Game Theory

4. Algorithms

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Zero-Sum Games

General Finite Two-Player Games

Summary

Motivation

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- We know: In finite strategic games, mixed-strategy Nash equilibria are guaranteed to exist.
- We don't know: How to systematically find them?
- Challenge: There are infinitely many mixed strategy profiles to consider. How to do this in finite time?

This chapter:

- Computation of mixed-strategy Nash equilibria for finite zero-sum games.
- Computation of mixed-strategy Nash equilibria for general finite two player games.

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Digression:

We briefly discuss linear programming because we will use this technique to find Nash equilibria.

Goal of linear programming:

Solving a system of linear inequalities over *n* real-valued variables while optimizing some linear objective function.

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Example

Production of two sorts of items with time requirements and profit per item. Objective: Maximize profit.

	Cutting	Assembly	Postproc.	Profit per item
(x) sort 1	25	60	68	30
(y) sort 2	75	60	34	40
per day	≤ 450	≤ 480	≤ 476	maximize!

Goal: Find numbers of pieces *x* of sort 1 and *y* of sort 2 to be produced per day such that the resource constraints are met and the objective function is maximized.

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Example (ctd., formalization)

$$x \ge 0, y \ge 0$$

$$25x + 75y \le 450$$
 (or $y \le 6 - \frac{1}{3}x$) (2)

$$60x + 60y \le 480$$
 (or $y \le 8 - x$) (3)

$$68x + 34y \le 476$$
 (or $y \le 14 - 2x$) (4)

$$maximize z = 30x + 40y (5)$$

- Inequalities (1)–(4): Admissible solutions (They form a convex set in \mathbb{R}^2 .)
- Line (5): Objective function

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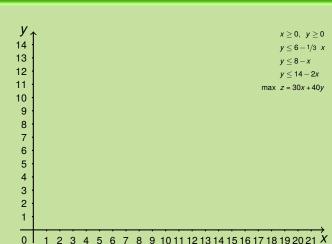
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Example (ctd., visualization)



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Example (ctd., visualization)



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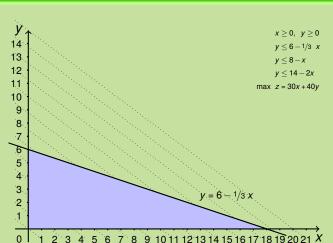
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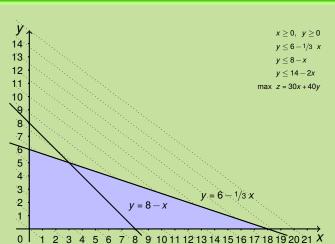
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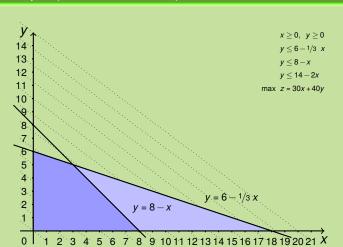
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Example (ctd., visualization)



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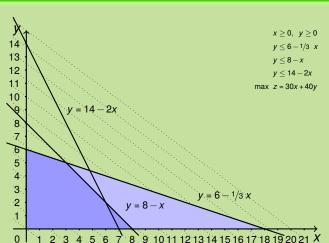
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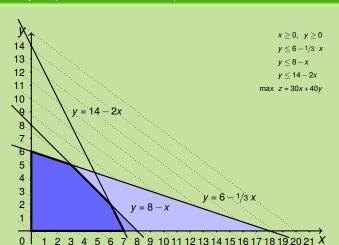
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Example (ctd., visualization)



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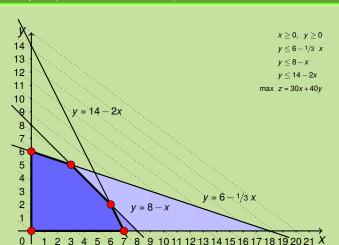
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Example (ctd., visualization)



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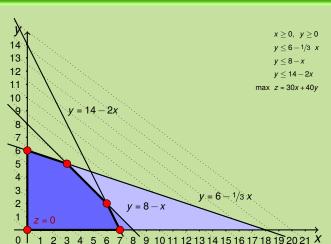
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Example (ctd., visualization)



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Example (ctd., visualization)



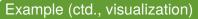
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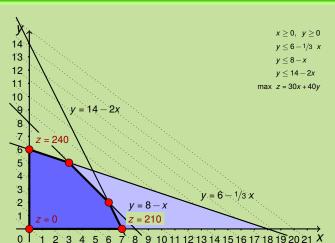
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Example (ctd., visualization)



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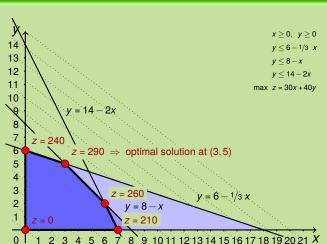
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Example (ctd., visualization)



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Definition (Linear program)

A linear program (LP) in standard from consists of

- *n* real-valued variables x_i ; *n* coefficients b_i ;
- *m* constants c_i ; $n \cdot m$ coefficients a_{ii} ;
- m constraints of the form

$$c_j \leq \sum_{i=1}^n a_{ij} x_i,$$

and an objective function to be minimized ($x_i \ge 0$)

$$\sum_{i=1}^n b_i x_i.$$

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Solution of an LP:

assignment of values to the x_i satisfying the constraints and minimizing the objective function.

Remarks:

- Maximization instead of minimization: easy, just change the signs of all the b_i 's, i = 1, ..., n.
- Equalities instead of inequalities: $x + y \le c$ if and only if there is a $z \ge 0$ such that x + y + z = c (z is called a slack variable).

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Solution algorithms:

- Usually, one uses the simplex algorithm (which is worst-case exponential!).
- There are also polynomial-time algorithms such as interior-point or ellipsoid algorithms.

Tools and libraries:

- Ip solve
- CLP
- GLPK
- CPLEX
- gurobi

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We start with finite zero-sum games for two reasons:

- They are easier to solve than general finite two-player games.
- Understanding how to solve finite zero-sum games facilitates understanding how to solve general finite two-player games.

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In the following, we will exploit the zero-sum property of a game *G* when searching for mixed-strategy Nash equilibria. For that, we need the following result.

Proposition

Let G be a finite zero-sum game. Then the mixed extension of G is also a zero-sum game.

Proof.

Homework.

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Let G be a finite zero-sum game with mixed extension G'.

Then we know the following:

- Previous proposition implies: G' is also a zero-sum game.
- Nash's theorem implies: G' has a Nash equilibrium.
- Maximinimizer theorem + (1) + (2) implies: Nash equilibria and pairs of maximinimizers in G' are the same.

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Consequence:

When looking for mixed-strategy Nash equilibria in G, it is sufficient to look for pairs of maximinimizers in G'.

Method: Linear Programming

Approach:

- Let $G = \langle N, (A_i)_{i \in N}, (u_i)_{i \in N} \rangle$ be a finite zero-sum game:
 - $N = \{1, 2\}.$
 - \blacksquare A_1 and A_2 are finite.
 - $U_1(\alpha,\beta) = -U_2(\alpha,\beta)$ for all $\alpha \in \Delta(A_1), \beta \in \Delta(A_2)$.
- Player 1 looks for a maximinimizer mixed strategy α .
- For each possible α of player 1:
 - Determine expected utility against best response of pl. 2. (Only need to consider finitely many pure candidates for best responses because of Support Lemma).
 - Maximize expected utility over all possible α .

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- Result: maximinimizer α for player 1 in G'(= Nash equilibrium strategy for player 1)
- Analogously: obtain maximinimizer β for player 2 in G' (= Nash equilibrium strategy for player 2)
- With maximinimizer theorem: we can combine α and β into a Nash equilibrium.

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"For each possible α of player 1, determine expected utility against best response of player 2, and maximize."

translates to the following LP:

$$\alpha(a) \geq 0 \quad \text{ for all } a \in A_1$$

$$\sum_{a \in A_1} \alpha(a) = 1$$

$$U_1(\alpha,b) = \sum_{a \in A_1} \alpha(a) \cdot u_1(a,b) \geq u \quad \text{ for all } b \in A_2$$
 Maximize u .

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Example (Matching pennies)

	Н	Т	
Н	1,-1	-1, 1	
T	-1, 1	1,-1	

Linear program for player 1:

Maximize *u* subject to the constraints

$$\begin{split} \alpha(H) \geq 0, \ \alpha(T) \geq 0, \ \alpha(H) + \alpha(T) = 1, \\ \alpha(H) \cdot u_1(H,H) + \alpha(T) \cdot u_1(T,H) = \alpha(H) - \alpha(T) \geq u, \\ \alpha(H) \cdot u_1(H,T) + \alpha(T) \cdot u_1(T,T) = -\alpha(H) + \alpha(T) \geq u. \end{split}$$

Solution: $\alpha(H) = \alpha(T) = 1/2$, u = 0.

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- Remark: There is an alternative encoding based on the observation that in zero-sum games that have a Nash equilibrium, maximinimization and minimaximization yield the same result.
- Idea: Formulate linear program with inequalities

$$U_1(a,\beta) \le u$$
 for all $a \in A_1$

and minimize u. Analogously for β .

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- For general finite two-player games, the LP approach does not work.
- Instead, use instances of the linear complementarity problem (LCP):
 - Linear (in-)equalities as with LPs.
 - Additional constraints of the form $x_i \cdot y_i = 0$ (or equivalently $x_i = 0 \lor y_i = 0$) for variables $X = \{x_1, \dots, x_k\}$ and $Y = \{y_1, \dots, y_k\}$, and $i \in \{1, \dots, k\}$.
 - no objective function.
- With LCPs, we can compute Nash equilibria for arbitrary finite two-player games.

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Let A_1 and A_2 be finite and let (α, β) be a Nash equilibrium with payoff profile (u, v). Then consider this LCP encoding:

$$u - U_1(a, \beta) \ge 0$$
 for all $a \in A_1$ (6)

$$v - U_2(\alpha, b) \ge 0$$
 for all $b \in A_2$ (7)

$$\alpha(a) \cdot (u - U_1(a, \beta)) = 0 \quad \text{for all } a \in A_1$$
 (8)

$$\beta(b) \cdot (v - U_2(\alpha, b)) = 0 \quad \text{for all } b \in A_2$$
 (9)

$$\alpha(a) \ge 0$$
 for all $a \in A_1$ (10)

$$\sum_{a \in A_1} \alpha(a) = 1 \tag{11}$$

$$\beta(b) \ge 0$$
 for all $b \in A_2$ (12)

$$\sum_{b \in A} \beta(b) = 1 \tag{13}$$

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Remarks about the encoding:

■ In (8) and (9): for instance,

$$\alpha(a) \cdot (u - U_1(a, \beta)) = 0$$

if and only if

$$\alpha(a) = 0$$
 or $u - U_1(a, \beta) = 0$.

This holds in every Nash equilibrium, because:

- if $a \notin supp(\alpha)$, then $\alpha(a) = 0$, and
- if $a \in supp(\alpha)$, then $a \in B_1(\beta)$, thus $U_1(a, \beta) = u$.
- With additional variables, the above LCP formulation can be transformed into LCP normal form.

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Theorem

A mixed strategy profile (α, β) with payoff profile (u, v) is a Nash equilibrium if and only if it is a solution to the LCP encoding over (α, β) and (u, v).

Proof.

- Nash equilibria are solutions to the LCP: Obvious because of the support lemma.
- Solutions to the LCP are Nash equilibria: Let (α, β, u, v) be a solution to the LCP. Because of (10)–(13), α and β are mixed strategies.

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Solutions to the LCP are Nash equilibria (ctd.): Because of (6), u is at least the maximal payoff over all possible pure responses, and because of (8), u is exactly the maximal payoff.

If $\alpha(a) > 0$, then, because of (8), the payoff for player 1 against β is u.

The linearity of the expected utility implies that α is a best response to β .

Analogously, we can show that β is a best response to α and hence (α, β) is a Nash equilibrium with payoff profile (u, v).

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Proof (ctd.)

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Solution Algorithm for LCPs



Naïve algorithm:

Enumerate all $(2^n - 1) \cdot (2^m - 1)$ possible pairs of support sets.

Convert the LCP into an LP:

For each such pair $(supp(\alpha), supp(\beta))$:

- Linear (in-)equalities are preserved.
- Constraints of the form $\alpha(a) \cdot (u U_1(a, \beta)) = 0$ are replaced by a new linear equality:

■
$$u - U_1(a, \beta) = 0$$
, if $a \in supp(\alpha)$, and
■ $\alpha(a) = 0$, otherwise,

Analogously for $\beta(b) \cdot (v - U_2(\alpha, b)) = 0$.

- Objective function: maximize constant zero function.
- Apply solution algorithm for LPs to the transformed program.

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Solution Algorithm for LCPs



- Runtime of the naïve algorithm: $O(p(n+m) \cdot 2^{n+m})$, where p is some polynomial.
- Better in practice: Lemke-Howson algorithm.
- Complexity:
 - unknown whether LcpSolve \in **P**.
 - LcpSolve ∈ **NP** is clear (naïve algorithm can be seen as a nondeterministic polynomial-time algorithm).

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- Computation of mixed-strategy Nash equilibria for finite zero-sum games using linear programs.
 - → polynomial-time computation
- Computation of mixed-strategy Nash equilibria for general finite two player games using linear complementarity problem.
 - \rightsquigarrow computation in **NP**.