
Theorems of what?

In the rest of the course, we will mostly be dealing with Isabelle HOL, and so when we speak of a theorem, we usually mean an Isabelle theorem, i.e., a theorem in Isabelle’s metalogic, what we also call a thm. Such theorems may contain the meta-level implication $\Rightarrow$ and universal quantifier $\forall$.

So they are not theorems within HOL. Logically, this is not a big deal as one switch between object and meta-level by the introduction and elimination rules for $\rightarrow$ and $\forall$. But technically (for the proof procedures), it makes a difference.

To see a theorem displayed in Isabelle, simply type the name of the theorem followed by “;”.

[Back to main referring slide]
Semantic Classes for Semantic Knowledge

The Isabelle type system records for any type variable what class constraints there are for this type variable. These class constraints may arise from the types of the constants used in an expression, or they may be given explicitly by the user in a goal. E.g. one might type

\[ \text{Goal } \left( x :: 'a :: \text{order} \right) < y \implies x \leq y \];

to specify that \( x \) must be of a type in the type class \( \text{order} \).

The axioms of an axiomatic class can only be applied if any constant declared in the axiomatic class (or a syntactic superclass) is applied to arguments of a type in the axiomatic class. E.g. \texttt{order_refl} can only be used to prove \( y \leq y \) if the type of \( y \) is in the type class \( \text{order} \).

In this sense the type information (\( y \) is of type in class \( \text{order} \)) is semantic knowledge (\( y \leq y \) holds).
Back to main referring slide
Sets
The Roadmap

We are still looking at how the different parts of mathematics are encoded in the Isabelle/HOL library.

- Orders
- Sets
- Functions
- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes
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theory Set = HOL:
typedecl 'a set
instance set :: (type) ord ..
consts
  "{}" :: 'a set ("{}")
  UNIV :: 'a set
  insert :: ['a, 'a set] => 'a set
  Collect :: ('a => bool) => 'a set
  "op :" :: "'a => 'a set => bool"

Note that Collect and ":: correspond to Abs_{set} and Rep_{set}.
Set.thy: More Constant Declarations

Un, Int :: ['a set, 'a set] => 'a set
Ball, Bex :: ['a set, 'a => bool] => bool
UNION, INTER:: ['a set, 'a => 'b set] => 'b set
Union, Inter:: (('a set) set) => 'a set
Pow :: 'a set => 'a set set
"image" :: ['a => 'b, 'a set] => ('b set)

We use old syntax here but only since it is more concise.
In what follows, recall that

\{x | f x\} = Collect f = Abs_{set} f
Set.thy: Constant Definitions

empty_def: "\{\} == \{x. False\}"

UNIV_def: "UNIV == \{x. True\}"

Un_def: "A Un B == \{x. x:A | x:B\}"

Int_def: "A Int B == \{x. x:A & x:B\}"

insert_def: "insert a B == \{x. x=a\} Un B"

Ball_def: "Ball A P == ALL x. x:A --> P(x)"

Bex_def: "Bex A P == EX x. x:A & P(x)"

Nice syntax:

\{x, y, z\} for insert x (insert y (insert z \{\}))

ALL x : A. Sx for Ball A S

EX x : A. Sx for Bex A S
**Set.thy: Constant Definitions (2)**

subset_def: "A <= B == ALL x:A. x:B"

Compl_def: "- A == {x. ~x:A}"

set_diff_def: "A - B == {x. x:A & ~x:B}"

UNION_def: "UNION A B == {y. EX x:A. y: B(x)}"

INTER_def: "INTER A B == {y. ALL x:A. y: B(x)}"

Note use of <= instead of ⊆!

Nice syntax:

\[ \bigcup_{x \in A} S x \quad \text{or} \quad \bigcup_{x \in A} S x \quad \text{for} \quad \text{UNION} \ A \ S \]

\[ \bigcap_{x \in A} S x \quad \text{or} \quad \bigcap_{x \in A} S x \quad \text{for} \quad \text{INTER} \ A \ S \]
Set.thy: Constant Definitions (3)

Union_def: "Union S == (UN x:S. x)"
Inter_def: "Inter S == (INT x:S. x)"
Pow_def: "Pow A == {B. B <= A}"
image_def: "f‘A == {y. EX x:A. y = f(x)}"

Nice syntax:
\( \bigcup S \) for Union \( S \)
\( \bigcap S \) for Inter \( S \)
Some Theorems in Set.thy

CollectI \quad P\ a \implies a \in \{x.\, P\ x\}

CollectD \quad a \in \{x.\, P\ x\} \implies P\ a

set_ext \quad (\bigwedge x. (x \in A) = (x \in B)) \implies A = B

subsetI \quad (\bigwedge x. x \in A \implies x \in B) \implies A \subseteq B

eqset_imp_iff \quad A = B \implies (x \in A) = (x \in B)

UNIV_I \quad x \in \text{UNIV}

subset_UNIV \quad A \subseteq \text{UNIV}

empty_subsetI \quad \emptyset \subseteq A

Pow_iff \quad (A \in \text{Pow}\ B) = (A \subseteq B)

IntI \quad [c \in A; c \in B] \implies c \in A \cap B
More Theorems in Set.thy

insert_iff  \((a \in \text{insert } b A) = (a = b \lor a \in A)\)

image_Un    \(f'(A \cup B) = f' A \cup f' B\)

Inter_lower  \(B \in A \implies \bigcap A \subseteq B\)

Inter_greatest  \(\forall X. X \in A \implies C \subseteq X \implies C \subseteq \bigcap A\)
Summary on Sets

Rich and powerful set theory available in HOL:

- No problems with consistency
- **Weaker** than ZFC (since typed set-theory:) there is no "union of sets"; but: complement-closed
- Good mechanical support for many set tautologies (Fast_tac, fast_tac set_cs, fast_tac eq_cs, ... simp_tac set_ss ...)
- Powerful basis for many problems in modeling
More Detailed Explanations
\[ \subseteq \text{ instead of } \subseteq \]

Sets are an instance of the type class `ord`, where the generic constant `\subseteq` is the subset relation in this particular case.

In fact, the subset relation is reflexive, transitive and anti-symmetric, and so sets are an instance of the `axiomatic class order`. This is non-obvious and must be proven, which is done not in `Set.thy` itself but in `Fun.thy`, later. This is a technicality of Isabelle.
Union of Arbitrary Sets?

In typed set theory (what we have here in HOL), it is not possible to form the union of two sets of different type. This is in contrast to ZFC.
Typed Sets Are Complement-Closed

The complement of a typed set $A$, i.e.

\[ \{ x \mid x \notin A \} \]

is again a set, whose type is the same as the type of $A$. In ZFC, the complement construction is not generally allowed since it opens the door to Russell’s Paradox.
Functions
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Fun.thy

The theory Fun.thy defines some important notions on functions, such as concatenation, the identity function, the image of a function, etc.

We look at it briefly.
Functions

978

Two Extracts from Fun.thy
Composition and the identity function:
constdefs
id :: "’a => ’a"
"id == %x. x"
comp :: "[’b => ’c, ’a => ’b, ’a] => ’c"
"f o g == %x. f(g(x))"
Recall constdefs syntax.

Smaus: CSMR; WS05/06


Instantiating an Axiomatic Class

Sets are partial orders: set is an instance of the axiomatic class order.

For some reason, this is proven in Fun.thy.

instance set :: (type) order 
  by (intro_classes,
      (assumption | rule subset_refl
       subset_trans subset_antisym psubset_eq)+)

- Axiomatic classes result in proof obligations.
- These are discharged whenever instance is stated.
- Type-checking has access to the established properties.
Conclusion of Orders, Sets, Functions

• Theory says: conservative extensions can be used to build consistent libraries.
Conclusion of Orders, Sets, Functions

- Theory says: conservative extensions can be used to build consistent libraries.
- Sets as one important package of Isabelle/HOL library:
  - Set theory is typed, but very rich and powerfully supported.
Conclusion of Orders, Sets, Functions

- Theory says: **conservative extensions can be used** to build consistent libraries.

- **Sets** as one important package of Isabelle/HOL library:
  - Set theory is typed, but **very rich** and **powerfully supported**.
  - Sets are instance of **ord** and **order** type class, demonstrates type classes as structuring mechanism in Isabelle.
Conclusion of Orders, Sets, Functions

- Theory says: 
  conservative extensions can be used to build consistent libraries.

- **Sets** as one important package of Isabelle/HOL library:
  - Set theory is typed, but very rich and powerfully supported.
  - Sets are instance of ord and order type class, demonstrates type classes as structuring mechanism in Isabelle.

- Will see more examples: Isabelle/HOL contains some 10000 thm’s.
More Detailed Explanations
Fun.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Fun.thy

Fun.thy builds on Set.thy, and it is here that it is proven and used that sets are an instance of the type class order.
Proof Obligations

To claim that a type is an instance of an axiomatic class, it has to be proven that the axioms (in the case of order: order_refl, order_trans, order_antisym, and order_less_le are indeed fulfilled by that type.)
Discharge Obligations

The Isabelle mechanism is such that the line

```
instance set :: (type) order
  by (intro_classes,
    (assumption | rule
      subset_refl subset_trans subset_antisym psubset_eq)+)
```

instructs Isabelle to prove the **axioms** using the previously proven **theorems** subset_refl, subset_trans, subset_antisym, and psubset_eq.
Background: Recursion, Induction, and Fixpoints
The Roadmap

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Recursion Based on Set Theory

Current stage of our course:

- On the basis of conservative extensions, set theory can be built safely.
Recursion Based on Set Theory

Current stage of our course:

- On the basis of conservative extensions, set theory can be built safely.
- But: our mathematical world is still quite small and quite remote from computer science: we have no means of introducing recursive definitions (recursive programs, recursive set equations, . . .).

How can we benefit from set theory to introduce recursion?
Recursion and General Fixpoints

Naïve Approach: One could axiomatize fixpoint combinator $Y$ as

$$Y = \lambda F. F (Y F)$$

This axiom is not a constant definition.

Then we could easily derive

$$\forall F^{\alpha \rightarrow \alpha}. Y F = F (Y F).$$
Recursion and General Fixpoints

Naïve Approach: One could axiomatize fixpoint combinator \( Y \) as

\[
Y = \lambda F. F(YF) \hspace{1cm} \text{fix}
\]

This axiom is not a constant definition.

Then we could easily derive

\[
\forall F^{\alpha \rightarrow \alpha} . YF = F(YF).
\]

- Why are we interested in \( Y \)?
- What is the problem with such a definition?
Why Are We Interested in $Y$?

First, why are we interested in recursion (solutions to recursive equations)?
Why Are We Interested in $Y$?

First, why are we interested in recursion (solutions to recursive equations)?

- **Recursively defined functions** are solutions of such equations (example: $fac$).
- **Inductively defined sets** are solutions of such equations (example: $Fin A$, all finite subsets of $A$).
Why Are We Interested in $Y$?

First, why are we interested in recursion (solutions to recursive equations)?

- Recursively defined functions are solutions of such equations (example: $\text{fac}$).
- Inductively defined sets are solutions of such equations (example: $\text{Fin } A$, all finite subsets of $A$).

We are interested in $Y$ because it is the mother of all recursions. With $Y$, recursive axioms can be converted into constant definitions.
What’s the Problem with such an Axiom?

Such a definition would lead to inconsistency. This is not surprising because not all functions have a fixpoint. Therefore we only consider special forms of fixpoint combinators.

We consider two approaches: Least fixpoints (Tarski) and well-founded orderings.
More Detailed Explanations
Axiom Is not a Definition

The axiom

\[ Y = \lambda F. F(YF) \]

is not a constant definition, since \( Y \) occurs again on the right-hand side.
\[ \forall F^{\alpha \rightarrow \alpha}. Y F = F(Y F) \]

In words, this says that \( Y F \) is a fixpoint of \( F \).
Recursive Equation

By a recursive equation, we mean an equation of the form

\[ f = e \]

where \( f \) occurs in \( e \). A fortiori, such an equation does not qualify as constant definition.
Converting Recursive Axioms

Any recursive function can be defined by an expression (functional) which is not itself recursive, but instead relies on the recursive equation defining $Y$.

Consider $\text{fac}$ or $\text{Fin} \ A$ as an example.
Least Fixpoints
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First Approach: Least Fixpoints (Tarski)

- Restriction: $F$ is not of arbitrary type ($\alpha \to \alpha$) but of set type ($\alpha \text{ set} \to \alpha \text{ set}$).
- Instead of $Y$ define $\text{lfp}$ by an equation which is not recursive.
- $\text{lfp}$ is fixpoint combinator, but only under additional condition that $F$ is monotone, and: this is not obvious (requires non-trivial proof)!

This leads us towards recursion and induction.
Lfp.thy

Lfp = Product_Type +

constsdefs

lfp :: ['a set => 'a set] => 'a set
"lfp(f) == Inter({u. f(u) <= u})"

Note:

• => is function type arrow.
• <= ("⊆") is a partial order.
• Inter ("∩") gives a "minimum": \( \forall A \in S. (\cap S) \subseteq A. \)
Lfp.thy

Lfp = Product_Type +
constdefs
  lfp :: ['a set => 'a set] => 'a set
  "lfp(f) == Inter({u. f(u) <= u})"

Note:
• => is function type arrow.
• <= ("\subseteq") is a partial order.
• Inter ("\cap") gives a "minimum": \forall A \in S. (\bigcap S) \subseteq A.
• Definition of lfp is conservative. That’s fine. But is it a fixpoint combinator?
Tarski’s Fixpoint Theorem

Theorem 1 (Tarski):
If $f$ is monotone, then $\text{lfp } f = f (\text{lfp } f)$.
In Isabelle, the theorem is shown in Lfp.ML and called lfp_unfold.
We show the theorem using mathematical notation and a graphical illustration to help intuition.
The proof has four steps.
Tarski’s Fixpoint Theorem (1)

Claim 1 ("lfp lower bound"): If \( f \subseteq A \) then \( lfp \, f \subseteq A \).
Tarski’s Fixpoint Theorem (1)

Claim 1 ("lfp lower bound"): If $f \ A \subseteq A$ then $lfp \ f \subseteq A$.

The box denotes “the set” $\alpha$. The three circles denote the sets $A$ for which $f \ A \subseteq A$. 
Tarski’s Fixpoint Theorem (1)

Claim 1 ("lfp lower bound"): If $f \ A \subseteq A$ then $\text{lfp } f \subseteq A$.

The box denotes “the set” $\alpha$. The three circles denote the sets $A$ for which $f \ A \subseteq A$.
By definition, $\text{lfp } f$ is the intersection.
Tarski’s Fixpoint Theorem (1)

Claim 1 (“lfp lower bound”): If $f \ A \subseteq A$ then $lfp \ f \subseteq A$.

The box denotes “the set” $\alpha$. The three circles denote the sets $A$ for which $f \ A \subseteq A$.

By definition, $lfp \ f$ is the intersection.

Pick an $A$ for which $f \ A \subseteq A$.

Clearly, $lfp \ f \subseteq A$.

Or as proof tree.
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $fU \subseteq U$ implies $A \subseteq U$, then $A \subseteq lfp f$. 
Tarski’s Fixpoint Theorem (2)

Claim 2 ("\(lfp\) greatest"): For all \(A\), if for all \(U\), \(fU \subseteq U\) implies \(A \subseteq U\), then \(A \subseteq lfp\ f\).

The three circles denote the sets \(U\) for which \(fU \subseteq U\).
Claim 2 ("\(lfp\) greatest"): For all \(A\), if for all \(U\), \(f(U) \subseteq U\) implies \(A \subseteq U\), then \(A \subseteq lfp f\).

The three circles denote the sets \(U\) for which \(f(U) \subseteq U\).

By hypothesis, \(A \subseteq U\) for each \(U\).
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $f(U) \subseteq U$ implies $A \subseteq U$, then $A \subseteq \text{lfp } f$.

The three circles denote the sets $U$ for which $f(U) \subseteq U$.
By hypothesis, $A \subseteq U$ for each $U$ (1st,
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $f U \subseteq U$ implies $A \subseteq U$, then $A \subseteq lfp f$.

The three circles denote the sets $U$ for which $f U \subseteq U$.
By hypothesis, $A \subseteq U$ for each $U$ (1st, 2nd,
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $f \ U \subseteq U$ implies $A \subseteq U$, then $A \subseteq lfp \ f$.

The three circles denote the sets $U$ for which $f \ U \subseteq U$.

By hypothesis, $A \subseteq U$ for each $U$ (1st, 2nd, 3rd . . . ).
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $f U \subseteq U$ implies $A \subseteq U$, then $A \subseteq lfp f$.

The three circles denote the sets $U$ for which $f U \subseteq U$.

By hypothesis, $A \subseteq U$ for each $U$ (1st, 2nd, 3rd . . . ).

By definition, $lfp f$ is the intersection.
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $f U \subseteq U$ implies $A \subseteq U$, then $A \subseteq \text{lfp } f$.

The three circles denote the sets $U$ for which $f U \subseteq U$.
By hypothesis, $A \subseteq U$ for each $U$ (1st, 2nd, 3rd . . . ).
By definition, $\text{lfp } f$ is the intersection.
Clearly, $A \subseteq \text{lfp } f$. 
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $f U \subseteq U$ implies $A \subseteq U$, then $A \subseteq lfp \ f$.

The three circles denote the sets $U$ for which $f U \subseteq U$.

By hypothesis, $A \subseteq U$ for each $U$ (1st, 2nd, 3rd . . . ).

By definition, $lfp \ f$ is the intersection.

Clearly, $A \subseteq lfp \ f$.

Or as proof tree.
Claim 3: If $f$ is monotone then $f(lfp \ f) \subseteq lfp \ f$. 

Tarski’s Fixpoint Theorem (3)
Tarski’s Fixpoint Theorem (3)

Claim 3: If $f$ is monotone then $f(\text{lfp } f) \subseteq \text{lfp } f$.

First show Claim 3*: $f \ U \subseteq U$ implies $f(\text{lfp } f) \subseteq U$. 
Tarski’s Fixpoint Theorem (3)

Claim 3: If $f$ is monotone then $f(\text{lfp } f) \subseteq \text{lfp } f$.

First show Claim 3*: $f \ U \subseteq U$ implies $f(\text{lfp } f) \subseteq U$.

Let the circle be such a $U$. By Claim 1, $\text{lfp } f \subseteq U$. 
Tarski’s Fixpoint Theorem (3)

Claim 3: If \( f \) is monotone then \( f(lfp \ f) \subseteq lfp \ f \).

First show Claim 3*: \( f \ U \subseteq U \) implies \( f(lfp \ f) \subseteq U \).

Let the circle be such a \( U \). By Claim 1, \( lfp \ f \subseteq U \).
\[ f \ U \subseteq U \text{ (hypothesis).} \]
Tarski’s Fixpoint Theorem (3)

Claim 3: If $f$ is monotone then $f(lfp\ f) \subseteq lfp\ f$.

First show Claim 3*: $f\ U \subseteq U$ implies $f(lfp\ f) \subseteq U$.

Let the circle be such a $U$. By Claim 1, $lfp\ f \subseteq U$.

$f\ U \subseteq U$ (hypothesis).

$f(lfp\ f) \subseteq f\ U$ (monotonicity).
Tarski’s Fixpoint Theorem (3)

Claim 3: If $f$ is monotone then $f(lfp f) \subseteq lfp f$.

First show Claim 3*: $f \overset{U}{\subseteq} U$ implies $f(lfp f) \subseteq U$.

Let the circle be such a $U$. By Claim 1, $lfp f \subseteq U$.

$f \overset{U}{\subseteq} U$ (hypothesis).

$f(lfp f) \subseteq f \overset{U}{\subseteq} U$ (monotonicity).

$f(lfp f) \subseteq U$ (transitivity of $\subseteq$).

Claim 3* shown.
Tarski’s Fixpoint Theorem (3)

Claim 3: If \( f \) is monotone then \( f(lfp \ f) \subseteq lfp \ f \).

First show Claim 3*: \( f \ Uparrow \subseteq Uparrow \) implies \( f(lfp \ f) \subseteq U \).

Let the circle be such a \( U \). By Claim 1, \( lfp \ f \subseteq U \).

\( f \ Uparrow \subseteq Uparrow \) (hypothesis).

\( f(lfp \ f) \subseteq f \ Uparrow \) (monotonicity).

\( f(lfp \ f) \subseteq U \) (transitivity of \( \subseteq \)).

Claim 3* shown.

By Claim 2 (letting \( A := f(lfp \ f) \)),

\( f(lfp \ f) \subseteq lfp \ f \).
Tarski’s Fixpoint Theorem (4)

Claim 4: If $f$ is monotone then $\text{lfp } f \subseteq f(\text{lfp } f)$. 
Tarski’s Fixpoint Theorem

Claim 4: If \( f \) is monotone then \( \text{lfp} \ f \subseteq f(\text{lfp} \ f) \).

By Claim 3, \( f(\text{lfp} \ f) \subseteq \text{lfp} \ f \).
Tarski’s Fixpoint Theorem (4)

Claim 4: If $f$ is monotone then $\text{lfp } f \subseteq f(\text{lfp } f)$.

By Claim 3, $f(\text{lfp } f) \subseteq \text{lfp } f$.
By monotonicity, $f(f(\text{lfp } f)) \subseteq f(\text{lfp } f)$. 
Claim 4: If $f$ is monotone then $\text{lfp } f \subseteq f(\text{lfp } f)$.

By Claim 3, $f(\text{lfp } f) \subseteq \text{lfp } f$.
By monotonicity, $f(f(\text{lfp } f)) \subseteq f(\text{lfp } f)$.
By Claim 1 (letting $A := f(\text{lfp } f)$), $\text{lfp } f \subseteq f(\text{lfp } f)$. 
Claim 4: If $f$ is monotone then $\text{lfp } f \subseteq f(\text{lfp } f)$.

By Claim 3, $f(\text{lfp } f) \subseteq \text{lfp } f$.

By monotonicity, $f(f(\text{lfp } f)) \subseteq f(\text{lfp } f)$.

By Claim 1 (letting $A := f(\text{lfp } f)$), $\text{lfp } f \subseteq f(\text{lfp } f)$.

Or as proof tree.
Tarski’s Fixpoint Theorem: QED

Claim 3 \((\text{lfp } f \subseteq f(\text{lfp } f))\) and Claim 4 \((f(\text{lfp } f) \subseteq \text{lfp } f)\) together give the result:

If \(f\) is monotone, then \(\text{lfp } f = f(\text{lfp } f)\).

So under appropriate conditions, \(\text{lfp}\) is a fixpoint combinator.
We will later reuse Claim 1.
Alternative: A Natural-Deduction Style Proof

The proof can also be presented in natural deduction style.
Tarski’s Fixpoint Theorem (1)

Claim 1 ("lfp lower bound"): If \( f A \subseteq A \) then \( \text{lfp } f \subseteq A \).

\[
\begin{align*}
[f \ A \subseteq A]^1 \\
A \in \{u.fu \subseteq u\} \\
\bigcap\{u.fu \subseteq u\} \subseteq A \\
\text{lfp } f \subseteq A \\
f \ A \subseteq A \rightarrow \text{lfp } f \subseteq A
\end{align*}
\]
Tarski’s Fixpoint Theorem (2)

Claim 2 ("lfp greatest"): For all $A$, if for all $U$, $f \ U \subseteq U$ implies $A \subseteq U$, then $A \subseteq \text{lfp } f$.

\[
\begin{align*}
&\forall x. f x \subseteq x \to A \subseteq x \tag{1} \\
&\forall x. x \in \{u. f u \subseteq u\} \to A \subseteq x \\
&A \subseteq \bigcap\{u. f u \subseteq u\} \\
&\text{Def. lfp} \\
&A \subseteq \text{lfp } f \\
&(\forall x. f x \subseteq x \to A \subseteq x) \to A \subseteq \text{lfp } f \tag{-I} \\
\end{align*}
\]
Tarski’s Fixpoint Theorem (3)

Claim 3: If $f$ is monotone then $f(lfp f) \subseteq lfp f$.

\[
\begin{align*}
\text{mono } f & \quad \text{1} \\
\text{lfp } f & \subseteq x \quad \text{2} \\
\hline
\frac{fx \subseteq x}{f(lfp f) \subseteq f x} \quad \text{order\_trans} \\
\hline
\forall x. fx \subseteq x \rightarrow f(lfp f) \subseteq x \\
\hline
\frac{f(lfp f) \subseteq lfp f}{\text{lfp\_greatest}, \rightarrow\neg E} \\
\hline
\frac{\text{mono } f \rightarrow f(lfp f) \subseteq lfp f}{\rightarrow\neg l^1}
\end{align*}
\]
Tarski’s Fixpoint Theorem (4)

Claim 4: If \( f \) is monotone then \( \text{lfp\,} f \subseteq f(\text{lfp\,} f) \).

\[
\begin{align*}
\text{Claim 3, } \rightarrow\text{-E} \\
\text{monoD} \\
\text{lfp\_lowerbound, } \rightarrow\text{-E} \\
\rightarrow\text{-I}^1
\end{align*}
\]
Completing Proof Tree

\[
\begin{align*}
lfp f & \subseteq f(lfp f) \\
\text{Claim 4} & \quad [\text{mono } f]^1 \\
lfp f & = f(lfp f) \\
\text{equalityI} & \\
\text{mono } f & \rightarrow lfp f = f(lfp f) \quad \rightarrow - f^1
\end{align*}
\]
Theorem 2 (lfp induction):

If

- $f$ is monotone, and
- $f(lfp \ f \cap \{x \mid P\ x\}) \subseteq \{x \mid P\ x\}$,

then $lfp \ f \subseteq \{x \mid P\ x\}$. 
Induction Based on Lfp.thy

Theorem 2 (lfp induction): If

- $f$ is monotone, and
- $f(lfp \ f \cap \{x \mid P \ x\}) \subseteq \{x \mid P \ x\}$,

then $lfp \ f \subseteq \{x \mid P \ x\}$.

In Isabelle, it is called lfp_induct:

\[
[a \in lfp \ f; \ mono \ f; \land \ x. x \in f(lfp \ f \cap \{x. P \ x\}) \Rightarrow P \ x] \\
\Rightarrow P \ a
\]

We now show the theorem similarly as Tarski’s Theorem.
Showing `lfp_induct`

Circles denote `lfp f` and `{x | P x}`.
Showing \texttt{lfp\_induct}

Circles denote \(lfp\ f\) and \(\{x \mid P\ x\}\).

By monotonicity, \(f(lfp\ f \cap \{x \mid P\ x\}) \subseteq f(lfp\ f)\). By Tarski, \(lfp\ f = f(lfp\ f)\).
Showing \texttt{lfp\_induct}

Circles denote \texttt{lfp \ f} and \{x \mid P \ x\}.

By monotonicity, \( f(\texttt{lfp \ f} \cap \{x \mid P \ x\}) \subseteq f(\texttt{lfp \ f}) \). By Tarski, \( \texttt{lfp \ f} = f(\texttt{lfp \ f}) \). Hence \( f(\texttt{lfp \ f} \cap \{x \mid P \ x\}) \subseteq \texttt{lfp \ f} \).
Showing \texttt{lfp\_induct}

Circles denote \( \text{lfp } f \) and \( \{ x \mid P \, x \} \).

By monotonicity, \( f(\text{lfp } f \cap \{ x \mid P \, x \}) \subseteq f(\text{lfp } f) \). By Tarski, \( \text{lfp } f = f(\text{lfp } f) \). Hence \( f(\text{lfp } f \cap \{ x \mid P \, x \}) \subseteq \text{lfp } f \).

By hypothesis, \( f(\text{lfp } f \cap \{ x \mid P \, x \}) \subseteq \{ x \mid P \, x \} \), and so we must adjust picture: \( f(\text{lfp } f \cap \{ x \mid P \, x \}) \subseteq \text{lfp } f \cap \{ x \mid P \, x \} \).
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By Claim 1, \( \text{lfp}\ f \subseteq \text{lfp}\ f \cap \{x \mid P \ x\} \) and so \( \text{lfp}\ f = \text{lfp}\ f \cap \{x \mid P \ x\} \).
Showing \texttt{lfp\_induct}

Circles denote \(\texttt{lfp} \ f\) and \(\{x \mid P \ x\}\).

By monotonicity, \(f(\texttt{lfp} \ f \cap \{x \mid P \ x\}) \subseteq f(\texttt{lfp} \ f)\). By Tarski, \(\texttt{lfp} \ f = f(\texttt{lfp} \ f)\). Hence \(f(\texttt{lfp} \ f \cap \{x \mid P \ x\}) \subseteq \texttt{lfp} \ f\).

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By Claim 1, \(\texttt{lfp} \ f \subseteq \texttt{lfp} \ f \cap \{x \mid P \ x\}\) and so \(\texttt{lfp} \ f = \texttt{lfp} \ f \cap \{x \mid P \ x\}\).

Conclusion: \(\texttt{lfp} \ f \subseteq \{x \mid P \ x\}\).
Approximating Fixpoints

Looking ahead: Suppose we have the set \( \mathbb{N} \) of natural numbers (the type is formally introduced later). The theorem approx

\[
(\forall S. f(\bigcup S) = \bigcup (f \cdot S)) \implies \bigcup_{n \in \mathbb{N}} (f^n \{\}) = \text{lfp } f
\]

shows a way of approximating \( \text{lfp} \), which is important for algorithmic solutions (e.g. in program analysis).

There will be an exercise on this.
Where Are We Going? Induction and Recursion

Let’s step back: What is an inductive definition of a set $S$?
Where Are We Going? Induction and Recursion

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It has the form: $S$ is the smallest set such that:

- $\emptyset \subseteq S$ (just mentioned for emphasis);
- if $S' \subseteq S$ then $F(S') \subseteq S$ (for some appropriate $F$).
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At the same time, $S$ is the smallest solution of the recursive equation $S = F(S)$.

Induction and recursion are two faces of the same coin.
**Lfp.thy for Inductive Definitions**

Least fixpoints are for building inductive definitions of sets in a definitional way: \( S := lfp \ F \).

This is obviously well-defined, so why this fuss about monotonicity and Tarski?
Least fixpoints are for building inductive definitions of sets in a definitional way: $S := lfp \ F$.

This is obviously well-defined, so why this fuss about monotonicity and Tarski?

Tarski allows us to exploit the equation $lfp \ f = f(lfp \ f)$ in proofs about $S$! That’s what $lfp$ is all about.
Example (Revisited)

The set of all finite subsets of a set $A$:

$$Fin \ A = lfp \ F$$

where $F = \lambda X.\{{}\} \cup \bigcup x \in A.((\text{insert } x) \ ' \ X)$. 
Example (Revisited)

The set of all finite subsets of a set $A$:

$$Fin\ A = lfp\ F$$

where $F = \lambda X.\ \emptyset \cup \bigcup x \in A.\ (\{\{\}\} \cup \{\{x\} \cup ((\text{insert } x) \ ' \ X)\}).$

Thus we can do using $lfp$ what we would have wanted to do using $Y$.

To show: $F$ is monotone!

In the Isabelle library, this is done a bit differently.

There will be an exercise on this.
The Package for Inductive Sets

Since monotonicity proofs can be automated, Isabelle has special proof support for inductive definitions. Example:

```plaintext
consts Fin :: 'a set => 'a set set
inductive "Fin(A)"
  intrs
    emptyI  "{} : Fin(A)"
    insertI "[| a: A; b: Fin(A) |] ==> insert a b : Fin(A)"
```

**Translated** into expression using *lfp*.

Package relies on **proven lemma lfp_unfold**.
Technical Support for Inductive Definitions

Support important in practice since many constructions are based on inductively defined sets (datatypes, . . .). Support provided for:

- Automatic proof of monotonicity
- Automatic proof of induction rule, for example:

\[
\begin{align*}
[xa \in Fin A; P \{\}] \land a b. [a \in A; b \in Fin A; P b] & \implies P (insert a b) ] \implies P xa
\end{align*}
\]

This works also for mutually recursive definitions, co-inductive definitions, . . .
Example: Program Semantics

This is an Isabelle/HOL add-on: Can reason about programming languages in Isabelle/HOL.

In imperative programming, program statements such as assignments or if-statements transform a program state (which consists of the current values of the program variables) into a new state.

This transformation is defined inductively.

We will later study a small imperative programming language.
Summary on Least Fixpoints

We are interested in recursion because \textit{inductively defined sets} and \textit{recursively defined functions} are solutions to recursive equations.

We cannot have general fixpoint operator \( Y \), but we have, by \textit{conservative extension}, least fixpoints for \textit{defining sets}.

There is an induction scheme (lfp induction) for proving theorems about an inductively defined set.

Restriction of \( F \) to \textit{set type} \((\alpha \text{ set} \rightarrow \alpha \text{ set})\) means that least fixpoints are not generally suitable for defining functions . . .
More Detailed Explanations
Defining \textit{fac}

In the following explanations, any constants like 1 or + or \texttt{if-then-else} are intended to have their usual meaning.

A \textit{fixpoint combinator} is a function $Y$ that returns a fixpoint of a function $F$, i.e., $Y$ must fulfill the equation $YF = F(YF)$. Doing $\lambda$-abstraction over $F$ on both sides and $\eta$-conversion (backwards) on the left-hand side, we have

$$Y = \lambda F.F(YF)$$

This is a recursive equation. We will now demonstrate how a definition of a function \textit{fac} (factorial) using a recursive equation can be transformed to a definition that uses $Y$ instead of using recursion directly.

In a functional programming language we might define

\[
fac \ n = (\textbf{if} \ n = 0 \ \textbf{then} \ 1 \ \textbf{else} \ n \times fac \ (n - 1)).
\]
We now massage this equation a bit. Doing $\lambda$-abstraction on both sides we get

$$\lambda n. \text{fac} \ n = (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } n \ast \text{fac}(n - 1))$$

which is the $\eta$-conversion of

$$\text{fac} = (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } n \ast \text{fac}(n - 1))$$

which in turn is a $\beta$-reduction of

$$\text{fac} = ((\lambda f. \lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } n \ast f(n - 1)) \text{ fac}) \quad (3)$$

We are looking for a solution to (3). We abbreviate the underlined expression by $Fac$. We claim $\text{fac} = Y \text{Fac}$, i.e., it is a solution to (3).
Simply replacing $\text{fac}$ with $Y \ Fac$ in (3) we get

$$Y \ Fac = Fac \ (Y \ Fac)$$

which holds by the definition of $Y$.

Thus we see that a recursive definition of a function can be transformed so that the function is the fixpoint of an appropriate functional (a function taking a function as argument).
**Defining** $Fin\ A$

We want to define a function $Fin$ such that $Fin\ A$ is the set of all finite subsets of $A$.

How do you construct the set of all finite subsets of $A$? The following pseudo-code suggests what you have to do:

\[
S := \{\{\}\}; \\
forever \text{ do} \\
\quad \text{foreach } a \in A \text{ do} \\
\quad \quad \text{foreach } B \in S \text{ do} \\
\quad \quad \quad \text{add } (\{a\} \cup B) \text{ to } S \\
\quad \text{od} \text{ od} \text{ od}
\]

This means that you have to add new sets forever (however, when you actually do this construction for a **finite** set $A$, it will indeed reach a
fixpoint, i.e., adding new sets won’t change anything).
Generally (even if $A$ is infinite), $\text{Fin } A$ is a set such that adding new sets as suggested by the pseudo-code won’t change anything. Written as recursive equation:

$$\text{Fin } A = \{\{}\} \cup \bigcup x \in A.((\text{insert } x) '\ (\text{Fin } A))$$

Recall that ‘ is nice syntax for image, defined in Set.thy.

The above is a $\beta$-reduction of

$$\text{Fin } A = (\lambda X. \{\{}\} \cup \bigcup x \in A.((\text{insert } x) '\ X)) (\text{Fin } A) \quad (4)$$

We are looking for a solution to (4). We abbreviate the underlined expression by $FA$. We claim

$$\text{Fin } A = Y \ FA,$$
i.e., it is a solution to (4). Simply replacing $Fin\ A$ with $Y\ FA$ in (4) we get

$$Y\ FA = FA(Y\ FA),$$

which holds by the definition of $Y$.

You should compare this to what we said about $fac$. Note that in this example, there is no such thing as a recursive call to a “smaller” argument as in $fac$ example.
Lfp.thy and Lfp.ML

These files should be contained in your Isabelle distribution. In Freiburg they are in

/usr/local/share/provers/Isabelle/src/HOL/
Algorithmic Version of \( \text{lfp} \)

The theorem

\[
(\forall S. f(\bigcup S) = \bigcup (f \; \cdot \; S)) \implies \bigcup_{n \in \mathbb{N}} (f^n\{\}) = \text{lfp } f
\]

says that under a certain condition, \( \text{lfp } f \) can be computed by applying \( f \) to the empty set over and over again:

- although the expression uses the union over all natural numbers, which is an infinite set, this can sometimes effectively be computed. Under certain conditions, there exists a \( k \) such that \( f^k \{\} = f^{k+1}\{\} \).
- Even if \( \bigcup n \in \mathbb{N}.f^n\{\} \) cannot be effectively computed, it can still be approximated: for any \( k \), we know that \( \bigcup i \leq k.f^i \{\} \subseteq \bigcup n \in \mathbb{N}.f^n \{\} \).
Monotone Functions

A function $f$ is monotone w.r.t. a partial order $\leq$ if the following holds: $A \leq B$ implies $f(A) \leq f(B)$.

In particular, we consider the order given by the subset relation.
“The Set” $\alpha$

$\alpha$ is not a set but a type (variable). But we can consider the set of all terms of that type (UNIV of type $\alpha$).

The polymorphic constant UNIV was defined in Set.thy. UNIV of type $\tau$ set is the set containing all terms of type $\tau$. 
Three Circles?

In general, needless to say, there could be any number of such sets, but the picture is to be understood in the sense that the three circles are all the sets $A$ with the property $fA \subseteq A$. 
Different Phrasings

The theorem is phrased a bit differently in the “mathematical” version we give here and in the Isabelle version (see Lfp.ML). This is convenient for the graphical illustration of the proof.

The “mathematical phrasing” corresponding closely to the Isabelle version would be the following:

**Theorem 3 (Induct (alternative)):**

If

- $a \in \text{lfp } f$, and
- $f$ is monotone, and
- for all $x$, $x \in f(\text{lfp } f \cap \{x \mid P x\})$ implies $P x$

then $P a$ holds.

Other phrasings, which may help to get some intuition about the
theorem:

**Theorem 4 (Induct (alternative)):**

If

- $a \in \text{lfp } f$, and
- $f$ is monotone, and
- $f(\text{lfp } f \cap \{x \mid P x\}) \subseteq \{x \mid P x\}$

then $P a$ holds.

**Theorem 5 (Induct (alternative)):**

If

- $f$ is monotone, and
- $f(\text{lfp } f \cap \{x \mid P x\}) \subseteq \{x \mid P x\}$

then for all $x$ in $\text{lfp } f$, we have $P x$. 

[Back to main referring slide]
Detail on Monotonicity

\[ \text{lfp } f \cap \{x \mid P x\} \subseteq \text{lfp } f, \text{ so by monotonicity,} \]
\[ f(\text{lfp } f \cap \{x \mid P x\}) \subseteq f(\text{lfp } f). \]
Use of Claim 1

We have just seen \( f(\text{lfp } f \cap \{ x \mid P x \}) \subseteq \text{lfp } f \cap \{ x \mid P x \} \).

By **Claim 1** (setting \( A := \text{lfp } f \cap \{ x \mid P x \} \)), this implies \( \text{lfp}(f) \subseteq \text{lfp } f \cap \{ x \mid P x \} \).
Antisymmetry of $\subseteq$

We have $\text{lfp } f \cap \{ x \mid P \ x \} \subseteq \text{lfp}(f)$ and $\text{lfp}(f) \subseteq \text{lfp } f \cap \{ x \mid P \ x \}$, and so $\text{lfp}(f) = \text{lfp } f \cap \{ x \mid P \ x \}$ by the antisymmetry of $\subseteq$. 

Back to main referring slide
Recursion in a Definitional Way

Recall why we were interested in fixpoints.

The problem with $Y$ is that it leads to inconsistency (and of course, the definition of $Y$ is not a constant definition/conservative extension.).

The definition of $lfp$ is conservative.

And in appropriate situations, it can be used to define recursive functions.

Compared to $Y$, the type of $lfp$ is restricted.

This restriction means that there is no obvious way to use $lfp$ for defining recursive numeric functions such as $fac$. 

Back to main referring slide
Finite Sets in Isabelle

Above, we defined the set of finite subsets of a set $A$. Alternatively, one could define “the set of all finite sets whose elements have type $\tau$”. In this case, no fixed set $A$ is involved, and it is closer to what actually happens in Isabelle. In `Finite_Set.thy` a constant $\text{Finites}$ is defined. It has polymorphic type $\alpha \text{ set set}$. We have $A \in \text{Finites}$ if and only if $A$ is a finite set. However, it would be wrong to think of $\text{Finites}$ as one single set that contains all finite sets. Instead, for each $\tau$, there is a polymorphic instance of $\text{Finites}$ of type $\tau \text{ set set}$ containing all finite sets of element type $\tau$.

In `Finite_Set.thy` we find the lines
inductive "Finites"

intros

emptyI [simp, intro!]: "{} : Finites"
insertI [simp, intro!]: "A : Finites ==> insert a A : Finites"

The Isabelle mechanism of interpreting the keyword inductive translates this into the following definition: \( Finites = \text{lfp} \ G \) where

\[
G \equiv \lambda S. \{ x | x = \{ \} \lor (\exists A \ a. x = \text{insert} \ a \ A \land A \in S) \}\]

You can see this by typing in your proof script:

```isabelle
open Finites;
defs;
```
Talking (ML-)technically, Finites is a structure (module), and defs is a value (component) of this structure.

As a sanity-check, consider the type of this expression. The expression \( \text{insert } a \ A \) forces \( A \) to be of type \( \tau \) set for some \( \tau \) and \( a \) to be of type \( \tau \). Next, \( \text{insert } a \ A \) is of type \( \tau \) set, and hence \( x \) is also of type \( \tau \) set.

Moreover, the expression \( A \in S \) forces \( S \) to be of type \( \tau \) set set. The expression \( \{ x \mid x = \{} \lor (\exists A \ a. \ x = \text{insert } a \ A \land A \in S) \} \) is of type \( \tau \) set set. Next, \( G \) is of type \( \tau \) set set \( \to \) \( \tau \) set set, and so finally, Finites is of type \( \tau \) set set. But actually, since \( \tau \) is arbitrary, we can replace it by a type variable \( \alpha \).

Note that there is a convenient syntactic translation

\[
\text{translations "finite } A\text{" }=\text{ "}A : \text{Finites}\text{"}
\]

When does Isabelle generate ML-structures, and what are the names of
those structures?
This question is highly Isabelle-technical, related to different formats used for writing theory files, which is in turn partly due to mere historic reasons.
It used to be the case that for a theory file called $F$.thy, a structure $F$ would be generated. Certain keywords in $F$.thy such as inductive, recursive, and datatype, would trigger the creation of substructures, so for example inductive $I$ would call for the creation of a substructure $I$.

For a newer format of theory files, this is no longer the case. The treatment of the keyword constdefs, followed by the declaration and definition of a constant $C$, also depends on the format used for writing theory files.

- Sometimes (when an older format is used), it will automatically
generate a \texttt{thm} called \texttt{C\_def} which is the definition of \texttt{C}.

- Sometimes (when a newer format is used), it will insert the definition of \texttt{C} into a database which can be accessed by a function called \texttt{thm} taking a string as argument. In this case, not \texttt{C\_def} would be the definition of \texttt{C}, but rather

\begin{verbatim}
 thm "C\_def"
\end{verbatim}

You should be aware of such problems, but we do not treat them in this course.
Finite_Set.thy
This file should be contained in your Isabelle distribution. In Freiburg it is
/usr/local/share/provers/Isabelle/src/HOL/Finite_Set.thy
$F$ is monotone

This proof is of course done in Isabelle.
Induction for Finite Sets

The theorem

\[
[\forall a \in \text{FinA}; \ P \ \{\}; \ \land \ ab. [a \in \ A; \ b \in \ \text{FinA}; \ P \ b] \implies P \ (\text{insert} \ a \ b)] \implies P \ xa
\]

is an instance of the general induction scheme. That is to say, if we take the general induction scheme \texttt{lfp_induct}

\[
[\forall a \in \text{lfp} \ f; \ \text{mono} \ f; \ \land \ x. x \in f(\text{lfp} \ f \cap \{x. P \ x\}) \implies P \ x] \implies P \ a
\]

and instantiate \( f \) to \( \lambda X.\{\{\}\} \cup \bigcup x \in A.((\text{insert} \ x) \ ' X) \) then some massaging using the definitions will give us the first theorem.

Note here that monotonicity has disappeared from the assumptions. This is because the monotonicity of \( F \) is shown by Isabelle once and for all.
This is one aspect of what we mean by special proof support for inductive definitions.

The least fixpoint of the functional is $Fin \ A$ (the set of finite subsets of $A$) in this case.
Mutually Recursive Definitions

Two functions $f$ and $g$ are mutually recursive if $f$ is defined in terms of $g$ and vice versa.
Co-induction

Co-induction is a construction analogous to induction but using greatest fixpoints.
Well-Founded Recursion
The Roadmap

We are still looking at how the different parts of mathematics are encoded in the Isabelle/HOL library.

- Orders
- Sets
- Functions
- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes
The Roadmap

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- Arithmetic
- Datatypes
Well-Founded Recursion

After least fixpoints, well-founded recursion is our second concept of recursion (and fixpoint combinator).

Idea: Modeling “terminating” recursive functions, i.e. recursive definitions that use “smaller” arguments for the recursive call.
Prerequisite: Relations

We need some standard operations on binary relations (sets of pairs), such as converse, composition, image of a set and a relation, the identity relation, . . .
These are provided by Relation.thy.
Relation.thy (Fragment)

constdefs

converse :: "('a * 'b) set => ('b * 'a) set"
"r^-1 == {(y, x). (x, y):r}"

rel_comp :: "[(b * 'c) set, ('a * 'b) set] => ('a * 'c) set"
"r O s == {(x,z). EX y. (x, y):s & (y, z):r}"

Image :: "[(a * 'b) set, 'a set] => 'b set"
"r 'v' s == {y. EX x:s. (x,y):r}"

Id :: "('a * 'a) set"
"Id == {p. EX x. p = (x,x)}"

Somewhat similar to Fun.thy.
Prerequisite: Closures

We need the transitive, as well as the reflexive transitive closure of a relation.
These are provided by Transitive_Closure.thy.
How would you define those inductively, ad-hoc?
Transitive Closure.thy (Fragment)

consts
  rtrancl :: "('a * 'a) set => ('a * 'a) set"
  ("(_^*)" [1000] 999)

inductive "r^*"

intros
  rtrancl_refl [...]: "(a, a) : r^*"
  rtrancl_into_rtrancl [...]: "(a, b) : r^* ==> (b, c) : r ==> (a, c) : r^*"
Transitive_Closure.thy (Fragment Cont.)

consts
 trancl :: "('a * 'a) set => ('a * 'a) set"
     "(_^+)" [1000] 999

inductive "r^+"
 intros
 r_into_trancl [...] : "(a, b) : r ==> 
     (a, b) : r^+
 trancl_into_trancl [...] : "(a, b) : r^+ ==> 
     (b, c) : r ==> (a,c) : r^+"
Well-Founded Orderings

Defined in Wellfounded_Recursion.thy.

Wellfounded_Recursion = Transitive_Closure + constdefs

\(\text{constdefs}\\
\text{wf} :: \text{('a} \times \text{'a}) \text{set} \Rightarrow \text{bool}\\
\text{"wf}(r) = (!P. (!x. (!y. (y,x):r \rightarrow P(y)) \\
\quad \rightarrow P(x)) \rightarrow (!x. P(x)))"\\
\)

What does this mean?
Well-Founded Orderings

Defined in *Wellfounded_Recursion.thy*.

Wellfounded_Recursion = Transitive_Closure + constdefs

\[
\text{wf} :: \text{"(}'a \ast 'a\text{) set \Rightarrow bool"}
\]

\[
\text{"wf}(r) = (\forall P. (\forall x. (\forall y. (y,x):r \rightarrow P(y))
\rightarrow P(x)) \rightarrow (\forall x. P(x)))\]

What does this mean? A relation $r$ is well-founded if well-founded (Noetherian) induction based on $r$ is a valid proof scheme.

Example: Is $\emptyset$ well-founded?
Intuition of Well-Foundedness

Intuition of $wf$: All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

- Not symmetric:
Intuition of Well-Foundedness

Intuition of $wf$: All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

- Not symmetric: $(x, y) \in r \rightarrow (y, x) \notin r$?
Intuition of Well-Foundedness

Intuition of $wf$: All descending chains are finite.
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- Not symmetric: $(x, y) \in r \rightarrow (y, x) \notin r$?
Intuition of Well-Foundedness

Intuition of $wf$: All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

- Not symmetric: $(x, y) \in r \rightarrow (y, x) \not\in r$?
- No cycles:
Intuition of Well-Foundedness

Intuition of \(wf\): All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

- Not symmetric: \((x, y) \in r \rightarrow (y, x) \notin r\)?
- No cycles: \((x, x) \notin r^+\)?
Intuition of Well-Foundedness

Intuition of \( wf \): All descending chains are finite.

But: Cannot express infinity; must look for alternatives.

- Not symmetric: \( (x, y) \in r \rightarrow (y, x) \notin r \)?
- No cycles: \( (x, x) \notin r^+ \)?
Intuition of Well-Foundedness

Intuition of $wf$: All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

- Not symmetric: $(x, y) \in r \rightarrow (y, x) \notin r$?
- No cycles: $(x, x) \notin r^+$?
- $r$ has minimal element:
Intuition of Well-Foundedness

Intuition of \( wf \): All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

- Not symmetric: \( (x, y) \in r \rightarrow (y, x) \notin r \)?
- No cycles: \( (x, x) \notin r^+ \)?
- \( r \) has minimal element: \( \exists x. \forall y. (y, x) \notin r \)?

Note: Trivial for \( r = \emptyset \).
Intuition of Well-Foundedness

Intuition of \( wf \): All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

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  Note: Trivial for $r = \emptyset$.
- Any subrelation must have minimal element:
Intuition of Well-Foundedness

Intuition of $wf$: All descending chains are finite.
But: Cannot express infinity; must look for alternatives.

- Not symmetric: $(x, y) \in r \rightarrow (y, x) \not\in r$?
- No cycles: $(x, x) \not\in r^+$?
- $r$ has minimal element: $\exists x. \forall y. (y, x) \not\in r$?
  Note: Trivial for $r = \emptyset$.
- Any subrelation must have minimal element:
  $\forall p.p \subseteq r \rightarrow \exists x. \forall y. (y, x) \not\in p$?
Intuition of Well-Foundedness

Intuition of \( wf \): All descending chains are finite.

But: Cannot express infinity; must look for alternatives.

- Not symmetric: \( (x, y) \in r \rightarrow (y, x) \notin r \)?
- No cycles: \( (x, x) \notin r^+ \)?
- \( r \) has minimal element: \( \exists x. \forall y. (y, x) \notin r \)?
  Note: Trivial for \( r = \emptyset \).
- Any subrelation must have minimal element:
  \( \forall p.p \subseteq r \rightarrow \exists x. \forall y. (y, x) \notin p \)? “Minimal element” badly formalized (already in previous point).
The Characterisation

All these attempts are just necessary but not sufficient conditions for well-foundedness.

Here is a characterization:

\[(\forall Q. x \in Q \rightarrow (\exists z \in Q. \forall y. (y, z) \in r \rightarrow y \notin Q))\]

Here is an alternative characterization (exercise):

\[(\forall r. r \neq \emptyset \land r \subseteq p \rightarrow (\exists x \in \text{Domain } r. \forall y. (y, x) \notin r))\]

Let’s see some theorems to confirm our intuition, including the statements just shown.
A Theorem on the Empty Set

\[ \text{wf}_\text{empty} \quad \text{wf} \ \{\} \]

Proof sketch:
\[ \text{wf}_\text{empty}: \text{ substitute } r \text{ into definition, simplify.} \]
A Theorem for Induction

By massage of the definition of well-foundedness

$$\forall P. (\forall x. (\forall y. (y, x) \in r \rightarrow P y) \rightarrow P x) \rightarrow (\forall x. P x)$$

one obtains the theorem \texttt{wf_induct}

$$[\text{wf } r; \forall x. \forall y. (y, x) \in r \rightarrow P y \Rightarrow P x] \Rightarrow P a.$$

This is a form suitable for doing induction proofs in Isabelle.
**Induction Theorem as Proof Rule**

The Isabelle theorem `wf_induct`

\[
[wf \ r; \ \bigwedge x. \forall y. (y, x) \in r \rightarrow P \ y \Longrightarrow P \ x] \Longrightarrow P \ a.
\]

as proof rule:

\[
\frac
{\forall y. (y, x) \in r \rightarrow P \ y}
{wf \ r \quad \vdots \quad P \ x}
{P \ a \quad \textbf{wf\_induct}}
\]
A Theorem on Antisymmetry

\( \text{wf\_not\_sym} \ [\text{wf } r; (a, x) \in r] \implies (x, a) \notin r \)

Proof sketch:

\[
\begin{align*}
[\forall y. (y, x) \in r \rightarrow (\forall z. (y, z) \in r \rightarrow (z, y) \notin r)] \\
\text{wf } r & \quad \forall z. (x, z) \in r \rightarrow (z, x) \notin r \\
\end{align*}
\]

\[
\forall z. (a, z) \in r \rightarrow (z, a) \notin r \qquad \text{wf\_induct}
\]

The induction part needs classical reasoning. We will now give it at a level of detail that shows the essential reasoning but hides all the \textit{swapping} involved in the Isabelle proof. A variation will be done as exercise.
The Induction Part in More Detail

\[ \forall y. (y, x) \in r \rightarrow (\forall z. (y, z) \in r \rightarrow (z, y) \notin r) \]
\[ \frac{(w, x) \in r \rightarrow (\forall z. (w, z) \in r \rightarrow (z, w) \notin r)}{(w, x) \notin r \lor (\forall z. (w, z) \in r \rightarrow (z, w) \notin r)} \equiv \phi \]

"(c)" stands for classical reasoning steps.

\[ \phi \quad [(w, x) \notin r]^1 \quad \text{impl}^2 \]
\[ \frac{(x, w) \notin r}{(x, w) \in r \rightarrow (w, x) \notin r} \]
\[ \frac{\forall z. (w, z) \in r \rightarrow (z, w) \notin r}{\forall z. (z, w) \in r \rightarrow (w, z) \notin r} \]
\[ \frac{\forall z. (z, w) \in r \rightarrow (w, z) \notin r}{\forall z. (x, z) \in r \rightarrow (z, x) \notin r} \]
\[ \frac{\forall z. (x, z) \in r \rightarrow (z, x) \notin r}{\forall z. (x, z) \in r \rightarrow (z, x) \notin r} \]

\[ \forall z. (x, z) \in r \rightarrow (z, x) \notin r \]
\[ \forall z. (x, z) \in r \rightarrow (z, x) \notin r \]
\[ \forall z. (x, z) \in r \rightarrow (z, x) \notin r \]
\[ \forall z. (x, z) \in r \rightarrow (z, x) \notin r \]
Theorems on Absence of Cycles

\[ \text{wf\_not\_refl} \quad \text{wf } r \implies (a, a) \notin r \]
\[ \text{wf\_trancl} \quad \text{wf } r \implies \text{wf}(r^+) \]
\[ \text{wf\_acyclic} \quad \text{wf } r \implies \text{acyclic } r \]

\[(\text{acyclic } r \equiv \forall x. (x, x) \notin r^+)\]

Proof sketch:
- \text{wf\_not\_refl}: Corollary of \text{wf\_not\_sym}.
- \text{wf\_trancl}: Uses induction.
- \text{wf\_acyclic}: Apply \text{wf\_not\_refl} and \text{wf\_trancl}

Ergo: Definition of \text{wf} really meets our intuition of “no cycles”.
Another Theorem (“Exists Minimal Element”) 

\[ \text{wf} \text{minimal} \quad \text{wf} r \iff \exists x. \forall y. (y, x) \notin r^+ \]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \notin r^+) \):

\[
\begin{align*}
\text{wf}(r) & \\
\hline
\phi & \text{wf\_minimal}
\end{align*}
\]

This is what we must construct.
Another Theorem ("Exists Minimal Element")

\[ \text{wf\_minimal} \quad \text{wf} \ r \implies \exists x. \forall y. (y, x) \notin r^+ \]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \notin r^+) \):

\[
\forall w. (w, v) \\
\in r^+ \rightarrow \phi
\]

\[
\begin{array}{c}
\text{wf}(r) \\
\text{wf}(r^+) \\
\hline
\phi \\
\hline
\end{array}
\]

\[ \text{wf\_induct} \]

Note "special case": \( w \) and \( v \) do not occur in \( \phi \)!
Another Theorem ("Exists Minimal Element")

\[
\text{wf\_minimal} \quad \text{wf} \ r \implies \exists x. \forall y. (y, x) \not\in r^+
\]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \not\in r^+) \):

\[
\forall w. \left( \left( w, v \right) \in r^+ \right) \implies \phi
\]

\[
\begin{array}{c}
\text{wf}(r) \\
\hline
\text{wf}(r^+) \\
\hline
\phi
\end{array}
\]

This is \texttt{wf\_trancl}.
Another Theorem ("Exists Minimal Element")

\[ \text{wf}_{\text{minimal}} \quad \text{wf } r \iff \exists x. \forall y. (y, x) \notin r^+ \]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \notin r^+) \):

\[ \neg \phi \quad \neg \phi \quad \forall w. (w, v) \in r^+ \rightarrow \phi \]

\[
\begin{array}{c}
\text{wf}(r) \\
\text{wf}(r^+) \\
\hline
\hline
\phi \lor \neg \phi \\
\phi \\
\hline
\hline
\phi \\
\hline
\text{disjE} \\
\hline
\text{wf}_{\text{induct}} \\
\phi
\end{array}
\]

We now try a proof by case distinction on \( \phi \).
Another Theorem ("Exists Minimal Element")

\[ \text{wf}_{\text{minimal}} \quad \text{wf } r \implies \exists x. \forall y. (y, x) \not\in r^+ \]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \not\in r^+) \):

\[
\begin{align*}
\neg \phi & \quad \neg \phi \\
\forall w.(w, v) \in r^+ & \to \phi \\
\end{align*}
\]

\[
\begin{array}{c}
\text{wf} (r) \\
\text{wf} (r^+) \\
\text{wf}_\text{induct}
\end{array}
\]

Classical reasoning.

Smaus: CSMR; WS05/06
Another Theorem ("Exists Minimal Element")

\[
\text{wf}_{\text{minimal}} \quad \text{wf } r \implies \exists x. \forall y. (y, x) \not\in r^+
\]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \not\in r^+) \):

\[
\begin{align*}
-\phi & \quad -\phi \\
\therefore \forall x. \exists y. (y, x) \in r^+ & \quad \forall w. (w, v) \in r^+ \rightarrow \phi
\end{align*}
\]

\[
\begin{array}{c}
\text{wf}(r) \\
\text{wf}(r^+)
\end{array}
\quad \text{disjE}
\]

Using some elementary equivalences.
Another Theorem ("Exists Minimal Element")

\[ \text{wf}_{\text{minimal}} \]

\[ \text{wf } r \implies \exists x. \forall y. (y, x) \notin r^+ \]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \notin r^+) \):

\[
\begin{array}{c}
\neg \phi \\
\forall x. \exists y. (y, x) \in r^+ \\
\end{array} \hspace{0.5cm}
\begin{array}{c}
\neg \phi \\
\forall w. (w, v) \in r^+ \rightarrow \phi \\
\end{array}
\]

\[
\frac{\text{wf}(r) \quad \phi \lor \neg \phi \quad \phi}{\text{wf}(r^+) \quad \phi \quad \text{disjE}}
\]

This step works for any \( \phi \). Think semantically or check!
Another Theorem ("Exists Minimal Element")

\[ \text{wf}_{\text{minimal}} \quad \text{wf} \; r \iff \exists x. \forall y. (y, x) \notin r^+ \]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \notin r^+) \):

\[
\begin{array}{c}
\neg \phi \\
\forall x. \exists y. (y, x) \in r^+ \\
\neg \exists w. (w, v) \in r^+ \\
\text{False}
\end{array}
\quad \begin{array}{c}
\forall w. (w, v) \in r^+ \rightarrow \phi \\
\neg \phi \\
\neg \phi \\
\text{False}
\end{array}
\]

\[
\begin{array}{c}
\text{wf}(r) \\
\phi \lor \neg \phi \\
\phi \\
\text{False}
\end{array}
\quad \begin{array}{c}
\text{FalseE} \\
\text{disjE}
\end{array}
\]

It is routine to derive \( \text{False} \).
Another Theorem (“Exists Minimal Element”)

\[ \text{wf}_{\text{minimal}} \quad \text{wf } r \implies \exists x. \forall y. (y, x) \notin r^+ \]

Proof sketch, writing \( \phi \equiv (\exists x. \forall y. (y, x) \notin r^+) \):

\[
\begin{array}{c}
[\neg \phi]^2 \\
\forall x. \exists y. (y, x) \in r^+ \\
\therefore \exists x. \forall y. (y, x) \notin r^+ \\
\end{array}
\]

\[
\begin{array}{c}
[\neg \phi]^2 \\
\forall w. (w, v) \in r^+ \implies \phi \\
\therefore \neg \exists w. (w, v) \in r^+ \\
\end{array}
\]

This completes the proof by case distinction . . .
Another Theorem ("Exists Minimal Element")

$\text{wf\_minimal} \quad \text{wf } r \implies \exists x. \forall y. (y, x) \notin r^+$

Proof sketch, writing $\phi \equiv (\exists x. \forall y. (y, x) \notin r^+)$:

$\text{wf}(r) \quad \phi \lor \neg \phi \quad \phi \lor \neg \phi$

$\phi \lor \neg \phi \quad \neg \exists w. (w, v) \in r^+$

$\phi \lor \neg \phi \quad \text{disj}\text{E}^2$

$\phi \quad \text{wf\_induct}^1$

$\phi \quad \text{disj}\text{E}^2$

$\phi \quad \text{wf\_induct}^1$

$\phi \quad \text{disj}\text{E}^2$

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$\phi \quad \text{disj}\text{E}^2$
Remarks on the Proof

We used an instance of \texttt{wf\_induct}, where we instantiated $x$ by $v$, $y$ by $w$, and $P$ by $\lambda w. (\exists x. \forall y. (y, x) \notin r^+)$. I.e., $\phi$ does not contain the “induction variables” $w$ and $v$.

Still this is a “proper” induction proof: Although $\phi$ does not contain the “induction variables”, the proof does depend on the actual form of $\phi$! (Try doing it without induction . . . )

Scoping of quantifiers (e.g., in general

$(\forall w. (w, v) \in r^+ \rightarrow \phi) \not\equiv (\forall w. (w, v) \in r^+) \rightarrow \phi$) and side conditions are very subtle in this proof. Underlines the importance of machine-checked proofs.
Remarks on $\text{wf}_{\text{minimal}}$

Ergo: Definition of $\text{wf}$ fulfills the condition corresponding to our first attempt of characterizing well-foundedness using minimal elements. However, this formalization had a problem: there could be local minima, and
Remarks on $\text{wf}_{\text{minimal}}$

Ergo: Definition of $\text{wf}$ fulfills the condition corresponding to our first attempt of characterizing well-foundedness using minimal elements. However, this formalization had a problem: there could be local minima, and isolated points are also always minima. In particular, if $r$ is empty, then any element is trivially a minimum.
A Characterization

The theorem \texttt{wf_eq_minimal} is characterization of well-foundedness:

\[
\text{wf } r = (\forall Q. x \in Q \rightarrow (\exists z \in Q. \forall y. (y, z) \in r \rightarrow y \notin Q))
\]

Proof uses \texttt{split =}, \texttt{wf_def}, rest routine.

Ergo: Definition of \texttt{wf} meets textbook definitions "every non-empty set \( Q \) has a minimal element in \( r \)".
A Theorem on Subsets

$$\text{wf\_subset} \quad \left[ \text{wf} \; r; p \subseteq r \right] \implies \text{wf} \; p$$

Proof sketch:

**wf\_subset**: simplification tactic using \texttt{wf\_eq\_minimal}. 
A Theorem on Subrelations

\[ \text{wf}_\text{subrel} \]

\[ \text{wf } r \iff \forall p. p \subseteq r \rightarrow \exists x. \forall y. (y, x) \notin p^+ \]

Proof sketch:

Combine \text{wf}_\text{minimal} and \text{wf}_\text{subset}.

This implies \[ \text{wf } r \iff \forall p. p \subseteq r \rightarrow \exists x. \forall y. (x, y) \notin p. \]

Ergo: Definition of \text{wf} fulfills the condition corresponding to our second attempt of characterizing well-foundedness using minimal elements.
A Theorem on Subrelations

\[
\text{wf} \_ \text{subrel}
\]

\[
\text{wf} \ r \implies \forall p. p \subseteq r \rightarrow \exists x. \forall y. (y, x) \notin p^+
\]

Proof sketch:

Combine \text{wf} \_ \text{minimal} and \text{wf} \_ \text{subset}.

This implies \( \text{wf} \ r \implies \forall p. p \subseteq r \rightarrow \exists x. \forall y. (x, y) \notin p \).

Ergo: Definition of \text{wf} fulfills the condition corresponding to our second attempt of characterizing well-foundedness using minimal elements.

However, this formalization still had a problem: The minimum could be an isolated element, unrelated to the subrelation.
Defining Recursive Functions

Idea of well-founded recursion: Wish to define $f$ by recursive equation $f = e$, e.g.

$$fac = (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } n \times fac(n - 1))$$

Define $F = \lambda f.e$, e.g.

$$Fac = (\lambda fac. \lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } n \times fac(n - 1))$$
Defining Recursive Functions

Idea of well-founded recursion: Wish to define \( f \) by recursive equation \( f = e \), e.g.

\[
\text{fac} = (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } n \times \text{fac}(n - 1))
\]

Define \( F = \lambda f.e \), e.g. \((\alpha\text{-conversion of what you have seen})\)

\[
\text{Fac} = (\lambda f. \lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } n \times f \ (n - 1))
\]

We say: \( F \) is the functional defining \( f \).

Recall that \( Y F \) would solve \( f = e \), but we don’t have \( Y \), so what can we do?
Coherent Functionals

A functional $F$ is coherent w.r.t. $<$ if all recursive calls are with arguments “smaller” than the original argument. This means that if $F$ has the form

$$\lambda f.\lambda n.e'$$

then for any $(f\ m)$ occurring in $e'$, we have $m < n$.

Here $<$ could be any relation (although the idea is that it should be a well-founded ordering).

(Simplification, assumes that recursion is on the first argument of $f$.)

Smaus: CSMR; WS05/06
Using Bad $f$’s

Let $f|_{<a}$ be a function that is like $f$ on all values $< a$, and arbitrary elsewhere. $f|_{<a}$ is an approximation, a “bad” $f$. If $F$ is coherent, then we would expect that for any $a$,

$$f \ a = (F \ f) \ a = (F \ f|_{<a}) \ a. \quad (5)$$

It’s not that we are ultimately interested in constructing such a “bad” $f$, but our formalization of well-founded recursion defines coherence by the fact that one could use such a “bad” $f$, i.e., via (5).
“Bad” $f$’s: Example

Consider $fac$. On the right-hand side, we show one possibility for $fac|_{<4}$:
**cut (in Wellfounded_Recursion.thy)**

constdefs

\begin{align*}
\text{cut} & : \ (('a \Rightarrow 'b) \Rightarrow ('a \times 'a) \text{ set} \Rightarrow \\
& \quad 'a \Rightarrow 'a \Rightarrow 'b \\
\text{cut} f r x &= \\
& \quad (\%y. \text{if} \ (y,x):r \ \text{then} \ f \ y \ \text{else} \ \text{arbitrary})
\end{align*}

\text{cut} f r x \ is \ what \ we \ denoted \ by \ f|_{<x} \ (\text{taking} \ < \ \text{for} \ r). \\
\text{arbitrary} \ is \ defined \ in \ HOL.thy.
**cut (in Wellfounded_Recursion.thy)**

constdefs

\[
\text{cut} :: (\texttt{'}a \Rightarrow \texttt{'}b) \Rightarrow (\texttt{'}a \times \texttt{'}a) \text{ set} \Rightarrow \\
\quad \texttt{'}a \Rightarrow \texttt{'}a \Rightarrow \texttt{'}b
\]

"\text{cut} f r x ==
(\%y. if (y,x):r then f y else arbitrary)"

\text{cut} f r x is what we denoted by \( f|<x \) (taking < for \( r \)).

\text{arbitrary} is defined in \texttt{HOL.thy}.

The function \text{cut} f r x is \textit{unspecified} for arguments \( y \) where \((y, x) \notin r\), but for each such argument, \((\text{cut} f r x) y\) must be the same (in any particular \textit{model}).
Theorems Involving \texttt{cut}

\begin{align*}
\text{cuts_eq} \quad (\text{cut } f \ r \ x \ = \ \text{cut } g \ r \ x) \ = \\
(\forall y. (y, x) \in r \rightarrow f y = g y)
\end{align*}

\begin{align*}
\text{cut_apply} \quad (x, a) \in r \implies \text{cut } f \ r \ a \ x = f x
\end{align*}

Or, using the more intuitive notation:

\begin{align*}
\text{cuts_eq} \quad (f|_{<x} = g|_{<x}) = (\forall y. y < x \rightarrow f y = g y)
\end{align*}

\begin{align*}
\text{cut_apply} \quad x < a \implies f|_{<a} x = f x
\end{align*}
\textbf{wfrec\_rel} (in \textit{Wellfounded\_Recursion.thy})

Auxiliary construction: “approximate” $f$ by a relation \textit{wfrec\_rel $R F$}.

\begin{verbatim}
wfrec\_rel :: "(('a * 'a) set => (('a => 'b) => 'a => 'b) => ('a * 'b) set"
inductive "wfrec\_rel $R F$"
intrs
  wfrec\_I
    "ALL z. (z, x) : R -->
    (z, g z) : wfrec\_rel $R F$
==> (x, F g x) : wfrec\_rel $R F"
\end{verbatim}
**wfrec_rel Explained**

\[ \forall z. (z, x) \in R \rightarrow (z, g z) \in \text{wfrec}_R F \implies (x, F g x) \in \text{wfrec}_R F \]

- For \( R \) and \( F \) arbitrary, \( \text{wfrec}_R F \) is defined but we wouldn’t want to know what it is.
- But if \( R \) is well-founded and \( F \) is coherent, \( \text{wfrec}_R F \) defines a recursive “function”.

Try to show that \((4, 24) \in (\text{wfrec}_R ' < ' \text{Fac})\).

Now let us really turn \( \text{wfrec}_R F \) into a function . . .
**wfrec (in Wellfounded_Recursion.thy)**

\[ \text{wfrec :: 'a set => ('a => 'b) => 'a => 'b} \]
\[ \text{wfrec R F == \%x. THE y.} \]
\[ (x, y) : \text{wfrec}_\text{rel} R (\%f x. F (cut f R x) x) \]

**THE\(x. P x\)** picks the unique \(a\) such that \(P a\) holds, if it exists. We don’t care what it does otherwise (see HOL.thy).
**wfrec Explained**

\[
wfrec \, RF \equiv \\
\lambda x. \text{THE} \, y. (x, y) \in \text{wfrec}_\text{rel} \, R \left( \lambda f x. F \left( \text{cut} \, f \, R \, x \right) \, x \right)
\]

We don’t care what this means for arbitrary \( R \) and \( F \). But if \( R \) is well-founded and \( F \) is coherent, then

\[
F \left( \text{cut} \, f \, R \, x \right) \, x = F \, f \, x \quad \text{(by (5))},
\]

and so

\[
\lambda f x. F \left( \text{cut} \, f \, R \, x \right) \, x = F,
\]

and so

\[
\lambda x. \text{THE} \, y. (x, y) \in \text{wfrec}_\text{rel} \, R \left( \lambda f x. F \left( \text{cut} \, f \, R \, x \right) \, x \right)
\]

is the function defined by \( \text{wfrec}_\text{rel} \, RF \) in the obvious way.

\( wfrec \, RF \) is the recursive function defined by functional \( F \).
The “Fixpoint” Theorem

\[ \text{wfrec } \quad \text{wf } r \implies \text{wfrec } r \ H \ a = H(\text{cut}(\text{wfrec } r \ H) \ r \ a) \ a \]

Note that \text{wfrec} is used here both as a name of a constant (defined above) and a theorem.

So if \( r \) is well-founded and \( H \) is coherent, we have

\[ \text{wfrec } r \ H \ a = H(\text{wfrec } r \ H) \ a \]

Theorem states that \text{wfrec} is like a fixpoint combinator (disregarding the additional argument \( r \)).

Thus we can do using \text{wfrec} what we would have liked to do using \( Y \).
Example for \textit{wfrec}: Natural Numbers

The constant \textit{wfrec} provides the mechanism/support for defining recursive functions. We illustrate this using \texttt{nat}, the type of natural numbers (\textit{pretending we have it}). \textit{wfrec} is applied to a well-founded order and a functional to define a function.
Example for \textit{wfrec}: Natural Numbers

The constant \textit{wfrec} provides the mechanism/support for defining recursive functions. We illustrate this using \texttt{nat}, the type of natural numbers (pretending we have it). \textit{wfrec} is applied to a well-founded order and a functional to define a function.

First, define predecessor relation:

\begin{verbatim}
constdefs
  pred_nat :: "(nat * nat) set"
  pred_nat_def "pred_nat == {(m,n). n = Suc m}"
\end{verbatim}

How would you define addition or subtraction?
Defining Division and Modulus

\[
div :: ['a::div, 'a] => 'a \quad (\text{infixl} 70)
\]
\[
"m \ div \ n == \text{wfrec} \ (\text{pred_nat}^+) \\
(\%f \ j. \ \text{if} \ j < n \ | \ n = 0 \ \text{then} \ 0 \ \text{else} \ \text{Suc} \ (f \ (j-n))) \ m"
\]

\[
mod :: ['a::div, 'a] => 'a \quad (\text{infixl} 70)
\]
\[
"m \ mod \ n == \text{wfrec} \ (\text{pred_nat}^+) \\
(\%f \ j. \ \text{if} \ j < n \ | \ n = 0 \ \text{then} \ j \ \text{else} \ f \ (j-n)) \ m"
\]

Here, \texttt{div} is a syntactic class for which division is defined (don’t worry about it). We \textbf{know how to define }—. The functions are recursive in one argument (\textit{just like add}).
Theorems of the Example

**wf_pred_nat**  \( \text{wf pred_nat} \)

**mod_if**

\[
m \mod n = \begin{cases} 
   m & \text{if } m < n \\
   (m - n) \mod n & \text{else}
\end{cases}
\]

**div_if**

\[
0 < n \implies m \div n = \begin{cases} 
   0 & \text{if } m < n \\
   \text{Suc}((m - n) \div n) & \text{else}
\end{cases}
\]
Theorems of the Example

\texttt{wf\_pred\_nat} \quad \texttt{wf\ pred\_nat}

\texttt{mod\_if} \quad m \mod n =
\quad (\textit{if} \ 0 < n \ \textit{then} \ m \ \textit{else} \ (m - n) \mod n)

\texttt{div\_if} \quad 0 < n \implies m \div n =
\quad (\textit{if} \ 0 < n \ \textit{then} \ 0 \ \textit{else} \ \texttt{Suc}((m - n) \div n))

This is very similar to functional programming code and hence lends itself to real \textbf{computations} (rewriting), as opposed to only doing \textbf{proofs}.
Conclusion on Well-founded Recursion

Well-founded recursion allows us to define recursive functions in HOL and thus reason about computations. But: We have used the THE operator (similar to the $\epsilon$-operator): it is not clear that there is always an effective way to compute the recursive functions.
Conclusion on Well-founded Recursion

Well-founded recursion allows us to define recursive functions in HOL and thus reason about computations. But: We have used the THE operator (similar to the ϵ-operator): it is not clear that there is always an effective way to compute the recursive functions.

It is not clear that we can actually do computations. This is only possible in particular cases, where we derived recursive theorems that can be used for rewriting just like in a functional programming language.

HOL is a logic, not a programming language.
Isabelle Package for Primitive Recursion

For primitive recursion, finding a well-founded ordering is simple enough for automation!
Isabelle Package for Primitive Recursion

For primitive recursion, finding a well-founded ordering is simple enough for automation!

Examples (use \texttt{nat} and \texttt{case}-syntax): \ldots
Recursion and Arithmetic

primrec
  add_0:   "0 + n = n"
  add_Suc: "Suc m + n = Suc (m + n)"

primrec
  diff_0:  "m - 0 = m"
  diff_Suc: "m - Suc n =
             (case m - n of 0 => 0 | Suc k => k)"

primrec
  mult_0:  "0 * n = 0"
  mult_Suc: "Suc m * n = n + (m * n)"
Conclusion on Recursion and Induction

We are interested in recursion because inductively defined sets and recursively defined functions are solutions to recursive equations.

We cannot have general fixpoint operator $Y$, but we have, by conservative extension:

- Least fixpoints for defining sets;
- well-founded orders for defining functions.

Both concepts come with induction schemes (lfp induction and definition of well-foundedness) for proving properties of the defined objects.
Conclusion on Recursion and Induction

Summary: Proof Support

The methodological overhead can be faced by powerful mechanical support, since many proof-tasks are routine. Isabelle offers extensibility for such routine task constructions.
More Detailed Explanations
Packages Rely on Lemmas

If you look around in the ML-files of the Isabelle/HOL library, you might not find any uses of `lfp_unfold`, so you may wonder: why is it important then? But you must bear in mind that the package for inductive sets relies on these lemmas.

This is a general insight about proven results in the library: Even though you might not find them being used in other ML-files, special packages of Isabelle/HOL might use those results.
More Detailed Explanations

Relation.thy
This file should be contained in your Isabelle distribution. In Freiburg it is
/usr/local/share/provers/Isabelle/src/HOL/Relation.thy
Wellfounded_Recursion.thy
This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/
Wellfounded_Recursion.thy

but in older versions it used to be called

/usr/local/share/provers/Isabelle/src/HOL/WF.thy
Transitive_Closure.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/
Transitive_Closure.thy
Defining $r^*$ and $r^+$

$r^*$ is the smallest set such that:

- $Id \subseteq r^*$;
- if $r' \subseteq r^*$ then $r' \cup r \circ r' \subseteq r'$.

Or, in line with the schema for inductive definitions:

- $\emptyset \subseteq r^*$;
- if $r' \subseteq r^*$ then $(\lambda s. Id \cup (r \circ s))r' \subseteq r^*$.

The latter form corresponds to the definition in Transitive_Closure.thy.

The definition of $r^+$ is similar.
One Way of Understanding $wf$

For a moment, forget everything you have ever heard about proofs using induction! The definition of $wf$ has the form

$$wf(r) \equiv \forall P.\phi(r, P) \rightarrow \forall x.P(x)$$

That is, it says: a relation $r$ is well-founded if a certain scheme $\phi$ can be used to show a property $P$ that holds for all $x$.

By the fact that this is a constant definition (conservative extension), it is immediately clear that this gives us a correct method of proving $\forall x.P(x)$. To prove $\forall x.P(x)$ for some given $P$, find some $r$ such that $\forall P.\phi(r, P) \rightarrow \forall x.P(x)$ holds, and show $\phi(r, P)$.

Once again, this method is correct regardless of what $\phi$ is. Forget about induction!
But how is that possible? How is it ensured that only true statements can be proven, if the method is correct for any old $\phi$? The point is this: The method is correct in principle, but it will typically not work unless $\phi$ is something sensible, e.g. an induction scheme as in the actual definition of $wf$. It will not work simply because we will fail to show either $\forall P. \phi(r, P) \rightarrow \forall x. P(x)$ or $\phi(r, P)$. 
Is $\emptyset$ well-founded?

The definition of $wf$ is:

$$wf(r) \equiv (\forall P. (\forall x. (\forall y. (y,x) \in r \rightarrow P(y)) \rightarrow P(x)) \rightarrow (\forall x. P(x)))$$
Is $\emptyset$ well-founded?

The definition of $wf$ is:
Let’s instantiate $r$ to $\emptyset$.

$$wf(\emptyset) \equiv (\forall P. (\forall x. (\forall y. (y, x) \in \emptyset \rightarrow P(y)) \rightarrow P(x)) \rightarrow (\forall x. P(x)))$$
Is $\emptyset$ well-founded?

The definition of $wf$ is:
Let’s instantiate $r$ to $\emptyset$.

$$wf(\emptyset) \equiv (\forall P. (\forall x. (\forall y. False \rightarrow P(y)) \rightarrow P(x)) \rightarrow (\forall x. P(x)))$$
Is $\emptyset$ well-founded?

The definition of $w$ is:
Let’s instantiate $r$ to $\emptyset$.

$$wf(\emptyset) \equiv (\forall P. (\forall x. (\forall y. True)) \rightarrow P(x)) \rightarrow (\forall x. P(x))$$
Is $\emptyset$ well-founded?

The definition of $wf$ is:

Let’s instantiate $r$ to $\emptyset$.

$$wf(\emptyset) \equiv (\forall P. \forall x. True \rightarrow P(x)) \rightarrow (\forall x. P(x))$$
Is $\emptyset$ well-founded?

The definition of $wf$ is:

Let’s instantiate $r$ to $\emptyset$.

$$wf(\emptyset) \equiv (\forall P. (\forall x. P(x)) \rightarrow (\forall x. P(x)))$$
Is $\emptyset$ well-founded?

The definition of $wf$ is:
Let’s instantiate $r$ to $\emptyset$.

$$wf(\emptyset) \equiv (\forall P. True)$$
Is $\emptyset$ well-founded?

The definition of $wf$ is:

Let’s instantiate $r$ to $\emptyset$.

$$wf(\emptyset) \equiv \text{True}$$

So the empty set is well-founded.
Expressing Absence of Infinite Chains

We will now try some ideas, work out their formalization as a formula, and then illustrate why the condition is either too weak or too strong, using an example. Finally, we will give the correct condition.
Bad Formalization of “Minimal Element”

In this attempt, we formalized the “minimal element in $p$” as an $x$ such that there is no $y$ with $(x, y) \in p$. But this is a bad formalization since an isolated element, i.e., one that is completely unrelated to $p$, or even to $r$, would meet the definition.

In fact, this problem was already present for the previous attempt where we just required $\exists x. \forall y. (y, x) \notin r$ (i.e., $r$ has a minimal element).
No Infinite Descending Chains

The final condition

$$(\forall Q. \; x \in Q \rightarrow (\exists z \in Q. \forall y. (y, z) \in r \rightarrow y \notin Q))$$

doesn’t use the concept of infinity to express the absence of infinite descending chains.

It’s a characterization of well-foundedness. One could say that the above formula expresses what well-foundedness is, while the “official” definition is somewhat indirect since it defines well-foundedness by what one can do with it.
Theorems of Wellfounded_Recursion.ML

The theorems we present here are proven in Wellfounded_Recursion.ML.

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Wellfounded_Recursion.ML

but in older versions it used to be called

/usr/local/share/provers/Isabelle/src/HOL/WF.ML
**induct_wf**

As far as the induction principle is concerned, `induct_wf` states the same as the very definition of `wf`. All that happens is that some explicit universal object-level quantifiers are removed and the according variables are (implicitly) universally quantified on the meta-level, and some shifting from object-level implications to meta-level implications using `mp`. This is why we dare say “logical massage”. See `Wellfounded_Recursion.ML`.

[Back to main referring slide]
Classical Reasoning in Antisymmetry Proof

In classical logic, we have the theorem $A \rightarrow B \equiv \neg A \lor B$. 
Classical Reasoning in Antisymmetry Proof

(2)

In classical logic, we have the theorem $A \rightarrow \neg B \equiv B \rightarrow \neg A$. 
Elementary Equivalences

For example $\neg\forall x.\phi = \exists x.\neg\phi$ or $\neg\neg\phi = \phi$, which hold because our reasoning is classical.
In the proof of $\exists x. \forall y. (y, x) \notin r^+$ we had the sub-proof

$$
\neg \phi \quad \forall w. (w, v) \in r^+ \rightarrow \phi
$$

$$
\therefore \neg \exists w. (w, v) \in r^+
$$

This sub-proof does not actually depend on $\phi$, it would hold no matter what $\phi$ is (unlike the entire proof)
In detail, the sub-proof looks as follows:

\[ \forall w. (w, v) \in r^+ \rightarrow \phi \]

\[ (w, v) \in r^+ \rightarrow \phi \]
In detail, the sub-proof looks as follows:

\[ (w, v) \in r^+ \quad \quad \frac{\forall w. (w, v) \in r^+ \rightarrow \phi}{\therefore (w, v) \in r^+ \rightarrow \phi} \]
In detail, the sub-proof looks as follows:

\[
\begin{align*}
\forall w. (w, v) \in r^+ \Rightarrow \phi \\
(w, v) \in r^+ & \Rightarrow \phi \\
\phi
\end{align*}
\]
In detail, the sub-proof looks as follows:

\[
\forall w. (w, v) \in r^+ \rightarrow \phi
\]

\[
\frac{(w, v) \in r^+}{\phi}
\]

\[
\exists w. (w, v) \in r^+
\]

\[
\frac{(w, v) \in r^+}{\phi}
\]

\[
\text{spec}
\]

\[
\text{mp}
\]

Back to main referring slide
In detail, the sub-proof looks as follows:

\[
\exists w. (w, v) \in r^+ \quad \forall w. (w, v) \in r^+ \rightarrow \phi \\
\Rightarrow \quad [(w, v) \in r^+]^2 \quad (w, v) \in r^+ \rightarrow \phi\\
\Rightarrow \quad \phi \\
\Rightarrow \quad \phi \quad \text{spec} \\
\Rightarrow \quad \phi \quad \text{mp} \\
\Rightarrow \quad \phi \quad \exists w \phi \\
\Rightarrow \quad \exists w \phi \\
\Rightarrow \quad \exists w \phi \\
\Rightarrow \quad \exists w \phi
\]
In detail, the sub-proof looks as follows:

\[
\neg \phi \quad \exists w. (w, v) \in r^+ \\
\forall w. (w, v) \in r^+ \rightarrow \phi \\
\begin{array}{c}
(w, v) \in r^+ \\
\phi
\end{array} \\
\frac{[(w, v) \in r^+]^2}{\phi} \\
\frac{(w, v) \in r^+ \rightarrow \phi}{\phi} \\
\frac{\forall w. (w, v) \in r^+ \rightarrow \phi}{\phi} \\
\exists w. (w, v) \in r^+ \\
\neg \phi \quad \phi
\]
In detail, the sub-proof looks as follows:

\[
\begin{align*}
\neg \phi & \quad \frac{\exists w. (w, v) \in r^+}{\phi} \quad \text{notE} \\
\exists w. (w, v) \in r^+ & \quad \frac{\forall w. (w, v) \in r^+ \rightarrow \phi}{\phi} \quad \text{spec} \\
\neg \phi & \quad \frac{[(w, v) \in r^+]^2}{(w, v) \in r^+ \rightarrow \phi} \quad \text{mp} \\
\forall w. (w, v) \in r^+ & \quad \frac{\phi}{\phi} \quad \text{existsE}^2
\end{align*}
\]
In detail, the sub-proof looks as follows:

\[
\begin{align*}
\neg \phi \\
[\exists w. (w, v) \in r^+]^1 \\
\neg \exists w. (w, v) \in r^+ & \quad \text{notI}^1 \\
\neg \phi & \quad \text{notE} \\
\neg \exists w. (w, v) \in r^+ & \quad \text{notl}^1 \\
\end{align*}
\]

\[
\begin{align*}
[ (w, v) \in r^+]^2 \\
( w, v ) \in r^+ \to \phi & \quad \text{spec} \\
( w, v ) \in r^+ \to \phi & \quad \text{mp} \\
\phi & \quad \phi \text{ existsE}^2 \\
\end{align*}
\]
Splitting $=\quad$

By this we simply mean to split a proof of $\phi = \psi$ into two proofs $\phi \implies \psi$ and $\psi \implies \phi$. 
What Is Arbitrary?

For the construction we have in mind, it would be fine that $f|_{<a}$ be a function that is like $f$ on all values $< a$, and arbitrary elsewhere. E.g., $\text{fac}|_{<4}$ could be

However, such a $\text{fac}|_{<4}$ could not be in a model for HOL (with the extensions we consider here). The way that arbitrary elements are
formalized in **HOL.thy**, it turns out that in any model and for each type, there must be **one specific** domain element for the constant arbitrary (you don’t have to understand why this is so). That is, in different models we could have different ones, but within each model the element must be a specific one. Since the value of \( \text{fac}|_{<4} \) is “arbitrary” for all arguments \( \geq 4 \), this means that in each model, this value must be the same for all arguments \( \geq 4 \), ruling out the function above.
Of course, these are considerations taking place only in our heads. In the actual deduction machinery, one never constructs these “arbitrary” terms.
Relation Is Function

When we say that a binary relation $r : \tau \times \sigma$ is in fact a function, we mean that for $t : \tau$, there is exactly one $s : \sigma$ such that $(t, s) \in r$. 
THE

The operator THE is similar to the Hilbert operator, but it returns the unique element having a certain property rather than an arbitrary one. The Isabelle formalization of HOL nowadays heavily relies on THE rather than the Hilbert operator.
Define Addition and Subtraction

\[
\text{add} :: \text{[nat, nat]} \Rightarrow \text{nat} \quad \text{(infixl 70)} \\
\text{"m add n == wfrec (pred_nat^+)}
\quad \left(\%f \ j. \text{ if } j=0 \text{ then } n \text{ else Suc } \left( f \left( \text{pred } j \right) \right) \right) \ m\"
\]

Here we suppose that we have a predecessor function \( \text{pred} \). The implementation in Isabelle is different, but conceptually, the above is a definition of the \text{add} function.

Note that \text{add} is a function of type \( \text{nat} \rightarrow \text{nat} \rightarrow \text{nat} \) (written infix), but it is only recursive in one argument, namely the first one.

You may be confused about this and wonder: how do I know that it is the first? Is this some Isabelle mechanism saying that it is always the first? The answer is: no. You must look at the two sides in isolation. On
the right-hand side, we have

\[
\text{wfrec (pred_nat}^+\text{)} \ni (\%f \ j. \text{ if } j=0 \text{ then } n \text{ else Suc (f (pred j)))}
\]

By the definitions (of \textit{wfrec} most importantly), this expression is a function of type \(\text{nat} \rightarrow \text{nat}\), namely the function that adds \(n\) (which is not known looking at this expression alone; it occurs on the left-hand side) to its argument. The function is recursive in its argument (and hence not in \(n\)). Now, this function is applied to \(m\). Therefore we say that the final function \textit{add} is recursive in \(m\) but not in \(n\).

Now look at subtraction:

\[
\text{subtract :: [nat, nat] => nat \ (infixl 70)}
\]

"m subtract n == wfrec (pred_nat}^+) \ni (\%f \ j. \text{ if } j=0 \text{ then } m \text{ else pred (f (pred j)))} n"
Note that \texttt{subtract} is recursive in its \textit{second} argument, simply because the right-hand side of the defining equation was constructed in a different way than for \texttt{add}.

Similar considerations apply for other binary functions defined by recursion in one argument.
Primitive Recursion

A function is primitive recursive if the recursion is based on the immediate predecessor w.r.t. the well-founded order used (e.g., the predecessor on the natural numbers, as opposed to any arbitrary smaller numbers).

This is not the same concept as used in the context of computation theory, where primitive recursive is in contrast to $\mu$-recursive [LP81].
Automating Recursion

The `primrec` syntax provides a convenient front-end for defining primitive recursive functions. Isabelle will guess a well-founded ordering to use. E.g. for functions on the natural numbers, it will use the usual $<$ ordering.
Arithmetic
The Roadmap

We are still looking at how the different parts of mathematics are encoded in the Isabelle/HOL library.

- Orders
- Sets
- Functions
- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes
The Roadmap

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Motivation

Current stage of our course:

• On the basis of conservative embeddings, set theory can be built safely.

• Inductive sets can be defined using least fixpoints and suitably supported by Isabelle.

• Well-founded orderings can be defined without referring to infinity. Recursive functions can be based on these. Needs inductive sets though. Support by Isabelle provided.
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Current stage of our course:

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- Inductive sets can be defined using least fixpoints and suitably supported by Isabelle.

- Well-founded orderings can be defined without referring to infinity. Recursive functions can be based on these. Needs inductive sets though. Support by Isabelle provided.

Next important topic: arithmetic.
Which Approach to Take?

• Purely definitional?
Which Approach to Take?

- Purely definitional?
  Not possible with eight basic rules (cannot enforce infinity of HOL model)!
Which Approach to Take?

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• Heavily axiomatic? I.e., we state natural numbers by Peano axioms and claim analogous axioms for any other number type?
Which Approach to Take?

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  Insecure!
Which Approach to Take?

• Purely definitional? Not possible with eight basic rules (cannot enforce infinity of HOL model)!

• Heavily axiomatic? I.e., we state natural numbers by Peano axioms and claim analogous axioms for any other number type? Insecure!

• Minimally axiomatic? We construct an infinite set, and define numbers etc. as inductive subset?
Which Approach to Take?

- Purely definitional? Not possible with eight basic rules (cannot enforce infinity of HOL model)!

- Heavily axiomatic? I.e., we state natural numbers by Peano axioms and claim analogous axioms for any other number type? Insecure!

- Minimally axiomatic? We construct an infinite set, and define numbers etc. as inductive subset? Yes. Finally use infinity axiom.
What is Infinity? Cantor’s Hotel

Cantor’s hotel has infinitely many rooms.
What is Infinity? Cantor’s Hotel

Cantor’s hotel has infinitely many rooms. New guest arrives.
Cantor’s hotel has infinitely many rooms. New guest arrives. The doors open,
Cantor’s hotel has infinitely many rooms. New guest arrives. The doors open, and all guests come out of their rooms.
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Cantor’s hotel has infinitely many rooms. New guest arrives. The doors open, and all guests come out of their rooms. They move one room forward, the new guest walks towards the first room, they turn around, enter their new rooms.
Cantor’s hotel has infinitely many rooms. New guest arrives. The doors open, and all guests come out of their rooms. They move one room forward, the new guest walks towards the first room, they turn around, enter their new rooms. The doors close, all guests are accommodated.
Axiom of Infinity

The axiomatic core of datatypes (and hence, numbers):

\[ \exists f :: (\text{ind} \to \text{ind}). \text{injective } f \land \neg \text{surjective } f \]

where

\[
\begin{align*}
\text{injective } f & = \forall x y. f x = f y \to x = y \\
\text{surjective } f & = \forall y. \exists x. y = f x
\end{align*}
\]

Forces \text{ind} to be “infinite type” (called “I” in [Chu40]). We will see soon how this is done in Isabelle.
Type-Closed Conservative Extensions

Why must conservative extensions be type-closed? (the standard example)
Consider $H \equiv \exists f :: \alpha \Rightarrow \alpha.\text{injective } f \land \neg \text{surjective } f$
Type-Closed Conservative Extensions

Why must conservative extensions be type-closed? (the standard example)

Consider $H \equiv \exists f :: \alpha \Rightarrow \alpha.\text{injective } f \land \neg\text{surjective } f$

Then the type of $H$ is $\text{bool}$, but $H$ contains a subterm of type $\alpha \Rightarrow \alpha$ ($H$ is not type-closed).

Then we could reason as follows . . .
Type-Closed Conservative Extensions (2)

\((H \equiv \exists f :: \alpha \Rightarrow \alpha.\text{injective } f \land \neg \text{surjective } f)\)
Type-Closed Conservative Extensions (2)

\((H \equiv \exists f :: \alpha \Rightarrow \alpha.\text{injective } f \land \neg \text{surjective } f)\)

\[ H = H \] holds by \textit{refl}

\[ \Rightarrow \exists f :: \text{bool} \Rightarrow \text{bool.}\text{inj } f \land \neg \text{sur } f = \exists f :: \text{ind} \Rightarrow \text{ind.}\text{inj } f \land \neg \text{sur } f \]

\[ \Rightarrow \text{False} = \text{True} \]

\[ \Rightarrow \text{False} \]

(unfolding \(H\) using two different type instantiations, and then using \textit{axiom of infinity} and the fact that there are only finitely many functions on \textit{bool}).
Types Affect the Semantics

Type instantiations may change semantic values, and hence cause inconsistency!

This example was somewhat more concrete than our previous simpler example.
consts
  Zero_Rep :: ind
  Suc_Rep :: "ind => ind"

axioms
  inj_Suc_Rep:  "inj Suc_Rep"
  Suc_Rep_not_Zero_Rep: "Suc_Rep x ~= Zero_Rep"

So the **axiom of infinity** is formulated by defining a constant
*Suc_Rep* having the two required properties.

*inj* and *sur* are defined in *Fun.thy*.

Think of *Zero_Rep*, *Suc_Rep* as **provisional 0**, successor.
Defining the Set $\text{Nat}$

Want to define new type $\text{nat}$. How?
Defining the Set $Nat$

Want to define new type $nat$. How?

Must define a set isomorphic to the natural numbers. How?
Defining the Set $Nat$

Want to define new type $nat$. How?

Must define a set isomorphic to the natural numbers. How?

By induction using the inductive syntax:

inductive Nat
intros
  Zero_RepI: "Zero_Rep : Nat"
  Suc_RepI: "i : Nat ==> Suc_Rep i : Nat"

Translated by Isabelle to:

$Nat = \text{lfp} (\lambda X.\{\text{Zero}_\text{Rep}\} \cup (\text{Suc}_\text{Rep} \cdot X))$
Defining the Type \( \text{nat} \)

Now we have the set \( \text{Nat} \). What next?
Defining the Type \( \text{nat} \)

Now we have the set \( \text{Nat} \). What next?

Define the type \( \text{nat} \), isomorphic to \( \text{Nat} \), using the \texttt{typedef} syntax:

\begin{verbatim}
typedef (open Nat)
    nat = "Nat" by (rule exI, rule Nat.Zero_RepI)
\end{verbatim}

After these two steps we have the type \( \text{nat} \).
**Constants in $\text{nat}$**

Moreover, define:

**consts**
- $\text{Suc} :: \text{"nat} \Rightarrow \text{nat}"
- $\text{pred}_\text{nat} :: \text{(nat} \times \text{nat}) \text{ set}$

**defs**
- $\text{Zero}_\text{nat}_\text{def}: "0 == \text{Abs}\_\text{Nat Zero}_\text{Rep}"
- $\text{Suc}_\text{def}: "\text{Suc} == (\%n. \text{Abs}\_\text{Nat (Suc}_\text{Rep (Rep}_\text{Nat n)})\""
- $\text{pred}_\text{nat}_\text{def}: "\text{pred}_\text{nat} == \{(m, n). n = \text{Suc} m\}"
Some Theorems in Nat.thy

\[
\text{nat_induct} \quad [P \ 0; \ \land \ n. \ P \ n \implies P \ (Suc \ n)] \implies P \ n
\]

\[
\text{diff_induct} \quad [\land \ x. \ P \ x \ 0; \ \land \ y. \ P \ 0 \ (Suc \ y); \\
\land \ xy. \ P \ x \ y \implies P \ (Suc \ x) \ (Suc \ y)] \\
\implies P \ m \ n
\]

We can now exploit that \textit{nat} is defined based on a set defined using least fixpoints. In particular, \textit{nat_induct} follows (but not “automatically”!) from the \textit{induct} theorem of Lfp.
Nat and Well-Founded Orders

Examples of theorems involving well-founded orders:

\begin{align*}
\text{wf\_pred\_nat} & \quad \text{wf pred nat} \\
\text{less\_linear} & \quad m < n \lor m = n \lor n < m \\
\text{Suc\_less\_SucD} & \quad Suc m < Suc n \implies m < n
\end{align*}
Using Primitive Recursion

`Nat.thy` defines rich theory on `nat`. Uses `primrec` syntax for defining recursive functions, and `case` construct.

```plaintext
primrec
  add_0    "0 + n = n"
  add_Suc  "Suc m + n = Suc(m + n)"
primrec
  diff_0   "m - 0 = m"
  diff_Suc "m - Suc n =
              (case m - n of 0 => 0 | Suc k => k)"
primrec
  mult_0   "0 * n = 0"
  mult_Suc "Suc m * n = n + (m * n)"
```
Some Theorems in Nat

\textbf{add\_0\_right} \quad m + 0 = m

\textbf{add\_ac} \quad m + n + k = m + (n + k)
\quad m + n = n + m
\quad x + (y + z) = y + (x + z)

\textbf{mult\_ac} \quad m \ast n \ast k = m \ast (n \ast k)
\quad m \ast n = n \ast m
\quad x \ast (y \ast z) = y \ast (x \ast z)

Note third part of add\_ac, mult\_ac, respectively.

Technically, add\_ac and mult\_ac are lists of \texttt{thm}'s.
Proof of \texttt{add\_0\_right}

\[ m + 0 = m \] \quad \text{add\_0\_right}
Proof of add_0_right

\[
\begin{align*}
\text{add}_0 & \implies 0 + 0 = 0 \\
S\text{uc } n + 0 &= S\text{uc } n \quad \text{nat_induct} \\
m + 0 &= m
\end{align*}
\]
Proof of add_0_right

\[
\frac{
\begin{align*}
\text{add}_0 & \quad 0 + 0 = 0 \\
\text{add}_\text{Suc} & \quad \text{Suc}n + 0 = \text{Suc}(n + 0) \\
\text{sym} & \quad \text{Suc}(n + 0) = \text{Suc}n + 0 \\
\text{arg}_\text{cong} & \quad n + 0 = n \\
\text{subst} & \quad \text{Suc}(n + 0) = \text{Suc}n \\
\text{nat}_\text{induct} & \quad \text{Suc}n + 0 = \text{Suc}n \\
\end{align*}
\right)
\text{Suc}n + 0 = \text{Suc}n
\]

Note that \(\text{Suc}n + 0 = \text{Suc}(n + 0)\) is an instance of \(\text{Suc}m + n = \text{Suc}(m + n)\).
Proof of add_0_right

\[
\begin{align*}
\text{add_0} & \quad 0 + 0 = 0 \\
\text{add_Suc} & \quad \text{Suc } n + 0 = \text{Suc } (n + 0) \\
& \quad \text{sym} \quad \text{Suc } (n + 0) = \text{Suc } n + 0 \\
& \quad \text{arg_cong} \quad [n + 0 = n]^1 \\
& \quad \text{Suc } (n + 0) = \text{Suc } n \\
& \quad \text{subst} \quad \text{Suc } n + 0 = \text{Suc } n \\
& \quad \text{nat_induct}^1 \quad m + 0 = m
\end{align*}
\]

Note that Suc \( n + 0 = \text{Suc } (n + 0) \) is an instance of Suc \( m + n = \text{Suc } (m + n) \).
Integers

The integers are implemented as equivalence classes over $\text{nat} \times \text{nat}$.

IntDef = Equiv + NatArith +
constdefs
  intrel :: "((nat * nat) * (nat * nat)) set"
  "intrel == {p. EX x1 y1 x2 y2.
            p=((x1::nat,y1),(x2,y2)) & x1+y2 = x2+y1}"

typedef (Integ)
  int = "UNIV//intrel"  (quotient_def)
Some Theorems in IntArith

\texttt{zminus\_zadd\_distrib} \quad -(z + w) = -z + -w

\texttt{zminus\_zminus} \quad -(-z) = z

\texttt{zadd\_ac} \quad z1 + z2 + z3 = z1 + (z2 + z3) \\
\quad z + w = w + z \\
\quad x + (y + z) = y + (x + z)

\texttt{zmult\_ac} \quad z1 * z2 * z3 = z1 * (z2 * z3) \\
\quad z * w = w * z \\
\quad z1 * (z2 * z3) = z2 * (z1 * z3)

Compare to \textit{nat} theorems.
Further Number Theories

- Binary Integers (Integ/Bin.thy, for fast computation)
- Rational Numbers (Real/PRat.thy)
- **Reals** (Real/PReal.thy: based on Dedekind-cuts of rationals [Ded])
- Hyperreals (Real/RealDef.thy for non-standard analysis)
- Machine numbers (floats); see work for Intel’s PentiumIV; built in HOL-light [Har98, Har00]
Conclusion on Arithmetic

Using conservative extensions in HOL, we can build

- the naturals (as type definition based on \textit{ind}), and
- higher number theories (via equivalence construction).
Conclusion on Arithmetic

Using conservative extensions in HOL, we can build
- the naturals (as type definition based on \( ind \)), and
- higher number theories (via equivalence construction).

Potential for
- analysis of processor arithmetic units, and
- function analysis in HOL (combination with computer
  algebra systems such as Mathematica).

Future: analysis of hybrid systems.

The methodological overhead can be tackled by powerful
mechanical support, since many proof-tasks are routine.
More Detailed Explanations
Enforcing Infinity

Our intuition/knowledge about arithmetics clearly requires that there are infinite sets, e.g., the set of infinite numbers. Technically, the HOL model of the set of natural numbers must be an infinite set, otherwise we would not be willing to say that have “modeled” arithmetic.
The Peano Axioms

The Peano axioms include

- $0 \in \text{nat}$
- $\forall x. x \in \text{nat} \rightarrow \text{Suc}(x) \in \text{nat}$
- $\forall x. \text{Suc}(x) \neq 0$
- $\forall P. (P(0) \land \forall n. (P(n) \rightarrow P(\text{Suc}(n)))) \rightarrow \forall n. P(n)$
Successors on Rooms

This means, there must be a successor function on rooms. To each room, it assigns the “next” room.
injective and surjective

These constants (actually called \textit{inj} and \textit{sur}) are defined in \texttt{Fun.thy}.
Is it Necessary to Add an Axiom?

Note that theoretically, it is not needed to add the infinity axiom (or some equivalent formulation) to HOL. Instead one could add the infinity axiom as premise to each arithmetic theorem that one wants to prove. However this would not be a viable approach since the resulting formulas would be very, very complicated.
Numbers as Datatype

The natural numbers can be built as an algebraic datatype by having a constant 0 and a term constructor $Suc$ (for successor).
inj and sur

We use *inj* and *sur* as abbreviations for *injective* and *surjective*.
A Type Definition Based on an Inductive Set

Note the two ingredients for defining the type $\text{nat}$:

- An inductively defined set $\text{Nat}$, i.e., a set defined as fixpoint of a monotone function. In Isabelle ($\text{Nat.thy}$), the inductive syntax is used for this purpose. This automatically generates an induction rule for the set.

- A type definition based on this set, defined using the `typedef` syntax. Recall that this process automatically generates the two constants $\text{Abs_Nat}$ and $\text{Rep_Nat}$.

But note: the induction theorem is not inherited automatically. More precisely, the `typedef` syntax does not cause the type $\text{nat}$ to inherit the inductive theorem of the set $\text{Nat}$. The theorem $\text{nat_induct}$ is explicitly proven in $\text{Nat.thy}$.
Constructor Abstraction

Based on the generic constants \texttt{Abs Nat} and \texttt{Rep Nat}, we define all the constants that we need to work conveniently with \texttt{nat}, most importantly, \texttt{0} and \texttt{Suc}.
Nat.thy
This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Nat.thy
The case Statement for nat

The case statement for nat is a function of type
\[ \text{nat} \rightarrow (\text{nat} \rightarrow \text{nat}) \rightarrow \text{nat} \rightarrow \text{nat}. \]
\[ \text{case } z f n \] is defined as follows (using a common mathematical notation):

\[
\text{case } z f n = \begin{cases} 
  z & \text{if } n = 0 \\
  f k & \text{if } n = \text{Suc } k 
\end{cases}
\]

The syntax

\[
\text{diff}\_\text{Suc } "m - \text{Suc } n = (\text{case } m - n \text{ of } 0 \Rightarrow 0 \mid \text{Suc } k \Rightarrow k)"
\]

used on the slide is a paraphrasing ("concrete syntax") of the original ("abstract") syntax. In the original syntax it would read

\[
\text{case } 0 (\lambda x.x) (n - m).
\]
**Left Commutation**

The theorems \( x + (y + z) = y + (x + z) \) and \( x \ast (y \ast z) = y \ast (x \ast z) \) are called **left-commutation laws** and are crucial for (ordered) rewriting. Suppose we have the term shown below.
Left Commutation

The theorems $x + (y + z) = y + (x + z)$ and $x \ast (y \ast z) = y \ast (x \ast z)$ are called left-commutation laws and are crucial for (ordered) rewriting. Suppose we have the term shown below. Using associativity $(m + n + k = m + (n + k))$ this will be rewritten to the second term.
**Left Commutation**

The theorems $x + (y + z) = y + (x + z)$ and $x \ast (y \ast z) = y \ast (x \ast z)$ are called **left-commutation laws** and are crucial for (ordered) rewriting.

Suppose we have the term shown below. Using associativity $(m + n + k = m + (n + k))$ this will be rewritten to the second term. Using left-commutation, this will be rewritten to the third term. This is a so-called **AC-normal form**, for an appropriately chosen term ordering.
**IntDef.thy**

The file should be contained in your Isabelle distribution. In Freiburg it is

```
/usr/local/share/provers/Isabelle/src/HOL/Integ/IntDef.thy
```

Note that `IntDef.thy` is in a special subdirectory.
Equivalence Classes

Recall the general concept of an equivalence relation. Generally, for a set $S$ and an equivalence relation $R$ defined on the set, one can define $S//R$, the quotient of $S$ w.r.t. $R$.

$$S//R = \{ A \mid A \subseteq S \land \forall x, y \in A. (x, y) \in R \}$$

That is, one partitions the set $S$ into subsets such that each subset collects equivalent elements. This is a standard mathematical concept. We do not go into the Isabelle details here, but we explain how this works for the integers. One can view a pair $(n, m)$ of natural numbers as representation of the integer $n - m$. But then $(n, m)$ and $(n', m')$ represent the same integer if and only if $n - m = n' - m'$, or equivalently, $n + m' = n' + m$. In this case $(n, m)$ and $(n', m')$ are said to be equivalent. The construction of the integer type is based on this.
equivalence relation, called \texttt{intrel}. More precisely, the definition of the integers will be \textbf{based on} the set of all pairs of naturals (which corresponds to the \texttt{UNIV} constant on the type \texttt{nat \times nat}) \textbf{modulo} the equivalence \texttt{intrel}. In other words, it will be based on the quotient of the set of pairs of naturals w.r.t. \texttt{intrel}. 
Reals According to Dedekind

The reals have been axiomatized by Dedekind by stating that a set $R$ is partitioned into two sets $A$ and $B$ such that $R = A \cup B$ and for all $a \in A$ and $b \in B$, we have $a < b$. Now there is a number $s$ such that $a \leq s \leq b$ for all $a \in A$ and $b \in B$. The irrational numbers are characterised by the fact that there exists exactly one such $s$. This axiomatization has been used as a basis for formalizing real numbers in Isabelle/HOL.
Hyperreals

In non-standard analysis, one works with sequences that are not necessarily converging. This is a relatively new field in mathematics and Isabelle/HOL has been successfully applied in it [FP98]. We just mention this here to say that Isabelle/HOL is used for “cutting-edge” mathematics and not just toy examples.
Hybrid Systems

Hybrid systems is a field in software engineering concerned with using finite automata for controlling physical systems such as ABS in cars etc.
Datatypes
The Roadmap

We are still looking at how the different parts of mathematics are encoded in the Isabelle/HOL library.

- Orders
- Sets
- Functions
- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes
The Roadmap

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- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes
What Are Datatypes?

We have seen types, but what are datatypes?
What Are Datatypes?

We have seen types, but what are datatypes?

- **Order 0** (no $\rightarrow$ in type).
- Terms defined by finite set of term constructors.
- Typically inductive definition.
- Term constructed by syntactic rule is unique.

Counterexample: $\alpha$ set.
Datatypes: Motivation

Last lecture: Construction of natural numbers.

How can we build “datatypes” (as in ML [Pau96])?

Can we base the construction of arbitrary datatypes on the natural numbers?
Datatypes: Motivation

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How can we build “datatypes” (as in ML [Pau96])?
Can we base the construction of arbitrary datatypes on the natural numbers?

• Well, yes — by Gödelization. But that wouldn’t be automatable easily . . .
Datatypes: Motivation

Last lecture: Construction of natural numbers.

How can we build “datatypes” (as in ML [Pau96])?

Can we base the construction of arbitrary datatypes on the natural numbers?

• Well, yes — by Gödelization. But that wouldn’t be automatable easily . . .

• Instead: We use S-expressions rather than \texttt{nat}.

Caveat: We will only sketch the construction and we will simplify, meaning that the technical details will not be strictly correct! See Datatype_Universe.thy and [Wen99].
S-Expressions as Basis

In the end we want to have datatypes such as \texttt{lists} and trees.
It turns out that LISP-like \texttt{S-expressions} are a datatype that is so rich that other datatypes can nicely be embedded in it.
Since we have not got the concept of \texttt{datatype} yet, we must first represent S-expressions using constructs we already have.
LISP-like S-expressions are a kind of binary trees. We call the type $\alpha dtree$. This uses $\alpha + \text{nat}$. 

![Diagram of S-expression](image-url)
LISP-like S-expressions are a kind of binary trees. We call the type \( \alpha dtree \). This uses \( \alpha + nat \).

This is encoded as a set of “nodes” (defined by their path from the root and a value in the leaves), e.g.:

\[
\{(\langle 0, 0 \rangle, a), (\langle 0, 1 \rangle, b), (\langle 1 \rangle, c)\}
\]

The type definition of \( \alpha dtree \) uses such an encoding.
Building Trees

- $\text{Atom}(n)$

- $\text{Scons } X \ Y$

\[
\begin{array}{c}
\text{S-Expressions} \\
\text{Building Trees} \\
\text{• Atom}(n) \\
\text{• Scons } X \ Y
\end{array}
\]
Tagging Trees

We want to tag an S-expression by either 0 or 1. This can be done by “$Scons$”-ing it with an S-expression consisting of an administration label. By convention, the tag is to the left.

- **In0_def** \( \text{In0}(X) \equiv Scons\, \text{Atom}(\text{Inr}(0))(X) \)

- **In1_def** \( \text{In1}(X) \equiv Scons\, \text{Atom}(\text{Inr}(1))(X) \)
Products and Sums on Sets of S-Expressions

Product of two sets $A$ and $B$ of S-expressions: All $Scons$-trees where left subtree from $A$, right subtree from $B$.

$$\text{uprod}_{\text{def}} \quad \text{uprod } A \ B \equiv \bigcup \bigcup \{(Scons \ x \ y)\} \quad x \in A \ y \in B$$
Products and Sums on Sets of S-Expressions

Product of two sets $A$ and $B$ of S-expressions: All $Scons$-trees where left subtree from $A$, right subtree from $B$.

$$\text{uprod}_\text{def} \quad \text{uprod } A B \equiv \bigcup_{x \in A} \bigcup_{y \in B} \{(Scons \, x \, y)\}$$

Sum of two sets $A$ and $B$ of S-expressions: union of $A$ and $B$ after S-expressions in $A$ have been tagged 0 and S-expressions in $B$ have been tagged 1, so that one can tell where they come from.

$$\text{usum}_\text{def} \quad \text{usum } A B \equiv \text{In0} \cdot A \cup \text{In1} \cdot B$$
Some Properties of Trees and Tree Sets

- \( \text{Atom, } \text{In0, In1, Scons} \) are injective.
- \( \text{Atom and Scons} \) are pairwise distinct. \( \text{In0} \) are \( \text{In1} \) pairwise distinct.
Some Properties of Trees and Tree Sets

- \( \text{Atom, In0, In1, Scons are injective.} \)
- \( \text{Atom and Scons are pairwise distinct. In0 are In1 pairwise distinct.} \)
- Tree sets represent a universe that is \text{closed under products and sums}: \text{usum, uprod have type} \\
  \[(\alpha \text{ dtree}) \text{ set, (}\alpha \text{ dtree}) \text{ set} \Rightarrow (\alpha \text{ dtree}) \text{ set}. \]
- \text{uprod and usum are monotone.}
Some Properties of Trees and Tree Sets

- Atom, In0, In1, Scons are injective.
- Atom and Scons are pairwise distinct. In0 are In1 pairwise distinct.
- Tree sets represent a universe that is closed under products and sums: usum, uprod have type 
  \[ ([\alpha \ dtree \ set, \ (\alpha \ dtree) \ set] \Rightarrow (\alpha \ dtree) \ set) \]
- uprod and usum are monotone.
- Tree sets represent a universe that is closed under products and sums combined with arbitrary applications of lfp.

Reminder: we simplified!
Lists in Isabelle

Similar to the construction of \textit{nat}, we first construct a \texttt{set} of S-expressions having the “structure of lists”. We start by defining “provisional” list constructors:

\begin{verbatim}
constdefs
  NIL :: 'a dtree
  "NIL == In0(Atom(Inr(0)))"

  CONS :: ['a dtree, 'a dtree] => 'a dtree
  "CONS M N == In1(Scons M N)"
\end{verbatim}

What type do you expect \texttt{Cons} to have, and how does \texttt{CONS} compare?
Lists in Isabelle

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\end{verbatim}

What type do you expect \textit{Cons} to have, and how does \textit{CONS} compare? Must wrap list elements by $\text{Atom} \circ \text{Inl}$. 

Smaus: CSMR; WS05/06
Lists as S-Expressions: Intuition

Examples of how lists would be represented as S-expressions:

\[
\begin{align*}
\text{Nil} & \quad \text{[]} \\
\text{Cons}(7, \text{Nil}) & \quad [7] \\
\text{Cons}(5, \text{Cons}(7, \text{Nil})) & \quad [5, 7]
\end{align*}
\]
Lists as S-Expressions: Intuition

Examples of how lists would be represented as S-expressions:

- \textit{Nil} \quad \rightarrow \quad []
- \textit{In0(Atom(Inr 0))} \\
  \hspace{1cm} \rightarrow \quad 7
- \textit{Cons(7, Nil)} \\
  \hspace{1cm} \rightarrow \quad [7]
- \textit{Cons(5, Cons(7, Nil))} \\
  \hspace{1cm} \rightarrow \quad [5, 7]
Lists as S-Expressions: Intuition

Examples of how lists would be represented as S-expressions:

\[
\begin{align*}
\text{Nil} & \quad [] \\
\text{In0(Atom(Inr 0))} & \\
\text{Cons(7, Nil)} & \quad [7] \\
\text{CONS (Atom(Inl 7)) In0(Atom(Inr 0))} & \\
\text{Cons(5, Cons(7, Nil))} & \quad [5, 7]
\end{align*}
\]
Lists as S-Expressions: Intuition

Examples of how lists would be represented as S-expressions:

\[
\begin{align*}
\text{Nil} & \quad \text{[]} \\
\text{In0(Atom(Inr 0))} & \\
\text{Cons(7, Nil)} & \quad [7] \\
\text{CONS (Atom(Inl 7)) In0(Atom(Inr 0))} & \\
\text{Cons(5, Cons(7, Nil))} & \quad [5, 7] \\
\text{CONS (Atom(Inl 5))} & \\
\text{(CONS (Atom(Inl 7)) In0(Atom(Inr 0)))} & \\
\end{align*}
\]

Now let’s construct the S-expressions having this form.
Lists as S-Expressions: Inductive Construction

Idea: let $A :: (\alpha \text{ dtree}) \text{ set}$ be the set of all “wrapped” elements, e.g. for $\alpha = \text{nat}$, the set $\{(\text{Atom Inl} 0), (\text{Atom Inl} 1), \ldots\}$. Then define $\text{list}(A)$, the set of S-expressions that represent lists of element type $\alpha$:

\[
\text{list} :: "'a dtree set => 'a dtree set"
\]

\[
\text{inductive} \ "\text{list}(A)"
\]

\[
\text{intrs}
\]

\[
\begin{align*}
\text{NIL}_I & \quad "\text{NIL} : \text{list}(A)" \\
\text{CONS}_I & \quad "[\mid a : A; M : \text{list}(A) \mid] \implies \text{CONS} a M : \text{list}(A)"
\end{align*}
\]

See \textit{SList.thy} for how it’s really done!
Defining the “Real” List Type

We now apply the type definition mechanism using the `typedef` syntax. How do we define $A$ formally?
Defining the “Real” List Type

We now apply the type definition mechanism using the typedef syntax. How do we define $A$ formally?

typedef (List)
  'a list =
    "list(range (Atom ° Inl)) :: 'a dtree set"

by ... 

Choosing $A$ as $\text{range} \ (\text{Atom} \circ \text{Inl})$ together with the explicit type declaration forces $A$ to be the set containing all $\text{Atom} \ (\text{Inl} \ t)$, for each $t :: \alpha$.

Example of a definition of a polymorphic type.
List Constructors

We define the real constructor names for lists:

\begin{align*}
\text{Nil} \text{\_def} & \quad "\text{Nil}::\text{'}a\text{ list} == \text{Abs\_list}(\text{NIL})" \\
\text{Cons} \text{\_def} & \quad "x\#(xs::\text{'}a\text{ list}) == \\
& \quad \text{Abs\_list}(\text{CONS (Atom(Inl(x))) (Rep\_list xs)})"
\end{align*}

We then forget about \textit{NIL} and \textit{CONS}.
Isabelle’s Datatype Package

Similar to the `typedef` syntax, Isabelle provides the datatype syntax to support the `construction` of a datatype:

```
datatype 'a list = Nil | Cons 'a ('a list)
```

In particular, this automates the proofs of:

- the induction theorem;
- distinctness;
- injectivity of constructors.
Isabelle’s Datatype Package

Similar to the `typedef` syntax, Isabelle provides the datatype syntax to support the `construction` of a datatype:

```isabelle
datatype 'a list = Nil | Cons 'a ('a list)
```

In particular, this automates the proofs of:

- the induction theorem;
- distinctness;
- injectivity of constructors.

The package also works for mutually and indirectly recursive datatype definitions.

Question: Why didn’t we use this package to define `nat`?

Smaus: CSMR; WS05/06
More Detailed Explanations
What Is a Datatype?

We have seen types, but what are datatypes?
First of all, a datatype must be of order 0, so it must be a non-functional type. Note that if we do not have polymorphism, this means that a datatype must be a in $\mathcal{B}$. But if we have polymorphism, it just means that the type must not contain $\to$. E.g., $\alpha \text{ list}$ could be a datatype. However, when one describes a datatype, one would usually speak about generic instances such as $\alpha \text{ list}$, and not about, say, $\text{nat list}$.

Secondly, the terms that inhabit a datatype $\tau$ must be defined using a finite set of term constructors that have $\tau$ as result type. At least one term constructor should just have type $\tau$. E.g., $\text{Nil} : \alpha \text{ list}$ and $\text{Cons} : \alpha \to (\alpha \text{ list}) \to \alpha \text{ list}$ are the term constructors that define the list datatype. One also finds a syntax where $\text{Nil}$ is written $[]$ and $\text{Cons}$ is written $::$. Intuitively, we could say: the terms of a datatype are exactly
the terms that can be constructed by some finite syntactic construction rule.

Whenever we have a term constructor that has \( \tau \) as argument as well as result, the construction rule is inductive. E.g., we have

- \( \text{Nil} \) is a list;
- if \( t \) is a list \( h \) is of type \( \alpha \), then \( \text{Cons}(h, t) \) is a list.

This is an inductive construction of lists. Usually, when one speaks about datatypes, one has inductively defined ones in mind. Examples are lists, natural numbers, trees. One could say that e.g. \( \text{bool} \) is also a datatype defined by the constants \( \text{True} \) and \( \text{False} \), but it is not particularly interesting in this context.

At the same time, each term constructed by such a syntactic rule is unique. So if we say: lists are defined by the above inductive construction, then we imply that \( \text{Cons}(1, \text{Nil}) \) must not be equal to
Cons(1, Cons(1, Nil))

To understand better the distinction of a datatype from another type, consider the following counterexample: \( \alpha \text{ set} \). Sets are not a datatype:

1. While the type \( \alpha \text{ set} \) does not contain an \( \rightarrow \), it is isomorphic to \( \alpha \rightarrow \text{bool} \) which does contain an \( \rightarrow \).

2. The most basic way of defining “what a set is” is: if \( f \) is of type \( \tau \rightarrow \text{bool} \), then \( \text{Abs}_{\text{set}} f \) (alternatively: \( \text{Collect} f \)) is a set. This is not an inductive syntactic construction rule.

3. One could define sets similarly to lists by an inductive rule saying: \( \{\} \) is a set; if \( S \) is a set and \( h \) is some term of type \( \alpha \), then \( \text{Insert}(h, S) \) is a set. But then \( \text{Insert}(1, \{\}) \) would be different from \( \text{Insert}(1, \text{Insert}(1, \{\})) \), which is not what we want! Moreover, we could not define infinite sets this way.

4. In point 2 we say: the definition of the terms called “sets” is not an
inductive definition. This is not in contradiction to the inductive definition of particular sets. These inductive definitions have the form: If \( \text{foo} \) is in the set then \( \text{bar} \) is in the set, e.g., if \( n \) is in the set then \( \text{Suc } n \) is in the set. This is in contrast to what is suggested in point 3, where we say: If \( \text{foo} \) is a set then \( \text{bar} \) is a set.
Gödelization

In computation theory, Gödelization is the process of encoding words over arbitrary alphabets, or any arbitrary datastructures, for that matter, as natural numbers.

As an example, how could we encode a list of natural numbers as a single natural number. Prime factors are one technique for that. Suppose the number $n$ has a factorization $2^i \cdot 3^j \cdot 5^k \cdot 7^l$. Then it would encode the list $[i, j, k, l]$. But such an encoding for datatypes would be very cumbersome. In particular, there is no way of realizing polymorphism.
Datatype_Universe.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

S-Expressions Explained

The datastructure we have in mind here consists of binary trees where the inner nodes are not labeled, and the leaves are labeled

- either with a term of arbitrary type, in which case the leaf would be an actual “piece of content” in the datastructure,
- or with a natural number, in which case the leaf serves special purposes for organizing our datastructure, as we will see later.

I.e., such binary trees have a type parametrized by a type variable $\alpha$, the type of the latter kind of leaves. Let us call the type of such trees $\alpha dtree$.

As always with parametric polymorphism, when we consider how the datastructure as such works, we are not interested in what the values in the former kind of leaves are. This is just like the type and values of list elements are irrelevant for concatenating two lists. Of course, $\alpha$ could,
by coincidence, be instantiated to type \( \text{nat} \).
Think of a label of the first kind as \textit{content label} and a label of the second kind as \textit{administration label}.

Technically, if something is \textit{either} of this type or of that type, we are talking about a \textit{sum type}. So a \textit{leaf label} has type \( \alpha + \text{nat} \) (written \((\alpha, \text{nat}) \text{ sum}\) before), and it has the form either \( \text{Inl}(a) \) for some \( a :: \alpha \), or \( \text{Inr}(n) \) for some \( n :: \text{nat} \).
Path Sets Explained

The set

\[ \{\langle 0, 0 \rangle, a), (\langle 0, 1 \rangle, b), (\langle 1 \rangle, c)\} \]

represents the tree

The path \(\langle 0, 0 \rangle\) means: from the root take left subtree, then again left subtree. The path \(\langle 1 \rangle\) means: take right subtree.

How can a path \(\langle p_0, \ldots, p_n \rangle\) be represented? One idea is to use the
function $f :: \text{nat} \Rightarrow \text{nat}$ defined by

$$f \ i = \begin{cases} p_i & \text{if } i \leq n \\ 2 & \text{otherwise} \end{cases}$$

as representation of $\langle p_0, \ldots, p_n \rangle$. 
Atom

*Atom* takes a *leaf label* and turns it into a (simplest possible) *S-expression* (tree).

So it has type $\alpha + \text{nat} \Rightarrow \alpha \text{ dtree}$. 
\textbf{\textit{Scons}}

\textit{Scons} takes two \textit{S-expressions} and creates a new \textit{S-expression} as illustrated below:

So it has type $[\alpha\text{\textit{dtree}}, \alpha\text{\textit{dtree}}] \Rightarrow \alpha\text{\textit{dtree}}$. 

\leavevmode\hspace{1em}\framebox[.5\textwidth]{Back to main referring slide}
\[ In0 \; \ldots, \; In1 \; \ldots \]

Recall that \( \cdot \) denotes the image of a function applied to a set.
Injective and Pairwise Distinct Functions

This means that any of \( \text{Atom}, \text{In0}, \text{In1}, \text{Scons} \) applied to different S-expressions will return different S-expressions. Moreover, a term with root \( \text{Scons} \) is definitely different from a term with root \( \text{Atom} \), and a term with root \( \text{In0} \) is definitely different from a term with root \( \text{In1} \).

Why is this important? It is an inherent characteristic of a datatype. A datatype consists of terms constructed using term constructors and is uniquely defined by what it is syntactically (one also says that terms are generated freely using the constructors). For example, injectivity of \( \text{Suc} \) and pairwise-distinctness of \( 0 \) and \( \text{Suc} \) mean for any two numbers \( m \) and \( n \), the terms \( \text{Suc}(\ldots\text{Suc}(0)\ldots) \) and \( \text{Suc}(\ldots\text{Suc}(0)\ldots) \) are different.
Computing the Closure

Given a set $T$ of trees (S-expressions), the closure of $T$ under $\text{Atom}$, $\text{In}_0$, $\text{In}_1$, $\text{Scons}$, $\text{usum}$, $\text{uprod}$ is the smallest set $T'$ such that $T \subseteq T'$ and given any tree (or two trees, as applicable) from $T'$, any tree constructable using $\text{Atom}$, $\text{In}_0$, $\text{In}_1$, $\text{Scons}$, $\text{usum}$, $\text{uprod}$ is also contained in $T'$.

Remembering the construction of inductively defined sets, the closure is the least fixpoint of a monotone function adding trees to a tree set. This function must be constructed using $\text{Atom}$, $\text{In}_0$, $\text{In}_1$, $\text{Scons}$, $\text{usum}$, $\text{uprod}$. We do not go into the details, but note that it is crucial that $\text{uprod}$ and $\text{usum}$ are monotone, and note as well that slight complications arise from the fact that $\text{usum}$ and $\text{uprod}$ have type $[(\alpha \text{ dtree})\text{ set}, (\alpha \text{ dtree})\text{ set}] \Rightarrow (\alpha \text{ dtree})\text{ set}$ rather than $(\alpha \text{ dtree})\text{ set} \Rightarrow (\alpha \text{ dtree})\text{ set}$. 
The Expected Type of Cons

Cons should have the polymorphic type \([\alpha, \alpha \text{list}] \Rightarrow \alpha \text{list}\). The important point is: the first argument is of different type than the second argument. If the first is of type \(\tau\), then the second must be of type \(\tau \text{list}\).

In contrast, CONS is of type \([(\alpha \ dtree), (\alpha \ dtree)] \Rightarrow \alpha \ dtree\).

In order to apply CONS to a “list” (in fact an S-expression) and a “list element”, we must first wrap the list element by \(\text{Atom} \circ \text{Inl}\), so that it becomes an S-expression.
List Syntaxes

Nil, Cons(7, Nil), Cons(5, Cons(7, Nil)) are lists written according to what some programming languages introduce as the first, “official” syntax for lists.

For convenience, programming languages typically allow for the same lists to be written as [], [7], [5, 7].
SList.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Induct/SList.thy
Why Didn’t We Use the Datatype Package to Define \( \textit{nat} \)?

The datatype syntax is very convenient since the complex construction we have seen today is transparent to the normal user. In particular, proofs of the induction theorem are automated. This is in contrast to the construction of \( \textit{nat} \) where this theorem was not generated automatically.

So why didn’t we use the datatype syntax to define \( \textit{nat} \), since it is so much more convenient?

The reason is that we needed \( \textit{nat} \) to define S-expressions, so the type \( \textit{nat} \) must exist before there can be a datatype package, and so the datatype package cannot be used to define \( \textit{nat} \).
Summary of HOL Library / Outlook on Modeled Systems
Summary

In the previous weeks, we looked at how the different parts of mathematics are encoded in the Isabelle/HOL library:

- Orders
- Sets
- Functions
- (Least) fixpoints and induction
- (Well-founded) recursion
- Arithmetic
- Datatypes
Summary (Cont.)

We conclude: HOL is a logical framework for theoretical computer science. Its features are:

- a clean methodology, which can be supported automatically to a surprising extent;
- a powerful set theory and proof support;
- adequate theories for arithmetics (proof-support: not quite satisfactory so far);
- a package for induction;
- a package for recursion;
- a package for datatypes.
Outline

We will now look at how various formalisms (specification and programming languages) can be embedded in HOL:

- Z and data-refinement
- Imperative languages
- Denotational semantics and functional languages
- Object-oriented languages (Java-Light . . . )
Semantics come in different flavors. Representing imperative languages in HOL:
• operational semantics, denotational semantics,
• ... deriving axiomatic semantics (Hoare-logic).
IMP: Introduction

Semantics come in different flavors.
Representing imperative languages in HOL:
• operational semantics, denotational semantics,
• ... deriving axiomatic semantics (Hoare-logic).
(In contrast, in MiniSML we would have:
• denotational semantics
• ... deriving operational semantics.)
Meaning of Imperative Languages

Question: What is the meaning of an imperative language?
Meaning of Imperative Languages

Question: What is the meaning of an imperative language?

- Syntax: language = set of symbols
- Semantics: set of denotations, the semantic domain
- Meaning is a function (interpretation) relating these two.
Imperative Languages in the Isabelle/HOL Library

There are several embeddings of imperative languages in Isabelle/HOL [Nip02]:

- Hoare
- IMP
- IMPP
- MicroJava
Imperative Languages in the Isabelle/HOL Library

There are several embeddings of imperative languages in Isabelle/HOL [Nip02]:

- Hoare: shallowish, good examples
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Imperative Languages in the Isabelle/HOL Library

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- **Hoare**: shallowish, good examples
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Imperative Languages in the Isabelle/HOL Library

There are several embeddings of imperative languages in Isabelle/HOL [Nip02]:

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**Imperative Languages in the Isabelle/HOL Library**

There are several embeddings of imperative languages in Isabelle/HOL [Nip02]:

- **Hoare**: shallowish, good examples
- **IMP**: deepish, good theory
- **IMPP**: extends IMP with procedures
- **MicroJava**: complex, powerful, state-of-the-art

We choose **IMP** to learn a bit about “good ole imperative languages”.

Smaus: CSMR; WS05/06
Semantics Provided for IMP

IMP offers:

- **operational semantics;**
  - natural semantics;
  - transition semantics;
- **denotational semantics;**
- **axiomatic semantics (Hoare logic);**
Semantics Provided for IMP

IMP offers:

- **operational semantics**;
  - natural semantics;
  - transition semantics;
- **denotational semantics**;
- **axiomatic semantics** (Hoare logic);
- **equivalence proofs**;
- **weakest preconditions and verification condition generator**.

It closely follows the standard textbook [Win96].
An Imperative Language Embedding

We will now define the syntax and various semantics of IMP, but in fact, we define those as Isabelle theories. We say that we embed IMP in Isabelle/HOL. You will see that such an embedding is more abstract and less detailed as if we were really going to define IMP for use as a programming language, i.e., if we were going to define a compiler for it.
The Command Language (Syntax)

The (abstract) syntax is defined in Com.thy.

Com = Main +

<table>
<thead>
<tr>
<th>types</th>
</tr>
</thead>
<tbody>
<tr>
<td>loc</td>
</tr>
<tr>
<td>val</td>
</tr>
<tr>
<td>state</td>
</tr>
<tr>
<td>aexp</td>
</tr>
<tr>
<td>bexp</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>datatype    com =</th>
</tr>
</thead>
<tbody>
<tr>
<td>SKIP</td>
</tr>
<tr>
<td>::= loc aexp (infixl 60)</td>
</tr>
<tr>
<td>Semi com com (&quot;<em>;</em>;&quot; [60, 60] 10)</td>
</tr>
<tr>
<td>Cond bexp com com (&quot;IF_;THEN_;ELSE_;&quot; 60)</td>
</tr>
<tr>
<td>While bexp com (&quot;WHILE_;DO_;&quot; 60)</td>
</tr>
</tbody>
</table>

The type loc stands for locations.

Note the abstractness of aexp and bexp.
The Command Language (Syntax)

The (abstract) syntax is defined in Com.thy.

\[
\text{Com} = \text{Main} + \\
\text{types} \\
\quad \text{loc} \\
\quad \text{val} = \text{nat} \quad (*\text{or whatever}*) \\
\quad \text{state} = \text{loc} \Rightarrow \text{val} \\
\quad \text{aexp} = \text{state} \Rightarrow \text{val} \\
\quad \text{bexp} = \text{state} \Rightarrow \text{bool}
\]

\[
\text{datatype com} = \\
\quad \text{SKIP} \\
\quad \text{"}::=\text{" loc aexp (infixl 60)} \\
\quad \text{Semi com com (" ; ; \text{"} [60, 60] 10)} \\
\quad \text{Cond bexp com com ("IF \_ \_ THEN \_ ELSE \_ \_" 60)} \\
\quad \text{While bexp com ("WHILE \_ \_ DO \_ \_" 60)}
\]

The type \text{loc} stands for \text{locations}.

Note the abstractness of \text{aexp} and \text{bexp}.

The datatype \text{com} stands for commands (command sequences).
Operational Semantics: Two Kinds

Natural semantics [Plo81] (idea: a program relates states):

\[ state \xrightarrow{a := b} state' \xrightarrow{WHILE \ldots \text{SKIP}} state'' \xrightarrow{\text{SKIP}} state''' \]
Operational Semantics: Two Kinds

Natural semantics [Plo81] (idea: a program relates states):

\[
\text{state} \xrightarrow{a := b} \text{state}' \xrightarrow{\text{WHILE} \ldots \text{SKIP}} \text{state''} \xrightarrow{\text{state'''} \text{evalc} :: ( \text{com} \ast \text{state} \ast \text{state} ) \text{ set}}
\]
Operational Semantics: Two Kinds

Natural semantics [Plo81] (idea: a program relates states):

\[
\text{state} \xrightarrow{a := b} \text{state}' \xrightarrow{\text{WHILE} \ldots} \text{state}''
\]

\[
\text{evalc} :: ( \text{com} \times \text{state} \times \text{state} ) \xrightarrow{\text{set}}
\]

Transition semantics (idea: sequence of “configurations”):

\[
a := b; X, \text{state} \xrightarrow{X, \text{state}'} \xrightarrow{X'', \text{state}''} \xrightarrow{X''', \text{state}'''}
\]
Operational Semantics: Two Kinds

Natural semantics \[\text{[Plo81]}\] (idea: a program relates states):

\[
\text{state} \quad a := b \quad \text{state}' \quad \text{WHILE} \ldots \quad \text{SKIP} \quad \text{state}''
\]

\[
\text{evalc} :: (\text{com} \ast \text{state} \ast \text{state}) \text{ set}
\]

Transition semantics (idea: sequence of “configurations”):

\[
a := b; X, \text{state} \quad X, \text{state}' \quad X'', \text{state}''
\]

\[
\text{evalc1} :: ((\text{com} \ast \text{state}) \ast (\text{com} \ast \text{state})) \text{ set}
\]
Embedding of the Natural Semantics

The natural semantics encoding in Isabelle is given by an inductive definition. We first declare its type and define a paraphrasing using an arrow symbol for readability:
Embedding of the Natural Semantics

The natural semantics encoding in Isabelle is given by an inductive definition. We first declare its type and define a paraphrasing using an arrow symbol for readability:

\[
\text{consts evalc :: } \{ \text{(com } \times \text{ state } \times \text{ state) set} \}
\]

\[
\text{translations } \langle c, s \rangle \rightarrow c \rightarrow s' \equiv (c, s, s') : \text{evalc}
\]

Note that \( \rightarrow \) is one fixed arrow symbol.
Embedding of the Natural Semantics

The natural semantics encoding in Isabelle is given by an inductive definition. We first declare its type and define a paraphrasing using an arrow symbol for readability:

```plaintext
consts evalc :: "(com * state * state) set"
translations "<c,s> \rightarrow s'" \equiv "(c,s,s') : evalc"
```

Note that \( \rightarrow \) is one fixed arrow symbol.

We now start giving the actual inductive definition. It defines the \( \rightarrow \) transitions (implicit: these are the only \( \rightarrow \) transitions) . . .
The Inductive Definition: Skip and Assignment

\[
\text{inductive evalc} \\
\quad \text{intrs} \\
\quad \text{Skip: } \langle \text{SKIP}, s \rangle \rightarrow_{c} s \\
\quad \text{Assign: } \langle x := a, s \rangle \rightarrow_{c} s[x := (a \ b)]
\]
The Inductive Definition: Skip and Assignment

\[
\text{inductive } \text{evalc} \\
\text{intrs} \\
\text{Skip: } \langle \text{SKIP}, s \rangle \to c \to s \\
\text{Assign: } \langle x := a, s \rangle \to c \to s[x::=(a \; s)]
\]

Skip and Assign are just names for the clauses of the inductive definition.

\(s[x ::= v]\) is short for \(update \; s \; x \; v\), where

\[
update \; s \; x \; v \equiv \lambda y. \; \begin{cases} 
  v & \text{if } y = x \\
  (s \; y) & \text{else}
\end{cases}
\]

Note that \(a\) is of type \(aexp\) or \(bexp\).
The Inductive Definition: Semicolon

Semi: \[
\llbracket <c_0, s> \to c \rightarrow s_1; <c_1, s_1> \to c \rightarrow s_2 \rrbracket
\implies <c_0; c_1, s> \to c \rightarrow s_2
\]
The Inductive Definition: Semicolon

\[
\text{Semi: } \left[ \langle c_0, s \rangle \rightarrow c \rightarrow s_1; \langle c_1, s_1 \rangle \rightarrow c \rightarrow s_2 \right] \\
\implies \langle c_0; c_1, s \rangle \rightarrow c \rightarrow s_2
\]

The rationale of natural semantics: To figure out the meaning of a program consisting of a “first instruction” \( c_0 \) and a “rest” \( c_1 \), starting from state \( s \), you have to show two subgoals: \( c_0 \) starting from state \( s \) goes to some state \( s_1 \), and \( c_1 \) starting in state \( s_1 \) goes to some state \( s_2 \).

Note that by the definition of \textit{Semi}, \( c_0 \) does not have to be “atomic” (whatever this means).
The Inductive Definition: Control

\textbf{IfTrue}: \[ [ \ b \ s; \ <c_0,s> \rightarrow c ightarrow s_1 ] \]
\[ \implies <\text{IF } b \ \text{THEN } c_0 \ \text{ELSE } c_1,s> \rightarrow c ightarrow s_1 \]

\textbf{IfFalse}: \[ [ \ \neg b \ s; \ <c_1,s> \rightarrow c ightarrow s_1 ] \]
\[ \implies <\text{IF } b \ \text{THEN } c_0 \ \text{ELSE } c_1,s> \rightarrow c ightarrow s_1 \]

\textbf{WhileFalse}: \[ [ \neg b \ s] \implies <\text{WHILE } b \ \text{DO } c,s> \rightarrow c \rightarrow s \]

\textbf{WhileTrue}: \[ [ \ b \ s; \ <c,s> \rightarrow c ightarrow s_1; \ <\text{WHILE } b \ \text{DO } c,s_1> \rightarrow c ightarrow s_2 ] \]
\[ \implies <\text{WHILE } b \ \text{DO } c,s> \rightarrow c \rightarrow s_2 \]

Note the termination problem in \textbf{WhileTrue}! Simplest example: \( b \equiv \lambda x. \text{True} \). Then, no proof is possible and no \( s_2 \) can effectively be computed.
Embedding of the Transition Semantics

The transition semantics encoding in Isabelle is also given by an inductive definition. We first declare its type and define a paraphrasing, as before:
Embedding of the Transition Semantics

The transition semantics encoding in Isabelle is also given by an inductive definition. We first declare its type and define a paraphrasing, as before:

```plaintext
cconsts evalc1 :: "((com * state) * (com * state)) set"
translations "cs_0 −1→ cs_1" ≡ "(cs_0, cs_1) : evalc1"
```

Note that −1→ is one fixed arrow symbol.
Embedding of the Transition Semantics

The transition semantics encoding in Isabelle is also given by an inductive definition. We first declare its type and define a paraphrasing, as before:

consts evalc1 :: "((com * state) * (com * state)) set"
translations "cs_0 −1→ cs_1" ≡ "(cs_0, cs_1) : evalc1"

Note that −1→ is one fixed arrow symbol.

We now start giving the actual inductive definition . . .
The Inductive Definition

\textbf{inductive \ evalc1}

\textbf{intrs}

Assign: $(x ::= a, s) \rightarrow 1 \rightarrow (\text{SKIP}, s[x ::= a, s])$

Semi1: $(\text{SKIP}; c, s) \rightarrow 1 \rightarrow (c, s)$

Semi2: $(c_0, s) \rightarrow 1 \rightarrow (c_0', s') \rightarrow (c_0; c_1, s) \rightarrow 1 \rightarrow (c_0'; c_1, s')$
The Inductive Definition

inductive evalc1
  intrs
  Assign: "(x := a, s) → ((SKIP, s)[x::=a s])"
  Semi1: "(SKIP;c, s) → (c, s)"
  Semi2: "(c₀, s) → (c₀', s') ⟷ (c₀;c₁, s) → (c₀';c₁, s')"

So far, we see that the component of com type in the configuration corresponds to a program stack (built by ";"), which represents a program counter.
The Inductive Definition: Control

IfTrue: ”b s \implies (IF b THEN c_1 ELSE c_2,s) -1 \rightarrow (c_1,s)”

IfFalse: ”\neg b s \implies (IF b THEN c_1 ELSE c_2,s) -1 \rightarrow (c_2,s)”

WhileFalse: ”\neg b s \implies (WHILE b DO c,s) -1 \rightarrow (SKIP,s)”

WhileTrue: ”b s \implies (WHILE b DO c,s) -1 \rightarrow (c;WHILE b DO c,s)”

Termination problem as before, but somehow less disturbing: we cannot be shocked about the fact that some computations are infinite, and at least, the transition semantics assigns a meaning to any finite prefix of an infinite computation.
Generalizations to more than one Step

\( n \)-step semantics:

\[
\text{"cs}_0 \xrightarrow{-n} \text{cs}_1 \equiv \text{"(cs}_0, \text{cs}_1 ) : \text{evalc}1^\wedge n"
\]

Unlike \( c \xrightarrow{-1} \) and \( 1 \xrightarrow{-1} \), \( n \xrightarrow{-1} \) is not a fixed arrow symbol, but meta-notation: for any number \( n \), there is the paraphrasing \( n \xrightarrow{-1} \) defined as above. Here, \( \text{evalc}1^\wedge n \) is defined in \text{Relation\_Power.thy}.

multistep-semantics:

\[
\text{"cs}_0 \xrightarrow{-\ast} (c_1, s_1 ) \equiv \text{"(cs}_0, c_1, s_1 ) : \text{evalc}1^\wedge \ast"
\]

\( -\ast \xrightarrow{-1} \) is a fixed arrow symbol.
Equivalence of Semantics

Natural semantics vs. transition semantics.

**Theorem 6** (evalc1_eq_evalc):

\[(c, s) \rightarrow^* (\text{SKIP}, t) = (\langle c, s \rangle - c \rightarrow t)\]

The proof is by induction on the structure of programs.
Embedding of the Denotational Semantics

Idea:

Domain: A semantics relates states (similar to natural semantics)

\[ \text{com\_den} = (\text{state} \times \text{state}) \text{ set} \]

Semantic function: assigns semantics to a program

\[ \text{consts } C :: \text{com} \Rightarrow \text{com\_den} \]
Characteristics of Denotational Semantics

A denotational semantics is a function (here: $C'$) assigning a meaning to a program. More precisely, the meaning of a program is some “mathematical” function of the meanings of its components.

This is in contrast to the operational view where computation order ("first do this, then that. . .") and logical reasoning using proof rules ("if ( . . . ) computes ( . . . ) then ( . . . ) computes ( . . . )") are focused. The “mathematics” uses the $lfp$ operator.
The Recursive Definition

The semantics $C$ is defined recursively:

\[
\begin{align*}
\text{primrec} \\
C \text{_skip} & \quad "C(\text{SKIP}) = \text{Id}" \\* \\
C \text{_assign} & \quad "C(x := a) = \{(s,t). t = s[x ::= a(s)]\}" \\
C \text{_comp} & \quad "C(c_0 ; c_1) = C(c_1) \circ C(c_0)" \\
C \text{_if} & \quad "C(\text{IF } b \text{ THEN } c_1 \text{ ELSE } c_2) = " \\
& \quad \{(s,t). (s,t) : C(c_1) \land b(s)\} \cup \\
& \quad \{(s,t). (s,t) : C(c_2) \land \neg b(s)\}" \\
C \text{_while} & \quad "C(\text{WHILE } b \text{ DO } c) = \text{lfp } (\Gamma b (C c))" \\
\end{align*}
\]

where

\[
\begin{align*}
\Gamma b \text{ cd} & \equiv (\lambda \phi. \{(s,t). (s,t) : (\phi \circ \text{ cd}) \land b(s)\} \cup \\
& \quad \{(s,t). s=t \land \neg b(s)\})"
\end{align*}
\]
Equivalence of Programs

We have seen an equivalence result relating different semantics.
Equivalence of Programs

We have seen an equivalence result relating different semantics. The following is an equivalence relating program fragments.

**Theorem 7 (C_While_If):**

\[
\begin{align*}
C (\text{WHILE } b \text{ DO } c) & = \\
C (\text{IF } b \text{ THEN } (c; \text{WHILE } b \text{ DO } c) \text{ ELSE SKIP})
\end{align*}
\]

Such a result is important because it justifies a program transformation (the two fragments have the same semantics and so they are interchangeable).
Equivalence of Semantics

We have already suggested that the natural semantics is a hybrid between operational and denotational semantics. In fact, there is a simple equivalence relationship between the two:

**Theorem 8 (denotational is natural):**

\[(s, t) : C c) = (\langle c, s \rangle \rightarrow c \rightarrow t)\]
Axiomatic (Hoare) Semantics

Idea: we relate “legal states” before and after a program execution. A set of legal states is modeled as “assertion”:

\[ \text{types } \text{assn} = \text{state } \Rightarrow \text{bool} \]
Axiomatic (Hoare) Semantics

Idea: we relate “legal states” before and after a program execution. A set of legal states is modeled as “assertion”:

types assn = state ⇒ bool

So rather than reasoning about single states, we reason about properties or sets of states. This is what we really need for verification of programs. Semantics called axiomatic for historic reasons. It is also called Hoare semantics.
Embedding of the Hoare Semantics

The Hoare semantics encoding in Isabelle is also given by an inductive definition. We first declare its type and a paraphrasing:

```
consts hoare :: "(assn * com * assn) set"
translations "\{P\} c \{Q\}" ⇔ "(P,c,Q) : hoare"
```

An object of the form \{P\} c \{Q\} is called a Hoare-triple. We now start giving the actual inductive definition . . .
The Inductive Definition: SKIP

inductive hoare
intrs
  skip "\{P\} SKIP \{P\}"

No surprise here.
The Inductive Definition

ass \[\vdash \{ \lambda s. \, P(s[x:=a]) \}, \, x:=a \, \{ P \} \]

This may be counter-intuitive, why not the other way round?
The Inductive Definition

$$\text{ass } "\vdash \{\lambda s. P(s[x:= (a s)])\} \ x:=a \ \{P\}"$$

This may be counter-intuitive, why not the other way round?

Consider an example: $a \equiv \lambda s.1$ and $P \equiv \lambda s. s x = 1$

$$\begin{align*}
\{\lambda s. (\lambda s.s x = 1)(s[x:= 1])\} x :=& \lambda s.1\{\lambda s.s x = 1\} \to_{\beta} \\
\{\lambda s. (s[x:= 1]) x = 1\} x :=& \lambda s.1\{\lambda s.s x = 1\} \to_{\beta} \\
\{\lambda s. (1 = 1)\} :=& \lambda s.1\{\lambda s.s x = 1\} \to_{\beta} \\
\{\lambda s. True\} x :=& \lambda s.1\{\lambda s.s x = 1\}
\end{align*}$$

What do we see? (You might also check the types.)
The Inductive Definition

\[ \text{ass } \vdash \{ \lambda s. P(s[x := (a \ s)]) \} \ x := a \ \{ P \} \]

This may be counter-intuitive, why not the other way round?
Consider an example: \( a \equiv \lambda s.1 \) and \( P \equiv \lambda s. s \ x = 1 \)

\[
\begin{align*}
\{ \lambda s. (\lambda s.s \ x = 1) (s[x := 1]) \} x :=& \lambda s.1 \{ \lambda s.s \ x = 1 \} \rightarrow \beta \\
\{ \lambda s. (s[x := 1]) \ x = 1 \} x :=& \lambda s.1 \{ \lambda s.s \ x = 1 \} \rightarrow \beta \\
\{ \lambda s. (1 = 1) \} :=& \lambda s.1 \{ \lambda s.s \ x = 1 \} \rightarrow \beta \\
\{ \lambda s. True \} x :=& \lambda s.1 \{ \lambda s.s \ x = 1 \}
\end{align*}
\]

What do we see? (You might also check the types.)
The \textit{ass} rule is such that it relates the pre-state \( True \) with the post-state \( \lambda s. \ s \ x = 1 \), which is what we expect.
The Inductive Definition: *Semi* and  

**IF** — **THEN** — **ELSE**

\[
\text{semi } "[ \vdash \{ P \} c \{ Q \}; \vdash \{ Q \} d \{ R \} ] \implies \vdash \{ P \} c; d \{ R \}"
\]

\[
\text{If } "[ \vdash \{ \lambda s. P s \land b s \} c \{ Q \}; \vdash \{ \lambda s. P s \land \neg b s \} d \{ Q \}] \implies \vdash \{ P \} \text{ IF } b \text{ THEN } c \text{ ELSE } d \{ Q \}"
\]

Since we are reasoning about sets of states, \(b s\) may sometimes be true and sometimes false, and so we have two premises for those two cases. It turns out that if \(b s\) is trivially true or trivially false, then one of the premises will be trivial to prove.
The Inductive Definition: \textit{WHILE}

While \( \vdash \{ \lambda s. P s \land b s \} \ c \ \{ P \} \implies \)
\( \vdash \{ P \} \text{ WHILE } b \text{ DO } c \ \{ \lambda s. P s \land \neg b s \} \)"

This has a flavor of \textit{loop invariants}: in the pre-state, \( b s \) holds, in the post-state, \( b s \) does not hold, and \( P \) holds all the time.
The Inductive Definition: Weakening and Strengthening

\[
\text{conseq } \begin{array}{ll}
\forall s. P' s \rightarrow P s ; \vdash \{ P \} c \{ Q \} ; \\
\forall s. Q s \rightarrow Q' s \end{array} \Rightarrow
\vdash \{ P' \} c \{ Q' \}
\]

One can always strengthen the pre-condition or weaken the post-condition.
The Rules at a Glance

inductive hoare

intrs

skip \( \vdash \{ P \}\text{SKIP}\{ P \} \)

ass \( \vdash \{ \lambda s. P(s[x::=a s]) \} \ x:=a \{ P \} \)

semi \[ \vdash \{ P \}\{ Q \}; \vdash \{ Q \}\{ R \} \] \implies \vdash \{ P \} \{ c; d \{ R \} \}

If \[ \vdash \{ \lambda s. P s \land b s \}\{ Q \}; \vdash \{ \lambda s. P s \land \neg b s \}\{ Q \} \] \implies \vdash \{ P \} IF b THEN c ELSE d \{ Q \}

While \( \vdash \{ \lambda s. P s \land b s \} \ c \{ P \} \implies \vdash \{ P \} WHILE b DO c \{ \lambda s. P s \land \neg b s \} \)

conseq \[ \forall s. P' s \rightarrow P s; \vdash \{ P \}\{ Q \}; \forall s. Q s \rightarrow Q' s \] \implies \vdash \{ P' \}\{ Q' \} \]
Validity Relation

We define a validity relation:

\[ \models \{ P \} c \{ Q \} \equiv \forall s \ t. (s, t) \in C(c) \rightarrow (P \ s) \rightarrow (Q \ t) \]
Validity Relation

We define a validity relation:

\[ \models \{ P \} c \{ Q \} \equiv \forall s \ t. (s, t) \in C(c) \rightarrow (P \ s) \rightarrow (Q \ t) \]

A Hoare triple \( \{ P \} c \{ Q \} \) is valid if it relates a set of input states and a set of output states correctly w.r.t. the denotational (or equivalently, operational) semantics: for any input state \( s \) and output state \( t \) related by the denotational semantics, if \( P \) holds for \( s \), then \( Q \) must hold for \( t \).
Validity Relation

We define a validity relation:

$$\models \{P\}c\{Q\} \equiv \forall s t. (s, t) \in C(c) \rightarrow (P s) \rightarrow (Q t)$$

A Hoare triple $\{P\}c\{Q\}$ is valid if it relates a set of input states and a set of output states correctly w.r.t. the denotational (or equivalently, operational) semantics: for any input state $s$ and output state $t$ related by the denotational semantics, if $P$ holds for $s$, then $Q$ must hold for $t$.

Why do we raise the issue of a semantics being valid, why don’t we just say “it’s defined like this, full stop”??
Relating Hoare and Denotational Semantics

Theorem 9 (Hoare soundness):

\[ \vdash \{ P \} c \{ Q \} \implies \models \{ P \} c \{ Q \} \]

Theorem 10 (Hoare relative completeness):

\[ \models \{ P \} c \{ Q \} \implies \vdash \{ P \} c \{ Q \} \]

Why relative?

So the Hoare relation is in fact compatible with the denotational semantics of IMP.
Example Program

tm := λx. 1;
sum := λx. 1;
i := λx. 0;
WHILE λs. (s sum) ≤ (s a) DO
  (i := λs. (s i) + 1;
  tm := λs. (s tm) + 2;
  sum := λs. (s tm) + (s sum))
Example Program

tm \:=\:=\lambda x. 1;
sum \:=\:=\lambda x. 1;
i \:=\:=\lambda x. 0;
WHILE \lambda s. (s sum) \leq (s a) DO
\begin{align*}
(i & \:=\:=\lambda s. (s i) + 1; \\
 tm & \:=\:=\lambda s. (s tm) + 2; \\
 sum & \:=\:=\lambda s. (s tm) + (s sum))
\end{align*}

What does this program do?
Example Program

\[ \text{tm} ::= \lambda x. 1; \]
\[ \text{sum} ::= \lambda x. 1; \]
\[ \text{i} ::= \lambda x. 0; \]
\[ \text{WHILE}\ \lambda s. (s \text{ sum}) \leq (s a) \text{ DO} \]
\[ (\text{i} ::= \lambda s. (s \text{ i}) + 1; \]
\[ \text{tm} ::= \lambda s. (s \text{ tm}) + 2; \]
\[ \text{sum} ::= \lambda s. (s \text{ tm}) + (s \text{ sum}) \]

What does this program do?

Try \( a = 1, a = 2, \ldots \), and look at \( i! \)
Square Root

Answer: The program computes the square root. Informally:

\[ Pre \equiv "True" \]
Square Root

Answer: The program computes the square root. Informally:

\[
Pre \equiv "True"
\]

\[
Post \equiv "i^2 \leq a < (i + 1)^2"
\]
Square Root

Answer: The program computes the square root. Informally:

\[
Pre \equiv " True"
\]
\[
Post \equiv " i^2 \leq a < (i + 1)^2"
\]

Formally

\[
Pre \equiv \lambda s. \ True
\]


**Square Root**

Answer: The program computes the square root. Informally:

\[
Pre \equiv \"True\"
\]
\[
Post \equiv \"i^2 \leq a < (i + 1)^2\"
\]

Formally

\[
Pre \equiv \lambda s. \ True
\]
\[
Post \equiv \lambda s. \ (s \ i) \ast (s \ i) \leq (s \ a) \land \\
\quad s \ a < (s \ i + 1) \ast (s \ i + 1)
\]
**Proving** \( \{ Pre \} \ldots \{ Post \} \)

We will now construct a proof tree showing that the program computes the square root.

Generally, the difficulty is to know when to apply *conseq*. We try to illustrate the search for the proof tree by animation. Still you may not understand each choice immediately, but only in hindsight!

We use two metavariables: *Inv* for the loop invariant, *PW* for the enter condition of the loop. We instantiate later.

Abbreviation: \( ExC \equiv \lambda s. Inv \ s \land \neg s \ sum \leq s \ a \) (“exit condition”). We omit \( \vdash \)!
Proof

\{ \text{Pre} \} \text{tm} \ldots \{ \text{Post} \}

This is what we want to prove.
Proof

\[
\begin{array}{c}
\{ \text{Pre} \} \quad tm \ldots \quad \{ \text{ExC} \} \\
\hline
I_2 \quad \text{conseq}
\end{array}
\]

Nothing happens after the loop, so intuition says that \( \text{ExC} \) must imply \( \text{Post} \).
Proof

Apply \textit{semi} three times. \textit{PW} ("pre while") is just a sensible choice of name: we don’t know yet what it is.
This application of \textit{ass} will allow us to reconstruct the precondition in the line just below.
And likewise $\mathcal{A}_2$. 
Proof

\[
\begin{align*}
\text{And likewise } A_1. \\
\end{align*}
\]
Proof

We now know (by the form of \textit{conseq}) what $I_1$ is.
Intuition says that \( PW \) must imply \( Inv \).
Of course, we are not ready yet. . .
Completing the Proof

$A_1$, $A_2$ and $A_3$ are complete, and $I_4$ is trivial.
Completing the Proof

$A_1$, $A_2$, and $A_3$ are complete, and $I_4$ is trivial.

$I_1$, $I_2$, $I_3$, and $\{Inv\}$ $WH \ldots \{ExC\}$ remain to be shown.
Completing the Proof

$A_1$, $A_2$, and $A_3$ are complete, and $I_4$ is trivial.

$I_1$, $I_2$, $I_3$, and $\{Inv\} WH \ldots \{ExC\}$ remain to be shown.

This also involves the question of how the metavariables must be instantiated.
What is $PW$?

The metavariable $PW$ ("precondition of WHILE") must fulfill (to show $I_1$)

$$\forall s. \text{Pre } s \rightarrow PW(s[i := 0][sum := 1][tm := 1])$$

where

$$s[i := 0][sum := 1][tm := 1] = \lambda y. \text{if } y = \text{tm} \text{ then } 1 \text{ else (if } y = \text{sum} \text{ then } 1 \text{ else (if } y = i \text{ then } 0 \text{ else (s y))})$$
What is \( PW \)?

The metavariable \( PW \) ("precondition of WHILE") must fulfill (to show \( \mathcal{I}_1 \))

\[
\forall s. \, \text{Pre } s \rightarrow PW(s[i := 0][sum := 1][tm := 1])
\]

where

\[
s[i := 0][sum := 1][tm := 1] = \lambda y. \, \text{if } y = tm \text{ then } 1 \text{ else (if } y = sum \text{ then } 1 \text{ else (if } y = i \text{ then } 0 \text{ else (s y))})
\]

Solution (recall that \( \text{Pre } \equiv \lambda s. \, \text{True} \)):

\[
PW = \lambda s. \, s \ i = 0 \land s \ sum = 1 \land s \ tm = 1
\]
What is $Inv$?

Continuing our proof tree construction:

\[
\begin{array}{c}
\{ \lambda s. Inv \ s \land s \ sum \leq s \ a \} \quad \text{"body"} \\
\text{While} \\
\{ Inv \} \quad WH \ldots \quad \{ ExC \}
\end{array}
\]
What is $\text{Inv}$?

Continuing our proof tree construction:

$$\{\lambda s.\text{Inv } s \land s\text{ sum } \leq s\text{ a}\} i :== \lambda s. s i + 1\{P'\}$$

$$\{P'\} tm :== \lambda s. s tm + 2\{P''\}$$

$$\{P''\} \text{sum} :== \lambda s. s tm + s\text{ sum}\{\text{Inv}\}$$

$$\{\lambda s.\text{Inv } s \land s\text{ sum } \leq s\text{ a}\} \text{"body"} \{\text{Inv}\}$$

$$\{\text{Inv}\} \text{WH } \ldots \{\text{ExC}\}$$

Just blindly applying $\text{semi}$ twice gives three formulas to be proven using $\text{ass}$, one for each assignment in the loop.
What is $Inv$?

Continuing our proof tree construction:

$$\{\lambda s. Inv \ s \land s \ sum \leq s \ a\}i :== \lambda s. s \ i + 1\{P'\}$$

$$\{P'\}tm :== \lambda s. t \ m + 2\{P''\}$$

$$\{P''\}sum :== \lambda s. t \ m + s \ sum\{Inv\}$$

$$\{\lambda s. Inv \ s \land s \ sum \leq s \ a\}\ "body" \ {Inv}\ semi^2$$

$$\{Inv\} WH \ \ldots \ \{ExC\}$$

Just blindly applying $semi$ twice gives three formulas to be proven using $ass$, one for each assignment in the loop.

Now what are $P'$ and $P''$? Have a look at rule $ass$ first!
Calculating $P'$ and $P''$ (by Rule $ass$)

\[ P'' = \lambda s. Inv(s[sum ::= s \cdot tm + s \cdot sum]) \]
Calculating $P'$ and $P''$ (by Rule $ass$)

\[
P'' = \lambda s. Inv(s[sum ::= s \, tm + s \, sum])
\]

\[
P' = \lambda s'. P''(s'[tm ::= s' \, tm + 2]) \quad \text{(rule $ass$)}
\]
Calculating $P'$ and $P''$ (by Rule $ass$)

\[ P'' = \lambda s.\text{Inv}(s[sum ::= s\ tm + s\ sum]) \]

\[ P' = \lambda s'.P''(s'[tm ::= s'\ tm + 2]) \quad \text{(rule $ass$)} \]
\[ = \lambda s'.(\lambda s.\text{Inv}(s[sum ::= s\ tm + s\ sum]))(s'[tm ::= s'\ tm + 2]) \]
Calculating $P'$ and $P''$ (by Rule $ass$)

$$P'' = \lambda s. Inv(s[sum ::= s \ tm + s \ sum])$$

$$P' = \lambda s'. P''(s'[tm ::= s' \ tm + 2]) \quad \text{(rule $ass$)}$$
$$= \lambda s'. \left(\lambda s. Inv(s[sum ::= s \ tm + s \ sum])\right)$$
$$\quad (s'[tm ::= s' \ tm + 2])$$
$$= \lambda s'. Inv((s'[tm ::= s' \ tm + 2])$$
$$\quad [sum ::= (s'[tm ::= s' \ tm + 2]) \ tm +$$
$$\quad (s'[tm ::= s' \ tm + 2]) \ sum])$$
Calculating $P'$ and $P''$ (by Rule $ass$)

$$P'' = \lambda s.\text{Inv}(s[\text{sum ::= s tm + s sum}])$$

$$P' = \lambda s'.P''(s'[tm ::= s' tm + 2]) \quad \text{(rule } ass\text{)}$$

$$= \lambda s'.(\lambda s.\text{Inv}(s[\text{sum ::= s tm + s sum}]))(s'[tm ::= s' tm + 2])$$

$$= \lambda s'.\text{Inv}((s'[tm ::= s' tm + 2])$$

$$[\text{sum ::= (s'[tm ::= s' tm + 2]) tm + (s'[tm ::= s' tm + 2]) sum}])$$

$$= \lambda s'.\text{Inv}(s'[tm ::= s' tm + 2]$$

$$[\text{sum ::= s' tm + 2 + s' sum}]).$$
Applying $ss$ to $i ::= \lambda s. s\ i + 1$

Now treat $i ::= \lambda s. s\ i + 1$ in the same way. Temporarily, let’s write $P$ for $\lambda s. Inv\ s \land s\ sum \leq s\ a$. Recall $P' =$

$$\lambda s. Inv(s[tm ::= s\ tm + 2][sum ::= s\ tm + 2 + s\ sum]).$$
Applying $\textit{ass}$ to $i :== \lambda s. s\ i + 1$

Now treat $i :== \lambda s. s\ i + 1$ in the same way. Temporarily, let’s write $P$ for $\lambda s.\text{Inv}\ s \land s\ \text{sum} \leq s\ \text{a}$. Recall $P' =$

$$\lambda s.\text{Inv}(s[tm ::= s\ tm + 2][sum ::= s\ tm + 2 + s\ \text{sum}]).$$

$P = \lambda s'.\ P'(s'[i ::= s'\ i + 1])$ \hspace{1cm} (by rule $\textit{ass}$)
Applying $ass$ to $i := \lambda s.s\ i + 1$

Now treat $i := \lambda s.s\ i + 1$ in the same way. Temporarily, let’s write $P$ for $\lambda s.\ Inv\ s \land s\ sum \leq s\ a$. Recall $P' = \lambda s.\ Inv(s[tm := s\ tm + 2][sum := s\ tm + 2 + s\ sum])$.

$P = \lambda s'.\ P'(s'[i := s'\ i + 1]) \quad \text{(by rule $ass$)}$

$= \lambda s'.\ (\lambda s.\ Inv(s[tm := s\ tm + 2][sum := s\ tm + 2 + s\ sum]))(s'[i := s'\ i + 1])$
Applying $ass$ to $i ::= \lambda s. s \ i + 1$

Now treat $i ::= \lambda s. s \ i + 1$ in the same way. Temporarily, let’s write $P$ for $\lambda s. Inv \ s \land s \ sum \leq s \ a$. Recall $P' =$

$$
\lambda s. Inv(s[tm ::= s \ tm + 2][sum ::= s \ tm + 2 + s \ sum]).
$$

$$
P = \lambda s'. P'(s'[i ::= s' \ i + 1]) \quad \text{(by rule $ass$)}
$$
$$
= \lambda s'. \left( \lambda s. Inv(s[tm ::= s \ tm + 2][sum ::= s \ tm + 2 + s \ sum]) \right)
$$
$$
\left( s'[i ::= s' \ i + 1] \right)
$$
$$
= \lambda s'. Inv((s'[i ::= s' \ i + 1])
$$
$$
[tm ::= (s'[i ::= s' \ i + 1]) \ tm + 2]
$$
$$
[sum ::= (s'[i ::= s' \ i + 1]) \ tm + 2 + (s'[i ::= s' \ i + 1]) \ sum])
$$
Applying $\text{ass}$ to $i :== \lambda s. s \ i + 1$

Now treat $i :== \lambda s. s \ i + 1$ in the same way. Temporarily, let’s write $P$ for $\lambda s. \text{Inv} \ s \land s \ \text{sum} \leq s \ \text{a}$. Recall $P' = \lambda s. \text{Inv}(s[tm ::= s \ tm + 2][sum ::= s \ tm + 2 + s \ sum])$.

\[
P = \lambda s'. P'(s'[i ::= s' \ i + 1]) \quad \text{(by rule $\text{ass}$)}
\]
\[
= \lambda s'. (\lambda s. \text{Inv}(s[tm ::= s \ tm + 2][sum ::= s \ tm + 2 + s \ sum]))(s'[i ::= s' \ i + 1])
\]
\[
= \lambda s'. \text{Inv}((s'[i ::= s' \ i + 1])
\]
\[
[tm ::= (s'[i ::= s' \ i + 1]) \ tm + 2] \quad [sum ::= (s'[i ::= s' \ i + 1]) \ tm + 2 + (s'[i ::= s' \ i + 1]) \ sum])
\]
\[
= \lambda s. \text{Inv}(s[i ::= s \ i + 1][tm ::= s \ tm + 2][sum ::= s \ tm + 2 + s \ sum]).
\]
Applying \texttt{ass} to \texttt{i :== \lambda s.s i + 1}

\[\lambda s.\text{Inv} s \land s \text{ sum} \leq s \text{ a}\]

\[= \lambda s.\text{Inv}(s[i := s i + 1][tm := s \text{ tm} + 2][sum := s \text{ tm} + 2 + s \text{ sum}]).\]

So \texttt{Inv} must solve this equation.
\textbf{Inv} Must Fulfill the Equation

\textit{Inv} must fulfill the equation

\[ \lambda s.\text{Inv} \; s \land s \; \text{sum} \leq s \; a = \]
\[ \lambda s.\text{Inv}(s[i ::= s \; i + 1][tm ::= s \; tm + 2]
\quad [\text{sum} ::= s \; tm + 2 + s \; \text{sum}]) \]
Inv must fulfill the equation

\[ \forall s. \text{Inv } s \land s \text{ sum} \leq s \text{ a} \leftrightarrow \forall s. \text{Inv}(s[i ::= s \ i + 1][tm ::= s \ tm + 2]
[sum ::= s \ tm + 2 + s \ sum]) \]

Don’t think syntactically! We are in HOL: $=$ means $\leftrightarrow$, and we can replace \( \lambda \) by $\forall$. 
**Inv** Must Fulfill the Equation

*Inv* must fulfill the equation

\[
\forall s. \text{Inv} \, s \land s \, \text{sum} \leq s \, a \iff \\
\forall s. \text{Inv}(s[i := s \, i + 1][tm := s \, tm + 2] \\
[sum := s \, tm + 2 + s \, \text{sum}])
\]

Don’t think syntactically! We are in **HOL**: = means ↔, and we can replace λ by ∀.

Guessing the right *Inv* is obviously difficult! Informally

\[
\text{Inv} \equiv "(i + 1)^2 = \text{sum} \land tm = (2 \times i) + 1 \land i^2 \leq a"
\]
Checking that \textit{Inv} Fulfills equation

$$s \ sum \leq s \ a \ \land \quad (6)$$
$$\ (s \ i + 1)^2 = (s \ sum) \ \land \quad (7)$$
$$s \ tm = (2 \ast (s \ i)) + 1 \ \land \quad (8)$$
$$\ (s \ i)^2 \leq (s \ a) \ \land \quad (9)$$

(recall: $= \text{ means } \leftrightarrow$) $=$ (10)
$$((s \ i + 1) + 1)^2 = (s \ sum) + (s \ tm) + 2 \ \land \quad (11)$$
$$\ (s \ tm + 2) = (2 \ast (s \ i + 1)) + 1 \ \land \quad (12)$$
$$\ (s \ i + 1)^2 \leq (s \ a) \quad (13)$$
Proof Sketch

First show the “→”-direction:

(8) → (12) and (6) ∧ (7) → (13) by simple arithmetic. (11) is shown as follows:

\[
((s \ i + 1) + 1)^2 = (s \ i + 1)^2 + 2 \cdot (s \ i + 1) + 1
\]
\[
\overset{(7)}{=} (s \ sum) + 2(s \ i) + 1 + 2
\]
\[
\overset{(8)}{=} (s \ sum) + (s \ tm) + 2
\]
Proof Sketch (Cont.)

Now show the “$\leftarrow$”-direction:

$$(12) \rightarrow (8) \text{ and } (13) \rightarrow (9)$$ by simple arithmetic. $(7)$ is shown as follows:

\[
(s \, i + 1)^2 = ((s \, i + 1) + 1)^2 - 2 \ast (s \, i + 1) - 1
\]

\[
(11) \quad (s \, sum) + (s \, tm) + 2 - 2 \ast (s \, i + 1) - 1
\]

\[
(12) \quad (s \, sum) + 2 \ast (s \, i + 1) + 1
\]

\[
- 2 \ast (s \, i + 1) - 1
\]

\[
= s \, sum
\]

Finally, $(7) \wedge (13) \rightarrow (6)$. 
Proof Sketch (Cont.)

Now show the “←”-direction:

(12) → (8) and (13) → (9) by simple arithmetic. (7) is shown as follows:

\[
(s \ i + 1)^2 = ((s \ i + 1) + 1)^2 - 2 \times (s \ i + 1) - 1
\]

\[
\overset{(11)}{=} (s \ sum) + (s \ tm) + 2 - 2 \times (s \ i + 1) - 1
\]

\[
\overset{(12)}{=} (s \ sum) + 2 \times (s \ i + 1) + 1
\]

\[
-2 \times (s \ i + 1) - 1
\]

\[
= s \ sum
\]

Finally, (7) ∧ (13) → (6). So Inv is indeed an invariant!
The *WHILE* Loop: Remarks

We have shown

\[(\text{“enter condition”} \land \text{“invar. at entry”}) \iff \text{“invar. at exit”}\]
The \textit{WHILE} Loop: Remarks

We have shown

\[
(\text{“enter condition”} \land \text{“invar. at entry”}) \leftrightarrow \text{“invar. at exit”}
\]

One would definitely expect $\rightarrow$, but $\leftarrow$ is remarkable!
The *WHILE* Loop: Remarks

We have shown

\[
(\text{"enter condition" } \land \text{"invar. at entry"}) \leftrightarrow \text{"invar. at exit"}
\]

One would definitely expect \(\rightarrow\), but \(\leftarrow\) is remarkable!

We can show this because our invariant is so *strong*: for showing \(\rightarrow\), the *weaker* invariant \((7) \land (8)\), i.e.

\[
(i + 1)^2 = \text{sum} \land tm = (2 \times i) + 1
\]

would do (check it!).
The \textit{WHILE} Loop: Remarks

We have shown

\[ (\text{“enter condition”} \land \text{“invar. at entry”}) \leftrightarrow \text{“invar. at exit”} \]

One would definitely expect $\rightarrow$, but $\leftarrow$ is remarkable!

We can show this because our invariant is so strong: for showing $\rightarrow$, the weaker invariant (7) $\land$ (8), i.e.

\[ (i + 1)^2 = \text{sum} \land tm = (2 \times i) + 1 \]

would do (check it!).

But the extra condition $i^2 \leq a$ is needed for showing $Post$, which states what the program actually computes.
Taking Care of $Post$

We have shown $\mathcal{I}_1$ and $\{Inv\} \{WH \ldots \} \{ExC\}$. Now continue with $\mathcal{I}_2$.

Does $Post \ s$ follow from $Inv \ s \land \neg s \ sum \leq s \ a$?
Taking Care of $Post$

We have shown $\mathcal{I}_1$ and $\{Inv\}WH \ldots \{ExC\}$. Now continue with $\mathcal{I}_2$.

Does $Post \ s$ follow from $Inv \ s \land \neg s \ sum \leq s \ a$?

Yes!

$(s \ i)^2 \leq (s \ a)$ follows from (9)

$(s \ a) < (s \ i + 1)^2$ follows from $\neg s \ sum \leq (s \ a)$ and (7).
The Final Missing Part

\[ I_3 \] remains to be shown, i.e.

\[ \forall s. PW\; s \rightarrow Inv\; s \]

or, expanding the solutions for \( PW \) and \( Inv \)

\[ \forall s. \; s\; i = 0 \land s\; sum = 1 \land s\; tm = 1 \rightarrow (s\; i + 1)^2 = s\; sum \land s\; tm = (2 \times (s\; i)) + 1 \land (s\; i)^2 \leq (s\; a) \]

This is easy to check.
An Alternative for Tackling the Loop Part

Recall that our loop invariant was “too strong”. An alternative:

\[
\lambda s. Inv \; s \land s\;sum \leq s\;a \quad \text{"body"} \quad \{Inv\}
\]

\[
\{Inv\} \text{WH} \ldots \{ExC\} \quad \text{While}
\]
An Alternative for Tackling the Loop Part

Recall that our loop invariant was “too strong”. An alternative:

\[ \forall s. (\text{Inv } s \land s \text{ sum } \leq s \text{ a}) \rightarrow \text{Inv'} s \]

\[ \{\lambda s. \text{Inv } s \land s \text{ sum } \leq s \text{ a}\} \text{ "body" } \{\text{Inv}\} \]

\[ \{\text{Inv}\} \text{WH } \ldots \{\text{ExC}\} \]

While

\[ \text{conseq} \]
An Alternative for Tackling the Loop Part

Recall that our loop invariant was “too strong”. An alternative:

\[
\forall s. \left( \text{Inv } s \land s \text{ sum} \leq s \ a \right) \rightarrow \text{Inv'} s
\]

\[
\begin{align*}
\{ \text{Inv'} \}i & := \lambda s. i + 1 \{P'\} \\
\{P'\}tm & := \lambda s. tm + 2 \{P''\}
\end{align*}
\]

\[
\{P''\} \text{sum} := \lambda s. tm + s \text{ sum} \{\text{Inv}\}
\]

\[
\text{semi}^2
\]

\[
\begin{align*}
\{\text{Inv'}\} \quad \text{"body"} & \quad \{\text{Inv}\}
\end{align*}
\]

\[
\begin{align*}
\{\lambda s. \text{Inv } s \land s \text{ sum} \leq s \ a\} \quad \text{"body"} & \quad \{\text{Inv}\}
\end{align*}
\]

\[
\begin{align*}
\{\text{Inv}\} \quad \text{WH \ldots} & \quad \{\text{ExC}\}
\end{align*}
\]
Alternative (Cont.)

Applying \textit{ass} as before gives

$$Inv' = \lambda s. Inv(s[i ::= s \cdot i + 1][tm ::= s \cdot tm + 2]$$
$$[sum ::= s \cdot tm + 2 + s \cdot sum])$$

We are left with the proof obligation

$$\forall s. (Inv s \land s \cdot sum \leq s \cdot a) \rightarrow Inv(s[i ::= s \cdot i + 1]$$
$$[tm ::= s \cdot tm + 2][sum ::= s \cdot tm + 2 + s \cdot sum])$$

Just this could be shown setting weak \textit{Inv} \equiv (7) \land (8), but
for actually showing \textit{Post}, \(i^2 \leq a\) is still needed.
Automating Hoare Proofs

In the example, we have verified a program computing the square root. But this was tedious, and parts of the task can be automated.
Weakest Liberal Preconditions

Observation: the Hoare relation is deterministic to a certain extent.

Idea: we use this fact for the generation of (weakest liberal) preconditions.

Weakest liberal preconditions are:

constdefs wp :: com ⇒ assn ⇒ assn

"wp c Q ≡ (λs. ∀ t. (s, t ) : C(c) −→ Q t)"

So $wp c Q$ returns the set of states containing all states $s$ such that if $t$ is reached from $s$ via $c$, then the post-condition $Q$ holds for $t$. Computable?
Weakest Liberal Preconditions

Observation: the Hoare relation is deterministic to a certain extent.

Idea: we use this fact for the generation of (weakest liberal) preconditions.

Weakest liberal preconditions are:

\[
\text{constdefs } \wp :: \text{com} \Rightarrow \text{assn} \Rightarrow \text{assn} \\
"\wp c Q \equiv (\forall s. \forall t. (s, t) : C(c) \rightarrow Q t)"
\]

So \( \wp c Q \) returns the set of states containing all states \( s \) such that if \( t \) is reached from \( s \) via \( c \), then the post-condition \( Q \) holds for \( t \). Computable? Not obvious.
Equivalence Proofs

Main results of the wp-generator are:

- **wp_SKIP:** \(\text{wp \ SKIP \ Q = Q}\)
- **wp_Ass:** \(\text{wp \ (x := a) \ Q = (\lambda s. \ Q (s[x:=a] s))}\)
- **wp_Semi:** \(\text{wp \ (c; d) \ Q = \text{wp \ c \ (wp \ d \ Q)}\)
- **wp_If:** \(\text{wp \ (IF \ b \ THEN \ c \ ELSE \ d) \ Q = (\lambda s. \ (b s \rightarrow wp \ c \ Q \ s) \land (\neg b s \rightarrow wp \ d \ Q \ s))}\)
- **wp_While_True:** \(\text{b s }\rightarrow wp \ (\text{WHILE \ b \ DO \ c) \ Q \ s = wp \ (c; \text{WHILE \ b \ DO \ c) \ Q \ s}}\)
- **wp_While_False:** \(\text{\neg b s }\rightarrow wp \ (\text{WHILE \ b \ DO \ c) \ Q \ s = Q \ s}\)
- **wp_While_if:** \(\text{wp \ (WHILE \ b \ DO \ c) \ Q \ s = (if \ b \ s \ then \ wp(c; \text{WHILE \ b \ DO \ c) \ Q \ s \ else \ Q \ s)}\)
WP-Semantics

Except for termination problem due to \textit{While}, (weakest liberal) precondition $\textit{wp}$ can be computed. This fact can be used for further proof support by verification condition generation.
Verification Condition Generation

First, we must enrich the syntax by loop-invariants:

```ml
datatype acom =
    Askip
  | Aass loc aexp
  | Asemi acom acom
  | Aif bexp acom acom
  | Awhile bexp assn acom
```

Almost same as `com`, but `While` gets an additional argument for asserting a loop invariant. Asserting this is the difficult, creative step to be done by a human.
Computing a Weakest Liberal Precondition

We define a function that computes a \( wp \):

\[
\begin{align*}
\text{primrec} & \\
"awp \text{ Askip } Q = Q" & \\
"awp (Aass x a) Q = (\lambda s. Q(s[x:=a s]))" & \\
"awp (Asemi c d) Q = awp c (awp d Q)" & \\
"awp (Aif b c d) Q = (\lambda s. (b s \rightarrow awp c Q s) \land (\neg b s \rightarrow awp d Q s))" & \\
"awp (Awhile b Inv c) Q = Inv" & \\
\end{align*}
\]

Idea: for all statements, the exact \( wp \) is computed, except for \textit{While}, where the assertion provided by the user is taken as approximation. \textbf{Proof obligation}: show that such an assertion is compatible with the program and the desired property . . .
A Verification Condition

Construct a formula $vc \ c \ Q \ s$ with the intuitive reading: as far as the invariant assertions are concerned, $s$ is a good pre-state for reaching desired post-property $Q$ using annotated program $c$. Invariants only occur in While statements, so $vc (A\text{while} \ b \ Inv \ c) \ Q \ s$ is the only interesting case. What should hold?
A Verification Condition

Construct a formula $\text{vc } c \ Q \ s$ with the intuitive reading: as far as the invariant assertions are concerned, $s$ is a good pre-state for reaching desired post-property $Q$ using annotated program $c$. Invariants only occur in While statements, so $\text{vc } (\text{Awhile } b \ \text{Inv } c) \ Q \ s$ is the only interesting case. What should hold?

• The body ensures the invariant: $\text{vc } c \ \text{Inv } s$;
• invariant + exit condition imply $Q$: $\text{Inv } s \land \neg (b \ s) \rightarrow Q \ s$;
• invariant + loop condition imply precondition of invariant: $\text{Inv } s \land (b \ s) \rightarrow \text{awp } c \ \text{Inv } s$. 
Verification Condition Generation

For all other constructs, \( vc \) is quite trivial:

\[
\begin{align*}
\text{primrec} \\
\text{"vc }\text{Askip }Q &= (\lambda s. \text{True})" \\
\text{"vc }\text{(Aass }x\text{ a) }Q &= (\lambda s. \text{True})" \\
\text{"vc }\text{(Asemi }c\text{ d) }Q &= (\lambda s. \text{vc }c\text{ (awp d }Q\text{) }s \land \text{vc }d\text{ }Q\text{ )"} \\
\text{"vc }\text{(Aif }b\text{ c d) }Q &= (\lambda s. \text{vc }c\text{ }Q\text{ ) }s \land \text{vc }d\text{ }Q\text{ )"} \\
\text{"vc }\text{(Awhile }b\text{ Inv c) }Q &= (\lambda s. (\text{Inv }s \land \neg b\text{ }s \rightarrow Q\text{ ) }s \land \\
& \quad (\text{Inv }s \land b\text{ }s \rightarrow \text{awp }c\text{ Inv }s\text{ ) }\land \text{vc }c\text{ Inv }s\text{ )")}
\end{align*}
\]

\( vc \) is not about distinguishing good pre-states from bad pre-states, but just about formalising good invariant assertions. So we want \( \forall s. vc\ c\ Q\ s \), i.e., \( vc\ c\ Q \equiv \lambda s. \text{True} \).
Equivalence Proofs

Main results of the wp-generator are:

\[
\forall Q. (\forall s. \text{vc ac } Q s) \implies \vdash \{ \text{awp ac } Q \} \text{ astrip ac } \{ Q \}
\]
\[
\text{vc_complete: } \vdash \{ P \} c \{ Q \}
\implies \exists \text{ ac. astrip ac } = c \land (\forall s. \text{vc ac } Q s) \land (\forall s. P s \implies \text{awp ac } Q s)
\]

The function \text{astrip} turns \text{acom} programs into \text{com} programs by removing the loop invariant assertions.

Quintessence: To prove that a program \text{c} has property \text{Q} after execution, you must \text{annotate} it with loop invariants (\text{ac}) and show \(\forall s. \text{vc ac } Q s\). This implies that a Hoare proof exists, for the computable precondition \text{awp ac Q}. For good (robust) programs, \text{awp ac Q} = \lambda s. True.
Summary

IMP closely follows the standard textbook [Win96]. Isabelle/HOL is a powerful framework for embedding imperative languages. Isabelle/HOL is also a framework for state-of-the-art languages like JAVA including interfaces, inheritance, dynamic methods. It works in theory and for non-trivial problems in practice (but of modest size).
More Detailed Explanations
Flavors of Semantics

One distinguishes

- operational,
- denotational,
- axiomatic

semantics.

For **operational semantics**, the idea is that our machine is always in some **state**, essentially consisting of the values of the **program variables**. The instructions of a program transform a state into a new state. Operational semantics are useful for compiler construction.

For **denotational semantics**, the idea is that the meaning of a particular program is a **relation** between “input” states and “output” states.

**Axiomatic semantics** consist of a calculus for constructing proof
obligations.
Imperative Languages in the HOL Library

You should find directories for each mentioned imperative language in your Isabelle distribution. In Freiburg it is in

```
/usr/local/share/provers/Isabelle/src/HOL/
```
Shallow and Deep

The notions shallow and deep refer to the way the imperative language at hand is encoded in Isabelle.

In a deep embedding, the syntax of the analysed programming is modeled by (an) explicit datatype(s).

In a shallow embedding, the syntax of the analysed programming language is implicit in the notation for operators on the semantic domain.
Equivalence Proofs

Summarizing, we have the following equivalence results:

- natural vs. transition semantics
- denotational vs. natural semantics
Com.thy

This file defines the command syntax. An Isabelle term of type $\textit{com}$ is an IMP program.

You should find the files in your Isabelle distribution. In Freiburg they are in

/usr/local/share/provers/Isabelle/src/HOL/IMP/
Locations

We realize program variables via pointers (locations). The type of pointers is an abstract datatype.
We take the type of values to be $\text{nat}$, just to have something simple.
A state is a function taking a location to a value, i.e. intuitively, each program variable has a value in a state.
Abstractness of $aexp$ and $bexp$

In a formalization of the syntax of an imperative language, there will usually be some grammar saying that $1$, $x + 1$ (provided that $x$ is an arithmetic variable) etc. are arithmetic expressions and that $True$, $x == 1$ etc. are Boolean expressions. Such expressions can only be evaluated if the state, i.e. the value of the program variables, is given.

Now, our notion of expressions (as realized by the types $aexp$ and $bexp$) is much more abstract than that. An expression is a function taking a state to a value or Boolean, as applicable.

The fact that IMP has no explicit expression language allows for simple and abstract proofs.
The Intuition of Natural Semantics

The idea of the natural semantics is that a program relates two states, the "input state" and the "output state".

This may remind you of denotational semantics, and in fact, the natural semantics is a kind of hybrid between operational and denotational semantics.

The fact that the natural semantics just relates an "input state" and an "output state" means, so to say, that it does not record what happens in between, i.e. at the single steps of a computation. In that respect, it resembles denotational semantics.

But the way the meaning of a whole program is defined is still operational in nature. Essentially, it is defined in terms of the meaning of the first execution step and the meaning of the rest of the program.
The Intuition of Transition Semantics

Unlike the natural semantics, the transition semantics records the single steps of the computation. A configuration is a pair consisting of a program and a state, and one step reaches a new program and a new state.

Why “reaching a new program”? This realizes a program counter. For example, if the first line of the program is an assignment, then the new program is obtained by removing that line from the old program.
The Power of Paraphrasing

As you see, paraphrasing in Isabelle is very powerful. One can think of $\neg c \rightarrow$ and $\neg 1 \rightarrow$ as infix symbols. But $\neg n \rightarrow$ is by no means one single symbol. In fact the term $cs_0 \neg n \rightarrow cs_1$ is a paraphrasing of $(cs_0, cs_1) \in evalc1^n$. 
Relation_Power.thy

This file should be contained in your Isabelle distribution. In Freiburg it is

/usr/local/share/provers/Isabelle/src/HOL/Relation_Power.thy
Define $C$ by Primitive Recursion

Recall that the `primrec` syntax is used for defining functions recursively. Here, the argument type of the function $C$ is the datatype $\text{com}$. It is characteristic for the definition of a datatype that its elements are defined by (structural) induction, i.e., its elements are syntactic terms formed from previously generated syntactic forms using a specific set of term constructors. For datatypes, it is clear that the subterm relation is a well-founded order. Hence it is legitimate to define $C$ using recursion.
Understanding $\Gamma$

Let’s try to understand

"$\Gamma \ b \ cd \equiv (\lambda \phi.\{(s, t) . \ s = t \land \neg b(s)\}) \cup \{(s, t) . \ (\phi \circ cd) \land b(s)\} \cup \{(s, t) . \ s = t \land \neg b(s)\}"

Note that in the definition of WHILE, the second argument to $\Gamma$ is $(Cc)$, which is the semantics of the body of the WHILE statement, i.e., a binary relation between input states and output states. So $cd$ above is the semantics of the body of the WHILE statement.

Let

$$S_0 = \{(s, t) | s = t \land \neg b(s)\}$$
and for $i > 0$,

$$S_i = \{(s, t) \mid \exists s_0, \ldots, s_i. s_0 = s \land s_i = t \land (s_0, s_1) \in cd \land \ldots \land (s_{i-1}, s_i) \in cd \land b(s_0) \land \ldots \land b(s_{i-1})\}$$

When we apply $(\Gamma b cd)$ to $\emptyset$ (the empty relation), then since $\emptyset \circ cd = \emptyset$, we get just $S_0$. Now it is easy to see that $(\Gamma b cd) S_0 = S_0 \cup S_1$, and generally, for all $i > 0$

$$(\Gamma b cd)(\bigcup_{j \leq i} S_j) = \bigcup_{j \leq i+1} S_j$$

So the intuition of the functional $(\Gamma b cd)$ is as follows: given the semantics of the $WHILE$ statement for up to $i$ passes through the loop, return the semantics of the $WHILE$ statement for up to $i + 1$ passes
through the loop. The $lfp$ of this functional is the actual semantics of the $WHILE$ statement.
Is the Axiomatic Semantics Really Axiomatic?

In terms of Isabelle/HOL, the semantics is not defined by axioms, but is an inductive definition.
The Types in the Hoare Assignment Rule

Things are getting a bit complicated, maybe it helps to recall the types of the terms occurring in

\[ \text{ass } \vdash \{ \lambda s. \, P(s[x::=(a \ s )]) \} \ x:=a \ \{P\} \]

\( P \) has type \( \text{assn} \), \textbf{which is} state \( \Rightarrow \) bool. In turn, state \textit{is} loc \( \Rightarrow \) val.

\( x \) has type \( \text{loc} \).

\( a \) has type \( \text{aexp} \), \textbf{which is} state \( \Rightarrow \) val.

\( s \) has type \( \text{state} \).
The Assignment Rule

You can also argue a bit more generally. Let $Q$ be an arbitrary assertion, and let

$$P \equiv \lambda s. \exists s'. Q s' \land s = s'[x ::= (a\ s')]$$

Intuitively: $P$ is an assertion allowing any state obtained from a state allowed by $Q$ by updating that state at location $x$ with the the expression $a$. Now consider the rule for assignment:

$$\text{ass } \vdash \{ \lambda s. P(s[x ::= (a \ s)]) \} \quad x ::= a \ \{P\}$$

in particular the assertion on the left-hand side. It reduces as follows:

$$\lambda s. P(s[x ::= (a \ s)]) \rightarrow_{\beta}$$
$$\lambda s. (\exists s'. Q s' \land s[x ::= (a \ s)] = s'[x ::= (a \ s')]) \rightarrow_{\beta} \ldots$$
$$\lambda s. (\exists s'. Q s' \land s = s') \rightarrow_{\beta} \ldots \lambda s. (Q s) \rightarrow_{\eta} Q$$

So you see that any pre-state $Q$ will be related to a post-state $P$ as
given above.
By this argument, we have only shown which post-states are possible given an arbitrary pre-state, not which post-states are not. Such an argument is more complicated.
A Table of Values

\( a \) is not modified anywhere. You should think of \( a \) as input of the program.

\( i \) counts the number of times the loop is entered, i.e. the final value of \( i \) is the number of times the loop was entered. This number depends on \( a \). The following table shows that final values of \( i, \) \( tm \) and \( sum \) depending on the value of \( a \):
\[ (i + 1)^2 = i^2 + 2i + 1 \]

Since \( tm \) takes the value \( 2i + 1 \) for all \( i \) successively, it follows that

| 0 ≤ a < 1 | 0 | 1 | 1 |
| 1 ≤ a < 4 | 1 | 3 | 4 |
| 4 ≤ a < 9 | 2 | 5 | 9 |
| 9 ≤ a < 16 | 3 | 7 | 16 |
| 16 ≤ a < 25 | 4 | 9 | 25 |
| 25 ≤ a < 36 | 5 | 11 | 36 |
| 36 ≤ a < 49 | 6 | 13 | 49 |

\( sum \) takes the values of all squares successively, computed by the famous binomial formula:
$sum + tm$ always gives the next value of $sum$. 
Informally we talk about variables $i, x$ etc. and say "$x$ has value 5", for example. But formally, variables are realized via locations, and so we get expressions of the form $s\, x$. That is, $s\, x$ is the value of variable $x$. 

$(s\, i), (s\, a)$ etc.
Nondeterminacy in the Hoare Calculus

The \textit{conseq} rule can always be applied. If one decides not to apply the \textit{conseq} rule, then the choice of any other rule is deterministic.
Why Do We Question Hoare?

You may wonder: Why do we raise the issue of a semantics being valid, why don’t we just say “it’s defined like this, full stop”? After all, we didn’t question the operational and denotational semantics in the same way. So why do we take the denotational semantics as the real semantics of a program that another semantics such as the Hoare semantics has to be somehow equivalent to in order to be correct? Couldn’t we do it the other way round?
Why Do We Question Hoare?

You may wonder: Why do we raise the issue of a semantics being valid, why don’t we just say “it’s defined like this, full stop”? After all, we didn’t question the operational and denotational semantics in the same way. So why do we take the denotational semantics as the real semantics of a program that another semantics such as the Hoare semantics has to be somehow equivalent to in order to be correct? Couldn’t we do it the other way round?

First: If you want to accept anything as the real semantics of a program, it would be the transition semantics, since we believe that by the transition semantics, we have modeled what the compiler of the programming language actually does. The transition semantics records the actual computation steps.

Secondly, we have shown that the transition semantics is equivalent to
the **natural semantics**, which in turn is equivalent to the **denotational semantics**.

Together this explains why we call a Hoare triple valid if it is correct w.r.t. the denotational semantics.
Relative Completeness

We will not give any details here, but the completeness result is restricted in the same way that the completeness of HOL is restricted to general models, as opposed to standard models.
Program “Fragment”

This is the entire program, namely:

\[
\begin{align*}
\text{tm} & := \lambda x. 1; \\
\text{sum} & := \lambda x. 1; \\
i & := \lambda x. 0; \\
\text{WHILE } & \lambda s. s \text{ sum} \leq s \text{ a DO} \\
& \quad (i := \lambda s. s i + 1; \\
& \quad \quad \text{tm} := \lambda s. s \text{ tm} + 2; \\
& \quad \quad \text{sum} := \lambda s. s \text{ tm} + s \text{ sum})
\end{align*}
\]

(return to main proof tree)
Program Fragment

This is the program fragment starting from $sum :=$, namely:

\[
\begin{align*}
    sum & := \lambda x. 1; \\
    i & := \lambda x. 0; \\
    \textbf{WHILE } & \lambda s. s sum \leq s a \textbf{ DO} \\
    & (i := \lambda s. s i + 1; \textcolor{red}{\textbf{DO}} \\
    & \quad \textcolor{red}{\textbf{tm := \lambda s. s tm + 2;}} \textcolor{red}{\textbf{DO}} \\
    & \quad \textcolor{red}{\textbf{sum := \lambda s. s tm + s sum})} \textcolor{red}{\textbf{DO}} \\
\end{align*}
\]

(return to main proof tree)
**Program Fragment**

This is the program fragment starting from $i :==,$ namely:

$$i :== \lambda x. 0;$$

WHILE $\lambda s. s \text{ sum} \leq s \text{ a}$ DO

$$(i :== \lambda s. s \ i + 1;$

$tm :== \lambda s. s \ tm + 2;$

$sum :== \lambda s. s \ tm + s \ sum)$$

(return to main proof tree)
Program Fragment

This is the program fragment starting from **WHILE**, namely:

\[
\text{WHILE } \lambda s. \ s \ \text{sum} \ \leq s \ a \ \text{DO}
\]

\[
(i \ := \ = \lambda s. \ s \ i \ + \ 1;
\]

\[
tm \ := \ = \lambda s. \ s \ \text{tm} \ + \ 2;
\]

\[
\text{sum} \ := \ = \lambda s. \ s \ \text{tm} \ + \ s \ \text{sum})
\]

(return to main proof tree)
Program Fragment

This is the program fragment consisting of the loop body, namely:

\[
\begin{align*}
    i & := \lambda s. s \; i + 1; \\
    tm & := \lambda s. s \; tm + 2; \\
    sum & := \lambda s. s \; tm + s \; sum
\end{align*}
\]

(return to main proof tree)
A Missing Part

$I_1$ is the formula

$$\forall s. Pre \ s \rightarrow PW(s["i, sum, tm"])$$

where $Pre$ is defined above and $PW$ is a metavariable ("precondition of $WHILE$").

(return to main proof tree)
A Missing Part

$I_2$ is the formula

$$\forall s. ExC s \rightarrow Post s,$$

i.e.

$$\forall s. Inv s \land \neg sum s \leq s \cdot a \rightarrow Post s,$$

where $Post$ is defined above and $Inv$ is a metavariable ("loop invariant").

(return to main proof tree)
A Missing Part

\[ A_1 \] is the proof tree

\[
\{ \lambda s. PW(s["i, sum, tm"]\}) tm := \lambda x.1\{\lambda s. PW(s["i, sum"]\}) \}
\]

where \( PW \) is a metavariable ("precondition of \( WHILE \)).

(return to main proof tree)
A Missing Part

$A_2$ is the proof tree

\[
\{ \lambda s. PW (s[i ::= 0][sum ::= 1]) \} \text{sum ::= } \lambda x.1 \{ \lambda s. PW (s[i ::= 0]) \} \\
\]

where $PW$ is a metavariable ("precondition of WHILE").

(return to main proof tree)
A Missing Part

$A_3$ is the proof tree

$$\begin{array}{c}
\{ \lambda s. PW(s[i ::= 0]) \} i ::= \lambda x.0\{ PW \}
\end{array}$$

ass

where $PW$ is a metavariable ("precondition of WHILE").

(return to main proof tree)
A Missing Part

\[ \mathcal{I}_3 \text{ is the formula} \]

\[ \forall s. PW s \rightarrow Inv s \]

where \( PW \) is a metavariable ("precondition of WHILE") and \( Inv \) is a metavariable ("loop invariant").

(return to main proof tree)
A Missing Part

\[ \mathcal{I}_4 \]
is the formula

\[ \forall s. \text{ExC } s \rightarrow \text{ExC } s \]

which is of course trivial to prove.

\( \text{(return to main proof tree)} \)
An Abbreviation for an Updated State

We use \( s["i, sum, tm"] \) as abbreviation for

\[
s[i ::= 0][sum ::= 1][tm ::= 1]
\]

Note that this is

\[
\lambda y. \text{if } y = tm \text{ then } 1 \text{ else } \\
(\text{if } y = sum \text{ then } 1 \text{ else } (\text{if } y = i \text{ then } 0 \text{ else } (s y)))
\]

(return to main proof tree)
An Abbreviation for an Updated State

We use $s["i, sum"]$ as abbreviation for

$$s[i ::= 0][sum ::= 1]$$

Note that this is

$$\lambda y. \text{if } y = \text{sum} \text{ then } 1 \text{ else (if } y = i \text{ then } 0 \text{ else (s y))}$$

{return to main proof tree}
An Abbreviation for an Updated State

We use $s["i"]$ as abbreviation for

$$s[i ::= 0]$$

Note that this is

$$\lambda y. \text{if } y = i \text{ then } 0 \text{ else } (s \ y)$$

(return to main proof tree)
Displaying Proof Tree

Of course, these three formulas should be side by side in the proof tree, but this cannot be displayed.
What must $\text{Inv}$ Be?

Recall that we had to prove the three formulas

\[
\{ \lambda s. \text{Inv } s \land s \sum \leq s \alpha \}\ i ::= \lambda s.s \ i + 1\{P'\}
\]

\[
\{P'\}tm ::= \lambda s.s \ tm + 2\{P''\}
\]

\[
\{P''\}sum ::= \lambda s.s \ tm + s \sum\{\text{Inv}\}
\]

all by $\text{ass}$. Dealing with the second and third formula using $\text{ass}$, we found that

\[P' = \lambda s'. \text{Inv}(s'[tm ::= s' \ tm + 2][sum ::= s' \ tm + 2 + s' \ sum]).\]

Therefore, to show

\[
\{ \lambda s. \text{Inv } s \land s \sum \leq s \alpha \}\ i ::= \lambda s.s \ i + 1\{P'\}
\]
as well, $Inv$ must have such a form that the formula becomes an instance of $ass$. 
Why “Precondition of Invariant”

Why should invariant + loop condition imply the precondition of the invariant?

To achieve that the invariant will still hold after another unfolding of the While-loop).
A Taste of some Isabelle and HOL Applications
Just a few Isabelle or HOL Applications

We briefly introduce two Isabelle/HOL applications, and one application of HOL Light:

- Java bytecode verification;
- floating-point arithmetic;
- red-black trees.

This is just to stimulate you to look for more applications on your own!
Java Bytecode Verification

Typically, Java programs are delivered as bytecode, as opposed to source code on the one hand and machine code on the other hand. Bytecode is machine-independent. A Java runtime system provides the Java Virtual Machine, i.e., an interpreter for Java bytecode.

Java is a typed language: the type system forbids things like pointer arithmetic, thus preventing illegal memory access. However, bytecode is not type-safe by itself. For various reasons, bytecode could be corrupted. This is obviously critical for security and possibly safety.
Ensuring Type Safety

The loader of a typical JVM has a bytecode verifier: A program that checks whether bytecode is type-safe. Klein and Nipkow have specified a JVM and a bytecode verifier in Isabelle and proved its correctness using Isabelle [KN03, Nip03]. Such applications may have big impact since they are concerned with the correctness of not just some particular program, but rather the programming language (implementation) itself.
JavaCard

JavaCard is a subset of Java employed on smart cards. Aspects in contrast to full Java:

- Memory on smart cards is limited.
- Security is vital for smart card applications (banking etc.).

Project Verificard concerned with ensuring reliability of smart card applications.

Verificard @ Munich have applied the work on bytecode verification (using Isabelle) to JavaCard.

End user panel includes Ericsson, France Télécom R&D, and Gemplus.
Floating Point Arithmetic

John Harrison has done much work on verifying arithmetic functions operating on various number types adhering to certain standards [Har98, Har99, Har00]. He has used HOL Light, not Isabelle. This means: no metalogic, specialized theorem prover for HOL. He formally proved that the floating point operations of an Intel processor behave according to the IEEE standard 754 [IEE85]. First machine-checked proof of this kind. We briefly review his work [Har99] using an Isabelle-like syntax where helpful.
What Are Floats?

Conventionally: floats have the form $\pm 2^e \cdot k$.

$e$ is called **exponent**, $E_{min} \leq e \leq E_{max}$.

$k$ is called **mantissa**, can be represented with $p$ bits.
Floats in HOL

For formalization in HOL, equivalent representation

\[ (-1)^s \cdot 2^{e-N} \cdot k \]

with \( k < 2^p \) and \( 0 \leq e < E \).

Thus a particular float format is characterized by maximal exponent \( E \), precision \( p \), and exponent offset ("ulpyscale") \( N \). The set of real numbers representable by a triple is:

format \((E,p,N) = \)
\[ \{ x \mid \exists s e k. \ s < 2 \land e < E \land k < 2^p \land x = (-1)^s \cdot 2^e \cdot k/2^N \} \]
Rounding

Rounding takes a real to a representable real nearby. E.g. rounding up:

\[
\text{round fmt } x = \epsilon a. \ a \in \text{format fmt} \land a \leq x \land \forall b \in \text{format fmt. } b \leq x \rightarrow b \leq a
\]

Formalization of the Standard [IEE85]. Useful lemmas such as:

\[
x \leq y \implies \text{round fmt } x \leq \text{round fmt } y
\]

\[
a \in \text{format fmt} \land b \in \text{format fmt} \land 0.5 \leq \frac{a}{b} \leq 2 \implies (b - a) \in \text{format fmt}
\]
Operations

For operations such as addition, multiplication etc., it is proven in HOL that they behave as if they computed the exact result and rounded afterwards. However, there are some debatable questions related to the sign of zeros.
Red-Black Trees

Red-black trees are trees that can be used for implementing sets/dictionaries, just like AVL trees. To formulate “balanced-ness” invariants, nodes are colored:

1. Every red node has a black parent.
2. Each path from the root to a leaf has the same number of black nodes.

Together these invariants ensure that maximal paths can differ in length by at most factor 2.

These invariants must be maintained by insertion and deletion operations.
Red-Black Trees in SML

Red-black trees provided in New Jersey SML library [Pau96]. Angelika Kimmig tried to verify the insertion operation of red-black trees using Isabelle. Findings?
Red-Black Trees in SML

Red-black trees provided in New Jersey SML library [Pau96]. Angelika Kimmig tried to verify the insertion operation of red-black trees using Isabelle. Findings?

- There is a mistake in the implementation of red-black trees in New Jersey SML! Insertion may lead to a violation of the first invariant, since the root may become red.
- As long as one just inserts, this is just a slight constant deterioration.
- Angelika has suggested a fix and proven the correctness of red-black tree insertion using Isabelle.
Node Deletion

- **Deletion** is also wrongly implemented!
- With deletion, not just the root can become red, but the tree coloring can become completely wrong.
- Angelika has an idea for fixing deletion as well, but no proof (yet?).

Read the Studienarbeit for more details [Kim03]!
More Detailed Explanations
Illegal Memory Access

By “illegal memory access”, we mean access to regions not assigned to the program.
Limited Memory on Smart Cards

The memory on smart cards is limited. A full-fledged bytecode verifier would be too large/slow. One approach to tackling this problem is to work with bytecode programs with type annotations. Checking if a bytecode program is consistent with its type annotations is a much simpler task than computing these type annotations, which is what a bytecode verifier is supposed to do. The task can therefore be performed on a smart card more easily than full bytecode verification.
Angelika Kimmig

Angelika Kimmig is a student who took this course in Wintersemester 02/03 in Freiburg. She then continued working with Isabelle in a Studienarbeit (a project required by computer science students in Freiburg).
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